

# Material Science and Material Engineering

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# CONTENTS

<b>Chapter 1. Introduction to Material Science .....</b>	<b>1</b>
— <i>Dr. Vikrant Sharma</i>	
<b>Chapter 2. Classification of Material Science .....</b>	<b>14</b>
— <i>Mr. Ravi Prakash Upadhyai</i>	
<b>Chapter 3. Composition of the Atoms.....</b>	<b>28</b>
— <i>Dr. Purnima Nag</i>	
<b>Chapter 4. Chemical Bonding .....</b>	<b>41</b>
— <i>Dr. Purnima Nag</i>	
<b>Chapter 5. Extensive and Intensive Properties.....</b>	<b>54</b>
— <i>Dr. Manisha Sharma</i>	
<b>Chapter 6. Free Electron Theory .....</b>	<b>68</b>
— <i>Dr. Sunil Sharma</i>	
<b>Chapter 7. Ferroelectricity .....</b>	<b>79</b>
— <i>Dr. Nitin Pratap Singh</i>	
<b>Chapter 8. Electrical Resistivity and Conductivity .....</b>	<b>91</b>
— <i>Dr. Manjunath C</i>	
<b>Chapter 9. Crystalline Materials.....</b>	<b>104</b>
— <i>Adarsha H</i>	
<b>Chapter 10. Crystal Defects .....</b>	<b>112</b>
— <i>Koushik V Prasad</i>	
<b>Chapter 11. Reason of Frenkel.....</b>	<b>116</b>
— <i>Sandeep V</i>	
<b>Chapter 12. Polymer Degradation .....</b>	<b>128</b>
— <i>Raghavendra Rao P S</i>	

## CHAPTER 1

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### Introduction to Material Science

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Materials science is the examination of the characteristics of solid objects and how a material's structure and composition affect those characteristics. Because of the vast diversity of material characteristics, it emerged from a synthesis of sturdy physics, metallurgy, and chemistry. This is because of these qualities cannot be fully understood within the confines of any one conventional science. Materials may be chosen or created for a huge variety of purposes, ranging from stainless applications to computer microchips, with just a rudimentary grasp of the sources of features. Engineering fields including electronics, aircraft, telecommunication, processing information, nuclear power, and conversion of energy depend on materials science as a result. Materials technology and science is a heterogeneous field that has only just begun to take on recognizable shape. The field's practitioners create and work with elements that are utilized to create things, including buildings, machines, and gadgets. The creation and use of information connecting the constitution, structure, and material processing to their qualities and applications is the focus of materials science and engineering

Materials are significant to humanity because of the advantages that may be obtained by modifying their inherent characteristics. Examples include optical transmittance, magnetism, dielectric constant, strength, and toughness. The interior structures of both the materials are the source of each of these characteristics. Materials' structural characteristics include their atom kinds, local atomic configurations, and groupings of these combinations into nanostructures. Different kinds of materials, including metallic, plastics, earthenware, composites, semiconductors, bio-materials, and nanomaterials, can be classified into discrete domains. It is possible to classify materials science as an interdisciplinary field due to its breadth. It encompasses research into the composition and characteristics of various materials, the development of novel material types, and the tinkering with the properties of existing materials to meet the demands of a certain application

The fundamental goal of materials science is to characterize a material in order to relate its desirable qualities and relative performance to the structure of its atoms and phases. The choice of metal for a given application is frequently influenced by the physical qualities of the material. The material structure and composition, fracture and stress analysis, conductivity, visual, and thermal conditions, to mention a few, are just a few of the numerous aspects that are involved in this. Additionally, it makes use of manufacturing, processing, modelling, and design techniques. Numerous ancillary fields, including as crystallography, microscopes, printing, mineralogy, photonics, and particle diffraction, are involved in materials science research.

The creation of metals and alloys into forms and with properties appropriate for practical use is known as metallurgy. It is an area of applied founded on a thorough knowledge of the



compositions, characteristics, and structures of metals and alloys. Steel has by far been the most significant engineering material during the past few centuries, with metallurgy having long held the top spot as the most significant engineering materials. However, this stance is being challenged more often in many fields by alternative materials including composites, plastics, and ceramics. Materials science and engineering, one of the broadest study disciplines, is a relatively recent development that combines metallurgy with other fields like bottle and ceramic new tech, mineral composition, physical and synthetic chemistry, strong quantum mechanics, and polymer science which includes all structural and practical materials.

The study of materials is a multidisciplinary endeavour known as materials science. Materials engineering is a branch of engineering that focuses on creating and enhancing materials as well as discovering new applications for them in various sectors of the economy. The Age of Enlightenment marked the beginning of materials science's intellectual development as scientists started to employ analytical methods from chemistry, economics, and engineering to comprehend early phenomenological data in metal and mineralogy. Engineering, chemistry, and physics are still used in materials science. As a result, academic institutions have traditionally regarded the discipline as a subfield of these linked fields. Major technical colleges all over the globe established specialised schools for its study as materials science became more generally acknowledged as a unique and separate discipline of the sciences and engineering starting in the 1940s.

Materials scientists place a strong emphasis on comprehending how a material's processing history affects its structure, and subsequently, its characteristics and functionality. The materials paradigm describes how links between processing, structure, and characteristics are understood. This paradigm is utilised to expand knowledge in a number of fields of study, including metallurgy, nanotechnology, and biomaterials. Investigating materials, goods, buildings, or components that fail or do not work as intended and result in human harm or property damage is a crucial component of forensic engineer and failure analysis, which also heavily relies on materials science. These kind of investigations are essential for understanding, for instance, the reasons behind different aircraft accidents and events.

## History

A period's preferred subject matter is often a distinguishing characteristic. Examples from history, although arbitrary, are the terms Stone Age, Bronze Age, Iron Age, and Steel Age. Materials science is one of the earliest branches of engineering and applied science. It is said to have originated from the production of ceramics and its alleged offshoot, metallurgy. Directly from metallurgy, which itself developed from the use of fire, came modern materials science. When American scientist Josiah Willard Gibbs proved that the thermodynamic qualities connected to atomic structure in different phases are linked to the physical properties of a material, it marked a significant advancement in our knowledge of materials. The study and engineering of the metallic alloys, as well as silica and carbon materials, utilised in manufacturing space vehicles allowing space exploration, were important contributions to contemporary materials science. Rubber, plastics, semiconductors, and biomaterials are just a few of the innovative inventions that materials science has both fueled and been fueled by.

Many future materials science departments were originally metallurgy or ceramics engineering departments before the 1960s (and in some instances decades later), reflecting the 19th and early 20th century concentration on metals and ceramics. The Advanced Research Projects Agency,



which provided funding for a number of university-hosted labs in the early 1960s "to extend the national programme of fundamental research and training in the materials sciences," played a role in the development of materials science in the United States. The emerging subject of material science, in contrast to mechanical engineering, concentrated on addressing materials at the macro-level and on the idea that materials are constructed using knowledge of behaviour at the microscopic level. The design of materials began to be based on particular desired features as a result of the increased understanding of the relationship between atomic and molecular processes as well as the general properties of materials. Since then, the discipline of materials science has expanded to include all types of materials, including ceramics, polymers, semiconductors, magnetic materials, biomaterials, and nanomaterials, which are often divided into three categories: ceramics, metals, and polymers. The active use of computational methods to discover novel materials, forecast attributes, and comprehend events has been the most significant shift in materials research during the last several decades.

### **Definition of material**

A period's preferred subject matter is often a distinguishing characteristic. Examples from history, although arbitrary, are the terms Stone Age, Ancient Egypt, Iron Age, and Steel Age. Computational physics is one of the earliest branches of engineering & applied science. It is said to have originated from the production of ceramics and its alleged offshoot, metallurgy. Directly from metallurgy, which itself developed from the use of fire, came modern materials science? When American scientist Josiah Willard Gibbs proved that the thermodynamic qualities connected to atomic structure in different phases are linked to the physical characteristics of a material, it marked a significant advancement in our study of materials. The study and engineering of the metallic alloys, as well as silica and carbon materials, utilised in manufacturing space vehicles allowing space exploration, were important contributions to contemporary materials science. Rubber, plastics, semiconductors, and biomaterials are just a few of the innovative inventions that materials science has both fueled and been fueled.

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One of the most important aspects of the study of materials is structure. The study of "the links that exist between structures and characteristics of materials" is central to the definition of the area. From the atomic level all the way up to the macro level, materials science investigates the

structure of materials. Characterization is the process through which materials scientists look at a material's structure. This encompasses techniques like X-ray, electron, or neutron diffraction as well as several types of spectroscopy and chemical analysis including Spectroscopic techniques, energy-dispersive spectroscopy, chromatography, differential thermal, electron microscope examination, etc.

### **Crystallography**

The study of crystallography looks at how atoms are arranged in crystalline substances. For material scientists, crystallography is a helpful technique. Since single crystals' natural forms mirror their atomic structure, the impacts of the crystallographic arrangement of atoms are often simple to see macroscopically. Furthermore, crystalline imperfections often regulate physical qualities. For one to comprehend crystallographic flaws, one must first have a solid grasp of crystal structures. Materials often don't exist as a single crystal, but rather as a polycrystalline aggregation of tiny crystals or grains with various orientations.

As a result, the powder diffraction technique, which makes use of polycrystalline materials containing many crystals and their diffraction patterns, is crucial for determining structural details. The majority of substances have a crystalline form, although certain significant substances lack a typical crystal structure. Many polymers are fully non-crystalline, whereas others exhibit variable degrees of crystallinity. Amorphous materials lack any long-range structure in their atomic configurations, including glass, certain ceramics, and many types of natural materials. To provide thermodynamic and mechanical explanations of physical characteristics, the study of polymers integrates components of chemical and stochastic thermodynamics.

The structure of a prepared surface or thin sheets of material as revealed by a microscope magnified above 25 times is referred to as microstructure. It works with objects ranging in size from 100 nm to a few centimetres. Strength, high hardness, ductility, hardness, damage tolerance, high tempsbehaviour, wear resistance, and other physical properties can all be significantly influenced by a material's microstructure, which can be broadly categorised into metallic, polymeric, ceramic, and composite materials. The majority of conventional materials, including metals and ceramics, have a microstructure. It is technically impossible to produce a material in its pristine crystal form. Defects like precipitates, grain boundaries (Hall-Petch relationship), vacancies, interstitial atoms, or substitutional atoms, for instance, may be found in any crystalline material. These bigger flaws are visible in the microstructure of materials, and improvements in modelling have enabled a better understanding of how faults might be exploited to improve material qualities.

### **Thermodynamics relating to material science**

The study of heat, temperature, and how they relate to work and energy is known as thermodynamics. It defines macro-level terms that help characterise a body of matter or radiation in part, such as internal energy, entropy, and pressure. It claims that universal restrictions that apply to all materials govern how those variables behave. The six laws of mechanics express these broad limitations. The behaviour of a body in its whole is described by thermodynamics, not the behaviour of the vast majority of its tiny components, such as molecules, at the microscopic level. The rules of thermodynamics is derived from statistical mechanics, which also describes the behaviour of these tiny particles. The science of materials depends heavily on the study of thermodynamics. Chemical reactions, magnetization, polarizability, and elasticity are

just a few examples of the broad phenomena that it serves as the basis for in materials science and engineering. Understanding phase diagrams and phase equilibria are also aided by it.

### **Materials for energy**

A civilization that has evolved industrially requires a lot of energy and resources. The movement and transformation of energy and materials via the techno-economic system is necessary for all physical aspects of contemporary life, including transportation, heating and cooling, industrial activities, communications, and so on. The lifeblood for industrial civilization is these two fluxes, which are inextricably linked. The connection between materials science and energy use is extensive and intricate. Materials play a crucial role in every step of energy generation, distribution, conversion, and consumption, and often, particular material qualities are required. New materials and enhancements to existing ones may be produced on a scientific foundation thanks to the remarkable advancement in our knowledge of the characteristics and structures of materials. This leads to higher efficiency and cheaper prices.

### **Classification of materials connected to energy**

Numerous categories exist for dividing up energy materials. For instance, they may be separated into passive and active materials. Those in the passive category serve as buildings, tools, or containers instead of actively participating in the energy conversion process, such as oil drills, pipelines, turbine blades, or reactor vessels. Active materials, such as solar cells, batteries, catalysts, and superconducting magnets, are those that actively contribute to the conversion of energy. The usage of energy materials in current, future, and potential energy systems is another approach to categorise them. The materials issues in traditional energy systems, such those using fossil fuels, hydroelectric power, and nuclear reactors, are well established and often linked to structural mechanical qualities or enduring chemical effects like corrosion. Advanced energy systems are currently under development and are being used in a small number of markets. Shale and tar sands oil, coal gasification and liquefaction, photovoltaics, geothermal energy, and wind power are a few of them. Potentially useful future energy technologies still need a lot more study and commercial deployment before they can be employed. These include of fast-breeder reactors with hydrogen fuel, biomass conversion, and superconducting magnets for power storage.

It is helpful to categorise energy materials as passive, active, or related to current, future, or advanced energy systems since it gives a sense of the kind and level of urgency of the linked material needs. However, the material qualities that are crucial for diverse energy applications provide the clearest foundation for understanding the relationship between energy and materials. Such a framework is best shown via instances due to its breadth and diversity. For instance, in the oil refining process, reaction containers need to have certain mechanical and temperature characteristics, but catalysis is the crucial step.

### **Applications of energy-related materials**

#### **High-temperature materials**

A fuel must first be burnt to a high enough temperature to heat some fluid (often steam) in order to extract usable work from it. The development of materials for combustion chambers, pistons, valves, rotors, and turbine blades that can perform at ever-higher temperatures is crucial since thermodynamics shows that the efficiency of converting heat to work increases with temperature. Modern steam turbines attain efficiencies of 35 percent or higher, but the original steam engines had efficiencies of less than 1 percent. This increase has been partially attributed to better design

and metalworking precision, but a significant percentage is due to the use of better high-temperature materials.

Cast iron and subsequently common steels were used to construct the first engines. Later, high-temperature alloys including silicon, nickel, molybdenum, chromium, and those elements failed or melted at temperatures more than 540° C (1,000° F). However, contemporary combustion processes are approaching the practical temperature limitations that can be accomplished with metals, thus new materials particularly intermetallic compounds and ceramics—that can work at higher temperatures are being researched.

Atomic and electronic properties are structural characteristics that restrict the usage of metals at high temperatures. Dislocations exist in all materials. The most basic of these are caused by atom planes that do not go all the way through the crystal, leaving a line where the plane terminates with fewer atoms than usual. The outer electrons are free to migrate in metals. This results in a delocalized cohesiveness, which enables dislocations to migrate to release tension when it is applied. As a consequence, metals are ductile; under stress, they not only yield plastically over time rather than snapping instantly, but they can also be readily manipulated into the necessary forms.

Although this is a positive characteristic, the material will lose its usefulness if the temperature is too high since the higher the temperature, the larger the plastic flow under stress. Materials that limit the mobility of dislocations are being researched as a workaround for this problem. Because the valence or ionic connections that hold ceramics like silicon nitride or silicon carbide and intermetallics like nickel aluminide together are extremely confined, they show promise. In contrast to nonmetals, where the atoms are joined by rigid rods, metals seem to be kept together by a slick glue. As a result, dislocations find it considerably more difficult to move in nonmetals; increasing the temperature does not promote dislocation motion, and a far larger amount of stress is required to get them to give.

They are also far more resistant to chemical assault and have melting values that are substantially higher than those of metals. But these appealing qualities cost money. They are fragile due to their appealing structure, which prevents them from flowing under high stress and makes them more likely to collapse by cracking. The goal of contemporary research is to improve the material's ductility by changing both its composition and manufacturing processes. For instance, the number of flaws at which cracks may form is reduced when ceramic powders are heated, and the cohesiveness between crystal grains at where fractures often form is strengthened when certain metals are added in trace quantities to intermetallics. These developments offer the potential of making it possible to create heat engines that are far more efficient than those now on the market, together with intelligent design.

### **Diamond drills**

A great illustration of how an outdated material may be improved upon is diamond drill bits. The hardest material known to man, diamond, would make an ideal drill bit if it weren't so costly and had weak planes in its crystalline lattice. The planes extend throughout the substance in natural diamonds because they are single crystals, making them easy to split. While these cleavage planes enable a diamond cutter to create stunning diamonds, they are a complete failure when drilling through rock. Stratapax, a powdered diamond material created by the American General Electric Company, overcame this restriction. This is made up of thin plates of synthetic diamond powder that have been sintered to attach tungsten-carbide studs (fusing by heating the material

below the melting point). The polycrystalline nature of the diamond plate prevents cleavage from spreading across it. The end product is an extremely tough bit that can drill through stone to get natural gas and oil without cleaving.

### **Oil platforms**

The prevention of fracture propagation in offshore platforms serves as an excellent illustration of solving old issues with contemporary techniques. The main structure is made up of welded steel tubing, which is stressed by the ocean waves in constantly changing ways. A platform must have a long lifespan and not be lost due to early metal failure since the cost of developing and installing one may reach several billion dollars.

75 percent of the waves in the North Sea are taller than 2 metres (six feet), which puts a lot of strain on the platform. The end effect of cyclic stress on a metal is fatigue failure, in which surface fissures develop, enlarge over time, and finally result in the metal breaking. The weak points in this procedure are the welds because weld metal has poorer mechanical qualities than steel and these are exacerbated by internal stresses and flaws (such as minute voids and oxide particles) that are created during the welding process. Additionally, the T- and K-shaped joints that make up the tube geometry at the weld act as natural stress concentrators. Welds are the site of fatigue breakdown on oil platforms.

Cyclic stress causes dislocations to develop and move back and forth in the metal, which leads to fatigue. Barriers like tiny spaces, grain boundaries, additional dislocations, contaminants, or even the surface itself may prevent dislocation motion. Dislocations that are held down in this way prevent additional stress-induced dislocations from moving, which leads to the formation of a tangled dislocation network and a hard point in the weld.

The stress is consequently difficult to release, and the fatigue process' distinctive forms of dislocation motion start a crack at the weld surface. This issue, which is a direct consequence of the weld's microstructure, might be reduced by making the weld very homogeneous, ideally out of the same substance as the tube, and by giving the junction a shape that is only very slightly bent. However, this is not yet practical despite the complexity of contemporary welding processes.

Therefore, a different approach is used in which the weld crack's development is tracked in order to make repairs in time to prevent catastrophic failure. This is possible because the shape of the joint allows for a relationship between the depth of the fracture and the amount of time it takes for it to become significant. In contrast, the growth rate rises as the fracture becomes bigger in laboratory testing when basic metal strips are subjected to cyclic stress. Stress is considerably more uniformly distributed in the T or K shape of oil platforms, and the fracture does not advance at an increasing rate until it is almost deadly.

The skin effect, a phenomena where a high-frequency alternating current is constrained to a conductor's surface, provides the basis for a method for determining the fracture depth. Due to the fact that an increase in crack depth results in an increase in the current route, which in turn produces a rise in voltage drop, it is now feasible to measure the surface of a tiny area using a conventional metre. As a result of measurement over time, the time to failure may be predicted and repairs can be made before failure happens. In this instance, understanding microstructure, materials science related to fatigue, and the investigation of fracture development have resulted in a straightforward testing method of significant economic value.



An in-depth knowledge of the variables affecting weld structure is being gained by investigations of solidification, gas dissolution, and the effects of fluxes, as well as mathematical modelling of mass motion and heat transport (including convection). This information should enable the production of welds with the far fewer flaws.

### **Radioactive waste**

Radioactive waste disposal offers a distinct illustration. Here, safety and the appearance of safety are more important than money. Until the public no longer believes that nuclear power poses a threat, waste disposal will remain one of the barriers to its use. The present strategy calls for three barriers to be placed between the garbage and people: a solid material encapsulation, a metal container, and burial of the metal container in geologically active formations. While the second stage calls for a material that is very resistant to oxidation and deterioration, the first step needs an inert, stable substance that will retain the radioactive atoms contained for a very long period.

Two strong encapsulation possibilities are shown here. The first is borosilicate glass, which may be heated together with radioactive material to incorporate it into the structure of the glass. Glass serves as a superb barrier to the passage of radioactivity due to its very low solubility and extremely low rate of atom movement. Glass devitrifies, or transforms from an amorphous glassy state to a crystalline one, at the high temperatures brought on by radioactive decay. During this transformation, the material develops many fissures and is no longer a reliable barrier to the escape of radioactive atoms. (Since salt has a greater thermal conductivity than rock and can disperse heat more readily, this issue is particularly acute in rock formations.) Storing the garbage above ground for around ten years may help with the issue. As a result, the temperature that would be attained after encapsulation would be reduced from the original high rate of decay. When handled in this manner, borosilicate glass makes a great encapsulation medium for reactor waste that has been sitting about for around ten years. The other contender is a man-made rock composed of mineral combinations like perovskite and zirconolite. These have been known to sequester radioactive elements for hundreds of millions of years in their natural condition because they are very soluble. They are ceramic, crystalline materials having crystal structures that may immobilise radioactive elements. They are already crystalline, thus devitrification is not a possibility.

Radioactive waste must be placed into corrosion-resistant canisters after being encapsulated. These can be manufactured of nickel-steel alloys, but the best material to far is a titanium compound with traces of carbon and iron, as well as minor quantities of nickel and molybdenum. These metals are evaluated by submerging them in brine even though they are intended to be buried in as dry an environment as feasible. According to tests, the surface of the titanium substance, also known as Ti code 12, would erode away less than one micrometre (one thousandth of a millimetre, or four tens of an inch), every year, in saltwater at a temperature of 250° C (480° F). This astounding performance is largely due to the titanium's formation of a thick, very resistant oxide skin when it is exposed to oxygen. Corrosion couldn't get into the canisters for thousands of years.

It is important to keep in mind that although the waste is initially very radioactive and harmful, the risk lessens with time when determining the efficacy of such waste disposal. After a few hundred years, the threat from radioactivity is significantly reduced, and after 500 years, it is very low and after 1,000 years, it is almost nonexistent. Groundwater must go to the canister,



consume it, and then leach out the radioactive atoms from the encasing glass or ceramic in order to get through the triple barrier system. Most likely, this process would go on for a lot longer than a single millennium. Radioactive waste disposal may be made safer than existing practises for other hazardous waste disposal with careful use of materials science.

### **Photovoltaics**

For the production of energy, photovoltaic systems are a promising substitute to fossil or nuclear sources. Sunlight is free, it doesn't deplete a finite resource, and it doesn't produce any pollution when it's turned into power. In fact, photovoltaics are being used in places like space or isolated, rural areas where electricity cables from utility grids seem to be either impractical or nonexistent the price of solar systems prevents sunshine from being widely used to produce power. In order to bring down the price to levels that can compete with those for fossil or nuclear fuels, materials science must be used.

The electrical structure of solar cells with two or more layers of semiconductor material that can absorb photons, the main energy units of light, is what allows light to be converted into electricity. The semiconductor's electrons' energy level is raised by the photons, which prompts some of them to move from the lower-energy valence band to the higher-energy conduction band. Both the conduction band's electrons and the holes they have left in the valence band are movable and may be made to move by applying a voltage. An electric current is made up of moving electrons and holes moving in the opposite direction. The junction of two incompatible semiconducting materials, one of which has a propensity to give up electrons and acquire holes (thereby becoming the positive, or p-type, charge carrier), while the other absorbs electrons, produces the force that pushes electrons and holes through a circuit (becoming the negative, or n-type, carrier). The band gap, a property of the electrical structure that makes this possible, is comparable to the energy needed to shift an electron from one band to another. The size of this difference is significant. Since there is a wider variety of light frequencies with high enough energies, the narrower the band gap, the more effectively light will be converted to electricity since only photons with energies larger than the band gap may excite electrons from the valence band to the conduction band. On the other hand, the gap cannot be too tiny since the electrons and holes would then easily merge, making it impossible to sustain a significant current.

The band gap specifies the theoretical maximum efficiency of a solar cell, but other material considerations prevent this from being achieved. Every material has an inherent rate at which electrons and holes recombine, eliminating their contributions to electric current. Surfaces, interfaces, and crystal defects including grain boundaries, dislocations, and impurities facilitate this recombination. Additionally, part of the light may travel through the cell without excitation of electrons to the conduction band and some of it is reflected by the surface of the cell as opposed to being absorbed. The manufacture of silicon, the primary component of modern solar cells, serves as a good illustration of improvements in the trade-off between cell cost and performance. In the beginning, high-purity silicon was created from a silicon melt by painstakingly picking out a crystals that had developed as the liquid material progressively accumulated and solidified. The high-purity, single-crystal ingot produced by this procedure, known as the Czochralski method, was subsequently cut into wafers that were roughly 1 millimetre (0.04 inch) thick. Then, impurities were "doped" onto the surface of each wafer to produce p- and n-type substances with junctions between them. After that, metal was placed to create electrical leads, and the wafer was enclosed to produce a cell with a diameter of around 100 millimetres.

This method was time-consuming and costly, but it has been significantly improved in many respects. For instance, by chemically transforming common silicon to silane or trichlorosilane and then reducing it back to silicon, high-purity silicon may be produced at much lower cost. With little energy input, this silane process can run continuously at a high output rate. Methods of directly pulling molten silicon into thin sheets or ribbons have been devised; they may yield crystalline, polycrystalline, or amorphous material. This avoids the expense and waste involved with cutting silicon into wafers. Making thin films on ceramic substrates is another option; this technology utilizes a lot less silicon than others. Although single-crystal silicon is more efficient than other types, it is also much more costly. Finding a material with the right balance of price and efficiency to make solar power commercially viable is the materials problem.

### **Materials for ground transportation**

An excellent context for illustrating how materials science works to develop new or better materials in response to important human needs is the global effort to increase the efficiency of ground transportation vehicles, such as cars, buses, trucks, and trains, and thereby reduce the humongous amounts of pollutants they emit. The narrative is intriguing, especially for the automotive sector, where the quest for lighter vehicles, fewer emissions, and better fuel efficiency has resulted in fierce rivalry between aluminium, plastics, and steel businesses for shares in the large markets involved (40 million to 50 million cars and trucks per year worldwide). Materials scientists have a crucial role to play in this conflict since the success of their work to create better materials will affect the design and feasibility of next cars.

The establishment of specialised programmes, consortia, or centres to create better metals, polymers, or ceramics for automotive applications shows how seriously suppliers to the industry take the need to either maintain or enhance their part of these vast markets.

For instance, in the US, the Aluminum Company of America (Alcoa) and Reynolds Metals both started programmes called the Aluminum Intensive Vehicle (AIV) to develop materials and methods for producing automobile "space frames" made of aluminium alloys rods and die-cast connectors joined by welding and glueing. Not to be outdone, another aluminium business, Alcan Aluminium Limited of Canada, started to research the creation of automotive unibodies from adhesively bonded aluminium sheet as part of a programme called aluminium structured vehicle technology (ASVT).

A centre named D&S Plastics International was established in the Detroit, Michigan, region of the United States by three firms in order to assist in achieving the plastics industry's strong desire in replacing as many metal automotive components as possible. This center's particular goal was to create materials and a method for concurrently producing many linked panels or components (such bumper fascias and body panels) out of various kinds of plastics. The centrepiece of the project was a 4,000-ton co-injection press, which might result in cost savings of up to 50% and increase the appeal of using plastics for automotive applications.

Materials scientists with specialised training in sophisticated metals, polymers, and ceramics have been driving a revolution in the automotive industry via programmes like these as well as several more run by suppliers and inside the vehicle corporations themselves. The following sections outline particular requirements that have been established for enhancing the performance of cars and other types of ground transportation, as well as the methods that scientists have used to meet those requirements.

## Aluminum

Since aluminium has a density that is around one-third that of steel, replacing steel with aluminium in vehicles would appear to be a rational way to reduce weight, improve fuel efficiency, and reduce hazardous emissions. However, such replacements cannot be done without taking into account the important variations in the other characteristics of the two metals. To assist in evaluating a material's acceptability for a particular applications based on how its qualities balance against the load and performance criteria provided by the design engineer is one significant aspect of the materials scientist's work. To evaluate the usage of aluminium in automobile panels—components like doors, hoods, cargo decks, and roofs that may account for more than 60% of a vehicle's weight in this example (aluminium vs steel), it is helpful to think about the materials scientist's method.

Any metal has two main characteristics: (1) yield strength, or the capacity to withstand permanent deformation (like a fender dent), and (2) elastic modulus, or the capacity to withstand elastic or springy displacement like such a drum head. The yield strength of aluminium may be alloyed to be the same as that of a fairly strong steel, giving it a comparable resistance to denting in an automotive panel. On the other hand, alloying typically has little to no impact on the elastic modulus of metals. For instance, automobiles door panels or hoods made of aluminium alloys, which all have a modulus that is roughly one-third that of steel, would be floppy and experience significant deflections when buffeted by the wind. Aluminum would seem to be a questionable option for body panels from this perspective.

By making the aluminium sheet stock three times as thick as the steel it is meant to replace, one may try to make up for this shortcoming. However, doing so would just raise the weight to a level that would be comparable to a steel structure, defeating the point of the exercise. Fortunately, when proper consideration is made of the way an actual door panel deflects, constrained as it is by the door edges, it is possible to use aluminium sheet that is only slightly thicker than the steel it would replace and still achieve equivalent performance, as was elegantly demonstrated in 1980 by two British materials scientists, Michael Ashby and David Jones. The overall consequence of using aluminium instead of steel for such body components would be a weight reduction of over two thirds. This shows that a key element in the effective use of materials science is a knowledge of the interactions between material characteristics and structural design.

The creation of alloys, which sometimes entails creating alloys for muchspecialised uses, is another significant task of the materials scientist. For use as cast aluminium nodes (connectors) in their space frame design, Alcoa's materials scientists and engineers created a specific casting alloy. Metal castings often have very little toughness or ductility, making them vulnerable to brittle fracture and catastrophic failure. Since having somewhat brittle body parts would compromise an automobile's integrity, a custom casting alloy and processing technique were created that provide a material with far more ductility than is typically offered by casting alloys.

A higher acceptance of aluminium in cars, trucks, buses, and even light rail vehicles is the result of several additional advancements in aluminium technology made by materials scientists and design engineers. Among these are alloys for air-conditioner parts that are designed to handle the greater pressures needed by ecologically safer refrigerants while still being chemically compatible with them. Additionally, alloys that combine high formability, corrosion resistance, and the capacity to attain maximal strength without heat treatment have been created; these

alloys gain strength throughout the forming process. As a result, a growing number of automobiles now incorporate significant amounts of aluminium in place of steel. With a limited-edition Jaguar sports vehicle that was almost entirely made of aluminium, including the engine, the chassis, and the skin, a milestone was attained in 1992. Honda's Acura NSX, which weighs more than 400 kilogrammes (900 pounds) of aluminium in comparison to the typical car's 70 kilos, and General Motors' Saturn, which has an aluminium engine block and cylinder heads, are both somewhat less costly and in full production. Alongside the British Land Rover, which started using all-aluminum body panels in 1948 because to a World War II-era lack of steel, came this and other vehicles. The automaker has kept using this material ever since.

## Steel

While the aluminium and plastics industries aim to reduce vehicle weight by replacing steel components with their products, the steel industry's objective is to fend off such advances with cutting-edge developments like high-strength, affordable "microalloyed" steels that achieve weight savings by layer reductions. Furthermore, alloys that can be bent (strengthened) in paint baking ovens rather than the separate, costly heat-treatment furnaces typically needed for standard steels have been created.

The microalloyed steels, also referred to as high-strength low-alloy (HSLA) steels, are fairly advanced in composition between carbon steels, whose characteristics are primarily determined by the amount of carbon they contain (typically less than 1%), and alloy steels, whose strength, toughness, and corrosion resistance are primarily determined by other elements, such as silicon, nickel, and manganese, added in slightly larger amounts. The HSLA steels were first created in the 1960s and revived in the late 1970s to meet the need for weight reduction via increased strength. They typically have low carbon content and little additions of other metals, including titanium or vanadium. By allowing for thickness reductions while still providing tensile strengths that can be up to three times greater than the carbon steels they are intended to replace (e.g., 700 megapascals versus 200 megapascals), they have helped to significantly reduce weight, albeit at the cost of a slight reduction in structural stiffness because their elastic moduli are identical to those of other steels. For two reasons, they are regarded as being quite competitive with aluminium substitutes: they are reasonably priced (steel sells for half the price of aluminium on a per-unit-weight basis); and very little change in fabrication and computation practises is needed when switching from carbon steel to HSLA steel, whereas significant changes are typically needed when switching to aluminium.

## Importance of Materials Science

The material science deals with the objects which are composed of what and why they act the way they do are lessons we learn from materials science. Materials engineering teaches us how to use knowledge to improve things and the way they are made. Research and industrial innovation in fields as diverse as aerospace and health are driven by materials science and engineering. The world needs ingredients that will result in success in order to build effective restorations. The materials used for restorations in dentistry have improved significantly in recent years. To help us do our tasks more effectively, producers who engage in research and development are always improving materials. The business is releasing this special edition of Compendium, which explores zirconia's material science, restorative methods, and products for actual restorations. Material study will be vital for scientists of all backgrounds to understand better how to engage in collaborative activities with the other disciplines as the contribution of

materials research and engineering to these other disciplines rises. Scientists must develop the abilities that will enable them to master certain topics, even while it is impractical for them to master a large corpus of scientific knowledge across numerous fields.

Choosing the appropriate material from among the tens of thousands of options is referred to as a materials challenge. The ultimate choice is often made based on a number of factors. Characterizing the in-service circumstances is the first step since they will determine the qualities needed from the material. Rarely does a material have the optimal or greatest combination of attributes. As a result, it can be required to swap out one quality for another. The traditional illustration incorporates ductility and strength; typically, a substance with considerable strength will only have little ductility. In these situations, a fair compromise among two or more attributes could be required. Materials and methods is perhaps the most critical heading to assess the overall quality of any data analysis dissemination product because it informs readers of the procedures, approaches, designs, and treatments we used in the research, enabling us to reproduce the studies, comprehend the linearity between the objectives' approach and the results, assess their applicability and relevance, and look for any signs of bias.

Materials science has been crucial to the advancement of technology. Different materials are preferable for distinct uses and have different abilities and drawbacks. Studying materials is a crucial first step in technology, which is the process of applying science to produce tools and items that benefit humans. A materials challenge involves choosing the best material from among the tens of thousands of options. The ultimate choice is often made based on a number of factors. Characterizing the in-service circumstances is the first step since they will determine the qualities needed from the material. Rarely does a material have the optimal or greatest combination of attributes. As a result, materials can be required to swap out one quality for another. The traditional illustration incorporates ductility and strength; typically, a substance with considerable strength will only have little ductility. In these situations, a fair compromise amongst two or more attributes could be required. A substance (often a solid, but some other condensing phases may be included) is characterized as a material if it is meant to be utilized for a certain purpose. We are surrounded by a wide variety of materials, which are used in everything from spaceships to automobiles and houses. Materials may be categorized into four primary groups: metals, semiconductors, ceramics, and polymers. Nanomaterials, biomolecules, and energy materials are just a few of the cutting-edge materials that are now being produced.

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## CHAPTER 2

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### Classification of Material Science

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Material is the substance that makes up an object. The definition of this phrase must be rather wide. They are categorised according to their characteristics. They possess qualities like as magnetism, thermal conductivity, heat capacity, stiffness, hardness, and thermal conductivity, among others. Materials are the fundamental components of industry, which are then treated and refined to produce new materials or usable items. Materials science is the field of study that deals with materials. Materials may be used in a variety of ways. In light of their application in various sectors, they are also categorised. Material selection is the process of deciding which materials will be utilised for a certain application.

Various qualities may be found in materials. Scientifically, however, matter's physical and chemical characteristics are taken into account. Electric, magnetic, thermal, and mechanical properties are subcategories of physical properties. Materials' states, such as solid, liquid, or gaseous, as well as solubility, pH, reactivity, surface tension, surface energy, corrosion, etc., are all examples of chemical characteristics. The elasticity, plasticity, ductility, durability, brittleness, hardness, malleability, resilience, stiffness, viscosity, and other mechanical qualities of a material are only a few examples.

**Elasticity:** When a force is released, a material usually rebounds to its original dimensions and form. The reverse of elasticity is a process called plasticity, in which the material maintains the altered form. Thermal conductivity, often known as conductivity, refers to how much heat can go through a substance. The mass of the substance per cubic centimeter is used to define density. Malleability or ductility refers to a material's capacity to alter shape while being stretched without deforming.

#### **Materials and Their Classification Bases on Properties:**

##### **Metal**

A metal is a substance that, when newly prepared, polished, or broken, has a brilliant look and transports electricity and heat quite well (from the Greek word *métallon*, "mine, quarry, and metal"). Typically, metals are malleable and ductile (can be drawn into wires) (they can be hammered into thin sheets). These characteristics are the outcome of the metallic link that exists between the metal's atoms or molecules. A metal may be a chemical element like iron, an alloy like stainless steel, a molecular complex like polymeric sulphur nitride, or any combination of these.

In physics, a metal is often thought of as any material that can conduct electricity at absolute zero degrees. Under extreme pressures, a variety of substances that are not typically categorised as metals become metallic. For instance, at pressures between 40 and 170 thousand times



atmospheric pressure, the nonmetal iodine progressively transforms into a metal. Equally, certain substances thought of as metals may change into nonmetals. At a pressure of little about two million times atmospheric pressure, sodium, for instance, turns into a nonmetal.

Arsenic and antimony are two elements that would normally qualify (in physics) as brittle metals but are often recognised as metalloids because of their chemistry (predominantly non-metallic for arsenic, and balanced between metallicity and nonmetallicity for antimony). Metals make up around 95 of the 118 elements in the periodic table (or are likely to be such). The number is approximate since there are no established definitions of the relevant groups, which causes the distinctions between metals, nonmetals, and metalloids to vary significantly. In astrophysics, the word "metal" is used more broadly to describe any chemical elements heavier than helium present in a star, rather than simply conventional metals. In this sense, carbon, nitrogen, oxygen, and neon, all of which are technically non-metals in chemistry, are the first four "metals" to accumulate in star cores via nucleosynthesis. Over the course of its lifespan, a star fuses lighter elements, mostly both hydrogen and helium, into heavier atoms. In this context, an astronomical object's metallicity is defined as the percentage of its mass that is made up of the harder chemical elements.

Metals are chemical elements that make up 25% of the crust of the Earth and are used in many facets of contemporary life. Because of their durability and strength, various metals are often used in construction of high-rise buildings and bridges, as well as in the majority of automobiles, household appliances, tools, pipelines, and train tracks. Historically, only precious metals were used as money, but in the contemporary period, coinage metals now include at least 23 different chemical elements. Copper usage is estimated to have started the history of refined metals about 11,000 years ago. Prior to the first recorded use of bronze in the fifth millennium BCE, gold, silver, iron (as meteoric iron), lead, and zinc were also in use. Early types of steel manufacturing, the discovery of sodium (the first light metal) in 1809, the emergence of contemporary alloy steels, and the creation of increasingly complex alloys following the conclusion of World War II are examples of later advances.

### **Properties of metal**

At least when they are newly prepared, polished, or shattered, metals appear bright and glossy. More than a few micrometres thick metal sheets look impenetrable, yet gold leaf emits green light. The ability of the metal atoms involved to easily shed their outer shell electrons is primarily responsible for the solid or liquid state of metals. In general, the attractive forces on the aluminum casing electrons of a single atom that result from interactions between the atoms in the solid or liquid form metal are stronger than the forces keeping those same electrons in place. The resulting delocalization of the electrons makes it possible to conceptualise the atomic structure of a metal as a collection of atoms encased in a cloud of relatively conduction electrons. A metallic link is the name given to this kind of contact. Due to the abundance of delocalized electrons in these elements, the toughness of metallic bonding for various elemental metals peaks around the middle of the ruthenium series.

There is a broad range in the densities of elemental metals, with lithium being the least dense (0.534 g/cm<sup>3</sup>) and manganese oxide being the most dense (22.59 g/cm<sup>3</sup>), despite the fact that most elemental metals have greater densities than most nonmetals. (Some of the 6d metal complexes are predicted to have densities greater than osmium, although projections on these densities vary greatly in the science, and in any event, mass manufacturing of these materials is

not feasible given the instability of their known isotopes.) Three light metals with major commercial significance are magnesium, aluminium, and titanium. Their relative densities of 1.7, 2.7, and 4.5 g/cm<sup>3</sup> may be compared to those of the more established structural metals, such as iron at 7.9 and copper at 8.9 g/cm<sup>3</sup>, which have densities of those metals. Thus, three aluminium balls of similar volume would weigh roughly as much as one iron ball.

Usually malleable and ductile, metals will flex under pressure without cleaving. It is believed that nondirectional metallic bonding has a substantial role in the ductility of the majority of metallic solids. In contrast, an ionic molecule like table salt crystallises when the planes of an ionic bond glide past one another and cause ions with the same charge to move closer to one another as a consequence. A covalently linked crystal, like a diamond, when fracture and crystal fragmentation occur, does not exhibit such a change. Hooke's Law for restoring forces, which states that the stress is directly proportional to the strain, may be used to explain reversible elastic deformation in metals. A persistent (irreversible) distortion known as plastic deformation or plasticity may be brought on by heat or pressures that exceed a metal's elastic limit. A force that is exerted may be tensile (pulling), compressive (pushing), shear, bending, or torsion (twisting).

The movement or displacement of structural flaws in the metal, such as grain boundaries, point vacancies, line and screw dislocations, stacking faults, and twins in crystalline and non-crystalline metals, may be impacted by a change in temperature. Metal fatigue, internal slide, and creep may follow. Metals often have one of three basic crystal structures: body-centered cubic (BCC), face-centered cubic (FCC), or hexagonal close-packed (hcp). Each atom in the bcc structure is positioned in the middle of an eight-atom cube. Each atom in fcc and hcp is surrounded by twelve others, however the way the layers are stacked varies. Depending on the temperature, certain metals adopt various structures.

### **Electrical and thermal properties of metal**

Metals are relatively excellent conductors of electricity. The energy levels of the electrons in a metal's electron cloud, at least in part, correspond to the energy levels during which electrical resistivity is possible since electrons in matter have only fixed rather than variable energy levels. There is an energy difference between the electrons in a material and the energy level at which conduction is possible in a semiconductor like silicon or a weak base like arsenic. As a result, nonmetals and semiconductors are relatively poor insulators.

The electrical conductivity of the elemental metals ranges from  $6.9 \times 10^3$  S/cm for manganese to  $6.3 \times 10^5$  S/cm for silver. A semiconducting metalloid like boron, in comparison, has an electrical conductivity of  $1.5 \times 10^6$  S/cm. Metallic components lose some of their electrical conductivity when heated, with one exception. When heated between 175 and +125 °C, plutonium becomes more electrically conductive. Metals are comparatively effective heat conductors. A metal's electronic structure contains highly mobile electrons that may quickly transfer vibrational energy brought on by heat.

The free electron model may be used to determine how a metal's electrons contribute to its heat capacity, thermal conductivity, and electrical conductivity. This, however, ignores the intricate structure of the metal's ion lattice. The positive potential brought on by the configuration of the ion cores makes it possible to take into account a metal's band structure or binding energy. Different mathematical models may be used, with the virtually free electron model being the most straightforward.

## Chemical properties of metal

Metals often have a tendency to lose electrons and generate cations. Over a range of periods, the majority will react with oxygen in the air to generate oxides (potassium burns in seconds while iron rusts over years). Others, such as palladium, gold, and platinum, do not react at all with the environment. In contrast to nonmetal oxides, that are acidic or neutral, metal oxides are often basic. There are certain exceptions, mostly extremely high oxidation state oxides like  $\text{CrO}_3$ ,  $\text{Mn}_2\text{O}_7$ , and  $\text{OsO}_4$ , which only undergo acidic reactions. Metals may be effectively protected against corrosion by painting, anodizing, or plating. But if chipping of the coating is anticipated, a more reactive metal from the electrochemical series has to be selected for coating. In an electrochemical cell made up of water and the two metals, corrosion is actually aided if the coating has become less reactive than the base metal.

## Alloys

A material with metallic qualities that is made up of two or more elements, at least one of which is metal, is referred to as an alloy. An alloy's composition may be either changeable or fixed. For instance, titanium and silicon make the alloy  $\text{Ti}_2\text{Si}$ , where the ratio of the two components is set, but gold and silver produce an alloy in which the proportions of precious metals may be freely modified (also known as an intermetallic compound). For practical application, the majority of pure metals are either excessively soft, brittle, or chemically reactive. Alloys are created by mixing various metal ratios to alter the properties of pure metals and obtain desired results. In general, alloys are created to increase a material's strength, hardness, corrosion resistance, or aesthetic appeal. The iron alloys (steel, stainless steel, cast iron, tool steel, alloy steel) make up the biggest share of all the metallic alloys now in use, both in terms of quantity and commercial value. Low-, mid-, and high-carbon steels are produced when iron is alloyed with different amounts of carbon, with higher carbon levels lowering ductility and toughness. Cast irons are created by adding silicon, whereas stainless steels are created by adding chromium, nickel, & molybdenum to metallic materials in amounts more than 10%.

The alloys made of aluminium, titanium, copper, and aluminium are further noteworthy metals. Since prehistoric times, when the Bronze Age got its name from bronze, metals have been used widely. Electrical wire is one of their most significant uses today. The remaining three metals' alloys were created very recently, and because of their chemical reactivity, they need to be extracted using electrolytic methods. The high strength-to-weight ratios of the alloys made of aluminium, titanium, and mg are prized; magnesium may also act as an electromagnetic shield. These materials are perfect for applications in the aerospace and certain automotive industries where a high strength-to-weight ratio takes precedence over material cost. For very demanding applications like jet engines, special alloys may include more than 10 elements.

## Base, noble, and precious metals

A metal that is quickly corroded or oxidised, such as one that readily reacts with diluted hydrochloric acid (HCl) to produce metal chloride and hydrogen, is referred to as a base metal in chemistry. Iron, nickel, lead, and zinc are among examples. Though it doesn't react with HCl, copper is regarded as a base metal due to how easy it may oxidise. Rhodium pellets, cylinders, and powder all lined up together. The phrase "noble metal" is often used to contrast with "base metal." In contrast to the majority of base metals, noble metals are resistant to corrosion or oxidation. They often are valuable metals because of their apparent scarcity. Gold, platinum, silver, palladium, iridium, and palladium are among examples. Base metal is used to contrast with

precious metal, or those with great economic worth, in numismatics and alchemy. The transformation of base metals to precious metals, especially coinage metals like silver and gold, has long been an aim of alchemists. Today, the majority of coins are composed of low-value base metals; in the past, coins typically got their worth mainly from the precious metals they contained.

The noble metals, like the precious metals, are less reactive chemically than other elements and have high lustre and electrical conductivity. While historically valuable as money, precious metals are today primarily valued as industrial and investment commodities. The ISO 4217 currency code is assigned to gold, silver, platinum, and palladium separately. Gold and silver are the most well-known precious metals. Although both have commercial use, their usage in jewellery, coins, and fine art is more well-known. The platinum group metals, of which platinum is the most traded, are also considered to be precious metals. These include ruthenium, rhodium, rhodium, osmium, iridium, and platinum. The demand for gold bullion is fueled by their position as investments and a store of wealth in addition to their practical usage. As of the autumn of 2018, the prices of palladium and platinum were around 75 percent lower than those of gold. Despite being far less costly than these metals, silver is nonetheless often regarded as a valuable metal due to its use in jewellery and coins.

### **Ceramics**

Any of the several tough, fragile, heat- and corrosion-resistant materials created by sculpting and then heating an inorganic, nonmetallic substance like clay to a high temperature are known as ceramics. Brick, porcelain, and earthenware are typical examples. Pottery items (pots, containers, or vases) or figurines composed of clay, either by itself or when combined with additional elements like silica, and then hardened then sintered in fire, were the first ceramics produced by humans. Later, glazing and firing of ceramics reduced porosity by using glassy, amorphous ceramic coatings on top of the crystalline ceramic substrates, resulting in smooth, colourful surfaces. Ceramics currently comprise a broad variety of materials produced for application in sophisticated ceramic technology, such as semiconductors, as well as household, industrial, and architectural items.

The term "ceramic" derives from the Greek words "of pottery" or "for pottery" (keramikos) and "potter's dough, tile, pottery" (keramos). The Mycenaean Greek word ke-ra-me-we, which means "workers of ceramic," written in Linear syllabic writing, is the first use of the root "ceram-." The term "ceramics" is more often used as a plural noun than as a single noun, while the word "ceramic" may be utilized as an adjective to denote a material, product, or process. An inorganic, non-metallic oxidation, nitride, or carbide substance is ceramic. Some substances, like silicon or carbon, may be categorised as ceramics. Brittle, rigid, strong in compression, fragile in shearing and tension, ceramic materials are. They resist chemical deterioration that happens to other materials in conditions that are caustic or acidic. Ceramics can often resist temperatures between 1,600 °C and 1,000 °C (1,800 °F and 3,000 °F).

Materials made of ceramic have a broad range of crystallinities. In most cases, fired ceramics, such as earthenware, stoneware, and porcelain, are either vitrification or semi-vitrified. The majority of ceramic materials are effective thermal and electrical insulators because of their varied crystallite size and electron composition in their ionic and covalent bonds. Due to the wide variety of alternatives for a ceramic's composition and structure (almost all elements, almost all bonding types, and all degrees of crystallinity), it is challenging to define the group's common

characteristics (hardness, toughness, and electrical conductivity). There are known exceptions to each of these general laws, such as high melting point, high hardness, poor conductance, high moduli of elasticity, chemical resistance, and low ductility. Even though they include ceramic components, many composites like fibreglass and carbon fibre are not regarded as belonging to the ceramic family.

The processing options for highly orientated crystalline ceramic materials are limited. They may be dealt with in one of two ways: either by reacting in situ to create the ceramic in the correct shape, or by "shaping" particles into the shape you want, then sintering them to create a solid body. Hand shaping (sometimes including the rotational process known as "throwing"), slip castings, tape casting (used to create very thin ceramic capacitors), investment casting, dry pressing, and various variants are some of the processes used to make ceramics.

Even though glassmaking includes numerous phases of the ceramic process and has mechanical characteristics comparable to ceramic materials, many ceramics specialists do not consider amorphous (noncrystalline) materials like glass to be ceramics. Glass may, however, undergo heat treatments to become glass-ceramic, a semi-crystalline substance. Clay minerals like kaolinite are used in traditional ceramic raw materials, while aluminium oxide, sometimes known as alumina, is used in more contemporary ceramics. Composite material and tungsten carbide are examples of contemporary ceramic materials, which are categorised as advanced ceramics. Both are employed in applications like the wear plates of breaking equipment in mining companies because they are appreciated for their abrasion resistance. The medicinal, electrical, electronics, and armour sectors all employ advanced ceramics.

### **Archaeology**

In order to comprehend the culture, science, and behaviour of ancient peoples, ceramic artefacts are crucial to archaeology. They are among the most often discovered objects at an archaeological site, typically in the form of sherds, which are tiny pieces of shattered pottery. The two primary methods of analysis that may be used to process gathered sherds are conventional and technological. According to style, content, production, and morphology, ceramic items, sherds, and bigger pieces are classified into distinct kinds in the conventional analysis. By developing these typologies, it is possible to differentiate between various cultural trends, the ceramic's intended use, and the people's technical level, among other findings. In addition, it is feasible to categorise ceramics into different diagnostic groups by examining the stylistic evolution of ceramics across time (assemblages). Ceramic artefacts may be chronologically assigned by comparing them to known dated assemblages.

The technical method of ceramic analysis entails a closer evaluation of the chemical makeup of ceramic artefacts and sherds in order to pinpoint the material's origin and, therefore, the potential production location. The composition of the clay and the temper used to create the object under investigation are important factors. The temper is a substance that is applied to the clay during the first manufacturing stage and is used to speed up the drying process thereafter. Temper types include granite shards, shell bits, and pulverised sherd particles known as "grog." Usually, a microscopic study of the altered material may identify the temper. By refiring the pottery and utilising Munsell Soil Color chart to give a colour to it, clay identification is accomplished. An attribution of the critical input may be achieved by calculating the compositions of both the clay and the temper and finding an area in which they are known to exist. Further research regarding the place of manufacturing may be done based on the artifact's source assignment.



## Polymers

A polymer is a chemical or material made up of macromolecules, which are extremely big molecules made up of several repeating subunits. Both natural and artificial polymers play significant and pervasive roles in daily life as a result of their wide range of features. From well-known synthetic plastics like polystyrene to natural biopolymers like DNA and proteins that are essential to biological development and function, polymers come in many shapes and sizes. Numerous tiny molecules, or monomers, are polymerized to produce polymers, including natural and manufactured. They have unusual physical features such as toughness, good machinability, viscoelasticity, and a propensity to form amorphous and nanocrystalline structures rather than crystals due to their subsequently huge molecular mass in comparison to small molecule compounds.

The words "polymer" and "o" are both derivatives of the Greek word *polus*, which means "many, many" (*meros*, meaning "part"). Jöns Jacob Berzelius first used the phrase in 1833, although his meaning was different from the one used today by the IUPAC. Hermann Staudinger formulated the contemporary theory that polymers are covalently bound macromolecular structures in 1920, and he spent the next ten years accumulating experimental data to support this theory. In the disciplines of supramolecular chemistry (which encompasses polymer chemistry and physics), biophysics, and plastics science and engineering, polymers are researched. Historically, the main emphasis of polymer research has been on the products that result from the covalent chemical bonding of repeating units. Supramolecular polymers created via non-covalent connections are now the focus of a growingly significant field. A natural polymer is polyisoprene found in latex rubber, whereas a manufactured polymer is polystyrene found in Styrofoam. Almost all biological macromolecules, such as proteins (polyamides), polynucleotides (polynucleotides), and polysaccharides, are entirely polymeric or include a significant amount of polymeric components when used in biological settings.

## Synthetic

The process of fusing several little molecules, called monomers, into a covalently bound chain or network is called polymerization. Each monomer may lose some chemical groups during the polymerization process. When PET polyester is polymerized, this takes place. Terephthalic acid and ethylene glycol are the monomers, and their formulas are  $\text{HOOC}-\text{C}_6\text{H}_4-\text{COOH}$  and  $\text{HO}-\text{CH}_2-\text{CH}_2-\text{OH}$ , respectively. However, the repeating unit is  $\text{OC}-\text{C}_6\text{H}_4-\text{COO}-\text{CH}_2-\text{CH}_2-\text{O}$ , which translates to the mixture of both monomers with the loss of two water molecules. A repetition unit or monomer residue is the unique portion of each component that is integrated into the polymer. Polysaccharides, polypeptides, even polynucleotides are examples of biopolymers. They may be produced in live cells by enzyme-mediated processes, for example the DNA synthesis process facilitated by DNA polymerase. Multiple enzyme-mediated pathways are used during the synthesis of proteins to translate genetic information from DNA to RNA and then use that information to create the specific protein from amino acids. Following translation, the protein may undergo further modifications to achieve the proper shape and functionality. Other biopolymers include rubber, lignin, and melanin, sobering, and sobering.

## Modification of natural polymers

Before synthetic polymers like polyethene and Perspex hit the market, naturally occurring polymers like cotton, flour, and rubber were widely used materials. By chemically altering naturally existing polymers, several economically significant polymers are created. Two notable



instances are the creation of nitrocellulose by the interaction of nitric acid and cellulose, and the vulcanization of rubber caused by heating natural rubber in the absence of Sulphur. There are many ways to alter polymers, including oxidation, cross-linking, and finished.

### **Composites material**

A composite material (also known as a composition material or, more colloquially, composite) is a substance made up of two or more component elements. [These component materials have significantly different chemical or physical characteristics and are combined to form a material with qualities that differ from the separate constituents. Individual constituents stay separate and distinct inside the completed construction, differentiating composites from mixes and solid solutions.

There are many reasons why fresh material may be preferred. Materials that are less costly, lighter, stronger, or more durable as compared to standard materials, as well as structural components inspired by animals and plant sources with a reduced carbon footprint, are typical examples. Researchers have lately started to actively incorporate sensing, actuation, computing, and connectivity into composites known as robotic materials. Composite materials are often utilized in the construction of buildings, bridges, and structures, such as boat hulls, pool panels, racing car bodywork, shower stalls, bathtubs, storage tanks, and imitation granite and cultured marble basins and countertops. They are also becoming more common in general automobile applications. The most modern models commonly operate aboard spaceships and aero planes in harsh settings.

Concrete is the most popular manmade composite material, and it is normally made up of cobble stones (aggregate) bound together by a cement matrix. Concrete is a low-cost material that will neither collapse nor break even when subjected to significant compressive force. Concrete, on the other hand, cannot withstand tensile stress (i.e., if stretched it will quickly break apart). As a result, to provide concrete the capacity to resist stretching, bars that can withstand significant stretching (tensile) stresses are often added to the mixture to make reinforced concrete. Carbon fiber reinforced polymers and glass-reinforced plastic are examples of fiber-reinforced polymers. There are four types of thermoplastic composites: short fiber thermoplastics, long fiber thermoplastics, and long fiber-reinforced thermoplastics. There are several thermoset composites available, including paper composite panels. In an epoxy resin matrix, several advanced hardener polymer matrix solutions often include aramid fiber and carbon fiber.

Shape memory polymeric materials are high-performance composites made using fiber or fabric reinforcements and a matrix of shape memory polymer resin. Because the matrix is a shape memory polymer resin, these composites may be readily manipulated into diverse forms when heated above their activate temperatures and have good strength and stiffness at lower temperatures. They can also be repeatedly reheated and molded without losing material qualities. These composites are perfect for lightweight, stiff, deployable constructions, as well as quick manufacture and dynamic reinforcing. High strain composites are a kind of high-performance composite that is intended to function in a high deformation environment and are often utilized in deployable devices where structural bending is favorable. Although high strain composites have many similarities to shape storage polymers, their performance is typically determined by the fibre architecture rather than the matrix's resin composition.

Metal fibers may be used to reinforce other metals in composites, such as metal matrix composites (MMC) or composites (CMC) which include bone (hydroxyapatite reinforced with

collagen fibers), cermet (ceramic and metal), and concrete. Ceramic polymer nanocomposites are designed for fracture toughness rather than strength. Another kind of composite material is woven fabric composite, which is made up of longitudinal and lateral laced threads. Because they are woven fabric composites, they are flexible. Asphalt concrete, polymer shotcrete, mastic asphalt, mastic roller hybrid, dental composite, syntactic foam, and mother of pearl are examples of organic matrix/ceramic aggregate composites. Chesham armor is a form of composite armor that is utilized in military purposes.

Furthermore, thermoplastic composite materials may be formed with specified metal powders to produce materials ranging in density from 2 g/cm<sup>3</sup> to 11 g/cm<sup>3</sup> (same density as lead). The term "high gravity compound" (HGC) is the most often used for this sort of substance, however "lead substitute" is also used. These materials may be utilized in weighing, balancing (for example, altering the centre of gravity of a tennis racquet), vibration dampening, and radiation shielding applications in lieu of typical materials such as aluminum, stainless steel, brass, bronze, copper, lead, and even tungsten. When some materials are regarded dangerous and are prohibited (such as lead) or when secondary operations expenses (such as machining, finishing, or coating) are a problem, high density composites are an economically feasible solution

Several studies have shown that interlacing stiff and brittle epoxy-based carbon fibre reinforced polymer laminates with flexible thermoplastic laminates may aid in the creation of highly toughened composites with increased impact resistance. Another intriguing feature of such interleaved composites is their ability to exhibit form memory behavior without the use of shape memory polymers or shape memory alloys, such as balsa plies interleaved with hot gluepolymer laminates interspersed with polystyrene

A sandwich-structured composite is a kind of composite material made by joining two thin but rigid skins to a lightweight but substantial core. The core material is typically low strength, but its increased thickness offers the sandwich composite with high bending stiffness while remaining low density. Wood is a naturally occurring composite made up of cellulose fibres in a matrix of lignin and hemicellulose.

Wood fibre board, plywood, oriented strand board, wood plastic composite (recycled wood fibre in polyethylene matrix), Pykrete (sawdust in ice matrix), plastic-impregnated or laminated paper or textiles, Arborite, Formica (plastic), and Micarta are all examples of engineered wood. Other designed laminate composites, such as Mallite, have an end grain balsa wood central core bonded to surface skins of light metal or GRP. This results in low-weight, high-rigidity materials. Particulate composites feature filler particles spread in a matrix that may be nonmetal, such as glass or epoxy. A particulate composite is an automobile tire. Advanced diamond-like carbon (DLC) coated polymer composites with increased surface hydrophobicity, hardness, and wear resistance have been reported.

Ferromagnetic composites, including those with a polymer matrix made up of nanocrystal line filler of Fe-based powders and a polymer matrix. Amorphous and nanocrystal line powders derived from metallic glasses, for example, may be employed. Their use allows for the creation of ferromagnetic nanocomposites with regulated magnetic characteristics.

## **Products**

Aerospace components (tails, wings, fuselages, and propellersboat and scull hulls, bicycle frames, and racing car bodywork have all benefited from the usage of fiber-reinforced composite

materials, despite their relatively high cost. Other applications include fishing tackle, storage tanks, pool panels, and baseball bats. The structures of the Boeing 787 and Airbus A350, including the sides and fuselage, are predominantly made of composite materials. Composite materials are becoming increasingly widespread in orthopedic surgery and they are the most often used hockey stick material.

Carbon composite is an important material for today's launch vehicles and heat shields for spacecraft re-entry. It's commonly utilized in solar panel substrate, antenna reflectors, and spacecraft yokes. It is also utilized in launch vehicle payload adapters, interstate structures, and heat shields. Furthermore, carbon/carbon material is used in the disc braking systems of aircraft and racing automobiles, and a composite material with graphite and a silicon carbide matrix has been launched in luxury sedans and sports cars.

In 2006, a fiber-reinforced composite pool panel was created as a non-corrosive option to galvanized steel for in-ground swimming pools, both residential and commercial. TPI Composites Inc and Armor Holdings Inc launched the first all-composite military vehicle, an all-composite military Humvee, in 2007. The vehicle is lighter as a result of the use of composites, allowing for greater payloads. Carbon fiber and DuPont Kevlar (five times tougher than steel) were coupled with upgraded thermoset resins in 2008 to create 30-percent lighter casings with great strength by ECS Composites.

Glass reinforced plastics are being used to make pipes and fittings for a variety of applications such as transfer of potable water, firefighting, irrigation, saltwater, desalinization, chemical or industrial waste, and sewage. The use of transparent composite materials in tensile constructions for façade applications gives an advantage. Better light transmission is achieved by combining the woven base fabric with the suitable coating. When compared toward the full blast of outdoors, this delivers a fairly comfortable level of light.

Wind turbine wings on the range of 50 m length have been produced in composites for many years two lower-leg amputees run as fast as non-amputee athletes with carbon-composite spring-like prosthetic feet. High-pressure gas cylinders for firefighters, approximately 7-9 liter capacity x 300 bar pressure, are now made of carbon composite. Metal is only present in Type-4 cylinders as a boss that bears one thread to screw there in valve. HMD Global introduced the Nokia 6.2 & Nokia 7.2, which are said to have polymer composite frames.

### **Semiconductors**

A semiconductor is a substance whose electrical conductivity falls between that of a conductor, such as copper, and that of an insulator, such as glass. Its resistance decreases as its temperature increases; metals do the reverse. By injecting contaminants ("doping") into the crystal structure, its conducting characteristics may be adjusted in beneficial ways. A photoelectric junction is formed when two differentially doped areas of the same crystal coexist. The behavior of charge carriers at these junctions, which include electrons, ions, and electron holes, is the foundation of diodes, transistors, and most contemporary electronics. Silicon, diode, gallium arsenide, and elements near the periodic table's "metalloid staircase" are examples of semiconductors. Gallium arsenide, the second-most prevalent semiconductor after silicon, is utilized in laser diodes, solar cells, microwave-frequency integrated circuits, or other applications. Silicon is a vital component in the fabrication of most electronic circuits. Semiconductor devices may have a variety of useful qualities, such as the ability to transmit current more readily in one way than the other, changeable resistance, and light sensitivities or heat. Devices manufactured from semiconductors

may be utilized for amplification, changing, and thermodynamic efficiency because the electrical characteristics of a semiconductor material can be adjusted by doping and the application of electromagnetic frequencies or light.

A modest quantity (on the order of 1 in 10<sup>8</sup>) of monovalent (antimony, phosphorus, or arsenic) or polyatomic (boron, gallium, indium) atoms are added to boost the conductivity of silicon. This is referred to as doping, and the resultant semiconductors are referred to as doped or extrinsic semiconductors. Aside from doping, raising the temperature of a semiconductor may boost its conductivity.

This is in contrast to how metals behave, where conductivity diminishes as temperature rises. To explain the passage of charge carriers in a crystal lattice, present knowledge of semiconductor characteristics depends on quantum physics. Doping increases the amount of charge carriers in the crystal significantly. A doped semiconductor is referred to as "p-type" when it includes free holes, and "n-type" when that contains free electrons. To manage the concentration and locations of p- and n-type dopants, semiconductor materials used during electrical gadgets are doped under exact circumstances. A single semiconductor device crystal may contain numerous p- and n-type areas; the useful electrical behaviour is caused by the p-n junctions between these regions. A hot-point probe can rapidly assess whether a silicon sample is p- or n-type.

## **Properties of semiconductor**

### **Variable electrical conductivity**

Semiconductors are poor conductors in their normal form because a current needs the transport of electrons, and transistors have their valence bands filled, prohibiting the whole flow of new electrons. Several developed approaches, like as doping and gating, enable semiconducting materials to act like conducting materials. These alterations have two outcomes: n-type and p-type. These terms allude to an excess or a scarcity of electrons, respectively. A balanced quantity of electrons would induce a current to flow through the material.

### **Heterojunctions**

When two differentially doped conductive materials are connected, heterojunctions form. For example, a setup may include p-doped and n-doped germanium. This causes an interchange of electrons and holes between the differentially doped semiconducting materials. The n-doped germanium would have an excess of electrons, whereas the p-doped germanium would have an excess of holes. The transfer continues until an equilibrium is established by a process known as recombination, which brings migrating electrons from the n-type into touch with migrating holes from the p-type. This process produces a thin strip of immobile ions, which generates an electromagnetic field across the junction.

### **Electrons**

A variation in electric potential on such a semiconductor diode would lead it to exit thermal equilibrium and produce a non-equilibrium condition. This introduces electrons and holes into the system, which interact via a process known as ambipolar diffusion. When thermal equilibrium in a semiconductor device is disrupted, the quantity of holes and electrons varies. Such disturbances may arise as a consequence of a temperature differential or photons entering the system and creating electrons and holes. The processes of creating and annihilating electrons and holes are known as generation and recombination, respectively.

## Preparation of semiconductor materials

Almost all of today's business technology makes use of semiconductors, the most essential of which is the integrated circuit (IC), which can be found in desktop computers, laptop computers, scanners, mobile phones, and many other electronic devices. Semiconductors for integrated circuits are mass-produced. Chemical purity is critical in the creation of a perfect semiconducting material. Because of the scale on which the materials are employed, every little flaw may have a significant impact on how the semi-conducting material performs.

A high degree of crystalline perfection is also necessary, since crystal structural flaws (such as misalignments, twins, and stacking faults) interact with the material's semiconducting capabilities. Crystalline faults are a primary source of semiconductor device failure. The greater the size of the stone, the more difficult it is to reach the required perfection. Current mass manufacturing procedures use crystal ingots with diameters ranging from 100 to 300 mm (3.9 to 11.8 in), grown as cylinders, and cut into wafers.

To create semiconducting materials for ICs, a variety of techniques are employed. Thermal oxidation is one mechanism that produces silicon dioxide on the surfaces of silicon. This serves as a gate insulator as well as a field oxide. Photomasks and photolithography are two more terms for similar techniques. This procedure is responsible for the patterns on the integrated circuit's circuit. Ultraviolet light is used with a photoresist layer to produce a chemical change that forms the circuit patterns.

The following procedure is required: etching. The silicon that was not covered by the previous step's photoresist layer may now be etched. Plasma etching is the most common method used nowadays. To make plasma, an etch gas is typically injected into a low-pressure chamber. Chlorofluorocarbon, or Freon as it is better known, is a popular etch gas. The plasma in the chamber is created by a high radio-frequency voltage here between cathode and anode. Because the silicon wafer is on the cathode, it is bombarded by positively charged ions emitted by the plasma. The end product is anisotropic ally etched silicon.

The final procedure is known as diffusion. This is the technique that imparts the necessary semiconducting characteristics on the semiconducting material. Doping is another term for it. The procedure adds an impure atom into the system, resulting in the formation of the p-n junction.

The silicon wafer is initially placed in a 1,100 celsius oven to insert the impure atoms. The atoms are injected into the silicon and gradually disperse with it. The doping process is finished after the silicon has arrived at room temperature and the semiconducting substance is ready to be utilized in an integrated circuit.

## Raw Material

Raw material is unprocessed and even little processed material that is utilised to manufacture large quantities of goods. It is the most basic form of material that is naturally accessible. These resources are then used by industry to create final items and products. These items are classified as direct and indirect.

The raw materials employed in the final product are referred to as direct materials. Indirect materials are utilised in manufacturing but are not present in the finished product. Raw materials include crude oil, iron ore, air, food, mineral, coal, cotton, raw feedstock, and so on. Tin, copper, alumina, iron ore, lead, and other metallic raw minerals are examples.

## Classification Of Materials on Physical properties

### Appearance:

Materials may be distinguished from one another based on their appearance. Some natural materials, such as diamond and gold, are glossy and shiny. Other materials, such as graphite and wood, do not seem glossy and are thus classified as non-lustrous. Metals are objects that are shiny in nature, such as iron, gold, and copper.

### Hardness:

When cleaning utensils, the sponge may be squeezed to some amount, but the utensils are often incompressible. Similarly, certain materials, such as chalk, are readily scratched, whilst others, such as aluminium, are not. Easy substances are materials that are able to readily squeezed or scratched. Hard substances are materials that are tough to scratch and crush.

### Transparency

We usually strive to conceal in this game so that no one can notice us. We usually hide behind the backs of items such as sofas and walls. These things are desirable because they cannot be seen through. These are known as opaque things, such as a tree or an iron sheet. Transparent items are materials that allow us to see the things clearly through them. For example, glass. A translucent object is a material through which items are partly visible. As an example, consider greasy patch paper.

### Plastics and composites

The motivation for replacing metal components of automobiles, trucks, and trains with plastics is the anticipation of significant weight savings owing to the enormous disparities in thickness involved: polymers are one-sixth the weight of steel and half the weight of aluminium per unit volume. However, much like when deciding whether to replace steel with aluminium, the resources scientist must analyse other features of the materials to see whether the tradeoffs are justifiable. For two reasons, most plastics, such as epoxies and polyesters, are unlikely to be acceptable for this sort of application: their strength is around one-fifth that of steel or aluminium, and their deformation is one-sixtieth that of steel and one-twentieth that of aluminium. Plastics do not seem to be appropriate for structural components on this premise. What, therefore, accounts for their effective application? The answer lies in the efforts of researchers and scientists, thermoplastic chemists, mechanical engineers, and manufacturing engineers over the years to combine relatively weak and minimal resins with rising, high-modulus reinforcements, resulting in new substances called composites with far more suitable properties than plastic materials alone.

As one would imagine, the reinforcements used in composites are normally selected for their high strength and modulus, although economic concerns sometimes demand compromises. Carbon fibres, for example, have extraordinarily high modulus properties (up to five times that of steel) and hence make great reinforcements. However, their high cost limits widespread usage in autos, trucks, and trains, while they are widely utilised in the aerospace sector. Glass fibres (whose modulus may reach 1.5 times that of aluminium) or, in certain situations, a blend of glass and carbon fibres are better suited for non-aerospace applications.



Many elements influence the physical morphology of the reinforcements. Long fibres are the most effective reinforcements, and they are used either as a woven fabric or as distinct layers of unidirectional fibres layered upon one another until the desired laminate thickness is obtained. The resin may be sprayed to the fibres or fabric before to setting up, resulting in prepregs, or it can be added afterwards by "watering out" the fibres. The assembly is subsequently cured, generally under pressure, to produce the composite in either scenario. This sort of composite takes full use of the qualities of the fibres and may therefore produce strong, stiff panels. Unfortunately, the labour necessary in the lay-up processes, as well as other variables, make long-fibre reinforcing too costly in the vehicle industry.

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## CHAPTER 3

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### Composition of the Atoms

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An atom is a particle made up of a nucleus of neutrons surrounded by an electron cloud. The atom is the fundamental particle of the alkali metals, and the chemical elements are characterised by the number of protons in their atoms. For example, every atom with 11 protons is salty, while any atom with 29 protons is copper. The element's isotope is defined by the number of neutrons.

Atoms are incredibly tiny, measuring around 100 picometers across. A human hair is about one million isotopes wide. Because this is smaller than the smallest wavelength of visible light, humans cannot detect atoms with normal microscopes. Because atoms are so tiny, it is impossible to anticipate their behaviour using classical physics, as as though they were tennis balls, owing to quantum phenomena.

The nucleus contains more than 99.94% of an atom's mass. Protons have a positive electric charge, electrons have just a negative electric charge, and neutrons have none. When the number of both protons and electrons in an atom is equal, the atom is electrically neutral. If an atom contains more electrons than protons, it has a negative or positive overall charge; such atoms are known as ions.

The electromagnetic force attracts electrons in an atom to protons in an atomic nucleus. The nuclear force attracts protons and atomic nuclei to each other. This force is frequently greater than the electromagnets that attracts positively charged protons. Under some conditions, the repelling electromagnetic force outweighs the nuclear force. In this situation, the nucleus separates, leaving behind several parts.

This is one kind of nuclear decay. Chemical bonds allow atoms to join with one or more other atoms to create chemical compounds such as molecule or crystals. For example, the Statue of Liberty in New York City was initially constructed of pure copper, but over time, the surface reacted with oxygen, carbon, and sulphur atoms to form a green patina on the copper. Most of the physiological changes seen in nature are caused by atoms' capacity to connect and detach. Chemistry is the scientific subject that investigates these changes.

#### History of atomic theory

The fundamental notion that everything is made up of small, indivisible particles is an old one that may be found in many ancient civilizations, including Greece and India. The term atom is derived from the ancient Greek word atomos, which meaning "uncuttable".

This old concept was founded on philosophical rather than scientific reasoning. These ancient assumptions have no place in modern atomic physics. In the early nineteenth century, the scientist Charles Dalton found that chemical elements tended to mix by basic units of weight,

and he opted to use the term "atom" to refer to these units since he felt they were the fundamental units of matter. It was revealed about a hundred years later that Sutton's atoms are not indivisible, yet the phrase lingered.

### **Dalton's law of multiple proportions**

The English chemist John Dalton found the "rule of multiple proportions" in the early 1800s after compiling experimental data obtained from both other scientists. He found that in chemical compounds a certain chemical element, the concentration of that element varies in weight by ratios of tiny whole numbers. This pattern indicated to Dalton that each nitrogen atom connects with other elements by a fundamental and constant unit of weight, and he chose to name these units "atoms".

Tin oxide, for example, comes in two forms: a black powder with 88.1% tin and 11.9% oxygen, and a white powder with 78.7% tin and 21.3% oxygen. Using these values, there is about 13.5 g of oxygen per each 100 g of tin in black oxide and approximately 27 g of oxygen for every 100 g of tin in white oxide. The ratio of 13.5 to 27 is 1:2. Dalton deduced that in these oxides, there are one or two oxygen atoms for every tin atom ( $\text{SnO}$  and  $\text{SnO}_2$ ).

Dalton also investigated iron oxides. There is a black powder iron oxide that has 78.1% iron and 21.9% oxygen, and a red powder iron oxide that contains 70.4% iron and 29.6% oxygen. Using these statistics, there's around 28 g of oxygen for every 100 g of iron in black oxide and approximately 42 g of oxygen for every 100 g of iron in red oxide. The ratio of 28 to 42 is 2:3. There are two or three oxygen atoms for every two iron atoms in these oxides ( $\text{Fe}_2\text{O}_2$  and  $\text{Fe}_2\text{O}_3$ ).

Finally, nitrous oxide has 63.3% nitrogen and 36.7% oxygen, nitric oxide contains 44.05% nitrogen and 55.95% oxygen, and nitrogen oxides contains 29.5% nitrogen and 70.5% oxygen. With these statistics adjusted, nitrous oxide contains 80 g of oxygen for every 140 g of nitrogen, nitric oxide has about 160 g of oxygen for every 140 g of nitrogen, and nitrogen dioxide contains 320 g of oxygen for every 140 g of nitrogen. The ratios of 80, 160, and 320 are 1:2:4. These oxides have the formulae  $\text{N}_2\text{O}$ ,  $\text{NO}$ , and Nitrogen dioxide respectively.

In 1738, Daniel Bernoulli and a group of other scientists discovered that by characterising gases as collections of thread particles and modelling their behaviour using statistics and probability, they could better understand their behaviour. Unlike Dalton's model of the atom, the kinetic theory of gases addresses how gases behave physically rather than chemically to create compounds: diffusion, viscosity, conductivity, pressures, and so on.

### **Brownian movement**

Botanist Robert Brown discovered "Brownian motion" in 1827 when he used a microscope to examine dust grains floating in water. Water molecules were supposed to be causing this by knocking the grains around. Albert Einstein produced the first statistical physics study of Brownian motion in 1905, proving the actuality of these particles and their movements. Jean Perrin, a French scientist, utilised Einstein's work to empirically estimate the mass and size of molecules, giving physical proof for matter's particle origin

### **Discovery of the electron**

J. J. Thomson discovered in 1897 that cathode rays are not electromagnetic waves but rather particles 1,800 times lighter than hydrogen (the lightest atom). Thomson deduced that these

particles originated from the cathode's atoms - they were subatomic particles. These new particles were first dubbed corpuscles, but were eventually renamed electrons. Thomson also demonstrated that electrons were the same as particles emitted by photoelectric and radioactive materials. Electrons were rapidly identified as the particles that conduct electric currents in metal wires. Thomson concluded that these electrons emanated from the cathode atoms in his instruments, indicating that atoms are not indivisible as Dalton believed.

### **Discovery of nucleus**

J. J. Thomson believed that negatively charged electrons were spread throughout the atom in a sea of positive charge that covered the whole volume of the atom. After having difficulty building an apparatus to determine the charge-to-mass ratio of alpha particles, Ernest Rutherford and his colleagues Hans Geiger and Ernest Marsden began to question the Thomson model (these are positively-charged particles emitted by certain radioactive substances such as radium). The air in the detecting chamber dispersed the alpha particles, making the readings incorrect. Thomson had experienced a similar difficulty with his cathode ray research, which he addressed by establishing a near-perfect vacuum in his apparatus. Rutherford did not expect to encounter this difficulty since alpha particles are substantially heavier than electrons. According to Thomson's atomic model, the positive charge in the atom is not concentrated enough to form an electric field strong enough to deflect an alpha particle, or the electrons are so light that the much heavier alpha particles should easily push them away. However, there was dispersion, so Rutherford and his team began to explore it further.

Rutherford and his colleagues carried out a number of experiments in which they blasted thin metal foils with alpha particles between 1908 and 1913. They discovered alpha particles deflected by angles larger than 90 degrees. To explain this, Rutherford hypothesised that the  $h^+$  of the atom is concentrated in a small nucleus at the core, rather than being dispersed throughout the atom's bulk as Thomson assumed. Only such a high concentration of charge could provide an electric field strong enough even to deflect incoming alpha particles.

### **Discovery of isotopes**

Isotopes are two or more kinds of atoms (or nuclides) that have the same atomic number (number of protons in respective nuclei) and periodic table position (and so belong to the same chemical element), but vary in nucleon numbers (mass numbers) owing to differing numbers of neutrons in their nuclei. While all isotopes of a particular element have almost identical chemical characteristics, their atomic weights and physical properties vary. The word isotope is derived from the Greek roots *isos* (o "equal") and *topos* (o "place"), which imply "the same location"; hence, the name implies that various isotopes of a specific item occupy a same position on the periodic table. Margaret Todd, a Scottish doctor and writer, invented the phrase in 1913 as a recommendation to British chemist Frederic Soddy. The number of protons in the nucleus of an atom is known as its atomic number, and it equals the electron density in a neutral (non-ionized) atom. Each atomic number identifies a single element but not an isotope; an element of a given element may have a broad range of neutron numbers. The mass number of an atom is determined by the amount of nucleons (combined protons and neutrons) in its nucleus, and each isotope of a particular element has a distinct mass number. Carbon-12, carbon-13, and carbon-14, for example, are three isotopes of carbon with mass numbers 12, 13, and 14, respectively. Carbon has an atomic number of 6, which implies that each carbon atom has 6 protons, hence the particle numbers of these atoms are 6, 7, and 8, respectively.

### **Radioactive, primordial, and stable isotopes**

Some isotopes/nuclides decay radioactively and are hence known as radioisotopes or radionuclides, but others have never been seen to decay radioactively and are known as stable isotopes or reliable nuclides.  $^{14}\text{C}$ , for example, is a radioactive type of carbon, while  $^{12}\text{C}$  and  $^{13}\text{C}$  are stable isotopes. There are around 339 naturally occurring nuclides upon Earth, of which 286 are primitive transuranic elements, indicating they have existed since the creation of the Solar System.

Primordial nuclides comprise 35 nuclides with very long half-lives (over 100 million years) and 251 that are technically classified as "stable nuclides" since no decay has been recorded. If an element possesses stable isotopes, such isotopes predominate in the elemental quantity found on Earth and in the Solar System for obvious reasons. Despite the fact that three parts (tellurium, indium, and rhenium) have one or more stable isotopes, the most frequent isotope found in nature is one (or two) extraordinarily long-lived radioisotope(s) of the element.

According to theory, many ostensibly "stable" isotopes/nuclides are radioactive, with exceptionally long quarter (discounting the possibility of proton decay, which would make all nuclides ultimately unstable). Some stable nuclides are in principle energetically vulnerable to other known kinds of decay, such like alpha decay or the double beta decay, but no decay particles have yet been detected, and therefore these isotopes are called to be "observationally stable". The projected half-lives for these nuclides often much surpass the estimated age of the universe, and there are 31 known isotopes with half-lives that are longer than the age of the universe.

### **Radioactive isotopes**

The radiochemist Frederick Soddy proposed the existence of isotopes in 1913, based on studies of radioactive decay chains that revealed approximately 40 different species referred to as based on effective communication (i.e. radioactive elements) between fissile material and lead, despite the periodic table only allowing for 11 elements between lead and uranium inclusive. Several efforts to chemically isolate these novel radioelements have failed. Soddy, for example, demonstrated in 1910 that it is difficult to distinguish mesothorium (later found to be  $^{228}\text{Ra}$ ), radon ( $^{226}\text{Ra}$ , the longest-lived isotope), and thorium X ( $^{224}\text{Ra}$ ). In 1913, Soddy and Kazimierz Fajans separately proposed their radioactive displacement law, which said that alpha decay created an element two places to the left in the periodic table, while beta decay emission produced an element one position to the right. Soddy discovered that emitting an alpha particle followed by two beta particle resulted in the production of an element that was chemically similar to the original element but had a mass four units lighter and distinct radioactive characteristics. Soddy argued that several sorts of atoms with different radioactive characteristics might coexist in the same space. For example, uranium-235 alpha decay produces thorium-231, while actinium-230 beta decay produces thorium-230. Margaret Todd, a Scottish physician and family friend, offered the name "isotope" to Soddy during a discussion in which he discussed his thoughts to her. He was awarded the Nobel Prize in Chemistry in 1921 in part for his work on isotopes.

### **Stable isotopes**

J. J. Thomson discovered the first evidence for numerous isotopes of either a stable (non-radioactive) element in 1912 as part of his investigation on the composition of canal rays

(positive ions). Thomson passed streams of neon ions across parallel electric and magnetic fields, observed their deflection using a photographic plate along their path, and calculated their mass and charge ratio using a technique that became known as Thomson's parabola method. Each stream left a bright area on the plate where it impacted. Thomson saw two distinct parabolic spots of light on the photographic plate indicating the presence of two different types of nuclei with differing mass-to-charge ratios.

Using a mass spectrograph, F. W. Aston identified many stable isotopes for a variety of elements. Aston investigated neon with enough rigour in 1919 to demonstrate that the two isotope masses are quite near to the numbers 20 and 22 and that neither is equal to the known molar mass (20.2) of neon gas. This is an example of Aston's whole number theorem for isotopic masses, which claims that substantial variances of elemental molar masses from integers are caused solely by the element's isotopic composition. Aston demonstrated in the same year that the molar mass of chlorine (35.45) is an average of the almost integral masses of the two isotopes  $^{35}\text{Cl}$  and  $^{37}\text{Cl}$ .

### **Chemical and molecular properties**

The number of electrons in a neutral atom is the same as the number of protons. As a result, various isotopes of the same element have the same amount of electrons and a comparable electrical structure. Because an atom's chemical activity is heavily influenced by its electronic structure, various isotopes display almost similar chemical behaviour. The kinetic isotope effect is the major exception to this: heavier isotopes tend to respond somewhat slower than lighter atoms of the same element owing to their higher weights. This is particularly obvious for protium (1 H), deuterium (2 H), and tritium (3 H), since deuterium has twice the mass of protium and tritium has three times the mass of protium. These mass discrepancies change the centre of gravity (reduced mass) of the atomic systems, which influences the life of their respective chemical bonds. However, since the relative mass disparity between isotopes is significantly smaller for larger elements, the bulk effects on chemistry are typically insignificant. (Because heavy atoms have more neutrons than lesser elements, the nuclear mass to collective electronic mass ratio is somewhat higher.) There is also an isotope effect at equilibrium.

### **Nuclear properties and stability**

Atomic nuclei are made up of protons and neutrons that are held together by the residual strong force. Protons repel each other because they are positively charged. Neutrons, which are electrically neutral, help to keep the nucleus stable in two ways. Their existence pulls protons apart somewhat, lessening electrostatic repulsion, and they exert the attractive nuclear force on each other and on protons. As a result, for two or so more protons to join to form a nucleus, one or more neutrons are required. As the number of protons grows, so does the neutron-to-proton ratio required to maintain a continuous series (see graph at right). Although the neutron-to-proton ratio of  $^3_2\text{He}$  is 1:2, the neutron-to-proton ratio of  $^{238}_{92}\text{U}$  is larger than 3:2. A handful of positive ions have stable nuclides with a 1:1 ( $Z = N$ ) ratio. The nuclide  $^{40}_{20}\text{Ca}$  (calcium-40) has the same amount of neutrons and protons as the heaviest stable nuclide. Neutrons outnumber protons in all stable nuclei heavier than calcium-40.

### **Bohr model**

Niels Bohr, a scientist, devised a model in 1913 in which electrons of an atom were thought to circle the nucleus but could only do so in a restricted set of orbits and could only hop between



these orbits in discrete changes of energy corresponding to photon absorption or radiation. This quantization was used to explain why electron orbits are stable (because charges in acceleration, including circular motion, lose kinetic energy that is emitted as electromagnetic energy, see synchrotron radiation) and why components absorb and emit electromagnetic radiation in discrete spectra.

Later that year, Henry Moseley gave further experimental data in support of Niels Bohr's hypothesis. These findings improved on Ernest Rutherford's and Antonius van den Broek's hypothesis, which stated that the atom has a number of positive nuclear charges in its nucleus equal to its (atomic) number with in periodic table. Until these investigations, it was unknown that atomic number was a physical and experimental fact. The accepted atomic model today is that it is equal to the atomic nuclear charge.

Gilbert Newton Lewis defined chemical bonds between atoms in 1916 as interactions between their component electrons. Because the chemical characteristics of the elements were known to mainly repeat itself according to the periodic rule, American scientist Irving Langmuir proposed in 1919 that this might be explained if the atoms in an atom were somehow linked or grouped. Electron group were supposed to inhabit a series of electron shells around the nucleus.

The first full physical model of the atom was the Bohr model. It detailed the general arrangement of the atom, what atoms connect to one another, and anticipated hydrogen spectral lines. Bohr's model was not flawless, and it was quickly overtaken by the more exact Schrödinger model, but it was enough to dispel any residual concerns that matter is made up of atoms. The concept of the atom had proven a valuable heuristic tool for chemists, but physicists were skeptical since no full physical description of the atom had yet been produced.

### **The Schrödinger model**

The Stern-Gerlach experiment, conducted in 1922, offered more proof of the quantum basis of atomic characteristics. A stream of silver atoms was divided in a manner that was connected with the path of an electron's angular momentum, or spin, when it was passed through a specifically structured magnetic field. Because the spin direction is originally random, the beam is predicted to deflect randomly. Instead, the beam was divided into two directional components, each of which corresponded to an atomic spin orientated up or down with reference to the magnetic field.

Werner Heisenberg published the first mathematical description of quantum mechanics in 1925. (Matrix mechanics). Louis de Broglie proposed the de Broglie hypothesis one year earlier: that all particles behave like waves to some extent, and Erwin Schrödinger used this idea to grow the Schrödinger equation, a mathematical model of the atom (wave mechanics) that described electrons as three-dimensional waveforms rather than point particles.

Because waveforms are used to describe particles, it is theoretically impossible to acquire accurate values for a particle's location and momentum at any given instant in time. This became known as the uncertainty principle, which Werner Heisenberg proposed in 1927. In this approach, a given precision in measuring a position might only provide a range of likely momentum values, and vice versa. This model explained atomic behaviour findings that earlier models could not, such as specific structural and spectral features of atoms bigger than hydrogen. As a result, the planetary version of the atom was abandoned in favour of one that characterised the atomic orbital zones from around nucleus where a certain electron is most likely to be detected.

## Discovery of neutron

With the invention of the mass spectrometer, the mass of atoms could be determined with greater precision. The device employs a magnets to bend the trajectory of an ion beam, and the degree of deflection is governed by the mass-to-charge ratio of an atom. This apparatus was used by scientist Francis William Aston to demonstrate that isotopes have distinct masses. The atomic masses of these isotopes varied by integer quantities, a phenomenon known as the whole number rule. The explanation for these distinct isotopes awaited scientist James Chadwick's discovery of the neutrino, an electron - deficient particle with a mass comparable to the proton, in 1932. Isotopes were then defined as elements that have the same number of protons but vary in the number of neutrons inside the nucleus.

## High-energy physics, fission, and condensed matter

Otto Hahn, a Rutherford pupil, focused neutrons onto uranium atoms in 1938, hoping to get uranium elements. His chemical investigations, on the other hand, revealed barium as either a product. Lise Meitner and her nephew Otto Frisch confirmed a year later that Hahn's results were the first experimental nuclear fission. Hahn was awarded the Nobel Prize in Chemistry in 1944. Despite Hahn's attempts, Meitner and Frisch's contributions were not acknowledged.

The advent of better particle accelerators and particle detectors in the 1950s enabled scientists to explore the consequences of high-energy atoms. Neutrons and protons have been discovered to be hadrons, or composites of smaller particles known as quarks. The standard model of particle physics was created, which has so far satisfactorily described the characteristics of the nucleus in terms of these subatomic particles and the forces governing their interactions.

## Structure Particles at the subatomic level.

Though the term "atom" was initially used to describe a particle that could not be divided into smaller particles, it is now used to describe a collection of subatomic particles. An atom's component constituents are the electron, proton, and neutron. The electron, with a negative electrical charge and a size too tiny to be detected with current methods, is by far the least massive of these particles, weighing  $9.111031 \times 10^{-31}$  kg. Until the discovery of neutrino mass, it was the lightest particle with a positive rest mass. Under normal circumstances, electrons are attracted to the positively charged nucleus by the attraction caused by opposing electric charges. When an atom contains more or less electrons than its atomic number, it becomes negatively or positively charged as a whole; a charged atom is referred to as an ion. Electrons have been known since the late nineteenth century, mostly owing to J.J. Thomson; for further information, see the history of subatomic physics.

Protons have a positive charge and a mass that is 1,836 times that of electrons, weighing  $1.67261027 \times 10^{-27}$  kg. The atomic number of an atom is the number of protons in it. Ernest Rutherford (1919) discovered that when bombarded with alpha particles, nitrogen ejects what looked to be hydrogen nuclei. By 1920, he had agreed that the hydrogen nucleus is a separate particle inside the atom and had given it the name proton. Neutrons have no electrical charge and a free mass of  $1.67491027 \times 10^{-27}$  kg, or 1,839 times the mass of an electron. Neutrons are the heaviest of the three component particles, although the nuclear binding energy may lower their mass. Neutrons and protons (collectively known as nucleons) have similar dimensions (on the order of  $2.51015 \times 10^{-15}$  m), although their 'surface' is not well defined. James Chadwick, an English scientist, discovered the neutron in 1932.

Electrons are really fundamental particles with no intrinsic structure in the Standard Model of physics, while protons and neutrons are composite particles made up of elementary particles called quarks. Atoms have two kinds of quarks, each with a fractional electric charge. Protons are made up of two up quarks (each with a charge of  $+2/3$ ) and one down quark (with a charge of  $1/3$ ). Neutrons are made up of one up and two down quarks. The difference in mass and charge between the two particles is explained by this distinction.

The strong interaction (or strong force) that gluons mediate holds the quarks together. The nuclear force, which is a residuum of the strong force with somewhat altered range-properties, holds the protons and neutrons together in the nucleus (see the article on the nuclear force for more). The gluon belongs to the gauge boson family of elementary particles that transmit physical forces.

### **Numbers of isotopes per element**

The most stable isotopes observed about any element among the 80 elements possessing a stable isotope are 10. There are no elements with nine or eight carbon isotopes. Five elements have seven stable isotopes, eight have six stable isotopes, ten have five stable isotopes, nine have four stable isotopes, five have three stable isotopes, sixteen have two stable isotopes (including  $^{180m}\text{Ta}$ ), and 26 have only one stable radionuclide. There are a total of 252 nuclides that have not been seen to decay. The overall amount of stable isotopes for the 80 elements with one or more unstable isotopes is  $251/80 = 3.14$  isotopes per element.

### **Occurrence in nature**

Elements are made up of either one nuclide (mononuclidic elements) or many naturally occurring isotopes. The radioactive (unstable) isotopes are either primordial or postprimordial. Primordial isotopes were created by star nucleosynthesis or another kind of nucleosynthesis, such as gamma ray spallation, and have survived to the current day due to their slow rate of disintegration (e.g. uranium-238 and potassium-40). Cosmic ray bombardment as cosmogenic nuclides (e.g., tritium, carbon-14) or the decay of a revolutionary primordial isotope to a radioactive radiogenic nuclide daughter produced post-primordial isotopes (e.g. uranium to radium).

A few isotopes are spontaneously created as nucleogenic nuclides as a result of another natural nuclear process, such as neutrons absorbed by another atom during natural nuclear fission, only 80 elements have stable isotopes, with 26 of them having just one stable isotope. Thus, around multiple of stable elements exist naturally on Earth in numerous stable isotopes, with tin ( $^{50}\text{Sn}$ ) having the most stable isotopes (ten). There are around 94 elements found in nature (up to plutonium), while some are only identified in trace levels, such as plutonium-244. According to scientists, the elements that occur naturally on Earth (some only as radioisotopes) exist as a total of 339 isotopes (nuclides). Only 251 of these naturally occurring nuclides are stable, meaning they have never been seen to decay as of yet. An additional 35 primordial nuclides (bringing the total to 286) are radioactive with known half-lives but have half-lives higher than 100 million years, enabling them to exist since the beginning of the Solar System. Details may be found in the list of nuclides.

All of the known stable nuclides exist naturally on Earth; the other naturally occurring nuclides are radioactive yet occur on Earth owing to their very lengthy half-lives or other continuous natural production. These include the previously stated cosmogenic and nucleogenic nuclides, as

well as any radiogenic nuclides created by the continuous decay of a primordial nuclear nuclide, such as radon and radium from aluminum. In nuclear reactors and particle accelerators, an extra 3000 radioactive nuclides not present in nature have been generated. Many summary nuclides not found natively on Earth have also been identified by spectroscopic research, having been generated naturally in stars or supernovae. Aluminium-26, for example, is not naturally found on Earth yet is abundant on an astronomical scale.

The atomic masses of elements shown in the table are values that account for the occurrence of numerous isotopes with differing masses. Prior to the discovery of isotopes, scientists were perplexed by experimentally established noninteger values of atomic mass. A sample of chlorine, for example, comprises 75.8% chlorine-35 and 24.2% chlorine-37, with an average number of atoms of 35.5 atomic mass units. According to widely accepted cosmology theory, only hydrogen and helium isotopes, traces of some lithium and beryllium isotopes, and possibly some boron, were created at the Big Bang, while all other nuclides were synthesised later, in stars and supernovae, and in interplay between energetic particles such as cosmic rays and previously produced nuclides. (For further information on the numerous mechanisms considered to be responsible for isotope generation, see nucleosynthesis.) The relative abundances of isotopes on Earth are determined by the amounts created by these processes, their dispersion around the galaxy, and the rates of decay for unstable isotopes. Isotopes were reallocated according to mass after the Solar System's initial coalescence, and the isotopic makeup of elements differs somewhat from planet to planet. This may occasionally be used to determine the origin of meteorite.

### **Standard model**

The integration of two particle physics theories into a single framework to explain all interactions of subatomic other than those caused by gravity. The standard model is made up of two parts: electroweak theory, which covers interactions through the electromagnetic and weak interactions, and quantum chromodynamics, which describes interactions via the strong nuclear force. Both of these theories are gauge field theories, which explain particle interactions by exchanging intermediate "messenger" particles with one unit of inherent angular momentum, or spin.

The standard model also includes two families of quantum particles that make up matter and have spins of one-half unit in addition to all these force-carrying particles. These particles are known as quarks and leptons, and each has six kinds, or "flavours," that are associated in pairs in three "generations" of increasing mass. Everyday matter is made up of members of the lightest generation: "up" and "down" quarks, which make up the protons and neutrons of atomic nuclei; the electron, which orbits within atoms and helps to bind atoms together to form molecules and more complicated structures; and the electron-neutrino, which plays a role in radioactivity and thus influences the stability of matter. Heavier quarks and leptons have been found by investigations of high-energy particle interactions, both in scientific labs using particle accelerators and in instinctive responses of high-energy cosmic-ray particles within the atmosphere.

The standard model has shown to be a very effective framework for accurately predicting quark-lepton interactions. However, it contains a number of flaws that prompt physicists to seek a more comprehensive explanation of subatomic particles but also their interactions. For example, the current standard model cannot explain why there are two generations of quarks and leptons. It

provides no predictions about the masses of quarks and leptons, nor about the strength of their interactions. Physicists believe that by examining the standard model in great detail and taking very exact measurements, they will find a method for the model to begin to break down and therefore uncover a more comprehensive theory. This might be a grand unified theory, in which a single theoretical framework is used to represent the strong, weak, and electric forces.

### **Nuclear Model**

Any of various theoretical theories of the structure and functions of atomic nuclei (the positively charged, dense cores of atoms). Each model is built on a realistic analogy that integrates a vast quantity of information and allows for predictions of nuclear characteristics.

Nuclear models are divided into two categories. The basic assumption in the first category, known as independent-particle models, is that there is little or no interaction between the component particles that make up nuclei; each proton and neutron travels in its own orbit and acts as though the other nuclear particles are passive players.

The primary assumption of a second set, known as strong-interaction or statistical models, is that protons and neutrons are mutually linked to each other and behave cooperatively in a fashion that represents the short-ranged great nuclear force between them. This category includes the liquid-drop model and the compound-nucleus model (qq.v.).

### **Nucleus**

All of the bonded protons and neutrons in an atom form a small atomic nucleus, which is referred to as a nucleon. A nucleus' radius is about equivalent to  $1.07 \sqrt[3]{A}$  femtometres, where  $A$  is the total number of nucleons. [This is substantially less than the length of an atom, which is about 105 fm. The nucleons are held together by the residual strong force, which is a short-ranged attractive potential. This force is substantially stronger than the electrostatic power that causes positively charged electrons to resist each other at distances less than 2.5 fm.

The atomic number of an element is the number of protons in each atom. The amount of neutrons inside a single element may change, defining the element's isotope. The nuclide is determined by the total amount of protons and neutrons. The stability of the nucleus is determined by the quantity of neutrons compared to protons, with some isotopes experiencing radioactive decay.

Fermion particles include the proton, electron, and neutron. Fermions are subject to the Pauli Exclusion Principle, which states that identical fermions, such as multiple protons, cannot occupy the same quantum state at the same time. As a result, every proton in the nucleus must be in a quantum state distinct from all other protons, and the same is true for all neutrons in the nucleus and electrons in the electron cloud.

A nucleus with more protons than neutrons might theoretically decay to a lower energy state through radioactive decay, causing the number of protons to more nearly match. As a consequence, atoms with the same number of protons and neutrons are more stable over decay; nevertheless, as the atomic number increases, the mutual repulsion of the protons necessitates an increasing percentage of neutrons to keep the nucleus stable.

A nuclear fusion process shown in which two protons fuse to generate a deuterium nucleus comprised of a proton and a neutron. Along with an electron neutrino, a positron ( $e^+$ ) an antimatter electron is released.



The number of protons and neutrons in the atomic nucleus may be changed, albeit this may need very high energies due to the strong force. Nuclear fusion happens when many atomic particles combine to produce a heavier nucleus, such as when two nuclei collide energetically. At the centre of the Sun, for example, protons need energy ranging from 3 to 10 keV to overcome their mutual repulsion the coulomb barrier and fuse together into a single nucleus. Nuclear fission is the inverse process, in which a nucleus splits into two smaller nuclei, generally by radioactive decay. The nucleus may also be altered by bombarding it with high-energy subatomic particles or photons. If somehow the number of protons in a nucleus changes, the atom becomes a new chemical element.

If the mass of the nucleus after a fusion reaction is less than the sum of the masses of the separate particles, the difference can be emitted as a type of usable energy (such as a gamma ray or the velocity of a beta particle), as described by Albert Einstein's mass-energy correlation formula,  $E=mc^2$ , where  $m$  is the mass loss and  $c$  is the speed of light. This shortfall is part of the new nucleus' binding energy, and it is the irreversible loss of energy that keeps the fused particles together in a condition that needs this energy to separate.

The fusing of two nuclei that results in bigger nuclei with lower molecular numbers than iron and nickel a total nucleon number of roughly 60 is often an exothermic process that produces more energy than is necessary to bring them together. Nuclear fusion in stars is a self-sustaining reaction because of this energy-releasing mechanism. The force of attraction per nucleon in the nucleus starts to decrease as the nucleus becomes heavier. That is, fusion reactions that produce nuclei with atomic numbers more than 26 and atomic weights greater than 60 are endothermic. These more large nuclei are incapable of undergoing an energy-producing fusion process capable of maintaining a star's hydrostatic stability.

### **Electron cloud**

The electromagnetic force attracts electrons in an atom to protons in the nucleus. This force confines the electrons inside an electric potential well that surrounds the smaller nucleus, requiring an additional source of energy for the electron to escape. The stronger the attractive force, the closer an electron is to the nucleus. As a result, electrons bonded at the centre of the potential well need more energy to depart than electrons bound at farther distances.

Electrons, like other particles, have both particle and wave qualities. The electron cloud is an area inside the potential well in which each electron forms a three-dimensional standing wave—a wave form which does not move in relation to the nucleus. An atomic orbital, a mathematical function that characterises the likelihood that an electron appears to be at a certain place when its position is measured, defines this behaviour. Other alternative wave patterns soon decay into a more stable form, thus only a definite (or quantized) set of these orbitals exist around the nucleus. Orbitals may feature one or more circular or node structures and vary in size, shape, and orientation.

Each atomic orbital corresponds to an electron's energy level. By absorbing a photon with enough energy to propel it into the new quantum state, the electron may shift its state to a higher levels of energy. Similarly, an electron in a higher energy state may decrease to a lower energy state while emitting the extra energy as a photon through spontaneous emission. Atomic spectral lines are caused by these distinctive energy values, which are characterized by variations in the energies of the quantum states.



The amount of energy required to remove or add an electron is significantly less than the binding energy the nucleons. For example, stripping a ground-state electron from a hydrogen needs just 13.6 eV, but splitting a deuterium nucleus requires 2.23 million eV. If an atom has an equal amount of protons and electrons, it is electrically neutral. Ions are atoms that have either a shortage or an excess of electrons.

Electrons closest to the nucleus may indeed be transported to other neighbouring atoms or shared amongst atoms. Atoms may bind into molecules and other kinds of chemical compounds, such as covalent and ionic network crystals, via this method.

### **Nuclear properties**

Any two atoms with the same proportion of protons in their cores belong to the same chemical element. Atoms that have the same numbers of protons but a different number of neutrons are isotopes of the same element. For example, all hydrogen atoms have precisely one proton, but there are isotopes with no neutrons (hydrogen-1, by far the most common type, also known as protium), one neutron (deuterium), two neutrons (tritium), and more than two neutrons (tritium). From the micro strip patch hydrogen through the 118-proton element oganesson, the known elements are assigned atomic numbers. All known isotopes of elements with atomic higher numbers than 82 are radioactive, while element 83 (bismuth) has so little radioactivity that it is almost non-existent.

Nearly 339 nuclides exist naturally on Earth, [66 of which 251 (about 74%) have not been seen to decay, and are referred to be "stable isotopes". Only 90 nuclides are theoretically stable, but another 161 (increasing the total to 251) have not been seen to decay, although being energetically feasible. These are also categorized as "stable" officially. An further 35 radioactive isotopes have half-lives greater than 100 million years and have been present ever since Solar System's inception. Primordial nuclides are a group of 286 nuclides. Finally, 53 short-lived nuclides are known to arise naturally, either as daughter products of primordial nuclide decay (such as radium from uranium) or as byproducts of natural energetic processes on Earth, such as cosmic ray bombardment (for example, carbon-14).

There is at least one stable isotope of each chemical element. As a general, each of these elements has just a few stable isotopes, with an average of 3.1 stable isotopes per element. Twenty-six "monoisotopic elements" have just one stable isotope, whereas the element tin has the most stable isotopes of any element, with 10. There are no stable isotopes of elements 43, 61, or 83 or above.

The ratio of protons to neutrons affects isotope stability, as does the existence of specific "magic numbers" of neutrons or protons that reflect closed and full quantum shells. These quantum shells corresponds to a set of energy levels inside the nucleus' shell model; full shells, such as the 50-proton shell for tin, bestow remarkable stability on the nuclide.

Only four of the 251 known stable nuclides contain an odd number of protons as well as an odd number of neutrons: hydrogen-2 (deuterium), lithium-6, boron-10, and nitrogen-14. (Tantalum-180m is odd-odd and general relativity robust, but decay with a very long half-life is expected.) Furthermore, only four naturally occurring radioactive odd-odd nuclides with half-lives longer than a billion years exist: potassium-40, vanadium-50, lanthanum-138, and lutetium-176. Because the decay products are even-even and hence more tightly bonded owing to nuclear pairing effects, most odd-odd nuclei are very unstable with regard to beta decay.

## The Atomic Nucleus

Atomic Nucleus of an atom is the focal point of the atom, where the majority of its mass is concentrated. We found that the atom holds a larger portion of the atom's mass via Rutherford's study of the dispersion of alpha particles. Numerically, an atom's nucleus has almost 10-14 times the volume of the atom yet contains 99.99% of the atomic mass. The nucleus of an atom is so small that if you expanded an atom to fill a room, the nitrogen atom would be no larger than a pinhead!

## Atomic Weight

An atom is very small, and as a result, its mass is also extremely small. A regular unit of mass, such as a Kilogram (Kg), cannot be used to measure something as tiny as an atom, thus researchers devised a new unit of mass. The symbol for this is u, which stands for Atomic Mass Unit. It is referred to as Carbon-12, and one Atomic Mass unit is equal to one-twelfth the weight of one Carbon-12 atom.

A hydrogen atom's mass may be represented as follows:

$$1 \text{ u} = 1 \text{ C-12/12 particle} = 1.992647 \times 10^{-26} \text{ kg}$$

$$1 \text{ u} = 1.660539 \times 10^{-27} \text{ kg}$$

This is the weight of one hydrogen atom.

## The Atomic Nucleus's Composition

The nucleus of an atom is made up of properly arranged protons and neutrons. Because these are the two solid particles in an atom, 99.9% of the mass is concentrated in the nucleus. The protons are the more positively charged of the two. The nucleus of an atom is now generally positively charged, while negatively charged electrons revolve around the nucleus's core. Because the mass concentration at an atom's nucleus is so great, the atomic powers that retain the protons and neutrons are likewise enormous. Because the protons are so near to one another within the small nucleus, electrostatic forces of repulsion also occur inside the nucleus. Nuclear energy is based only on releasing the energy trapped in an atom's nucleus. Because the total number of protons is equal to the total number of electrons spinning around the nucleus, the atom is electrically neutral in general.

There are almost 100 different sorts of atoms. Approximately 92 of these occur naturally, with the others created in laboratories. The addition of additional protons to an atomic nucleus aids in the formation of new atoms. Technetium, which possesses 43 protons, was the first atom created by man.

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## CHAPTER 4

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### Chemical Bonding

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Any of the interactions that account for the association of atoms into molecules, ions, crystals, and other stable organisms that make up the recognisable compounds of daily life is referred to as chemical bonding. When atoms collide, their nuclei and radicals interact and tend to disperse themselves in space in such a manner that the total energy is lower than in any other arrangement. If the overall energy of a collection of atoms is less than the sum of the energies of the component atoms, they bind, and the energy reduction is the bonding energy.

After the electron was discovered and quantum mechanics gave a vocabulary for describing the behaviour of electrons in atoms, the theories that contributed to determine the nature of chemisorption came to fruition in the early twentieth century. Despite the fact that quantum mechanics is required for a full quantitative knowledge of bond formation, chemists' pragmatic grasp of bonding is stated in simple intuitive models.

These models distinguish between two types of bonds: ionic and covalent. The sort of bond that will be most likely to form between two atoms may be anticipated based on the elements' positions in the periodic table, and the qualities of the substances created can be connected to the type of bonding to some degree.

The molecule is an important concept to understand when discussing chemical bonding. Molecules are the tiniest units of compound existence. The form of molecules is one property that may be reasonably anticipated. Knowing the processes that compounds may experience is greatly aided by understanding their molecular structures.

Although basic bonding models are helpful as rules of thumb for justifying the existence of compounds as well as the physical and chemical characteristics and structures of compounds, they must be justified by referring to more complicated bonding descriptions. Furthermore, certain features of molecule structure are beyond the reach of basic theories. To acquire this understanding, a comprehensive quantum mechanical description is required. In reality, these descriptions rely heavily on computers. These numerical techniques to the chemical bond give useful information regarding bonding.

the historical history of current knowledge of chemical bonding but then explains how contemporary theories of chemical bond formation have originated and matured into a compelling explanation of matter's structure. Following the historical prelude, qualitative bonding theories are examined, with special emphasis on the creation of covalent and ion bonds and their association with molecular shapes. Following that, the more advanced quantum mechanical techniques to predisposing factor are explained, followed by an examination of a variety of exceptional instances that create fascinating challenges or lead to key discoveries.

### **The law of conservation of mass**

The contributions of the French aristocrat Antoine-Laurent Lavoisier (and his wife, Marie-Anne) shortly before he lost his head to the guillotine at the height of the Reign of Terror were critical in transforming chemistry from a collection of vain hopes and alchemical meddlings to a corpus of valid and reliable knowledge. Lavoisier pioneered quantitative chemistry by demonstrating that the transformations of materials, which had hitherto been represented mostly by a jumble of uncoordinated accounts, could be quantified by measuring the amounts of substances consumed and created in reactions. The most important discovery he made was that, even though one material is changed into another during a reaction, the total mass of the products equals the total mass of the reactants. The conclusion of this discovery is that, even though the identity of the chemicals may change throughout a reaction, something stays constant.

#### **The proportionality principle**

Lavoisier's experiments sparked more research, eventually leading to the demise of the belief that matter is a structureless continuum. These results resulted in the English scientist John Dalton's atomic theory, which asserts that everything is made up of indestructible particles that are unique to and distinctive of each element. Two significant sets of observations contributed to the formation of this viewpoint. First, it was discovered that compounds, regardless of their origin, always have a set composition. As a result, regardless of how the sample was obtained, 18 grammes of water always included 2 grammes of hydrogen and 16 grammes of oxygen. Such results, at least briefly, overturned the French scientist Claude-Louis Berthollet's belief that compounds had changing composition. However, recent study has shown that there are specific groups of chemicals whose composition varies. Nonetheless, they are the exception rather than the norm, and the law of definite proportions (also known as the law of constant composition) is the rule rather than the exception.

### **The multiple proportions law**

The realisation of the presence of linked series of compounds created by the same components was the second step toward Dalton's synthesis. For example, although 28 grammes of carbon monoxide always contains 12 grammes of carbon and 16 grammes of oxygen, carbon also forms the complex carbon dioxide, and 44 grammes of this molecule always contains 12 grammes of carbon and 32 grammes of oxygen. In this case, the amount of oxygen that combines with a constant mass of carbon to generate carbon dioxide is precisely double that of carbon monoxide. Such findings strongly showed that carbon dioxide contains precisely twice as many oxygen entities as carbon monoxide. When two elements combine in a sequence of compounds, Dalton predicted that the ratios of the masses of one element that combine with a fixed mass of the other are reducible to tiny whole numbers; this is now known as the law of multiple proportions.

### **The atomic hypothesis of Dalton**

John Dalton combined these insights together, establishing a vocabulary that has remained ubiquitous in chemistry with slight alterations. He argued that elements are made up of indestructible atoms, that each atom of an element is identical, that atoms of various elements vary in mass, and that compounds are made up of distinct groupings of atoms. Because a compound is defined by the arrangement of atoms, and each atom has a distinct mass, it was immediately apparent that compounds had a set composition by mass. Furthermore, the presence of related families of compounds that vary in their composition by mass in an integral way may

be explained instantly by assuming that the different compounds varied in the number of atoms of one element that combine with one atom of a second element. Carbon monoxide, for example, is made up of one carbon atom coupled to one oxygen atom, but carbon dioxide is made up of one carbon atom linked to two oxygen atoms. Thus, carbon monoxide is abbreviated CO, and carbon dioxide is abbreviated CO<sub>2</sub>.

## Features of bonding

### Valence

The nineteenth-century chemists accumulated a huge amount of empirical data that led to the understanding that patterns exist in the sorts of chemicals that elements may make. The most valuable rationalising property of an atom is its valence, which was initially described as the greatest amount of hydrogen atoms that may bond to an element's atom. Hydrogen was chosen as the valence probe because researchers determined that single atom of oxygen is never found in conjunction with more than one other atom, making it the most fundamental of the elements. As a result, it was determined that oxygen (O) has a valence of 2 (as in water, H<sub>2</sub>O), nitrogen (N) has a valence of 3 (as in ammonia, NH<sub>3</sub>), and chlorine (Cl) has a valence of 1 (as in hydrogen chloride, HCl). Examining overall patterns of bonding between atoms allowed for the assignment of typical valences to all elements, despite the fact that their compounds with hydrogen were unknown. Although the idea of valence was strongly indicative of an inherent feature of atoms, certain parts remained perplexing, such as the discovery that some elements seem to have more than one common valence. Carbon, for example, is discovered to have common valences of 2 and 4.

### Compounds with ionic and covalent bonds

In the early days of chemistry, a second universal property of bonding became evident. It was discovered that two major types of compounds may be separated by their behaviour when dissolved in water. Electrolytes are one kind of substance; they are so named because they dissolve to form solutions that conduct electricity. Nonelectrolytes, on the other hand, dissolve to produce solutions that do not conduct electricity. The difference in the two classes led to the belief that there are two sorts of chemical bonds. In solution, electrolytes generate ions; an ion is an electrically charged atom that carries its electric charge as it passes through a solution. As a result, electrolytes either contain ions before dissolving or create ions after dissolving. Nonelectrolytes do not create ions when dissolved and do not contain ions when undissolved. It became clear that certain compounds are made up of ions, whilst others are made up of distinct groups of atoms bound together. Covalent compounds are the latter. In fact, it took a long time for the view that ions exist even before dissolution to be confirmed, and it wasn't until the early twentieth century that crucial evidence was obtained that showed the presence of distinct entities, specifically sodium cations (positively charged atoms), Na<sup>+</sup>, and chloride anions (negatively charged atoms), Cl<sup>-</sup>, in solid sodium chloride (NaCl).

### The periodic table

The pattern of valence and the kind of bonding—ionic or covalent—characteristics of the elements were critical components of the evidence used by Russian scientist Dmitri Mendeleev to assemble the periodic table, which arranges the chemical elements in a way that indicates familial resemblances. Thus, oxygen and sulphur (S), both of which have an usual valence of 2, were placed in the same family, whereas nitrogen and phosphorus (P), both of which have a

typical valence of 3, were placed in a neighbouring family. The periodic table, seen in Figure 1, has proven to be the most unifying notion in chemistry since it summarises a plethora of features. Metallic elements are often found on the left side of the periodic table and create ionic compounds.

Nonmetallic components, which form a significant number of covalent compounds, are often found on the right side of the table. If the special case of the band of elements in columns 3 through 12 of the table, referred to as the transition elements, is ignored for the time being, then the typical valences of elements increase from 1 on the far left, rising in steps of 1 on passing to the right, to 4 at the family headed by carbon (C), and then falling in steps of 1 to 1 itself at the family containing chlorine and headed by fluorine (F). Finally, a valence pattern that any explanation in chemical bond formation must support.

Unknown to Mendeleev, and not found until the late nineteenth and early twentieth centuries, is another family containing elements that were initially assumed to be inert, thus the name inert gases. Helium (He) is the leader of this family, which also contains neon (Ne), argon (Ar), krypton (Kr), xenon (Xe), and radon (Rn). It wasn't until the 1960s that their chemical inertness was broken, and several members of the family (mostly krypton and xenon) were induced to form compounds. As a result, the word inert gas has been superseded by the phrase noble gas, which denotes chemical aloofness but not absolute inertness. This element family may have seemed unimportant to a knowledge of chemical bonding at first. However, the fact that they do not easily form any bonds was crucial for the development of contemporary bond formation theories.

### **Additional atomic evidence**

#### **Avogadro's theorem**

Until the early twentieth century, some saw the atomic idea as little more than an unproven concept or a simple accounting method. The existence of atoms and molecules was frequently supported but far from generally acknowledged. However, as experimental data increased, resistance to the actuality of atoms faded. Quantitative measurements of gas quantities were among such historically important evidence.

Thus, it was discovered that when water is electrolyzed (that is, when an electric current is sent through it), the gases hydrogen and oxygen are created in a 2:1 volume ratio. Amedeo Avogadro, an Italian physicist, proposed that identical quantities of gases (at the same temperature) contain the same number of molecules.

Water electrolysis was then shown to be compatible with a water molecule composed of two oxygen atoms and one hydrogen atom, and hence with the chemical formula  $H_2O$ . (It is now established that hydrogen gas is made up of  $H_2$  molecules and oxygen gas is made up of  $O_2$  molecules, but this little detail does not change the meaning.)

#### **The gas kinetic theory**

The measured quantities of gases confirmed the presence of atoms and molecules. The development of mechanics advanced our knowledge of atoms and molecules by predicting the qualities of gases based on the notion that they are made up of granules in constant chaotic motion. The pressure exerted by a gas and the speed of its molecules could be calculated using this kinetic model of gases (see gas: Kinetic theory of gases), and good agreement with observation was achieved.



## Atom

When tools for depicting visual representations of atoms were discovered in the early twentieth century, the final objection to the existence of atoms dissipated. The early approaches used X-ray diffraction, in which the pattern of confusion between rays reflected by a crystal may be interpreted in terms of scattering from individual atoms. More images of atoms were created in the 1960s by using methods that stripped electrons from arrays of atoms at the surfaces of solids in order to create a map of the surface, as well as by using improved electron microscopy techniques that increased the high resolution of the microscope to nearly the point where individual atoms could be distinguished. The discovery of scanning tunnelling microscopy in the 1980s provided the most visually striking proof. A needle tip honed to consist of both a single atom is pushed like a tiny plough just over the surface of a sample in this procedure, and its location is monitored. The findings are shown as a visual picture of the sample's surface. The method has been refined to the point that it can be used to pinpoint the precise position of individual atoms. Electron microscopy is the closest approach to a genuine "sighting" of an atom since the picture needs the least amount of building. Images are acquired only after extensive mathematical processing of X-ray diffraction data. Field-emission and scanning tunnelling microscopy both provide atomic-scale representations of surface characteristics and reveal atom like features.

## The structure of molecules

Long before these advanced methods supplied such solid proof, most scientists were convinced that atoms existed. When the chemical compositions of innumerable compounds were identified in the nineteenth century, it was discovered that in certain situations, various compounds share the same chemical makeup. Thus, the formula  $C_3H_4$  was discovered for two completely distinct organic molecules (as determined by both their physicochemical characteristics), namely propyne and allene. Chemists were obliged to conclude, despite their confidence in their findings, that the two molecules vary in the way their component atoms are joined together.

Chemists in the nineteenth century had to deduce the structure of molecules via sophisticated but indirect testing. The contemporary knowledge of molecular form is more straightforward X-ray diffraction, in particular, has yielded breathtakingly detailed pictures of molecules as big as proteins, which comprise thousands of atoms. Scanning tunnelling microscopy has produced realistic pictures that unequivocally demonstrate the key characteristics of molecular geometry.

The significance of determining (and comprehending) molecule structure cannot be overstated. At the most basic level, the characteristics of tiny molecules (including the ubiquitous and crucial water molecule,  $H_2O$ ) are determined by their shapes rather than their atomic compositions. The oceans, for example, may not exist if water molecules were linear rather than angular, since the interactions between  $H_2O$  molecules would be weaker, and hence life might not have evolved if water molecules were linear. Geometric shape is fundamental to biochemical activity at the most complicated level, that of proteins, and so plays a key role in all biological systems.

### Atomic internal structure

Thus, the notion of atoms arose from the rigorous measurement of mass and volume, and were the only quantitative probes of matter accessible in the early days of chemistry. The model's explanatory capacity, on the one hand, and ever more direct representations of tiny things, on the

other, confirmed the actuality of atoms. As the atomic concept of matter gained traction, researchers focused on the existence of structures, which are unique assemblages of atoms. When molecules were studied, it was revealed that they had unique atomic linkages and that the atoms are arranged in three-dimensional patterns that are unique to the compound and the component atoms.

The problems presented by this wealth of information went unanswered until the internal structure of atoms was discovered at the end of the nineteenth century. The basic concept, provided by John Dalton, that atoms are irreducible, immutable entities, effectively ruled out the possibility of knowing their attributes since it assumed the lack of internal structure. The discovery of the electron as a universal element of matter resulted in the mutability of atoms, and hence the first glimmers of a knowledge of their composition and behaviour. The electron was the first subatomic particle identified, and it eventually proved to be the most crucial for explaining the chemical bond. This significance arises in large part from the ease with which electrons may be transported from one atom to another. This transferability of electrons is the essential to bond formation, as will be shown below, and all theories of the chemical bond rely on the redistribution of an atom's electrons as it connects to another atom.

More on the important properties of electron arrangement in atoms will be discussed in the next section. The knowledge that electrons are grouped in shells that surround a core positively charged nucleus was the key to comprehending the structure of the periodic table and hence the pattern of bonding between atoms. Each shell can only hold a certain amount of electrons. The electrons involved in bond formation are found at the outermost shell because they are the least firmly connected to the nucleus and hence may be released most easily. The valence shell is the name given to this shell. The most essential aspect of the valence shell is that it is complete (in the sense discussed below) for noble gases, with its full complement of electrons (i.e., eight, excepting the case of helium). Thus, the creation of chemical bonds seems to be tied to the valence shell's incompleteness.

### **Lewis's contributions**

Gilbert N. Lewis, an American chemist, proposed the importance of the valence shell in bond formation about 1916. German physicist Walther Kossel conducted important independent research, while American scientist Irving Langmuir subsequently contributed. First, Lewis proposed that ionic bonds are formed by the complete transfer of electrons from one atom's valence shell to the valence shell of another atom, and that the transfer continues until both valence shells reach the electronic composition characteristic of the nearest noble gas atom in the periodic table. As a consequence, sodium has one electron in its valence shell, and its loss results in a singly charged cation,  $\text{Na}^+$ , with a neon-like electron configuration. The valence shell of chlorine, on the other hand, requires one additional electron to reach the closed shell typical of its noble gas neighbour, argon, and so quickly forms the singly charged anion  $\text{Cl}^-$ . As a result, the synthesis of sodium chloride as a collection of  $\text{Na}^+$  ions and  $\text{Cl}^-$  ions is simple to understand.

Lewis hypothesised that a covalent bond is made up of two electrons shared between atoms rather than being completely contributed by one atom to another. He had no idea why a pair of electrons was so crucial (that knowledge would come later with the advent of quantum physics), but his discovery explained a large body of chemical facts. Lewis stressed the relevance of the nearest-noble-gas valence shell in the creation of ionic bonds and postulated that, as in the formation of ionic bonds, electron sharing continues until each atom has a noble gas

configuration., Lewis' theories are encapsulated by his famous octet rule, which asserts that electron transfer or electron sharing continues until an atom has an octet of electrons (i.e., the eight electrons characteristic of the valence shell of a noble gas atom). Ionic bonding occurs when full transfer happens. When electrons are simply shared, the link is covalent, and each shared electron pair forms one chemical bond.

This is the foundation of the generally believed notion of chemical bonding. However, there is much to explain and comprehend, and there are numerous key exceptions to Lewis' concepts, which cannot offer a full account of bonding. The parts that follow take a step back from this historical narrative and place Lewis's significant ideas in a larger perspective, revealing more of their impact. Simultaneously, the more sophisticated analysis of bonding will exceed Lewis' concepts and account for aspects of bonding that his views could not accommodate.

### **Helium and hydrogen**

The atomic orbitals of oxygen are used to describe the architecture of many-electron atoms. The following is a brief qualitative overview of their application, without describing the technical, computer-based calculations required to get excellent agreement with trial: such agreement may be accomplished with the right procedures, and extremely exact energies can be estimated. The technique detailed in the upcoming sections is known as the building-up (or, in German, Aufbau) principle.

In the building-up concept,  $Z$  electrons (for a neutral atom of an element with atomic number  $Z$ ) are sequentially deposited into an array of hydrogen-like atomic orbitals in order to obtain the lowest total energy feasible. To account for the structure of a diatomic molecule (for which  $Z = 2$ ), one electron is permitted to occupy a hydrogen-like  $1s$  orbital, and then another electron is allowed to join it, resulting in the electron configuration  $1s^2$  (read "one-s-two").

### **From lithium to neon**

One additional electron is added to generate the ground-state electron configuration of the following element, lithium ( $Z = 3$ ). However, that electron cannot inhabit the  $1s$  orbital since it contains a basic feature called as spin. Spin, like mass and charge, is an inherent feature of an electron. Spin is often shown as a spinning motion in primary treatments. It is, however, a quantum mechanical feature with no classical equivalent, therefore seeing spin in this manner may be deceptive. Nonetheless, for the sake of this debate, such a representation is beneficial. An electron has a constant quantity of spin in the sense that every electron in the cosmos spins at the same rate all the time. Although an electron's spin is constant, the direction of its spin axis is flexible, but quantum physics limits that orientation to just two possibilities. The two potential spin states of an electron are shown by the arrows and are separated by the spin magnetic quantum number,  $m_s$ , which may be  $+1/2$  (for the spin) or  $-1/2$  (for the spin).

An electron must fulfil a basic condition known as the Pauli exclusion principle due to its spin. This principle (a result of the more basic Pauli principle) stipulates that no more than two electrons may occupy a particular orbital, and that if two electrons do occupy one orbital, their spins must be paired (denoted; that is, one electron must be  $\uparrow$  and the other must be  $\downarrow$ ). The electron pair's role in the creation of covalent bonds is due to the Pauli Exclusion Principle. On a larger scale, it is also the reason why matter has mass; that is, all electrons cannot occupy the lowest energy orbitals and must instead be found in the numerous shells that surround the nucleus. Because of the presence of spin, two objects cannot simply blend into one another when they

come into contact; the electrons of nearby atoms cannot occupy the same area, preventing the fusion of two atoms into one. This is another example of an apparently little feature, in this instance spin, having enormous and macroscopic repercussions. In this case, the electron's spin is responsible for the existence of distinguishable forms of matter.

With the Pauli Exclusion Principle in mind, it is clear that the 1s orbital (and hence the whole  $n = 1$  shell, since that shell consists of just one orbital) is full in helium. Helium is classified as a closed-shell species. There is a clear link between the prior observations about helium's inertness and the fact that its valence shell is complete. The specifics of this link will be discussed more below. With the  $n = 1$  shell completed, the third lithium electron must enter an orbital of the next higher shell,  $n = 2$ . This shell is divided into two subshells, each of which contains a single 2s orbital and three 2p orbitals.

The next issue to address is the experimental (i.e., spectroscopic) finding that the third electron occupies the 2s orbital rather than either of the three 2p orbitals, resulting in the configuration  $1s^2 2s^1$ . All shell orbitals of a hydrogen atom are degenerate. That is not the case in atoms with more than one electron; in such cases, the s subshell has lower energy than the p subshell inside a given shell. The lower energy of an ns orbital compared to an np orbital results from an s electron's ability to be located very near to the nucleus.

If the electrons in the ns and np orbitals were dispersed evenly outside the closed shells that make up the helium-like heart of the atom, the two core electrons would reject them equally. As a consequence, they would have a reduced effective nuclear charge, which is the difference between the real charge of the nucleus and the net charge encountered after accounting for electron repulsion. Shielding of the nuclear charge refers to the lowering of the real nuclear charge by the influence of the other electrons in the atom. It is also worth noting that a 2s electron may pass through core (that is, have nonzero probability of being found closer to the nucleus than the bulk of the core electron density). If penetration happens, the electron is exposed to the entire nuclear charge and hence has less energy than an electron in an orbiting that cannot enter the shielding core. Because a ns orbital has zero amplitude at the nucleus, the combination of the effects of penetration and shielding results in a somewhat lower energy than a np orbital.

According to spectroscopic data, the third electron in a lithium atom should occupy the 2s orbital in order to reach the lowest feasible energy. Following elements finish the 2s subshell (at beryllium, Be;  $Z = 4$ ) before beginning the 2p subshell. After the addition of six additional electrons, which happens at neon (Ne;  $Z = 10$ ), the three orbitals of the 2p subshell are completed.

Another feature of the building-up concept should be highlighted at this time, albeit its relevance will become clear later. If Hund's rule is applied when there are numerous orbitals of the same energy available for occupancy, the electron configurations seen in atoms are found to be duplicated. This rule specifies that if more than one orbital is available for the electrons now being accommodated, those electrons occupy different orbitals with parallel spins (both, for example, which would be indicated). The occupancy of different orbitals reduces the repulsion energy between the electrons, resulting in less energy than if they were confined to the same area of space. Hund's rule requires electrons to have parallel spins, which is more delicate. When electrons have parallel spins, quantum physics forces them to keep away from one another; as a

consequence, the atom might shrink somewhat, improving the energy of attraction between its electrons and nucleus.

The whole  $n = 2$  shell is complete at neon. It should be noted at this point that both the second noble gas, neon, and the first noble gas, helium, have a closed-shell electron structure. Also, eight electrons are required to move from helium to neon, eight is the greatest number of electrons that the  $n = 2$  shell can hold, and the major portion of the periodic table has eight columns of elements. Thus, the main structure of this table has been described using a combination of the Pauli Exclusion Principle and the effects of penetration and shielding.

From sodium to argon

Following neon on the periodic table is sodium (Na), with  $Z = 11$ . The Pauli principle prevents its extra electron from entering neon's closed shell and forces it to enter the next higher energy shell, when  $n = 3$ . This shell has three subshells, 3s, 3p, and 3d, and the energy of these subshells are in the sequence 3s 3p 3d due to the effects of penetration and shielding. As a consequence, the incoming electron enters the 3s orbital, resulting in the sodium atom's ground-state electron configuration being  $[\text{Ne}]3s1$ , where  $[\text{Ne}]$  denotes the neon-like  $1s2s2p6$  closed shell. The electron configuration of sodium,  $[\text{He}]2s1$ , with its helium-like closed-shell core, is the precise equivalent of the electron configuration of lithium (Li),  $[\text{He}]2s1$ . Furthermore, sodium is a member of the same chemical family as lithium and has very comparable chemical characteristics, including the capacity to create ionic compounds containing singly-charged cations, notably  $\text{Na}^+$  and  $\text{Li}^+$ .

The periodic table's third row (sodium through argon) is a reproduction of the second row (lithium through neon), with the main variation being that a more distant shell of s and p orbitals (the shell with  $n = 3$ ) is filled. The components in this row have a significant familial resemblance to the ones just above them in the second row, notably in terms of valences. Furthermore, after eight members, the row comes to an end with the noble gas argon, which has a closed set of 3s and 3p subshells.

However, potassium via krypton chemistry is a nuanced issue, and its variation is dependent on that complexity. The detail required at this point (but not overly emphasised) is that the effects of penetration and shielding are so pronounced that the 4s orbital is significantly lower in energy by its ability to penetrate close to the nucleus that it lies lower than the 3d orbitals, despite belonging to a shell with a lower principal quantum number. Thus, following argon, the next electron enters the 4s orbital rather than the 3d orbital, resulting in the potassium configuration  $[\text{Ar}]4s1$ , where  $[\text{Ar}]$  indicates the argon configuration. Indeed, potassium has chemical characteristics that are comparable to sodium, which is compatible with its corresponding electron arrangement.

After potassium, calcium comes next, and its extra electron completes the 4s subshell. At this point, the five 3d orbitals are next in line for occupancy, and their sequential filling accounts for the ten transition elements (from scandium to zinc). Only once the 3d subshell has been completed are the 4p orbitals ready for occupancy, and six electrons are required to carry the elements to the next noble gas, krypton. The existence of 3d orbitals in the scheme of occupancy extends the fourth row of the periodic table from 8 to 18 members, and the row from potassium to krypton is known as the periodic table's first long period. As electrons are added, the pattern illustrated by this discussion continues, and the following row of the table duplicates the electron configurations of the fourth row. The periodic table's overall pattern is now determined.



## Trends and periodic arrangement

### The components' arrangement

Groups are periodic table columns that include elements that have a familial resemblance. All members of a certain group have comparable outermost (valence) electron configurations, so that the kinds and quantities of chemical bonds that they may form should exhibit a familial link. Periods are the horizontal rows of the periodic table. Each period corresponds to the consecutive occupancy of orbitals in the atom's valence shell, with the lengthy periods corresponding to the occupation of orbitals in the atom's d subshell. Following phases in the table correspond to increasing values of  $n$  for the valence shell. The first phase corresponds to  $n = 1$ , the second period (from lithium to neon) to  $n = 2$ , and so on. These consecutive phases correspond to atoms in which the valence shell is located outside of a more electron-rich core of completed inner shells. The first six periods each end at a noble gas with a closed-shell electron structure. The replication of analogous electron configurations that characterises the periodic table is an example of periodicity and is responsible for the overall pattern of the elements when arranged as Dmitri Mendeleev originally proposed, with chemical insight but without the benefit of quantum mechanics.

Property trends occur on a regular basis.

The elements exhibit a wide range of periodicities. The periodicity of the qualities that are directly relevant to the formation of chemical bonds will be emphasised. These parameters are basically atom size and the energy needed to detach or attach electrons to neutral atoms.

### Atomic weight

In general, atom radii grow from top to bottom of the periodic table and decrease from left to right. As a result, the biggest atoms are at the bottom left of the table, while the tiniest are at the top right. The rise in radius along each group is caused by the formation of one additional layer of the atomic "onion" in subsequent periods; that is, electrons are added to a new shell outside the atom's closed-shell core. Thus, lithium has one electron outside of a compact, helium-like core, sodium has one electron outside of a neon-like core (which has a helium-like core deep inside its structure), and so on.

The drop in atomic radius from left to right during a period may be more startling, since it happens despite the existence of extra electrons in each succeeding element. Thus, lithium has three electrons and beryllium (Be) has four, although beryllium is slightly smaller. Fluorine, with nine electrons, would seem to be a much bigger atom than lithium, however this is not the case. The rationale for this apparently illogical pattern is that, although subsequent elements have more electrons, they also have a greater nuclear charge due to the rising number of protons. The positive charge attracts the electrons around it, compacting the atom. The inner-shell, or core, electrons, which do not grow while passing through a period, effectively buffer the outer-shell electrons from the nucleus's positive charge. However, the outer-shell electrons that are added upon crossing a period do not protect other valence electrons from the growing charge of the nucleus as effectively as the core electrons. As a result, the larger charge of the nucleus pulls the outer-shell electrons in closer. There is definitely rivalry (as is frequently the case in chemistry) between the expanding effects of additional electrons and the shrinking effects of the higher



nuclear charge. With a few exceptions, the latter impact somewhat predominates, and succeeding atoms are smaller as they move through a period.

Ions, both cations and anions, exhibit a comparable fluctuation in size with the periodic table position of their parent elements. However, there are two significant variances. First, cations (which are generated by the loss of electrons from the parent atom's valence shell) are always smaller than their parent atoms. In certain circumstances, the difference might be significant (more than 50 percent). When the valence electrons are gone, the outer layer of the atomic "onion" is eliminated, and the radius of the cation is that of the compact atomic core.

Anions, which are generated by an atom gaining electrons (usually into the imperfect valence shell), are generally bigger than the parent atoms. In this situation, the extra electrons reject the existing electrons, causing the atom to expand.

#### Ionization power

The element's ionisation energy is the next most important factor in determining the number and kind of chemical bonds that an atom may form. It is the least amount of energy required to remove one electron from an element's atom. The energy is necessary because the positive charge of the nucleus attracts all of an atom's electrons, and effort must be done to pull the electron off the atom to generate a cation. Because chemical bond formation is based on the transfer or sharing of electrons, the energy needed to remove an electron is an important factor in an atom's capacity to create a bond.

In general, the range in ionisation energy throughout the periodic table matches the change in atomic radii, with tiny atoms having high ionisation energies and big atoms having low. Hence, elements with the lowest ionisation energies (and thus from which an electron is most easily removed) are found near cesium and francium on the lower left of the periodic table, while elements with the greatest ionisation energies are located near fluorine and helium on the upper right. Because a valence electron in a bulky atom is on average distant from the nucleus and so feels only a mild attraction to it, the variation in ionisation energy coincides with the difference in atomic radius. A valence electron in a tiny atom, on the other hand, is near to its parent nucleus and is exposed to a strong attractive force.

At this moment, the relative inertness of noble gases may be explained in part. They are located on the right side of the periodic table, and the members of the family that are closest to helium (specifically, neon and argon) have among the greatest ionisation energies of any element. As a result, their electrons are unavailable for bond formation. Only at the lower end of the group, at krypton and xenon, do the ionisation energies approach those of other elements, and these elements can be coaxed into compound formation by sufficiently aggressive reagents (most notably by fluorine).

The energy necessary to remove a second electron from an atom is always greater than the energy required to remove the first electron, which is a significant aspect of the ionisation energy. Because there are less electrons to reject one another in the cation after one electron is removed, more effort is required to drive the next electron away from the nucleus. The third electron, which is considerably less accessible than the second, is the same. However, if an electron must be taken from the core of the atom (as is the case with a second electron removed from sodium), the ionisation energy may be quite large and not achievable in the course of a conventional chemical process (as will be justified below). The high ionisation energy of core

electrons are primarily due to the fact that these electrons are far closer to the nucleus than valence electrons, and hence are grasped by it much more tightly.

It is a general rule that for elements on the left side of the periodic table with one, two, or three electrons in their valence shells, enough energy is available in chemical processes to remove them, but not enough energy is available to remove any electrons from the inner shells. As a result, sodium may produce  $\text{Na}^+$  ions, magnesium can produce  $\text{Mg}^{2+}$  ions, and aluminium can produce  $\text{Al}^{3+}$  ions.

One explanation for the significance of noble gas configurations in chemical bond formation is now clear. Once a noble gas has a closed-shell structure, the facile removal of electrons to create cations stops (as does the opportunity for the partial removal of electrons for the sharing required in the formation of covalent bonds, as discussed below). When proceeding beyond the removal of an atom's valence electrons, a substantial energy barrier is met.

Ionization energies do not perfectly match with atomic radii because the energy required to remove an electron is determined by factors other than the electron's distance from the nucleus. These factors include the specifics of orbital occupancy in the valence shell. Once again, the birth of a new option for competition emerges, this time between impacts dictated just by size and those driven by the energy needs for ionization.

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## CHAPTER 5

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### Extensive and Intensive Properties

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The system's behaviour is determined by the interplay of energy with or without mass transfer across the border. Every system contains features that may be used to define its physical circumstances. The attributes of a system refer to such system behavior/characteristics. A system's behaviour is described by 8 (eight) attributes. Pressure, temperature, volume, entropy, internal energy, enthalpy, Gibbs function, and Helmholtz functions are among them. Pressure, temperature, and volume are all quantifiable quantities known as physical attributes (also known as macroscopic properties). Other attributes are derivations (they can not be measured directly). Pressure is always represented in terms of absolute pressure in thermodynamics, while temperature is always given in Kelvin. When all of a system's attributes have definite values, the system is said to exist in a definite state. A thermodynamic system's state may be represented in a diagram using attributes as coordinates.

#### Properties that are both intense and comprehensive

Thermodynamic qualities are classified into two (two) broad categories: intense and extended properties. An intense property is a physical attribute of a system that is independent of system size or material content. An extensive attribute of a system, on the other hand, is dependent on the system size or the quantity of material in the system. Density, pressure, and temperature are defined as intense attributes, whereas volume and internal energy are defined as extensive properties.

Extensive attributes are represented by upper case (capital) letters such as  $V$  (volume),  $KE$  (kinetic energy),  $PE$  (potential energy), and so on. Lower case letters are used to represent intensive attributes such as  $v$  (specific volume),  $ke$  (specific kinetic energy),  $e$ ,  $u$  (specific internal energy),  $h$  (specific enthalpy), and so on. Lower case letters with overbars represent mole-based characteristics. For example, and are molar rate structures, molar specific kinetic energy, and molar specific potential energy, respectively.

#### Ionization power

The element's ionisation energy is the next most important factor in determining the number and kind of chemical bonds that an atom may form. It is the least amount of energy required to remove one electron from an element's atom. The energy is necessary because the positive charge of the nucleus attracts all of an atom's electrons, and effort must be done to pull the electron off the atom to generate a cation. Because chemical bond formation is based on the transfer or sharing of electrons, the energy needed to remove an electron is an important factor in an atom's capacity to create a bond.

In general, the range in ionisation energy throughout the periodic table matches the change in atomic radii, with tiny atoms having high ionisation energies and big atoms having low. Hence, elements with the lowest ionisation energies (and thus from which an electron is most easily removed) are found near cesium and francium on the lower left of the periodic table, while elements with the greatest ionisation energies are located near fluorine and helium on the upper right. Because a valence electron in a bulky atom is on average distant from the nucleus and so feels only a mild attraction to it, the variation in ionisation energy coincides with the difference in atomic radius. A valence electron in a tiny atom, on the other hand, is near to its parent nucleus and is exposed to a strong attractive force.

At this moment, the relative inertness of noble gases may be explained in part. They are located on the right side of the periodic table, and the members of the family that are closest to helium (specifically, neon and argon) have among the greatest ionisation energies of any element. As a result, their electrons are unavailable for bond formation. Only at the lower end of the group, at krypton and xenon, can the ionisation energies approach those of other elements, and these elements may be persuaded into compound formation by suitably vigorous reagents (most notably by fluorine).

The energy necessary to remove a second electron from an atom is always greater than the energy required to remove the first electron, which is a significant aspect of the ionisation energy. Because there are less electrons to reject one another in the cation after one electron is removed, more effort is required to drive the next electron away from the nucleus. The third electron, which is considerably less accessible than the second, is the same.

However, if an electron must be taken from the core of the atom (as is the case with a second electron removed from sodium), the ionisation energy may be quite large and not achievable in the course of a conventional chemical process (as will be justified below).

The high ionisation energy of core electrons are primarily due to the fact that these electrons are far closer to the nucleus than valence electrons, and hence are grasped by it much more tightly.

It is a general rule that for elements on the left side of the periodic table with one, two, or three electrons in their valence shells, enough energy is available in chemical processes to remove them, but not enough energy is available to remove any electrons from the inner shells. As a result, sodium may produce  $\text{Na}^+$  ions, magnesium can produce  $\text{Mg}_2^+$  ions, and aluminium can produce  $\text{Al}_3^+$  ions.

One explanation for the significance of noble gas configurations in chemical bond formation is now clear. Once a noble gas has a closed-shell structure, the facile removal of electrons to create cations stops (as does the opportunity for the partial removal of electrons for the sharing required in the formation of covalent bonds, as discussed below).

When proceeding beyond the removal of an atom's valence electrons, a substantial energy barrier is met.

Ionization energies do not perfectly match with atomic radii because the energy required to remove an electron is determined by factors other than the electron's distance from the nucleus.

These factors include the specifics of orbital occupancy in the valence shell. Once again, the birth of a new option for competition emerges, this time between impacts dictated just by size and those driven by the energy needs for ionisation.

## Electron attraction

After size and ionisation energy, the energy shift associated with electron attachment to a neutral atom is the third most important factor in bond formation. The energy produced when an electron is connected to an atom of the element is described as the electron affinity. The electron affinity is often positive, indicating that energy is released when an electron binds to an atom. This is the circumstance when an incoming electron fills a vacancy in the atom's valence shell. Although it is repulsed by the electrons already there, it is near enough to the nucleus to cause a net attraction.

As a result, when an electron is a component of an atom, its energy is lower than when it is not. However, if the incoming electron must begin a new shell because the neutral atom's orbitals are full, it will remain so far from the nucleus and so strongly repelled by the electrons already present that there will be a net repulsion, and energy will be required to attach the electron to form an anion. The electron affinity is negative in such instances.

This is the second reason why a noble gas configuration represents the end of the road for the creation of ions—in this example, anions. Once the noble gas arrangement is achieved, the connection of extra electrons may result in significant energy losses. Thus, to complete its valence shell, a chlorine atom may take one electron, thus Cl is a frequent species. To complete its shell, an oxygen atom may take two electrons, thus O<sub>2</sub> is also common. These observations disguise some complications, but they are generally correct and account for the creation of the anions typical of the elements on the right side of the periodic table.

Electron affinities fluctuate over the periodic table and have a more complicated periodicity than ionisation energies. However, electron affinities are greatest at the top right of the periodic table, near fluorine. As previously stated, closed-shell noble gases have lower electron affinities. In summary, the elements on the bottom left of the periodic table have low ionisation energies and electron affinities, which explain for their atoms' ability to form cations. They also connect with the fact that certain elements are metallic, as mentioned below, since that quality is dependent on the quick loss of electrons. The high ionisation energies and electron affinities of elements on the top right of the periodic table, on the other hand (with the exception of the noble gases), explain for their rapid production of anions (and for the fact that they are generally nonmetals, since that property is associated with the difficulty of removing electrons from atoms).

## Electronegativity

This comprehensive picture of ion production is summed up by the idea of electronegativity. Electronegativity is defined in a variety of ways. The capacity of one of an element's atoms to draw electrons toward itself when it is part of a compound is referred to as its electronegativity (this definition was originally proposed by the American chemist Linus Pauling). Such an ability is strong if the element's ionisation energy is high (indicating that the atom is unwilling to give up electrons) and its electron affinity is likewise high (for then it is energetically favourable for it to acquire electrons). As a result, elements with high electronegativities are found in the top right corner of the periodic table, near fluorine (but excluding the noble gases). When such components combine, they are likely to create anions. Elements with low electronegativities (i.e., electropositive) and low ionisation energies (such that they rapidly give up electrons) appear toward the bottom left of the periodic table. During compound formation, such elements are prone to produce cations. (The influence of electronegativity on a bond's polarity is described more below in the section the polarity of molecules.) Because the emphasis in this section has



been focused on ion production, it may seem that covalence has been overlooked. However, the stage is now prepared for an introduction to the whole variety of bonding types, and how the atomic feature of electronegativity aids in unifying the subject.

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## The Born-Haber cycle

The synthesis of an ionic compound from its constituents is typically addressed in terms of a Born-Haber cycle, which divides the whole process into a number of known energy stages. depicts the Born-Haber cycle for the production of sodium chloride. The elements are assumed to be in their usual pressure and temperature state at the start of the cycle. To begin, sodium metal is evaporated to form a sodium atom gas. This procedure requires an energy input known as the atomization energy of sodium metal. Following that, a sufficient amount of chlorine molecules ( $\text{Cl}_2$ ) are broken apart to produce a gas of chlorine atoms. This phase also requires a significant amount of energy, which is known as the dissociation energy of chlorine. The origin of these two contributions to energy may be elucidated by looking more closely at metallic and covalent bonding (particularly, the decrease in energy that happens when metallic or covalent bonds form); here, they can be viewed as empirical quantities. An electron is withdrawn from each sodium atom and connected to each chlorine atom at this step. The ionisation process costs a significant amount of energy, and a portion of that investment is returned via the electron affinity of chlorine atoms. However, there is a significant gain in energy when compared to the two beginning materials.

At this point, the ions are permitted to combine and create a crystalline array. This phase releases a huge amount of energy known as the compound's lattice energy. Because a cation first gets surrounded by anions, then that cluster of anions becomes surrounded by cations, and so on, energy is released throughout the crystal formation process. Because of this packing, every cation has anions as neighbours, and every anion has cations surrounding it, resulting in a strong overall attractive interaction among the numerous ions of opposite charge in the crystal. Because the lattice energy of sodium chloride is so high, more energy is released in this stage than is needed for all of the previous processes combined, and solid sodium chloride has a lower energy than sodium metal and chlorine gas. As a result, when sodium combines with chlorine, a tremendous amount of heat is generated.

## Mechanical Properties of Engineering Materials

When materials are utilised, they are often subjected to forces (loads). Material scientists and mechanical engineers determine how materials deform (elongate, compress, twist) or shatter as either a function of applied stress, time, temperature, and other factors. Testing materials teaches materials scientists about mechanical qualities. The size and shape of the substance to be tested (specimen), how it is handled, and how the test is performed all influence the results. That is why we utilise standard operating procedures or standards.

The engineering tension test is frequently used to give basic design information on material strength and as an acceptance test for material specification. In the tension test, a specimen is exposed to a continuously rising tensile stress tensile force while its elongation is measured simultaneously. The compressive modulus, yield strength or yield point, % elongation, and decrease of area are the characteristics used to define a metal's stress-strain curve. A first two are strength characteristics, whereas the latter two are ductility parameters.

In the tension test, a specimen is exposed to a continuously rising uniaxial tensile force while its elongation is measured simultaneously. The load elongation data are used to create an engineering stress-strain curve.

The tensile test is perhaps the simplest and most extensively used test for determining a material's mechanical characteristics. The test is carried out with the use of a loading device, including the Tinius Olsen machine. This machine has a capacity of 10,000 pounds (tension and compression). In its undeformed (no permanent strain or residual stress) or original shape, the specimen of a particular material (e.g., steel, aluminium, cast iron) has a cylindrical shape that is 2.0 in. long and 0.5 in. in diameter. The tensile test findings have immediate design consequences. Many typical engineering major elements are built to withstand tension. The most frequent example of a structure whose parts are meant to be in tension is the truss.

### Concepts of Stress and Strain

Engineering stress is defined as the ratio of the perpendicular force applied to a specimen divided by its initial cross sectional area. The load is determined per unit area, also known as normalisation to the area, to compare specimens of various sizes. Stress is defined as force divided by area. The important region in tension and compression testing is that perpendicular to the force. The region in shear or torsion tests is perpendicular to the axis of rotation. The stress is calculated by dividing the load ( $F$ ) by the initial area of the specimen's cross section ( $A_0$ ).  $\text{Megapascal} = 10^6 \text{ Newtons/m}^2$  is the unit.

As a consequence of tensile or compressive stress, there occurs a change in dimensions, called deformation elongation,  $L$ . The elongation is likewise standardised, this time to the length  $l_0$ , to allow comparing with specimens of varied lengths. This is referred to as strain. So, Strain, often known as engineering strain, is the ratio of the change in size due to bending to the initial length of the specimen. Although strain is unitless, units of  $\text{m/m}$  (or  $\text{mm/mm}$ ) are often employed.

The strain utilised for the engineering stress-strain curve is the average linear strain, which is calculated by dividing the specimen's elongation by its initial length. The load-elongation curve will be of the same form as the engineering stress-strain curve since both the stress and strain are derived by dividing the load and elongation by constant factors. The terms "two curves" and "two curves" are commonly used interchangeably. The shape and amplitude of a metal's stress-strain curve are determined by its composition, heat treatment, previous experience of plastic

deformation, and the strain rate, temperature, and state of stress applied during testing. Tensile strength, ultimate tensile or yield point, percent elongation, and decrease of area are the characteristics used to define the stress-strain curve. The first two are strength characteristics, whereas the latter two are ductility parameters.

The overall form of the engineering stress-strain curve has to be explained further. Stress is proportional to strain in the elastic area. The specimen experiences substantial plastic deformation when the load reaches a value proportional to the yield strength. If the load is released to zero, it becomes permanently distorted.

The stress required to generate continuing plastic deformation rises as plastic strain increases, i.e., the metal strain-hardens. The volume of the specimen stays constant throughout plastic deformation,  $AL = A_0L_0$ , and as the specimen elongates, the cross-sectional area falls equally along the gauge length.

Initially, strain hardening compensates for this loss in area, and engineering stress (proportional to load  $P$ ) rises with increasing strain. Eventually, the reduction in specimen cross sectional area becomes higher than the rise in deformation load caused by strain hardening. This state will be attained first in a specimen that is somewhat weaker than the others. All subsequent plastic deformation is localized in one location, and the specimen starts to neck or thin locally. Because the cross-sectional area is now reducing significantly faster than strain hardening raises the deformation load, the actual load necessary to deform the specimen goes off, as does the engineering stress, until fracture occurs.

### **Yield strength**

In engineering and materials science, the yield point is defined as the tension at which a material starts to plastically deform. The material will deform elastically before to the yield point and will revert to its original shape so when applied force is removed. Once the yield point is reached, a portion of the deformation becomes permanent and irreversible. When designing a component, understanding the yield point is critical since it often reflects the maximum load that may be applied. It is also critical for controlling several materials manufacturing procedures like as forging, rolling, and pressing.

Yield is the persistent viscoelastic material of a structural element under stress in structural engineering. This is a soft failure mode that, unless it accelerates buckling, does not usually result in catastrophic failure. Because of the vast range of stress-strain behaviours seen by actual materials, it is sometimes difficult to determine yield properly. Furthermore, there are numerous approaches to define the yield point in a particular material. Yield happens when dislocations first start moving. Given the difficulties in identifying such movement and the fact that dislocations begin to move at extremely low loads, this term is seldom utilised.

The lowest stress at which permanent deformation can be measured is known as the elastic limit. This necessitates a sophisticated iterative load-unload method that is significantly reliant on the precision of the equipment and the operator's expertise. The point at which the anxiety curve becomes nonlinear is referred to as the proportional limit. The elastic limit and proportional limit are nearly the same in most metallic materials. Offset Yield Point (proof stress) - Because many materials lack a distinct boundary between the elastic and plastic areas, the yield point is sometimes defined as the stress at an arbitrary plastic strain (usually 0.2%). The intersection of a line offset from the linear area by the necessary strain determines this. Because there is no linear

area in certain materials, a particular amount of plastic strain is established instead. Although somewhat arbitrary, this approach allows for constant material comparison and is the most often used.

### **Point of yield.**

The strain deviates from being proportional to the load if the stress is too great.

The yield point is when this occurs because the material yields and irreversibly deforms (plastically).

Yield pressure. Hooke's law is no longer applicable beyond the yield point. The tension at the yield point is known as yield stress, and it is an essential metric of a material's mechanical characteristics. In practise, the yield stress is selected to be the one that causes a permanent strain of 0.002, which is referred to as a proof stress. The yield stress is a measure of plastic deformation resistance.

The yield strength is the amount of stress necessary to cause a tiny quantity of plastic deformation. The offset yield strength is defined as the stress corresponding to the junction of the stress-strain curve and a line parallel to the elastic component of the curve offset by a given strain. In the United States, the offset is often described as a 0.2 or 0.1 percent strain ( $\epsilon = 0.002$  or  $0.001$ ).

A nice way to think about offset yield strength is that after being loaded to its 0.2 percent offset yield strength and then unloaded, the specimen will be 0.2 percent longer than before the test. In the United Kingdom, the offset yield strength is often referred to as the proof stress, where offset values are either 0.1 or 0.5 percent. Because it overcomes the practical challenges of measuring the elastic limit or proportional limit, the yield strength derived by an offset approach is often utilised for design and specification reasons.

The tensile strength is the most often stated figure from tension test findings; nonetheless, it is a value of little basic relevance in terms of a metal's strength. Tensile strength should be viewed as a measure of the maximum load that a ductile metal can take given the relatively limited constraints of uniaxial loading for ductile metals. It will be shown that this number has no relationship to the usable strength of the metal under the more complicated stress circumstances that are often encountered. For many years, it was common practise to base the strength of members on tensile strength, appropriately decreased by a safety factor. The current tendency is toward a more logical approach to static design of ductile metals based on yield strength.

However, due to the lengthy practise of determining the strength of materials using tensile strength, it has become a highly recognisable attribute, and as such it is a very helpful identification of a material in the same way as chemical composition helps to identify a metal or alloy. Furthermore, since tensile strength is a simple to calculate and repeatable attribute, it is important for product standards and quality control. Extensive empirical connections between tensile strength and characteristics like hardness and fatigue strength are often quite beneficial. Tensile strength is a valid design criteria for brittle materials.

### **Ductility**

Deformability prior to braking. Brittleness is the inverse of it. Ductility may be expressed as a percentage of maximum elongation  $\epsilon_{max}$  or as a maximum area decrease. To the best of our

knowledge, ductility is a qualitative, subjective attribute of a material. In general, ductility measures are useful in three ways:

1. To describe the amount to which a metal may be bent without fracturing during metalworking procedures such as rolling and extrusion.
2. To convey to the designer, in general, the metal's propensity to flow plastically before fracture. A high ductility suggests that the material is "forgiving" and likely to deform locally without breaking if the stress calculation or forecast of severe loads is incorrect.
3. To act as a signal for changes in impurity levels or processing conditions. Even though there is no direct link between ductility measures and service performance, they might be specified to check material quality.
4. The tension test yields two common metrics of ductility: the engineering strain at fracture  $\epsilon_f$  (also known as elongation) and the decrease of area at fracture  $q$ . After fracture, both of these parameters are acquired by reassembling the specimen and measuring  $L_f$  and  $A_f$ .

## Resilience

The triangular area under the elastic zone of the curve represents the material's resilience. In general, resilience refers to the capacity to recover from (or resist being impacted by) a shock, insult, or disruption. However, it is employed in many disciplines in quite varied ways. In physics and engineering, resilience is described as a material's ability to absorb energy when deformed elastically and then recover this energy upon unloading. In other words, it is the highest amount of energy that can be stored elastically per volume. In the Stress-Strain diagram, it is represented as the area under the curve in the elastic region.

$U_r$  can be calculated using the following formula:, where  $\sigma_y$  is the yield stress,  $E$  is the Young's modulus, and  $\epsilon_y$  is the strain. Resilience is a material's capacity to absorb energy when bent elastically and restore it when unloaded. The modulus of resilience, which is the strain energy per unit volume needed to stress the material from zero stress to yield stress, is often used to assess this. Resilience is a material's capacity to absorb energy when bent elastically and restore it when unloaded. The modulus of resilience, which is the strain energy per unit volume needed to stress the material from zero stress to the yield stress  $\sigma_y$ , is often used to assess this. For uniaxial stress, the strain energy per unit volume is

The region under the stress-strain curve represents the material's toughness, or the amount of energy it can absorb prior to rupture. It may also be described as a material's resistance to fracture propagation. Toughness is the resistance of a material to fracture when strained in materials science and metallurgy. It is defined as the amount of energy that a material can absorb before rupturing and may be calculated by calculating the area (i.e., the integral) under the stress-strain curve.

Toughness refers to a metal's capacity to bend plastically and absorb energy before fracture. The capacity to absorb energy before fracture should be emphasised in this definition. Remember that ductility is a measure of how much something deforms plastically before fracture, yet being ductile does not imply that it is tough. A suitable blend of strength and ductility is essential for toughness. Toughness is higher in materials with high strength and ductility than in materials with low strength and high ductility. As a result, calculating the area under the stress strain curve from a tensile test is one method of measuring toughness. This number is simply known as "material toughness," and it is measured in units of energy per volume. Material toughness is defined by the material's sluggish absorption of energy.



A material's toughness is defined as its capacity to absorb energy in the plastic range. The capacity to sustain occasional stresses over the yield stress without fracturing is especially important in elements like freight-car couplings, gears, chains, and crane hooks. Toughness is a widely used term that is difficult to nail down and describe. One way to think of toughness is as the whole area under the stress-strain curve. This region indicates how much effort per unit volume may be done on the material without causing it to break.

The stress-strain curves for high- and low-toughness materials are shown in the figure below. The yield and tensile strength of high-carbon spring steel are greater than those of medium-carbon structural steel. The structural steel, on the other hand, is more ductile and has a higher total elongation. Because structural steel has a larger total area under the stress-strain curve, it is a harder material. As a result, toughness is a metric that includes both strength and ductility.

Modulus of resilience for each steel as crosshatched areas. Spring steel offers more resilience due to its higher yield strength. There have been many mathematical estimates proposed for the area under the stress-strain curve. The area under the stress-strain curve of ductile metals, such as structural steel, may be approximated by either of the following equations:

The stress-strain curve for brittle materials is commonly believed to be a parabola, and the area under the curve is given by these are all simply estimates of the area under the stress-strain curves. Furthermore, since the curves are all based on the initial area of the specimen, they do not accurately depict the genuine behavior in the plastic range. Metals' resilience and hardness are compared.

### **Toughness to Impact**

Impact toughness, notch toughness, and fracture toughness are three toughness qualities that will be studied in further depth.

A Charpy or Izod test may be used to measure a material's impact toughness (also known as impact strength). These tests were created in the early 1900s when fracture mechanics theory was accessible and are named after their founders. Although impact characteristics are not directly employed in fracture mechanics calculations, they are nonetheless used as a quality control approach to measure notch sensitivity and to compare the relative toughness of engineering materials.

The two tests use distinct specimens and techniques of specimen handling, but both employ a pendulum-testing mechanism. In all experiments, the specimen is shattered by a single overload event caused by the pendulum's contact. A stop pointer is used to mark how far the pendulum swings back up after the specimen has been fractured. The energy absorbed in the fracture of the specimen is used to estimate the impact toughness of a metal. This is easily acquired by observing the height at which the pendulum is released and the height at which it swings after striking the specimen. The potential energy is produced by multiplying the pendulum's height by its weight, and the difference in potential energy between the start and finish of the test is equal to the absorbed energy.

Because temperature has a large impact on toughness, a Charpy or Izod test is often performed many times, with each specimen evaluated at a different temperature. This generates a graph showing the material's impact toughness as a result of temperature.

The graphic depicts an impact toughness vs temperature graph for a steel. At low temperatures, the material becomes more brittle and has a poor impact toughness. At high temperatures, the

material becomes more ductile and has a greater impact toughness. The transition temperature is the threshold between brittle and ductile behaviour, and it is often a very essential aspect in material selection.

### **Notch Toughness**

Notch toughness is a material's capacity to absorb energy in the presence of a defect. As previously stated, a material's toughness will be reduced in the presence of a fault, such as a notch or fracture. Loading creates a triaxial tension stress condition near to a fault when a flaw exists in a material. When the yield stress in the area around the fracture tip is surpassed, the material produces plastic strains. The degree of plastic deformation, however, is limited by the surrounding material, which remains elastic. Brittle failure occurs when a material is stopped from deforming plastically.

Notch-toughness is assessed using a number of specimens, including the Charpy V-notch impact specimen and the dynamic tear test specimen. As with ordinary impact testing, the tests are often performed many times with varying temperature specimens. It is feasible to produce curves like those illustrated in the graph using these specimens and altering the loading speed and temperature. Only static and impact testing are often performed, although it should be noted that many components in service experience intermediate loading rates in the region of the dashed red line.

### **Fracture Toughness**

In materials science, fracture toughness is a characteristic that specifies a material's capacity to resist fracture in the presence of a crack, and it is one of the most significant qualities of any material for practically all design applications. It is indicated by the symbol  $K_{Ic}$  and has units of. the subscript 'Ic' implies mode 1 crack release or simple strain; the material must be sufficiently thick to shear or tear in mode 2 or mode 3.

Fracture toughness is a quantifiable measure of a material's resistance to brittle fracture in the presence of a crack. If a metal has a high fracture toughness rating, it will most likely fracture ductilely. Brittle fracture is highly common in materials with low fracture toughness values. Fracture mechanics, which led to the idea of fracture toughness, was primarily based on the work of A. A. Griffith, who researched the behavior of fractures in brittle materials, among other things.

The amount of force needed to propagate a preexisting fault is indicated by fracture toughness. It is a critical material attribute since defects cannot be totally avoided during the processing, manufacture, or servicing of a material/component. Cracks, voids, metallurgical defects, weld faults, design discontinuities, and other flaws may emerge. Because engineers can never be completely certain that a material is fault-free, it is standard practice to anticipate that a flaw of some predetermined magnitude will exist in some number of components. This method evaluates the capacity of a defect-containing component to resist fracture using flaw size and features, component design, loading circumstances, and a material attribute termed fracture toughness. Concrete and ceramics, for example, do not have a ductility. The rupture strength and ultimate strength of these materials are the same.

Ductile materials (such as steel) have a fairly linear stress-strain relationship up to a well-defined yield point. The elastic section of the curve is represented by the linear component of the curve, and the slope represents the modulus of elasticity, also known as Young's Modulus. The curve

often declines somewhat beyond the yield point owing to dislocations escaping from Cottrell atmospheres. The stress rises owing to strain hardening as the deformation continues until it achieves the highest strength. Until this moment, Poisson contractions cause the cross-sectional area to shrink equally. Beyond this limit, however, a neck arises where the local bridge area declines faster than the remainder of the sample, resulting in an increase in actual stress. This is shown as a reduction in stress on an engineering stress-strain curve. If the curve is represented in terms of real stress and true strain, the stress will climb till failure. The specimen ruptures as the neck becomes unstable (fractures).

Other than steel, most ductile metals lack a well-defined yield point. The yield strength of these materials is often evaluated using the "offset yield technique," which involves drawing a line parallel toward the linear elastic section of the curve and crossing the abscissa at an arbitrary number (most commonly, 0.2%). The yield point is defined as the point at which this line intersects the stress-strain curve. Ductile materials exhibit considerable permanent deformation and energy absorption.

### **Crystallography in materials**

The study of atom arrangement in materials is known as crystallography. This is accomplished by measuring the radiation's diffraction by the crystal's atomic planes and columns, and then recreating the original atomic configuration. The word used to describe the field that analyses crystalline structures is crystallography. In reality, such as in rocks and jewels, there are several crystalline formations. However, crystallography is mostly employed in the study of proteins and other significant biological molecules that do not normally crystallize there in field of life sciences.

The study of crystallites was based on physical measurement techniques of their geometry to determine their symmetry before the development of crystallography. The field was created after X-Rays were discovered in 1895. H. and W.L. Bragg carried out ground-breaking research in the mid - twentieth century, establishing the connection between crystalline phase and X-ray refraction patterns. The name of this equation is Bragg's law. The study of atom arrangement in materials is known as crystallography. Usually, this is accomplished by measuring the radiation's diffraction by the crystal's atomic planes and columns, and then recreating the original atomic configuration.

Crystallography focuses on using various diffraction and spectroscopic techniques to investigate the microstructure of substances and materials. The Technical University of Darmstadt's materials science department research is illustrated through a number of instances. By using X-ray, neutron, and NMR spectroscopy along with inelastic neutron scattering, researchers are able to better understand the structure and dynamics of aliphatic biomolecules in catalytically active zeolites. Grazing incidence methods are used to study the surfaces and interfaces of semiconductor and thin superconducting films. Details on thickness, structure, surface finish, and a potential alteration of these variables are discovered by looking at the reflect gram.

### **Surface X-Ray Diffraction**

An effective method for determining the arrangement of atoms on a sample's surface is surface X-ray diffraction. Hard X-rays (usually at 15keV) enable the study of interfaces in a variety of environments, such as liquids, high gas pressures, or buried solid-solid contacts. a case of grazing Geometry gives surface sensitivity, and a variety of measures can identify the sample's layer

structure, in-depth atomic surface structure, or nanoparticle size and shape. Surfaces are where materials come into contact with one another, and they play a crucial role in many fields, including catalysis, batteries development, lubrication, and electronics, to name a few. The characteristics are significantly impacted by the surface structure.

### **Principles and Theory of Crystallization**

Crystallography techniques examine the diffraction patterns that a substance experiences as a result of being exposed to radiation. Although X-rays and other forms of electromagnetic radiation are most frequently used, neutrons and electrons also are employed. X-ray, electron, and neutron beams all have unique interactions with the material. Each is appropriate for a distinct study. X-rays interact with valence protons of electrons and its spatial distribution to produce the diffraction patterns. Atomic nuclei with their surrounding electrons' charge distributions are seen in electron beams. Strong nuclear forces, magnetic fields, and other factors disperse neutron beams.

Because of the microscopy is inadequate for studying atomic structures, crystallography is utilized instead. This is so because the wavelength of visible light is several orders of magnitude greater than the lengths of atomic bonds between atoms. Therefore, the examination of structures at this size is better suited to electromagnetic radiation's shorter wavelength. Crystallography and optical methods vary significantly except that the beam can also be focused to create pictures in the traditional sense. Instead, the structure is recreated using a number of methods, including software, from the diffraction pattern. Sharp features are formed by photons mirrored by the molecules in the structure in the diffraction pattern created by crystallographic methods, whereas diffused and weak features are made by non-periodic components. Diffraction patterns produced by crystallographic techniques are excellent for revealing data on the structure of substances because of the repeating and organized character of crystal lattices.

### **Technique of crystallography**

A steady crystal must first be made. Since many biological compounds don't form crystals spontaneously, crystallographers use a number of methods. Different chemicals crystallize at different rates. The molecule is kept in a solutions, and a buffer, precipitants, and the molecule are all contained inside a reservoir to create the crystal. Crystallization is accomplished by the slow precipitation of the molecule-containing solution into the reservoir, which contains a hygroscopic solution. A proper crystal may form if the process is carried out too quickly. A stable crystal is supplied to the crystallographic apparatus after it has formed. A beam is then pointed towards it. The most frequent source of the beam is a synchrotron because of the radiation's high purity. Additionally, they generate the most thorough diffraction patterns. Although there are other sources, synchrotrons continue to be the norm.

Extremely sophisticated mathematics are utilized to examine the diffraction patterns that are created. A statistically predicted pattern is contrasted with two randomly created patterns. Before the real design of the crystalline is discovered, the procedure is refined multiple times. Revisions are no longer nearly as necessary thanks to modern tools. Without software, revealing the crystals' morphology may be a very time-consuming and arduous procedure. Due to an underlying degree of order, the diffraction pattern produced by these kinds of substances can nevertheless offer important information. As an illustration, consider how the diffraction pattern that showed the double-helical structure of DNA was acquired from a fiber sample.

## Applications

X-ray crystallography has a wide range of scientific applications. When it was first proven to be an effective method, it was primarily applied to fundamental science problems, such as figuring out how big atoms are, how long and different kinds of chemical bonds are, how materials are arranged atomically, how different they are from one another, and how alloys and minerals' crystalline impartiality, grain orientation, grain boundaries, film thickness, and interface roughness.

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## CHAPTER 6

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### Free Electron Theory

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The metals produce the lattice structure by forming a unique sort of bonding known as metallic bonding. The distinction in this type of bonding fashion is that, unlike ionic and covalent bonding, where electrons are shared between two atoms and remain localized, in metallic bonding the bond is founded among all the atoms in the lattice and the free electrons of each atom are shared by the entire lattice. Because these free electrons flow freely across the lattice, they are referred to as electron gas. Without considering the electron-electron and electron-ion interactions, it seems that electrons travel in a restricted box with periodic collisions with ions in the lattice. Drude proposed this notion, which he used to successfully explain numerous metal qualities such as conductance, thermal conductivity, and so on.

Drude used basic mechanics equations on electrons to obtain various expressions as well as Ohm's Law. Normally, the electrons move randomly across the lattice, owing mostly to thermal energy, as well as the net average impact is zero. When an electric field is given to a metal, however, another part of velocity is superimposed on each ion as a result of the force acting on it owing to its charge.

Newtonian mechanics allows

Where  $e$  = electron charge,  $E$  = applied electric field in V/m,  $m$  = electron mass, and  $x$  = distance in the direction of travel.

Equation of integration (i)

In where  $A$  and  $C$  are constants. Because equation (ii) is an equation of electron velocity,  $C$  has a velocity dimension and can only be the random velocity of electrons that it had at the start when no field was applied. However, as previously explained, this random velocity averages down to zero, therefore the electrons' average velocity may be represented as-

The following equation implies that the velocity increases forever with time until  $E$  is turned on, however this is not feasible. The rationale for this is because electrons do not flow freely in the lattice, but rather collide with the ions present in the lattice structure, lose velocity, and then accelerate and clash again, and so on.

As a result of the average effect, we estimate that the time between two collisions is  $T$  on average, which is known as the relaxation time or collision time, and the average velocity obtained by electrons in  $T$  time period is known as the drift velocity. Now, for a given number of electrons per unit volume  $n$ , the quantity of charge travelling through a cross section  $A$  in time  $dt$  may be calculated as follows: As a result, the current flowing will be provided by,



As a result, the current density will be, putting the drift velocity value from equations (iv) in (v), Which is nothing more than Ohm's Law in action, where, Now we establish a new concept called mobility, which is defined as drift velocity per unit electric field.

### **Drude-Lorentz or Classical Theory**

A free electron model is the most basic technique to depict metal electrical structures. Although the free electron version is a gross simplification of reality, it works so well in many circumstances that it can represent many essential features of metals. According to this hypothesis, the two electrons of the crystal's component atoms become conduction electrons and freely flow throughout the crystal. As a result, we ignore the interaction of conduction electrons with lattice ions and the interaction between conduction electrons in our model. In this sense, we are discussing a free electron gas. Yet, there is a fundamental distinction between free electron gas and regular molecular gas.

To begin with, electrons are charged particles. As a result, positive ions are required to preserve the charge neutrality of the whole crystal. This is accomplished using the jelly model, in which the positive charge of ions is dispersed equally throughout the crystal. This positive backdrop preserves charge neutrality while exerting no field on the electrons. Ions combine to produce a homogeneous jelly in which electrons travel. The second key condition of the free electron gas is that it should satisfy the Pauli Exclusion Principle, which has significant implications.

In these quantum states, we must now accommodate  $N$  valence electrons. The Pauli exclusion principle states that no two electrons may have the same quantum number. That is, each electronic quantum state can only have one electron occupying it. The electronic state of a 1D solid is described by two quantum numbers,  $n$  and  $m_s$ , where  $n$  specifies the orbital ( $n_x$ ) and  $m_s$  describes the spin momentum projection on a quantization axis.

Because electron spin equals  $S=1/2$ , there are  $(2S+1)=2$  possible spin states with  $m_s = \pm 1/2$ .

As a result, each orbital identified by the quantum number  $n$  may hold two electrons, one spin up and one spin down.

Let  $n_F$  signify the highest filled energy level, where we start at the bottom ( $n = 1$ ) and fill upper levels with electrons until all  $N$  electrons are accommodated. It is simpler to assume that  $N$  is an even integer. The condition  $2n_F = N$  determines  $n_F$ , the topmost filled level's  $n$  value. A free electron model is the most basic technique to depict metal electrical structures. Although the free electron model is a gross simplification of reality, it works so well in many circumstances that it can represent many essential features of metals.

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### Drude's Theory of Free Electrons

It is predicated on the following fundamental assumptions: A metal is made up of positive ions, and its valence electrons may freely flow between them, as if they were an electron gas. The crystal is kept together by electrostatic forces of attraction between positively and negatively charged ions. The electrons' mutual repulsion is disregarded. Because the potential field produced by positive ions is totally uniform, electrons may migrate from one location in the crystal to another without losing energy.

They clash with the atoms on occasion, and their velocities may be calculated using the Maxwell-Boltzmann distribution equation at any temperature. When an electric field  $E$  is given to a metal, an electron experiences a force  $eE$ , resulting in an acceleration  $a = eE/m$ , where  $e$  and  $m$  are the electronic charge and mass, respectively. The mean free route is the distance travelled between two subsequent collisions.

### Thermal conductivity

A material's thermal conductivity is a measure of its capacity to conduct heat. It is often represented as,  $k$ ,  $\lambda$ , or  $\kappa$ . Heat transmission happens at a slower pace in low thermal conductivity materials than in high thermal conductivity materials.

Metals, for example, have high thermal conductivity and are particularly effective at transferring heat, while insulating materials like Rockwool or Styrofoam are the reverse. Materials with high thermal conductivity are often utilised in heat sink applications, whereas materials with low thermal conductivity are employed as thermal insulation. Thermal resistivity is the counterpart of thermal conductivity.

The defining equation for thermal conductivity is  $q = -k \nabla T$ , where  $q$  is the heat flow,  $k$  is the thermal conductivity, and  $\nabla T$  is the temperature gradient. This is referred to as Fourier's Law of Heat Conduction. The most generic form of heat conductivity, albeit often stated as a scalar, is a second-rank tensor. However, the tensorial description is only required in anisotropic materials.

### Simple definition

Consider a solid substance sandwiched between two distinct temperature settings. Let  $T_1$  be the thermometer at  $x=0$  and  $T_2$  be the temperature at  $x=L$ , and assume  $T_2 > T_1$ . A building on a chilly winter day may be a potential manifestation of this scenario: the solid substance in this instance would be the building wall, isolating the frigid external environment from the warm internal environment.

Heat will move from the hot to the cold surroundings as the temperature difference is equalised via diffusion, according to the second law of thermodynamics. This is characterised by a heat flux  $q$ , which is the rate at which heat travels in a particular direction per unit area (in this case minus  $x$ -direction).  $q$  is shown to be directly related to the temperature difference and inversely proportional to the separation distance  $L$  in various materials:

The thermal conductivity is a physical attribute of the material and is represented by the proportionality constant  $k$ . In the current case, since  $T_2 > T_1$ , heat flows in the minus  $x$ -direction and  $q$  is negative, which indicates that  $k > 0$ . In general,  $k$  is always

specified as a positive number. The same concept of  $k$  may be used to gases and liquids if additional means of energy movement, such as radiation or convection are excluded or accounted.

### General definition

Thermal conduction is defined as the transmission of energy across a temperature differential caused by random molecule motion. It differs from convection and molecular work in that it does not include macroscopic flows or work-performing internal tensions.

Heat flow is defined as energy flow owing to thermal conduction and is quantified by the vector  $(\cdot)$  which yields the heat flux at location  $\mathbf{r}$  and time  $t$ . Heat moves from high to low temperature, according to the second rule of thermodynamics. As a result, it is acceptable to assume that where the constant of proportionality,  $k > 0$ , represents the thermal conductivity. This is referred to as Fourier's law of heat conduction. Despite its name, it is not a rule, but rather a description of thermal conductivity in terms of the independent physical quantities. As a result, its use is dependent on the capacity to calculate  $k$  for a specific material under certain circumstances. The constant  $k$  itself is frequently dependent on  $T(\mathbf{r}, t)$  and hence implicitly on space and time. If the material is inhomogeneous or changes over time, an explicit spatial and temporal dependency may develop.

Thermal conduction in certain substances is anisotropic, which means that the heat flow is not necessarily parallel to the thermal gradient. A tensorial variant of Fourier's law must be employed to account for such behavior: where  $\kappa$  is a symmetric, second-rank tensor known as the heat conductivity tensor. The existence of local equilibria is an automatic assumption in this description, which enables one to construct a temperature field assumption may be broken in systems that are not able to achieve local equilibrium, such as when there is substantial nonequilibrium forcing or long-ranged interactions.

### Other quantities

It is customary in engineering practise to work in terms of values that are derivatives of thermal conductivity or implicitly account for design-specific factors such as component size. Thermal conductance, for example, is defined as the amount of heat that travels in unit time through a plate of a certain area and thickness when the temperatures of its opposing sides diverge by one kelvin. The conductance for a plate with thermal conductivity  $k$ , area  $A$ , and thickness  $L$  is  $kA/L$ , measured in  $\text{WK}^{-1}$ . Thermal conductivity and permeability have a similar connection to electrical conductivity and conductance.

The inverse of thermal conductivity is thermal resistance.

Because thermal resistances are cumulative when they occur in series, it is a suitable parameter to utilise in multicomponent design.

There is also a heat transfer coefficient, which is the amount of heat that transfers per unit time across a unit area of a plate of a certain thickness when its opposing sides vary in temperature by one kelvin.

This area-independent number is referred to as "thermal conductance" in ASTM C168. Thermal insulance is defined as the reciprocal of the heat transfer coefficient. In summary, given a plate with heat conductivity  $k$ , area  $A$ , and thickness  $L$ , in the sense that the material allows heat to pass, the heat transfer coefficient is also known as thermal admittance. Thermal transmittance,

another term, assesses a structure's thermal conductivity as well as heat transmission owing to radiation and conduction.

It has the same units as thermal conductance and is often referred to as composite thermal conductance. The phrase "U-value" is also used. Finally, alpha thermal diffusivity combines thermal conductivity, density, and specific heat: As such, it estimates a material's thermal inertia, or the difficulty of heating a material to a certain temperature using heating elements supplied at the boundary.

### Measurement

There are various methods for measuring thermal conductivity, each of which is confined to a certain set of materials. In general, measuring methods are classified into two types: steady-state and transient. Transient procedures act on the instantaneous state of a system on the approach to steady state, while steady-state techniques infer thermal conductivity from data on the state of a material after a steady-state air temperature has been established. Because there is no clear time component, steady-state approaches do not need complex signal analysis. The downside is that a well-designed experimental apparatus is generally necessary, and the time needed to reach steady state prevents quick measurement. Fluid thermal characteristics seem to be more difficult to investigate experimentally than solid materials. This is due to the fact that, in addition to thermal conduction, evaporative and radiative energy movement are often present unless precautions are made to minimize these processes. The creation of an insulating boundary layer may also cause a visible decrease in heat conductivity.

### Lattice waves

Heat is transported via elastic vibrations of the lattice in both amorphous and crystalline dielectric materials (i.e., phonons). The elastic dispersion of acoustic phonons at lattice faults is thought to restrict this transport mechanism. Chang and Jones' investigations on commercial glassware and glass ceramics corroborated this, with mean free pathways restricted by "internal boundary scattering" to length scales of 10<sup>2</sup> cm to 10<sup>3</sup> cm.

For processes with no directional connection, the phonon mean free path has been directly related to the effective relaxation length. If  $V_g$  is the group velocity of a phonon wave packet, then  $l$  is defined as follows:

where  $\tau$  is the typical relaxing time. Because longitudinal waves have a substantially higher phase velocity than transverse waves  $V_{\text{long}}$  is much larger than  $V_{\text{trans}}$ , thus the relaxation length or mean free path of longitudinal phonons is much longer. Thus, the speed of longitudinal phonons will be a major determinant of thermal conductivity.

In terms of wave velocity dependency on the wavelength or frequency (dispersion), elastic Rayleigh scattering would restrict the relaxation length of low-frequency phonons of long wavelength. This form of light scatter from microscopic particles is equivalent to the frequency's fourth power. The power of the frequency decreases with increasing frequency until, at the highest frequencies, scattering is practically frequency independent. Using Brillouin scattering, similar ideas were later expanded to various glass-forming compounds.

Because phonons there in acoustical branch have more energy dispersion and hence a broader variety of phonon velocities, they dominate phonon heat conduction. Additional optical modes may be created by the existence of internal structure (e.g., charge or mass) at a lattice point; it is

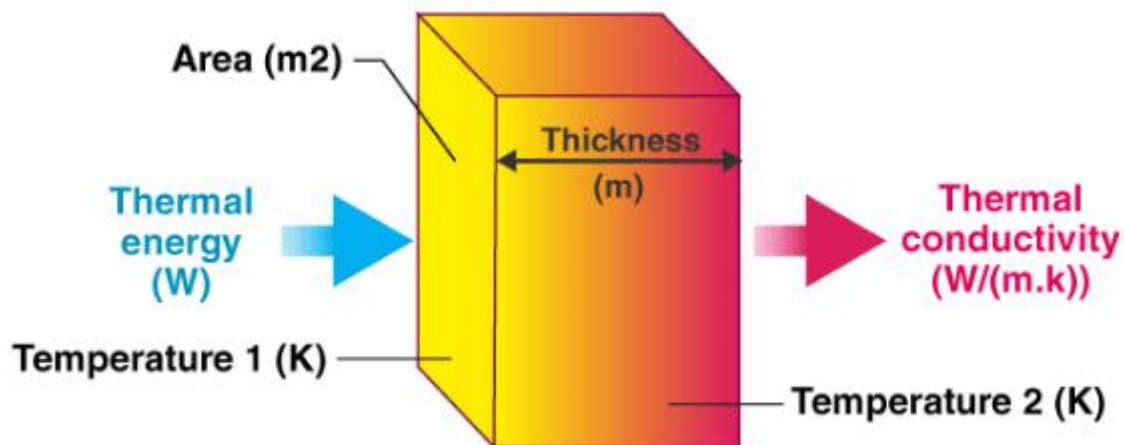
assumed that the group velocity of these modes is low, and therefore its contribution to the lattice thermal conductivity  $L$  ( $\kappa L$ ) is modest.

Each phonon mode has one longitudinal polarisation branch and two transverse polarisation branches. When the phenomenology of lattice points is extrapolated to unit cells, the total number of degrees of freedom is  $3pq$ , where  $p$  is the number of primitive cells of  $q$  atoms/unit cell. Only  $3p$  are connected with acoustic modes, whereas the remaining  $3p(q-1)$  are accommodated through optical branches. This means that structures with higher  $p$  and  $q$  have more optical modes and a lower  $L$ .

Based on these assumptions, it is possible to assume that increasing crystal complexity, as indicated by a complexity factor  $CF$  (measured as the number of atoms/primitive unit cell), reduces  $L$ .

This was accomplished by assuming that the relaxation time decreases with increasing number of atoms in the unit cell and then adjusting the parameters of the formula for high-temperature thermal conductivity correspondingly.

It is more difficult to describe anharmonic effects since an accurate approach, as in the harmonic case, is not feasible, and phonons are no longer perfect Eigen solutions to the equation of motion. Even if the crystal's state of motion could be characterized with a plane wave at a certain instant, its accuracy would diminish with time. The introduction of a spectrum of additional phonons, known as the phonon decay, would have to be used to depict time development. Thermal expansion and phonon thermal conductivity are the two most prominent anharmonic effects.



The rate at which heat is transported through a material is proportional to the negative of the temperature gradient and also proportional to the area through which the heat flows, according to Fourier's law of thermal conduction (also known as the law of heat conduction). This law's differential version is stated by the following equation:

$$q = -k \cdot \nabla T$$

$T$  signifies the temperature gradient,  $q$  the thermal flux or heat flow, and  $k$  the thermal conductivity of the material under issue.

Thermal conductivity (commonly represented by  $k$ , or  $\kappa$ ) refers to a material's inherent capacity to transport or conduct heat. It is one of three heat transmission techniques, the other 2 being wind

and radiation. Heat transport processes may be quantified using suitable rate equations. This heat transfer mode's rate equation is based on Fourier's law of heat conduction. It is also described as the amount of heat that can be carried per unit time per unit area through a plate of given thickness of a certain material, with the faces of the plate varied by one unit of temperature.

Thermal conductivity is caused through molecule agitation and contact, rather than by bulk movement of the material itself. Heat flows along a temperature gradient, from a high temperature and high molecular energy region to a lower temperature and lower higher vibrational region. This process will be repeated until thermal equilibrium is established. The pace at which heat is transmitted is determined by the size of the temperature difference as well as the material's unique thermal properties.

A material's thermal conductivity is highly reliant on a variety of variables. These include the thermal gradient, material characteristics, and the length of the heat channel. The thermal conductivity of the components around us varies greatly, from those with low conductivities like air ( $0.024 \text{ W/m}\cdot\text{K}$  at  $0^\circ\text{C}$ ) to those with high conductivities like copper ( $385 \text{ W/m}\cdot\text{K}$ ).

Materials with low thermal conductivities are excellent at insulating our homes and businesses, whereas those with high thermal conductivities are ideal for applications where heat needs to be gone quickly and efficiently from one area to another, such as cooking utensils and cooling systems in electronic devices. We can obtain the optimal performance by choosing materials with the right heat conductivity for the application.

Because molecular mobility is the foundation of thermal conductance, a material's temperature has a substantial impact on its thermal conductivity. Because molecules travel faster at higher temperatures, heat is transported through the materials at a faster pace. This implies that the heat capacity of the same sample might alter dramatically when the temperature rises or falls. Understanding how temperature affects thermal conduction is crucial for ensuring that items respond as predicted when exposed to thermal stress. This is particularly critical when creating fire and heat protection materials and dealing with devices that create heat, such as electronics.

Thermal conductivity levels vary greatly amongst materials and are heavily influenced by the architecture of each individual substance. These are anisotropic materials, which have varying thermo conductivity values depending on the direction of heat transport. Because of the way the structure is constructed in certain circumstances, heat travels more readily in one direction. Materials may be separated into three groups when studying thermal conductivity trends: gases, nonmetallic solids, and metallic solids. The discrepancies in heat transmission capacity of these three groups may be linked to variances in their structures and molecule motions. Because the molecules in gases are not as closely packed as those in solids, their relative thermal conductivities are lower, and heat transmission is heavily reliant on the free molecular diffusion and molecular velocity.

Gases are ineffective thermal transmitters. In contrast, since the molecules in nonmetallic solids are bonded into a lattice network, heat conductivity is predominantly caused by vibrations in all of these lattices. Because of the near closeness of these molecules to those of gases, nonmetallic solids have the greater thermal conductivities of something like the two, although there is a wide range within this category. This variance is due in part to the quantity of air present inside the solid; materials with a large multitude of small pockets are good insulators, while those with a smaller number of air pockets have a greater thermal conductivity rating.



Thermal conductivity in metallic solids varies from the preceding instances even again. Metals, with the exception of graphene, have the greatest thermal conductivities of any substance and the unique combination of good electrical conductivity. The Wiedemann-Franz Law explains the link between these two qualities, which are communicated via the same molecules. This equation states that at a certain temperature, electrical conductivity is proportional to thermal conductivity; however, when temperature rises, the thermophysical properties of the material increases while electrical conductivity decreases.

Thermal conductivity is an important component of the material-material connection, and understanding it allows us to get the best performance out of the materials we use in many parts of our life. Thermal conductivity testing and measurement are essential components of this attempt. Thermal conductivity testing techniques are divided into two types: steady state and transient. This distinction is a distinguishing feature of how each approach operates. Steady state techniques need that the reference and sample parts be in thermal equilibrium prior to initiating measurements. Transient approaches do not need this rule to be followed and hence provide results faster.

### **Band theory**

In solid-state physics, band theory is a theoretical model that describes the states of electrons in solid materials that can only have energy values within specified particular ranges. The behaviour of an electron (and hence its energy) in a solid is connected to the behaviour of most other particles surrounding it. This is in sharp contrast to an electron's behaviour in free space, where it might have any given energy. Allowable bands are the ranges of electron energy that can exist in a material. Certain energy ranges between two such permissible bands are referred to be prohibited bands; that is, electrons inside the material may not possess such energies. The band theory accounts for a number of electrical and thermal characteristics of solids and is the foundation of solid-state electronics technology.

The discrete permissible energies—the energy levels—of single, isolated atoms are connected to the band of energies permitted in a solid. When atoms are brought together to create a solid, quantum mechanical forces cause these discrete energy levels to be disrupted, and the many electrons in the collection of individual atoms occupy a spread of levels with in solid known as the valence band. Empty states in each individual atom also widen into a band of generally empty levels known as the conduction band. Just as electrons at one energy level in an individual atom may move to another empty energy level, electrons in a solid can transfer from one higher energy in a given band to another in the same band or another band, often crossing a prohibited energy gap in the process. Studies of such energy shifts in solids interacting with photons of light, energetic electrons, X-rays, and other similar particles corroborate the band theory's general validity and offer precise information regarding permissible and prohibited energies.

Pure elements, alloys, and composites all have different ranges of acceptable and banned bands. Metals, insulators, and semiconductors are the three main types of materials. Forbidden bands do not exist in metals in the energy range of the most energetic (outermost) protons. As a result, metals are excellent electrical conductors. Insulators contain large prohibited energy gaps that can only be bridged by an electron with several electron volts of energy. Insulators are poor conductors because electrons cannot travel freely in the applied field voltage. Semiconductors, like intermediate conductors, have very small prohibited gaps that may be bridged by an electron with an energy of around one electron volt.

## Semiconductor materials

Solid-state materials are usually classified as insulators, semiconductors, and conductors. (Some conductors, semiconductors, even insulators may become superconductors at low temperatures.) The picture depicts the conductivities (and related resistivities =  $1/\rho$ ) associated with several key materials in each of the three classes. Insulators, such as silicon dioxide ( $\text{SiO}_2$ ) and glass, have very low conductivities, on the order of  $10^{18}$  to  $10^{10}$  siemens per centimetre, while conductors, such as aluminium, have extremely high conductivities, generally  $10^4$  to  $10^6$  siemens per centimetre. Semiconductor conductivities fall between these two extremes and are often affected by temperature, light, magnetic fields, and trace quantities of impurity atoms. For example, adding around 10 atoms of boron (a dopant) per million atoms of silicon will enhance its electrical conductivity 1,000-fold

The investigation of semiconductor materials started in the early nineteenth century. Elements such like silicon (Si), germanium (Ge), and tin (Sn) in column IV and selenium (Se) and tellurium (Te) in column VI of the periodic table are examples of elemental semiconductors. However, there exist various compound semiconductors, which are made up of two or more elements. Gallium arsenide (GaAs) is a binary III-V chemical composed of gallium (Ga) from column III and arsenic (As) from column V. Ternary compounds, such as mercury indium telluride ( $\text{HgIn}_2\text{Te}_4$ ), may be created by components from three distinct columns. They may also be created by elements from two columns, for as aluminium gallium arsenide ( $\text{Al}_x\text{Ga}_{1-x}\text{As}$ ), a ternary III-V compound in which both Al and Ga are from column III and the subscript  $x$  is connected to the composition of the two elements, ranging from 100% Al ( $x = 1$ ) to 100% Ga ( $x = 0$ ). For integrated circuit applications, pure silicon is the most essential material, while III-V binary and ternary compounds are the most crucial for light emission.

Prior to the 1947 creation of the bipolar transistor, semiconductors were exclusively utilised in two-terminal devices like rectifiers and photodiodes. In the early 1950s, germanium was the most important semiconductor material. However, it proved inappropriate for many applications due to significant leakage currents in devices fabricated of the material at just mildly increased temperatures. Since the early 1960s, silicon has been by far the most frequently used semiconductor, supplanting germanium as a device manufacturing material. There are two basic causes behind this: (1) Silicon devices have substantially lower leakage currents, and (2) silicon dioxide ( $\text{SiO}_2$ ), a high-quality insulator, is simple to include into a silicon-based device. As a result, silicon technology has grown very sophisticated and omnipresent, with silicon devices accounting for more than 95 percent of all semiconductor goods marketed globally.

## Electronic properties

The semiconductor materials discussed here are single crystals, which means that the atoms are organised in a multi periodic pattern. Part A of the diagram depicts a simplified two-dimensional depiction of an intrinsic (pure) silicon crystal with minor impurities. In the crystal, each silicon atom is surrounded by four of its closest neighbours. Each atom contains four electrons in its outer orbit, which it shares with its four neighbours. A covalent bond is formed by each shared electron pair. The atoms are held together by the attraction that exists between the electrons and both nuclei. Electrons in solitary atoms (e.g., in a gas rather than a solid) can only have discrete energy levels. When a huge number of atoms come together to create a crystal, the atoms' interactions lead the discrete energy levels to spread out from energy bands. When there is no thermal vibration (i.e., when the temperature is low), the electrons in an insulator or

semiconductor crystals entirely occupy a number of energy bands, leaving the other energy bands unoccupied. The valence band is the highest filled band. The conduction band follows, separated from the valence band by an energy gap (much larger gaps in crystalline insulators than in semiconductors). This energy gap, also known as a bandgap, denotes energies that the electrons in the crystal cannot have. The majority of significant semiconductors have bandgaps ranging from 0.25 to 2.5 electron volts (eV). Silicon, for example, has a bandgap of 1.12 eV, whereas gallium arsenide has a bandgap of 1.42 eV. Diamond, an excellent crystalline insulator, with a bandgap of 5.5 eV.

At low temperatures, electrons in a semiconductor are confined in their respective crystal bands and hence unavailable for electrical conduction. Thermal vibration may dissolve certain covalent bonds at higher temperatures, releasing free electrons that may participate in feed forward control. There is an electron vacancy associated with a covalent link when one electron travels away from it. This vacancy may be filled by either a neighbouring electron, causing the vacancy position to change from one crystal site to another. This vacancy may be thought of as a hypothetical particle called a "hole," which has a positive charge and goes in the opposite direction as an electron. When an electric field is applied to a semiconductor, both free electrons (now in the conduction band) and holes (left in the valence band) travel through the crystal, resulting in an electric current. A material's electrical conductivity is determined by the amount of free electrons and holes (charge carriers) per unit volume as well as the pace at which these carriers travel when subjected to an electric field. There are an equal amount of free electrons and holes in an intrinsic semiconductor. Electrons and holes, on the other hand, have distinct mobilities; that is, they travel at different speeds in an electric field. For intrinsic silicon at normal temperature, for example, the electron mobility is 1,500 square centimetres per volt-second ( $\text{cm}^2/\text{Vs}$ )—that is, an electron will travel at a velocity of 1,500 centimetres per second under a one volt per centimetre electric field—while the hole mobility is 500  $\text{cm}^2/\text{Vs}$ . The electron and hole mobilities in a certain semiconductor often decrease as temperature rises.

At room temperature, electrical conduction in intrinsic semiconductors is relatively weak. Impurities may be purposely introduced to increase conduction (typically to a concentration of one part per million host atoms). Doping is a method that boosts conductivity while causing some mobility loss. For example, if a silicon atom is substituted with an element with five outside electrons, such as arsenic four of the electrons establish covalent connections with the four silicon atoms that are next to it. The fifth electron is converted into a conduction electron and contributed to the conduction band. Because of the incorporation of the electron, silicon would become an n-type semiconductor. The donor is the arsenic atom. Part C of the diagram also indicates that when an element with three outer electrons, including boron, is replaced for a silicon atom, an extra electron is taken to form four covalent bonds surrounding the carbon atom, and a positively charged hole is produced in the valence band. This results in a p-type semiconductors, with the boron acting as an acceptor.

### **The p-n junction**

A p-n junction is generated when a sudden shift in impurity type happens inside a single crystal structure, from acceptors (p-type) to donors (n-type) (see parts B and C of the figure). On the p side, the holes are the main carriers and hence the majority carriers. Minority carriers are electrons that are created thermally and reside in the p side. The electrons are the majority carriers on the n side, whereas the holes are the minority carriers. A location near the intersection has no free charge carriers. This layer, known as the depletion layer, acts as an insulator.

The fact that p-n junctions correct is their most essential property. When a forward bias (i.e., a positive voltage applied to the p-side with respect to the n-side, as indicated in section B of the figure) is applied to the p-n junction, the majority of charge carriers migrate across the junction, allowing a substantial current to flow. When a reverse bias is provided, the charge carriers created by the impurities migrate in opposing directions away from the junction, resulting in just a little leakage current flowing. The leakage current stays relatively tiny when the reverse bias is raised until a critical voltage is reached, at which time the current rapidly surges. This abrupt surge in current is known as junction breakdown, and it is normally a nondestructive process provided the ensuing power dissipation is kept to a safe level. The forward voltage applied is normally less than one volt, but the reverse critical value, known as the breakdown voltage, may range from less than one volt to several thousands of volts, depending on the impurity concentration of the junction and other device factors. Despite the invention of alternative junction types (including p-n-p and n-p-n), p-n junctions remain crucial to semiconductor devices.

### **P-n junction**

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## CHAPTER 7

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### Ferroelectricity

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Ferroelectricity is a property of certain nonconducting crystals or dielectrics that exhibit spontaneous electric polarisation (the separation of the centre located of positive and negative electric charge, resulting in one side of the crystal being positive and the opposite side being negative) that can be reversed in direction by applying an appropriate electric field. Ferroelectricity is called after ferromagnetism, which occurs in materials such as iron. Because iron atoms are small magnets, they naturally align oneself in clusters known as ferromagnetic domains, which may then be orientated preferentially in a certain direction by applying an external magnetic field.

Ferroelectric minerals, such as inorganic materials ( $\text{BaTiO}_3$ ) and Rochelle salt, are made up of crystals with small electric dipoles as structural units; that is, the centres of positive and negative charge are slightly separated in each unit. These electric dipoles naturally line up in clusters termed domains in certain crystals, and domains in ferroelectric crystals may be directed mainly in one direction by a strong external electric field. The predominant orientation of the ferroelectric domains is reversed when the external electric field is reversed, however the changeover to a new direction lags considerably beyond the shift in the external electric field. Ferroelectric hysteresis, named after ferromagnetic hysteresis, is the lag of electric polarisation after the applied electric field. Because heat agitates the dipoles enough to overpower the forces that spontaneously align them, ferroelectricity stops in a particular material at a certain temperature known as its Curie temperature.

#### Electric Displacement

Auxiliary electric field or electric vector that describes the aspect of an electric field that is purely connected with the existence of separated free electric charges, with the contribution of any electrostatic attraction bound together in neutral atoms or molecules purposefully excluded. When an electric charge is transferred between two parallel metal plates that were previously uncharged, one becomes positively charged and the other attracted to the negative by the equal amount, and an electric field develops between the plates. When a slab of insulating material is inserted between the charged plates, the bound electric charges that comprise the insulation's internal structure are slightly displaced, or polarised; bound charge (atomic electrons) shift a fraction of an atomic diameter toward the plate, and bound positive charges shift very slightly toward the negative. This charge shift, or polarisation, diminishes the value of the electric field that existed before to the insertion of the insulator. The electric field's real average value As a result,  $E$  has a component  $P$  that is determined by the bound polarisation charges and a portion  $D$ , electric displacement, that is determined by the free separated electrons on the plates. In the

metre-kilogram-second (mks) or SI system, the connection between the three vectors  $D$ ,  $E$ , and  $P$  is:  $D = \epsilon_0 E + P$  ( $\epsilon_0$  is a constant, the permittivity of a vacuum). The connection in the centimetre-gram-second (cgs) system is:  $D = E + 4\pi P$ .

The electric displacement value  $D$  may be thought of as the quantity of free charge on one plate divided by the plate's area. Because of the strong link between electric flux and electromotive force,  $D$  is commonly referred to as the electric flux density or free charge surface density. In the metre-kilogram-second system, the dimensions of electric displacement, or electric flux density, are charge per unit area, with units of coulombs per square metre. The dimensions of  $D$  in the centimetre-gram-second system are the same as those of the main electric field  $E$ , the units of which are dynes per electrostatic unit or statvolts per centimeter.

### Dielectric Constant

The dielectric constant is a property of an electric insulating material (a dielectric) equal to the ratio of the capacitance of a circuit filled with the supplied material to the capacitance of an identical circuit in a vacuum without the dielectric material. Inserting a dielectric between the plates of a parallel-plate capacitor, for example, always improves its capacitance, or capacity to store opposing charges on each plate, as compared to when the plate are separated by a vacuum. If  $C$  is the capacitance of a capacitor filled with a specific dielectric and  $C_0$  is the capacitance of an identical battery in a vacuum, the dielectric constant, denoted by the Greek letter kappa, may be represented simply as  $\kappa = C/C_0$ . The dielectric constant is a dimensionless quantity. The dielectric constant and permittivity are the same in the centimetre-gram-second system. It refers to a large-scale dielectric characteristic without describing the electrical properties on the atomic scale.

Any material's static dielectric constant is always larger than one, the value for a vacuum. When the electric field is applied perpendicularly to the major axis of the crystal, the dielectric properties at room temperature (25 °C, or 77 °F) is 1.00059 for air, 2.25 for paraffin, 78.2 for water, and about 2,000 for barium titanate ( $\text{BaTiO}_3$ ). Because the dielectric constant of air is almost the same as that of a vacuum, air does not enhance the capacitance of a capacitor in any practical sense. The dielectric constants of liquids and solids may be calculated by comparing the capacitance while the dielectric is present to the capacitance when the capacitor is filled with air.

### Electrostriction

Electrostriction is a feature of all electrical nonconductors, or dielectrics that presents itself as a very little change in shape, or mechanical deformation, when an electric field is applied. The direction of the deformation is not reversed when the electric field is reversed.

The inverse piezoelectric effect occurs exclusively in a certain type of nonconducting crystals and is distinguished by a substantially larger deformation for a given magnitude of the electric field as well as a reversal with in direction of deformation when the emf is reversed. According to the band theory of solids, electrons may move from the valence band to the conduction band even at room temperature, and if this occurs, the solid conducts electricity. The distance between the valence and conduction bands determines conductivity. The material will function as an insulator if the gap or energy difference between both the valence and conduction bands is greater than or equal to 5eV.

The material or solid is considered a semiconductor if the energy difference between the valence and the conduction bands band is equal to or less than 3eV. When the valence band the



conduction band overlap, the solid is referred to be a conductor. The logic is that electrons may move from the valence band to the conduction band and therefore carry electricity. If the gap between the valence band and the conduction band is too large (more than or equal to 5eV), electrons cannot jump from the valence to the conduction band, and hence these materials or solids cannot conduct electricity. If the valence band and conduction band are not overlapping or too far apart, a few electrons may jump from the valence to the conduction band, then the material is referred to be a semiconductor.

### **Electronic band structure**

The electronic band structure (or merely band structure) of a material in solid-state physics explains the range of energy levels that electrons may have inside it, as well as the ranges of energy that they might not have (called band gaps or forbidden bands).

These bands and band gaps are derived from band theory by evaluating the permissible quantum mechanical expansion method for an electron in a vast, periodic lattice of atoms or molecules. Band theory has been utilised effectively to describe numerous physical features of solids, including as electrical resistivity and optical absorption, and it is the cornerstone of all solid-state device knowledge (transistors, solar cells, etc).

A single, solitary atom's electrons inhabit atomic orbitals, each with a distinct energy level. When two or more atoms create a molecule, their number of atoms overlap and hybridise. Similarly, when a high number  $N$  of similar atoms gather together to create a solid, such as crystal lattice, the atomic orbitals of the atoms overlap with the orbitals of the neighbouring atoms. Each discrete energy level is subdivided into  $N$  levels, each with its own energy. Because the number of atoms in such a macroscopic piece of solid ( $N \approx 10^{22}$ ) is quite huge, the number of orbitals is also very big, and they are relatively tightly spaced in energy (on the order of 1022 eV). The energy of the neighboring levels is so near that they may be thought of as a continuum, an energy band.

This band development is primarily a property of the atom's outermost electrons (valence electrons), which are important in chemical bonding and electrical conductivity. Because the inner electron orbitals do not overlap much, their bands are relatively thin. Due to the limiting widths of the energy bands, band gaps are basically residual regions of energy that are not covered by any band. The widths of the bands vary depending on the degree of overlap as in atomic orbitals from which they emerge. Two neighboring bands simply simply not be broad enough to encompass the whole energy spectrum. Because of the tiny overlap between nearby atoms, the bands associated with core orbitals (such as 1s electrons) are exceedingly narrow. As a consequence, there are often significant band gaps between the main bands. Higher bands have bigger orbitals with greater overlap, which get increasingly broader as energy increases, such that there are no band gaps at higher energies.

### **Assumptions and Limits Of Band Structure Theory**

Band theory is simply an approximation to a solid's quantum state, and it only applies to solids made up of many similar atoms or molecules bound together. The following assumptions are required for band theorist to be valid:

**Infinite-size system:** In order for the bands to be continuous, the material must be made up of a vast number of atoms. This is not a major limitation since a macroscopic piece of material includes on the order of  $10^{22}$  atoms; band theory even applies to microscopic-sized gates in

integrated circuits. The idea of band structure may be extended to systems that are only "big" in certain dimensions, such as two-dimensional electron systems, with some adjustments.

**System homogeneous:** The band structure of a material is an inherent feature that presupposes the substance is homogenous. In practise, this implies that the chemical composition of the material must remain consistent throughout the work.

The band structure defines "single electron states," which are non-interactive. These states arise if electrons move in a static potential without actively interacting with inelastic scattering, other electrons, photons, and so on. The aforementioned assumptions are violated in a number of critical practical circumstances, therefore using band structure necessitates keeping a careful eye on band theory's limitations:

### **In homogeneities and interfaces:**

The bulk band structure is disturbed at surfaces, junctions, and other inhomogeneities. Local small-scale disturbances (e.g., surface states or dopant states within the band gap) coexist with local charge imbalances. These charge imbalances cause electrostatic effects in semiconductors, insulators, and the vacuum (see doping, band bending). Similarly, most electronic phenomena (capacitance, electrical conductance, electric-field screening) are related to the physics of electrons moving through surfaces and/or near interfaces. A basic model of electron-electron interactions is required for a complete explanation of these effects in a band structure image (see space charge, band bending).

Small-scale systems: There is no continuous band structure for systems that are tiny in every dimension (e.g., a small molecule or a quantum dot). Mesoscopic physics is concerned with the transition between tiny and large dimensions.

Strongly correlated materials (such as Mott insulators) simply cannot be explained in terms of single-electron states. These materials' electronic band structures are poorly characterised (or, at the very least, not uniquely defined) and may not give valuable information on their physical state.

### **Density-functional theory**

A large majority of electronic structures and band plots in recent physics literature are calculated using density-functional theory (DFT), which is not a model but rather a theory, i.e., a microscopic first-principles theory of condensed matter physics that attempts to deal with the electron-electron many-body problem by introducing an exchange-correlation term in the functional of the electronic density. Many times, DFT-calculated bands agree with experimentally observed bands, such as angle-resolved photoemission spectroscopy (ARPES). The band form, in particular, is often adequately recreated by DFT. However, when compared to experiment findings, there are systematic mistakes in DFT bands. DFT, in particular, seems to routinely underestimate the band gap in insulators and semiconductors by 30-40%.

It is often assumed that DFT is merely a theory for predicting ground state attributes of a system (e.g., total energy, atomic structure, etc.), and that DFT cannot predict excited state features. This is a misunderstanding. In theory, DFT may identify any attribute of a system (ground state or excited state) given a functional that maps the ground state density to that characteristic. The Hohenberg-Kohn theorem boils down to this. However, no defined set exists in practise that connects the ground state density to electron excitation frequencies inside a material. Thus, what is referred to as a DFT band plot in the literature is a depiction of the DFT Kohn-Sham energies,

i.e., the energies of a fictive non-interacting system, the Kohn-Sham system, with no physical meaning. The Kohn-Sham electronic structure should not be mistaken with a system's true, quasiparticle electronic structure, and there is no Koopmans' theorem for Kohn-Sham energies, as there is for Hartree-Fock energies, which may legitimately be regarded an approximation for quasiparticle energies. As a result, in principle, Kohn-Sham-based DFT is not a music theory, that is, it is not suited for computing bands and band-plots. In theory, time-dependent DFT may be used to compute the real band structure, but in practice, this is often challenging. The use of hybrid functional, which integrate a component of Hartree-Fock exact exchange, is a common strategy that yields a significant increase in projected bandgaps of semiconductors but is less dependable for metals other wide-bandgap materials.

### **X-ray diffraction**

X-ray diffraction is a phenomenon in which the atoms of a crystal generate an interference pattern of the waves in an incoming X-ray beam due to their regular spacing. The atomic planes of the crystal operate on the X-rays in the same way that an evenly governed diffraction grating acts on a light beam. An X-ray beam strikes a crystal at an angle of incidence. It is reflected at the same angle off the crystal's atoms. The X-rays reflected off atomic planes separated by  $d$  in the crystal. To generate an interference pattern, the X-rays reflecting off two separate planes must interact constructively; otherwise, the X-rays will interfere destructively and no pattern will be formed. To interact constructively, the path length difference between two atomic planes must equal the full number ( $n$ ) of wavelengths ( $\lambda$ ), or  $n\lambda$ . This results in the Bragg law  $n\lambda = 2d \sin \theta$ . The interior structure of the crystal may be inferred by studying the interference pattern.

### **Band Theory of Insulators**

Insulators have a very large band gap energy or forbidden energy gap between the conduction and valence bands. This is the basis why such compounds have no conductivity. In the case of an insulating material, there is a large prohibited gap between the valence band and the conduction band. It is almost hard for an electron to go from the valence band to the conduction band. Be a consequence, such materials cannot conduct electricity and are referred to as insulators. In insulators, the forbidden energy gap between conduction and valence bands is large enough, roughly 7 eV. Diamond is an insulator with a forbidden energy gap of around 6 eV. These particular materials may only conduct at very high temperatures or when subjected to high voltage.

This form of conduction is uncommon and is referred to as "insulation breakdown" or "insulator breakdown." Wood, glass, paper, mica, and other insulating materials are available. The Forbidden Band is the band that separates the two bands (V & C) (F). Insulators because insulators lack free charge carriers, they are non-conductive in nature.

### **Atomic bonding**

Atomic bonds are entirely reliant on the sharing of electron pairs in nonmetals. Because those elements that behave like nonmetals want to capture electrons, there are no free electrons to perform the task as charge carriers.

### **Ionic bonding**

Ions in a solid state are organized into a grid structure. The particles are held together with the assistance of electrical forces. There are no free charge carriers present, allowing current to flow. As a result, ionic compounds may be both insulators and conductors.

No electrons are stimulated from V.B to unoccupied C.B due to the huge gap. The remaining valence band is totally filled. The majority of solid substances are insulators, which indicates that there is a large forbidden energy gap between the energies of valence electrons.

Assume that glass is an insulating substance that is transparent to light and visible for roughly comparable reasons, in addition to its own kind as an electrical insulator. The visible light photons do not have enough quantum energy to fill the band gap or energy gap and get the electrons to a suitable energy level in the conduction band. The visual qualities of glass may even provide some insight into the impact of doping on the properties of solids. A tiny number of impure atoms or impurity atoms present in glass may give colour by allowing various energy levels to absorb distinct visible light hues.

### **Steno's law**

Steno's law states that the angles between two matching faces on the crystals of each solid chemical or mineral species are constant and distinctive of the species; this angle is measured between perpendicular lines drawn to each face. The law, also known as the law of interfacial angle constancy, applies to any two crystals, regardless of size, location of occurrence, or whether they are natural or man-made.

The Danish geologist Nicolaus Steno established the connection in 1669, noting that, although quartz crystals varied in form, the angles between matching sides are always the same. Steno's results were corroborated in 1772 by a French mineralogist, René L. Romé de l'Isle, who also noticed that the angles are distinctive to the composition. René-Just Haüy, the pioneer of crystallography, demonstrated in 1774 that the known interfacial angles could be accounted for if the crystal were built up of minute building blocks that correspond to today's unit cells.

### **Max von Laue**

Max von Laue, full name Max Theodor Felix von Laue, was born on October 9, 1879 in Pfaffendorf, near Koblenz, Germany, and died on April 23, 1960 in Berlin, West Germany. He was awarded the Nobel Prize in Physics in 1914 for his discovery of X-ray diffraction in crystals. This allowed scientists to analyse crystal structure and so heralded the beginning of sturdy physics, a crucial topic in the creation of contemporary electronics.

In 1912, Laue was appointed professor of physics at the University of Zürich. Laue was the first to propose using a crystal as a grating for X-ray diffraction, demonstrating that if an X-ray beam travelled through a crystal, diffraction would occur and a pattern would emerge on a photographic plate positioned at a right angle to the path of the rays. The pattern would represent the atoms' symmetrical groupings in the crystal. This was empirically confirmed in 1912 by two of Laue's pupils working under his supervision. This result revealed that X-rays are electromagnetic radiations comparable to light and offered experimental confirmation that crystal atomic structure is a regularly recurring configuration.

Band theory is a technique for separating two types of bands, specifically Valence bands and Charge transfer, by calculating the energy gap in electrons of a certain material. Based on its qualities, every solid may be classed as a conductor, semiconductor, or insulator. In contrast to the discrete energy of unbound atoms, the energy source in a hard molecule is the quasi-visible bands. In conductors, such as metals, the valence band overlap the conduction bands, but in semiconductors, such as silicon, there is a slight gap between the two types of bands. Extreme conductors, on the other hand, are insulators that do not carry heat or electricity and retain a huge

gap between electrons in conduction and valence bands. Because of the unusual placement of the conduction and valence bands, certain things may transfer heat and transport electricity.

### **Band Theory's Characteristics**

Solids are massive molecules made up of numerous atoms in a close-knit structure.

When the valence shells of each atom make contact in a solid, atomic orbitals combine to produce molecular orbitals.

These outer shells serve as the sole electron system for both atoms. The pattern is followed by every other atom in the crystal.

### **Forming of bands**

Valence shells are an atom's outermost shells, which are a collection of orbitals that bind with another atom. Valence electrons are electrons that exist in these shells. Lower energy orbitals fill up before higher energy orbitals, according to the Aufbau principle. As a result, vacant orbitals move up the energy levels.

Overlapping bands are two separate energy states in which electrons may travel apart from one another if no external energy is given. Higher energy bands may be found above lesser energy bands.

In silicon, for example, the valence 3S band corresponds with an empty 3P band.

Non-overlapping bands are energy states that are ordered in a hierarchy, with the other band being either above or below one specific energy band. It makes no difference how many valence electrons there are.

For example, the valence 3S band does not overlap with the 3P band containing no electrons.

Valence band: Valence electron bands have lower energy and are referred to as valence bands. It may be partly or completely populated by electrons.

Eg.

Fe, Cu are partially packed with electrons.

Mg is completely charged with electrons.

Conduction band: The conduction band is the band right above the valence band. It may be partly or completely depleted of electrons. If it contains electrons, they are referred to as free electrons.

The forbidden gap is the gap between the conduction band and the valence band because no electrons can exist between these two bands. The Fermi level in semiconductors is located in the forbidden gap, at an equal distance from the two types of bands.

Fermi energy:  $f$  denotes the chance of detecting electrons at a particular energy level and temperature as introduced by the Fermi-Dirac distribution function ( $E$ ). Because  $f(E) = 1$ , no electron can move from the valence band to the conduction band at absolute zero. The Pauli exclusion principle in quantum physics states that any permissible energy status can only hold two electrons with opposing spins. At low temperatures, this energy level is referred to as the Fermi level. Some electrons may travel above this barrier as temperature increases, and high temperature causes additional electrons to shift, resulting in an electrical flow.

## Solids of various types

Insulators are substances in which electrons cannot pass from the valence band to the conduction band due to a huge forbidden gap between them. These objects are employed as heat-resistant additions, such as kettle handles, or as shockproof goods to guard against electrical shock. Examples include wood, glass, and plastic. When the prohibited gap is less than 5 eV, the item may be utilised for the purposes listed above.

As the forbidden gap approaches 0, electrons in the conductor may readily jump from the valence band to the conduction band. Metals are often used as examples of such elements.

Semiconductors contain a prohibited gap of 3 that causes electrons to leave the valence band and enter the conduction band.

Intrinsic semiconductors: Silicon, Germanium, and other pure intrinsic semiconductors with four valence electrons. The current is created by the simultaneous migration of electrons from the conduction band to the valence band in the opposite direction.

Extrinsic semiconductor: When intrinsic semiconductors are doped with small impurities, they become extrinsic. The conductivity may be increased up to 10000 times. This may be further classified into two types based on the microscopic addition of the replacement ingredient.

N-type conductor: N-type semiconductors include a pentavalent impure element, such as phosphorus, which generates an additional electron that commences the energy flow. Four covalent connections are formed by the phosphorus atom.

When a trivalent impurity, such as Boron, is injected into an intrinsic semiconductor, it forms three covalent bonds and one positive hole that circulates energy.

Organic semiconductors: Conjugated organic polymers with high conductivity. Their inherent semiconductivity maintains a gap of 1-2eV. Polyphenyl and polyacetylene are two examples. These also create n-type and p-type semiconductors when doped with oxidizing chemicals.

## Spectroscopy

Spectroscopy is the study of the electromagnetic spectra that occur from the interaction of electromagnetic radiation with matter as a function of the wavelength or frequency of the energy.

Matter waves and acoustic waves are other kinds of radiative energy, and gravitational waves have recently been connected with a spectral signature as part of the Laser Interferometer Gravitational-Wave Observatory (LIGO)

In layman's words, spectroscopy is the exact study of colour as it applies to all bands of the electromagnetic spectrum, beginning with visible light. Historically, spectroscopy began as a study of the wavelength dependence of visible light absorption by gas phase materials dispersed by a prism. Spectroscopy, particularly in the electromagnetic spectrum, is a fundamental exploratory tool in astronomy, chemistry, materials science, and physics, allowing the composition, structural characteristics, and electronic structure of matter to be studied at the atomic, molecular, and macro scales, as well as over astronomical distances. Biomedical spectroscopy has important uses in tissue analysis and diagnostic imaging.

Spectroscopy is a field of science that studies the spectra that electromagnetic rayon as a function of wavelength or frequency using spectrographic equipment and other methods to learn about the structure and characteristics of materials. Spectral measuring instruments are known as



spectrometers, spectrophotometers, spectrographs, and spectral analyzers. Most spectroscopic analysis in the laboratory begins with a sample to be analysed, followed by the selection of a light source from any desired range of the light spectrum, and finally the light passes through the data set to a dispersion array (diffraction grating instrument) and is captured by a photodiode. The light dispersion device must be installed on the telescope for astronomical applications. There are other variations on this basic arrangement that may be used.

The science of spectroscopy originated with Isaac Newton dividing light with a prism and then was known as optics.

As a result, it was initially the study of visible light, which we call colour, that eventually expanded to embrace the full electromagnetic spectrum thanks to the research of James Clerk Maxwell. [ Although colour is used in spectroscopy, it is not synonymous with the colour of elements or things, which involves the absorption and reflection of particular electromagnetic waves to provide objects with a feeling of colour to human eyes. Rather, spectroscopy includes the splitting of light by a prism, diffraction pattern, or similar equipment to produce a specific discrete line pattern known as a "spectrum" that is unique to each kind of element. Most elements are initially placed into a gaseous phase to investigate their spectra, while various techniques may now be employed on other phases. Depending on whether the element is being cooled or heated, each element diffracted by a prism-like apparatus exhibits either an absorption spectrum or an emission spectrum.

Until recently, all spectroscopy entailed the investigation of line spectra, and the majority of spectroscopy still does.

Vibrational spectroscopy is the study of spectra in the field of spectroscopy. However, recent advances in spectroscopy allow for the dispersion approach to be avoided in certain cases. Absorption and light scattering methods are used in biochemical spectroscopy to acquire information about biological tissue. Light scattering spectroscopy is a form of reflectance spectroscopy that examines elastic scattering to detect tissue architecture. In this situation, the tissue serves as a diffraction or dispersion mechanism.

Because the first useful atomic models described the spectra of Hydrogen, which models include the Bohr model, the Schrödinger equation, and Matrix mechanics, all of which can produce the spectral lines of Hydrogen, providing the basis for discrete quantum jumps to match the discrete hydrogen spectrum, spectroscopic studies were central to the development of quantum mechanics?

Furthermore, Max Planck's explanation of blackbody radiation included spectroscopy since he was correlating the wavelength of light to the temperature of a Black Body using a photometer. Because atoms and molecules have distinct spectra, spectroscopy is employed in physical and analytical chemistry. As a consequence, these spectra may be utilised to detect, identify, and measure atom and molecule information.

On Earth, spectroscopy is also utilised in astronomy and remote sensing. Spectrographs are often seen on research telescopes. The spectral data collected is utilised to identify the chemical composition and physical attributes of celestial objects (such as their temperature, density of elements in a star, velocity, black holes and more). Biochemistry is a major use of spectroscopy. Molecular samples may be tested to determine species identity and energy content.

The core premise of spectroscopy is whether light is composed of several wavelengths, each of which corresponds to a particular frequency. The significance of spectroscopy stems from the fact that each element in the periodic table has a distinct light spectrum defined by the frequencies of light it produces or absorbs that consistently appear in the same portion of the electromagnetic spectrum when diffracted. This opened up a whole new area of research for everything containing atoms, which is all matter. Understanding the atomic characteristics of all matter requires the use of spectroscopy. As a result, spectroscopy uncovered numerous previously unknown subfields of study. The concept that each atomic element has a distinct spectral signature allows spectroscopy to be employed in a wide range of domains, each with a particular aim that various spectroscopic processes may accomplish. The National Institute of Standards and Technology keeps a public Atomic Spectra Database up to date with exact data.

The study of spectroscopy has expanded owing to the fact that every section of the electromagnetic spectrum, from infrared to ultraviolet, may be utilised to evaluate a sample, revealing scientists distinct characteristics about the same material. The most popular forms of spectroscopy in chemical analysis, for example, include atomic spectroscopy, infrared spectroscopy, ultraviolet and visible spectroscopy, Raman spectroscopy, and nuclear magnetic resonance. The idea underlying nuclear magnetic resonance (NMR) is that frequency is equivalent to resonance and its corresponding frequency range.

Spectroscopy is the study of the emission of light and other radiations by materials. They mostly deal with the wavelength of the radiation. Spectroscopy also investigates the interactions of particles such as protons, electrons, and ions. Spectroscopy may also be used to investigate particle interactions as a function of impact energy. Spectroscopic analysis is crucial in quantum mechanics, relativity theory, and quantum electrodynamics.

This page delves into the principles of spectroscopy, the usage of spectrometers, and the many kinds and applications of spectroscopy.

### **Spectroscopy Principle**

Spectroscopy is most often used to detect and explain the elements and compounds of atoms and molecules. They are determined by evaluating the radiant energy absorbed or emitted by the sample or object. In this case, a beam of electromagnetic radiation such as infrared rays, UV rays, and so on is passed on the sample, and the response of the sample is measured using the wavelength of the electromagnetic spectrum applied from an external energy source.

A spectrometer is a scientific equipment that is primarily used to analyse the wavelength of electromagnetic radiations by detecting and isolating the spectrum components based on their physical phenomena. Molecular spectroscopy is frequently performed using a spectrometer. The spectrometer is made up primarily of a radiation source as well as detecting and analysis equipment. Emission spectrometers are used to excite molecules in a sample to higher energy levels and then evaluate the radiation produced when the molecules return to their original state. Typically, absorption spectrometers will pass known wavelength radiations. As a result, variations in radiation wavelength may be determined. The method of Fourier-transform spectrometers is identical to that of absorption spectrometers, except that they use broadband radiations and the output is analysed by a computer. Mass spectrometers are mostly used to analyse the masses of atomic or molecular components in a sample. Spectroscopy is mostly used to investigate the structure of molecules and atoms. Spectroscopy will explore the structure and electron configurations of atoms and molecules using a long wavelength.

Spectroscopy may also be used to determine the chemical makeup of things that are unknown. The emission spectrum of spectroscopy will aid in focusing on a few parts per million of a trace element in a substance.

The study of spectral emission lines will aid astronomers in their studies of distant galaxies. This will aid in the analysis of the cosmos in all directions. Astronomers will also observe the doppler shift of spectral lines. A doppler shift occurs when the source of radiation, such as a star or nebula, moves relative to an observer.

This page describes the idea of spectroscopy, a few key kinds of spectroscopy and their applications, and a detailed list of spectroscopy applications in numerous disciplines.

1. Spectroscopy Application Examples
2. Monitoring the level of diffused oxygen in freshwater and aquatic habitats.
3. Identifying a sample's atomic structure.
4. Identifying a muscle's metabolic structure.
5. Investigating distant galaxies' spectral emission lines.
6. Changing the structure of medications to increase their efficacy.
7. Exploration of space
8. Protein characterization

### **Hospital respiratory gas analysis**

A spectroscope is a device that measures the characteristics of light in a specific region of the electromagnetic spectrum. Spectroscopes are sometimes referred to as optical spectroscopes, spectrophotometers, and spectrographs. Typically, the spectrometer in the spectroscope will generate spectral lines and aid in the measurement of light wavelengths and intensities.

### **Spectroscopy Types**

A few major varieties of spectroscopy are discussed here, along with their characteristics and uses.

#### **Infrared Spectroscopy**

Infrared spectroscopy focuses on the electromagnetic spectrum in the infrared area. They mostly study absorption spectroscopy. The primary use of IR spectroscopy is to determine the chemical makeup of a substance. FTIR spectrometers primarily use infrared (IR) spectroscopic methods. Infrared electromagnetic spectrum is divided into three types: near-infrared, far-infrared, and mid-infrared.

The near-infrared ranges from 14000 to 4000  $\text{cm}^{-1}$ , which will aid in the research of overtone or harmonic vibrations. The mid-infrared spans from 4000-400  $\text{cm}^{-1}$ , which will aid in the investigation of basic vibrations and the accompanying rotational-vibrational structure. The mid-infrared extends from 400-10  $\text{cm}^{-1}$ , which will aid in the study of low-energy microwave zones and may be utilised for rotational spectroscopy.

#### **Spectroscopy of UV Light**

Absorption spectroscopy and reflectance spectroscopy are other terms for ultraviolet spectroscopy. The ultraviolet portion of the electromagnetic spectrum is near to the infrared area. UV spectroscopy is mostly used for bacteria cultivation, drug identification, and nucleic acid purity testing.

### **Spectroscopy of Masses**

Mass spectroscopy is mostly used to examine protein-protein interactions. As a result, mass spectroscopy may be used to detect biomolecules or proteins in biological samples. These mass spectroscopy detectors will analyse the chemical based on mass and charge ratio. Ion deflection is primarily determined by mass, velocity, and charge in this case.

### **Spectroscopy using Raman**

Raman spectroscopy is typically based on photon absorption. Raman spectroscopy analyses materials based on photon scattering at higher or lower frequencies. Photons impacted on molecules or atoms may acquire or lose energy depending on the vibration or rotation of the molecules. Rayleigh scattering occurs when the majority of light photons are dispersed by the sample without any changes in frequency. The Raman spectra are typically the monochromatic visible laser spectra. For radiation analysis, a scanning optical monochromator with a phototube is utilised as a detector.

### **Spectroscopy of Fluorescence**

One of the most significant forms of electromagnetic spectroscopy is fluorescence spectroscopy. They are mostly used to measure a sample's fluorescence. UV lamps are often employed in fluorescence spectroscopy. Fluorescence spectroscopy is mostly utilised in biochemical, medicinal, and chemical studies to analyse organic components. Microfluorimetry may be used to do fluorescence spectroscopy at the tiny level. We may discover the component present in air, water, or other media by employing Atomic Fluorescence Spectroscopy (AFS) methods.

### **Thermofluorescence Infrared Spectroscopy**

Fourier-transform infrared spectroscopy is another name for FTIR spectroscopy. An infrared spectrum of absorption or emission of a solid, liquid, or gas is used to acquire this approach. FTIR spectroscopy is extensively utilised in the analysis of nano and biological materials, the assessment of water content in plastics and compositions, detectors in chromatography, and so on. Spectroscopy is mostly used to investigate the structure of molecules and atoms. Spectroscopy will explore the structure and electron configurations of atoms and molecules using a long wavelength. Spectroscopy may also be used to determine the chemical makeup of things that are unknown. The emission spectrum of spectroscopy will aid in focusing on a few parts per million of a trace element in a substance.

The study of spectral emission lines will aid astronomers in their studies of distant galaxies. This will aid in the analysis of the cosmos in all directions. Astronomers will also observe the doppler shift of spectral lines. A doppler shift occurs when the source of radiation, such as a star or nebula, moves relative to an observer.

### **Spectroscopy Application Examples**

1. Monitoring the level of diffused oxygen in freshwater and aquatic habitats.
2. Investigating distant galaxies' spectral emission lines.
3. Changing the structure of medications to increase their efficacy.
4. Exploration of space
5. Protein characterization

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## CHAPTER 8

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### Electrical Resistivity and Conductivity

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Electrical resistivity (also known as specific electrical resistance or volume resistivity) is a material attribute that quantifies how well a substance resists electric current. A substance with a low resistivity enables electric current to flow easily. The Greek letter  $\rho$  is widely used to denote resistivity. The ohm-meter ( $\Omega$ ) is the SI unit of electrical resistance. For example, if a 1 m<sup>3</sup> solid cube of material contains sheet connections on two opposing sides and the resistance between these contacts is 1  $\Omega$ , the material's resistivity is 1  $\Omega \cdot \text{m}$ .

Electrical conductivity, also known as particular conductance, is the inverse of electrical resistivity. It denotes the capacity of a substance to conduct electric current. It is generally represented by the Greek letter  $\sigma$ , although  $\kappa$  (particularly in electrical engineering) and  $\gamma$  are also used. Siemens per metre (S/m) is the SI unit for electrical conductivity. Resistivity and conductivity are material qualities that provide the opposition of either a standard cube to current. Electrical resistance and permeability are two broad qualities that describe an object's resistance to electric current.

Electrical conductivity is a material attribute that governs how effectively a substance conducts electricity. Electrical conductivity and resistivity (the more widely used term) are closely related:

Where  $\sigma$  is the conductivity (measured in  $\text{m}/\Omega$ ) and  $\rho$  is the resistivity (measured in  $\Omega \cdot \text{m}$ ). To calculate the resistance of a rope (which may be constructed of nearly anything: copper, aluminium, or wood! ), use:

Where  $A$  is the wire's cross-sectional area (in  $\text{m}^2$ ) and  $l$  is its length (in  $\text{m}$ ).

Electrical conductivity and electrical conductance are inextricably linked. Electrical conductivity is a material quality (such as silver), while electrical conductance is a property of a specific electrical component (like a particular wire).

Electrical conductivity is defined as the amount of voltage necessary to for an electric current to flow. The quantity of electrons in the outermost shell significantly determines this; these electrons dictate the ease with which mobile electrons are formed. Another, although minor, component is the number of atoms per cubic centimeter, which impacts the quantity of electrons that may easily migrate in response to an electric field. Conductors are materials with strong conductivity, such as copper and aluminium. Electrical insulators (or just insulators when there is no chance of mistake with thermal insulation) are materials having poor conductivity, such as rubber and glass. In between, there is a specific class of materials known as semiconductors, which includes silicon and germanium. Because the electrons in their outermost shell may flow

readily, most metals have high conductivity (which is a different way of stating metals prefer to be conductors). Nonmetals have a poor conductivity.

### The Formula of Electrical Conductivity

Assume that a piece of conductive material has a perfect cross-section and physical composition. Furthermore, the electric field and current density are always parallel and constant. However, since diverse resistors and conductors have a consistent cross-section with a uniform electrical current flow and are made of a single material, this model is valid. In this situation, the electrical resistivity ( $\rho$ ) may be computed using the formula:

$$R = \rho \frac{l}{A} \quad (1)$$

Here,

R - the electrical resistance of a homogeneous material specimen  
 $\rho$  - particular resistance or resistivity

l - the material's length

A - the material's cross-sectional area

Because we know that a particular material's electrical conductivity is just the reciprocal of its resistance, the formula for this statement is:

$$\sigma = \frac{1}{\rho}$$

Let us now calculate the unit of electrical conductivity.

Because the resistance of any material is exactly proportional to its length and inversely proportional to its cross-sectional area.

So,

$$\rho = \frac{RA}{l}$$

Changing their units:

$$\rho = \frac{\text{ohm} \cdot \text{m}^2}{\text{m}} = \text{ohm} \cdot \text{m}$$

The opposite of resistivity is  $\text{ohm}^{-1} \text{m}^{-1}$  or mho/m.

Because  $\text{ohm}^{-1}$  is expressed as S (Siemens), the electrical conductivity unit becomes Siemens/meter or S/m.... Aside from that, the dimensional formula for electrical conductance is as follows: Because we know that the dimensional formula for resistance (Ohm) is  $[M^1 L^2 T^{-3} A^{-2}]$ , becomes  $[M^{-1} L^{-2} T^{-3} A^2]$ .

### Facts on Electrical Conductivity

Though not all liquids transmit electricity, some, such as lemon juice, milk, vinegar, common salt mixture, sulphuric acid workaroud, saltwater, and rainfall, may. Sugar solution, distilled water, and honey, on the other hand, cannot carry electricity. The conductivity of drinking water ranges from 200 to 800 S/cm.

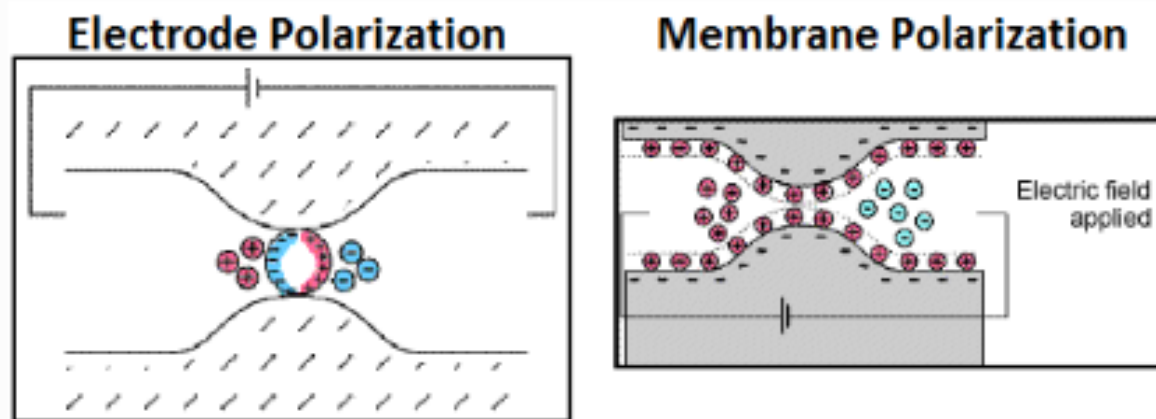
When doing environmental or process monitoring, electrical conductivity is an important metric to measure. This measure is useful in detecting numerous changes, such as variations in conductivity, which might indicate pollution.



So, based on our discussion of what is electrical conductivity, its formula, unit, and examples, we can conclude that materials through which electric current may readily move are referred to as conductors of electricity. Electrical conductivity indicates a substance's capacity to allow the passage of an electric current, which may be computed using the formula  $\sigma = 1/\rho$  and  $J = \sigma E$  both solid metals and graphite are strong electrical conductors with high electrical conductivity. Some liquids, like as seawater and lemon juice, are also effective conductors.

### Chargeability and Frequency-Dependence

An electric field causes free charges (such as ions) to flow through materials in the direction of the applied field. The movement of electrical impulses is in phase with the applied electromagnetic current in most practical applications. Ionic charges, on the other hand, begin to accumulate when they hit an impermeable barrier. As a consequence, some materials may behave as ionic charge capacitors, a process known as induced polarisation. Two instances of induced polarisation in rocks are shown below. Ionic charges build on the left because the pore route is obstructed by metallic particles (electrode polarization). Ionic charges collect on the right because the capillary throat is inadequately big (membrane polarization).



Chargeability is defined as the amount of charge buildup (capacitance) under the influence of an external electromagnetic field. Although the two are connected, chargeability is typically seen as a distinct physical quality from conductivity. The constitutive connection (Ohm's law) becomes frequency-dependent for charged materials

### Importance to Geophysics

The bulk of EM surveys use electrical conductivity contrasts to scan the subsurface. Electrical current is driven into the Earth during alternating current resistivity (DCR) studies, for example. The current's route, as well as the collected data, are affected by the subsurface share information.

Many EM systems work on the basis of EM induction principles. These include frequency-domain electromagnetic (FDEM), time-domain electromagnetic (TDEM), maritime controlled source electromagnetic (CSEM), and exploded ordnance (UXO) surveys. During these examinations, a transmitter emits time-varying electromagnetic signals into the ground, which create electric currents. The distribution of subsurface conductivities affects the strength of the induced currents and the secondary magnets they generate.

The conductivity of the Earth affects data obtained during present in healthy (MT) and Z-axis Tipper EM (ZTEM) surveys. To create EM responses, these technologies depend on natural sources. For MT, the correlations between recorded electric and magnetic field components offer information about the Earth's electromagnetic impedance and, indirectly, its electrical conductivity.

### Electron mobility

The electron mobility in solid-state physics describes how rapidly an electron may travel through a metal or device when dragged by an electric field. For holes, there is a corresponding quantity known as hole mobility. The phrase carrier mobility applies to both electron – hole mobility in general. Electron and hole mobility are subsets of the electrical motion of charged particles in a fluid in the presence of an applied electric field.

When an emf  $E$  is given to a material, the electrons react by moving at an average velocity known as the drift velocity,  $v_d$ . The electron mobility is then defined as

$$v_d = \mu E$$

Electron mobility is nearly commonly expressed as  $\text{cm}^2/(\text{Vs})$ . This is not the same as the SI unit of mobility,  $\text{m}^2/(\text{Vs})$ . They are connected by the formula  $1 \text{ m}^2/(\text{Vs}) = 10^4 \text{ cm}^2/(\text{Vs})$ .

The product of mobility and carrier concentration determines conductivity. For example, the same conductivity might be produced by a small number of electrons with high mobility or a large number of electrons with low mobility. The behaviour of transistors and other devices in semiconductors may vary greatly depending on whether there are many electrons with low mobility or few electrons with high mobility. As a result, mobility is a critical metric for semiconductor materials. When everything else is equal, more mobility almost always leads to improved device performance.

Impurity concentrations (including the donor and acceptor concentrations), defect concentration, temp, and electron and hole concentrations all influence semiconductor mobility. It is also affected by the electric field, especially at high fields when movement saturation occurs. The Hall effect may determine it, or it can be deduced from transistor behavior.

### Effective Mass and Statistical Considerations

When an electric field perturbs a free electron, it is subjected to forces that drive it to accelerate; it travels in the opposite direction of the electric field and speeds up over time. In a crystal, however, the situation is different because the electron is travelling through a lattice trillions of jiggling atoms, all of which impose electromagnetic forces. We cannot utilise the normal electron mass; instead, we must use an effective mass for the electron in the crystal, which is caused by the periodic forces of the crystal's host atoms<sup>1</sup>. The great thing is that we can see the electron travelling as if it were in a vacuum, but with this new effective mass that changes from material to material.

Another distinction is that a moving electron within the crystal will not go far before colliding with a host atom or impurity. Because these collisions randomise the electron's travel, it is desirable to utilise an average amount of time, the relaxation time, which is based on the electrons' random thermal motion. The scattering mechanisms of the electron bouncing about lead it to lose energy, which is released as heat. With an applied electric field, we also have a mean free route length, or an average net displacement for a specific electron.

## Thermogravimetric analysis

Thermogravimetric analysis (TGA) is performed on a thermogravimetric analyzer. A thermogravimetric analyzer constantly measures mass as a sample's temperature changes over time. In thermogravimetric analysis, mass, temperature, and time are regarded basic measurements, from which numerous other metrics may be generated.

A thermogravimetric analyzer is typically made up of a precision balance with a sample pan housed within a furnace with programmable control temperature. To cause a thermal reaction, the temperature is normally raised at a consistent pace (alternatively, in certain applications, the temperature is regulated for a constant mass loss). The thermal reaction can take place in a variety of atmospheres, such as ambient air, vacuum, inert gas, oxidizing/reducing gases, corrosive gases, carburizing gases, liquid vapours, or "self-generated atmosphere," as well as pressures such as a high vacuum, high pressure, constant pressure, or controlled pressure.

The thermogravimetric data gathered from a thermal reaction is shown as a plot of mass or percentage of starting mass on the y axis vs temperature or time on the x axis. This figure, which is often softened, is known as a TGA curve. The first derivative of the TGA curve (the DTG curve) may be displayed to find inflection points for detailed interpretations and differential thermal analysis. A TGA may be used to characterize materials by analyzing typical degradation patterns. It is particularly beneficial for researching polymeric materials such as thermoplastics, thermosets, epoxies, composites, plastic films, fibers, coatings, paints, and fuels.

## Oxidation and combustion

The residue left behind after a reaction is the most basic material characterisation. A combustion process, for example, might be examined by inserting a sample into a differential thermal analysis under normal circumstances. By heating the material over its ignition point, the analysis (TGA analyzer would initiate ion combustion. The residue would be seen at the end point of the TGA curve if the y-axis was shown as a percentage of the original mass. The most prevalent visible losses in TGA are oxidative mass losses.

It is critical to investigate the oxidation resistance of copper alloys. NASA (National Aeronautics and Space Administration), for example, is doing research on improved copper alloys for potential application in combustion engines. However, oxidative deterioration may occur in these alloys since copper oxides develop in oxygen-rich environments. Because NASA intends to reuse shuttle components, oxidation resistance is important. TGA may be used to investigate the static oxidation of materials like these for practical applications.

Combustion during TG analysis is seen in the TGA thermograms as discrete traces. One intriguing example is samples of as-produced unpurified carbon nanotubes with a significant quantity of metal catalyst. A TGA trace may diverge from the typical shape of a well-behaved function due to combustion. This phenomena occurs as a result of a sudden temperature shift. When the weight and temperature are plotted against time, a major slope shift in the first derivative plot occurs concurrently with the sample's mass loss and the thermocouple's abrupt spike in temperature. Beyond the oxidation of carbon owing to poorly managed weight loss, the mass loss might be caused by particles of smoke generated from burning caused by irregularities in the material itself

Various weight losses on the same sample at different times may also be used to determine the anisotropy of the sample. For example, sampling the top and bottom sides of a sample with

scattered particles within may be beneficial for detecting sedimentation since thermograms will not overlap but will reveal a gap if the particle distribution varies from side to side.

### Calorimetry

Calorimetry (from Latin calor 'heat' and Greek  $\nu$  (metron)'measure') is the science or act of measuring changes in state variables of a body to derive the heat transfer associated with changes in its state caused by chemical reactions, physical changes, or phase transitions under specified constraints. A calorimeter is used to conduct calorimetry. The discipline of calorimetry is considered to have been founded by Scottish physician and scholar Joseph Black, who was among the first to establish the difference between heat and temperature.

Indirect calorimetry determines heat produced by live organisms by measuring either their generation of nitrogen and carbon waste (usually ammonia in aquatic organisms or urea in terrestrial species) or their consumption of oxygen. Using multiple regression, Lavoisier discovered in 1780 that heat output can be predicted from oxygen consumption. This technique is accurate, according to the dynamic energy budget hypothesis. Heat produced by live creatures may also be measured via direct calorimetry, which involves placing the whole organism inside the calorimeter for the study. The scanning electron microscopy calorimeter, a device that permits thermal data to be gathered on tiny volumes of material, is a commonly used contemporary equipment. It entails heating the sample at a regulated pace and measuring the heat flow into or out of the specimen.

### Basic classical calculation with respect to volume

Calorimetry necessitates the use of a temperature-changing reference material with well-defined thermal constitutive characteristics. The classical rule, established by Clausius and Kelvin, states that the pressure produced by a calorimetric material is completely and promptly determined merely by its temperature and volume. This rule applies to changes that do not require phase change, such as ice melting. Many materials do not conform to this criteria, and the current classical calorimetry formula does not offer an appropriate account for them. The classical rule is considered to hold for the calorimetry material used here, and the statements are expressed mathematically:

The pressure completely describes the calorimetric material's thermal reaction.  $p$  denotes the value of its basic function  $(, )$ .  $p(V,T)$  of just the volume  $V$  as well as the temperature. All increments must be quite modest in this case. This calculation relates to a volume and temperature domain of the body with no phase shift happens and only one phase exists. The continuity of property ownership is a crucial assumption here. For phase transition, a separate analysis is required. A stirrer is housed in an insulating jacket.

### Uses of Calorimetry

Matter always obeys the principle of lowest energy, which means that given the choice, matter will exist in the lowest energy state conceivable. Regardless, matter may exist in a multitude of energy states. Uranium atoms, for example, are very powerful. Matter's energy has a significant impact on its natural occurrence, reactivity, and so on., we can anticipate the natural occurrence, reactivity, and physical attributes on the energy measurements we take using calorimetry. Understanding a substance's thermodynamic qualities will always lead to answers about its structure and other aspects.

Adiabatic calorimetry is a valuable technique for improving plant safety. A calorimeter is a device used to calculate the amount of heat produced by chemical or physical processes. An adiabatic calorimeter is intended to prevent heat transmission between the system and the surrounding environment.

As a result, an adiabatic calorimeter is constructed in such a way that the exothermic heat generated by a process immediately contributes to raising the temperature. The pace of reactions frequently increases exponentially as the temperature rises. The available cooling capacity on a big plant scale is fixed, therefore as the rate of reaction rapidly grows, the heat created by an exothermic reaction might exceed available cooling. This may result in a chain reaction. Fire exposure, loss of cooling, overcharging of a reagent or catalyst, all-in addition of a reagent, and other frequent circumstances may all contribute to a runaway reaction. Adiabatic calorimetry may be used to mimic these situations in order to analyse the possibility of a runaway reaction and to gather data for emergency relief system (ERS) design using software such as FERST powered by CHEMCAD. Adiabatic calorimeters monitor temperature and pressure rises caused by exothermic processes, which are then used to calculate adiabatic rates of pressure and temperature rise.

### **Low-Thermal Inertia Calorimetry: Phi-Factor**

The Phi-factor is a dimensionless metric calculated by dividing the total heat capacity of the filled testing machine (or vessel) by the total heat capacity of the sample (or vessel contents). This ratio indicates how much heat is necessary to heat the test cell (or vessel) and its contents in comparison to just heating the sample (or vessel contents). If the material starts exothermically reacting, a hefty test cell will absorb part of the heat, and the sample will not achieve its full adiabatic potential. In other words, we include heat loss to the container as well as heat loss to the environment in the discipline of adiabatic calorimetry (i.e. test cell).

This parameter is a correction factor that may be used to alter adiabatic data obtained. The Phi - factor approaches one for big vessels, light vessels, or real adiabatic circumstances. As a result, a Phi - factor of 1.1 implies that temperature increase data acquired in an adiabatic device may need to be corrected by 10%. (for example, to estimate the adiabatic temperature rise). It should be noted that the influence on kinetics (such as reaction rates) is nonlinear. As the Phi - factor is increased, so is the amount of data correction needed. A issue with a high Phi - factor is that you may be losing out on greater thermal potential. The ARSST and VSP2 have low Phi - factor adiabatic calorimetry, which is appropriate for immediately scaling the acquired data to full size vessels.

The Similar is a reaction calorimeter used in process development to examine the thermal characteristics of a chemical reaction under suggested operating circumstances. Based on the acquired thermodynamic and kinetic characteristics of the reaction, the Similar enables for the adjustment of process settings for optimum product yield and lowest safety threats.

The Similar calculates the plant cooling capacity necessary to maintain a reaction isothermal ( $T_p$ ) and the maximum temperature that the primary reaction will reach in the case of a thermal runaway. The Maximum Temperature of Synthesis Reaction (MTSR) parameter is crucial in establishing if a plant's emergency cooling capability can handle an increase in temperature. The Similar may be used to find better response circumstances. The Similar supports both the traditional heat flow calorimetry technique and the faster, more efficient, calibration-free power compensation calorimetry approach, enabling you to choose the best method for the case at hand.

## Reaction Calorimeters

A reaction calorimeter is a calorimeter that initiates a reaction inside a closed insulated container. The heat content is calculated by integrating heat flow against time and measuring reaction heats. Because industrial processes are designed to operate at consistent temperatures, this is the quality used in industry to survive heats. There are four basic ways for measuring heat in a reaction calorimeter:

- 1) Heat Flow Calorimeter - The cooling/heating jacket is critical in managing the temperature of the technique or the warmth of the jacket. The temperature differential between the heat transfer fluid and, hence, the process fluid is used to quantify heat.
- 2) Heat Balance Calorimeter - The cooling/heating jacket regulates the method's temperature. The warmth acquired or lost by the temperature transfer fluid is monitored to determine heat.
- 3) Power Compensation - To maintain a constant temperature, a heater is installed inside the vessel. Because the energy provided to the current heater is often altered as reactions need, the calorimetry signal is exclusively generated from this electric power.
- 4) Constant Flux Calorimeter - Constant flux endothermic reaction (or COFLUX) is a subset of heat balance calorimetry that employs specific control mechanisms to maintain a constant heat flow (or flux) over the vessel wall.

## Bomb Calorimeters

A bomb is a kind of constant-volume calorimeter used to measure the heat of combustion of a given reaction. To ignite the fuel, electrical energy is used; when the fuel burns, it heats up the surrounding air, which expands and exits via a tube that leads the air out of the calorimeter. When air escapes through the copper tube, it heats up the water outside the tube. The temperature differential in the water enables the calorie content of the fuel to be calculated. A bomb is made consisting of a small cup to hold the sample, oxygen, a chrome steel bomb, water, a stirrer, a thermometer, a dewar or insulating container (to prevent heat from being transferred from the calorimeter to the surroundings), and an ignition circuit linked to the bomb. The reaction will occur with no volume change if the explosive is made of chromium steel.

## Calorimeters of the Calvet type

A three-dimensional fluxmeter sensor is used for detection. The fluxmeter element is made up of a hoop with serial thermocouples. Within the calorimetric block, an alternate thermopile with strong heat conductivity surrounds the experimental region. The radially placed thermopiles provide almost full heat incorporation. Calibration of calorimetric detectors is a critical parameter that must be done properly. A specific calibration, known as the Joule effect or electrical calibration, has been created and utilised for these Calvet-type calorimeters to overcome a variety of difficulties.

The following are the primary benefits of this kind of calibration:

- 1) It is a precise calibration.
- 2) The use of standard calibration materials is not required. Calibration is often conducted at a constant temperature, both in heating and cooling modes.



- 3) It may be used to any size experimental vessel.
- 4) It is a very precise calibration.

### **Calorimeters for Adiabatic Fluid**

Adiabatic calorimeters estimate the enthalpy change of a reaction in solution. There is no heat exchange with the surroundings throughout the reaction, and the air pressure stays constant.

### **Calorimeter for Differential Scanning**

Heat flows into a sample that is normally confined inside a tiny aluminium capsule or 'pan' in this differential scanning calorimeter, or DSC. This heat flow is measured differentially, which means that it is compared to the flow into an empty reference pan.

### **Calorimeter for Isothermal Titration**

The temperature of the reaction is used to track a titration experiment in an isothermal titration calorimeter. This approach is gaining popularity, particularly in the area of biochemistry, since it makes it easier to determine substrate binding to enzymes. In the pharmaceutical sector, the approach is often used to characterize prospective medication candidates.

### **Crystallography in materials**

The study of atom arrangement in materials is known as crystallography. This is accomplished by measuring the radiation's diffraction by the crystal's atomic planes and columns, and then recreating the original atomic configuration. The word used to describe the field that analyses crystalline structures is crystallography. In reality, such as in rocks and jewels, there are several crystalline formations. However, crystallography is mostly employed in the study of proteins and other significant biological molecules that do not normally crystallize there in field of life sciences.

The study of crystallites was based on physical measurement techniques of their geometry to determine their symmetry before the development of crystallography. The field was created after X-Rays were discovered in 1895. H. and W.L. Bragg carried out ground-breaking research in the mid - twentieth century, establishing the connection between crystalline phase and X-ray refraction patterns. The name of this equation is Bragg's law. The study of atom arrangement in materials is known as crystallography. Usually, this is accomplished by measuring the radiation's diffraction by the crystal's atomic planes and columns, and then recreating the original atomic configuration.

Crystallography focuses on using various diffraction and spectroscopic techniques to investigate the microstructure of substances and materials. The Technical University of Darmstadt's materials science department research is illustrated through a number of instances .By using X-ray, neutron, and NMR spectroscopy along with inelastic neutron scattering, researchers are able to better understand the structure and dynamics of aliphatic biomolecules in catalytically active zeolites. Grazing incidence methods are used to study the surfaces and interfaces of semiconductor and thin superconducting films. Details on thickness, structure, surface finish, and a potential alteration of these variables are discovered by looking at the reflect gram.

### **Surface X-Ray Diffraction**

An effective method for determining the arrangement of atoms on a sample's surface is surface X-ray diffraction. Hard X-rays (usually at 15keV) enable the study of interfaces in a variety of

environments, such as liquids, high gas pressures, or buried solid-solid contacts. A case of grazing Geometry gives surface sensitivity, and a variety of measures can identify the sample's layer structure, in-depth atomic surface structure, or nanoparticle size and shape. Surfaces are where materials come into contact with one another, and they play a crucial role in many fields, including catalysis, batteries development, lubrication, and electronics, to name a few. The characteristics are significantly impacted by the surface structure.

### **Principles and Theory of Crystallization**

Crystallography techniques examine the diffraction patterns that a substance experiences as a result of being exposed to radiation. Although X-rays and other forms of electromagnetic radiation are most frequently used, neutrons and electrons also are employed. X-ray, electron, and neutron beams all have unique interactions with the material. Each is appropriate for a distinct study. X-rays interact with valence orbitals of electrons and its spatial distribution to produce the diffraction patterns. Atomic nuclei with their surrounding electrons' charge distributions are seen in electron beams. Strong nuclear forces, magnetic fields, and other factors disperse neutron beams.

Because of the microscopy is inadequate for studying atomic structures, crystallography is utilized instead. This is so because the wavelength of visible light is several orders of magnitude greater than the lengths of atomic bonds between atoms. Therefore, the examination of structures at this size is better suited to electromagnetic radiation's shorter wavelength. Crystallography and optical methods vary significantly except that the beam can also be focused to create pictures in the traditional sense. Instead, the structure is recreated using a number of methods, including software, from the diffraction pattern. Sharp features are formed by photons mirrored by the molecules in the structure in the diffraction pattern created by crystallographic methods, whereas diffused and weak features are made by non-periodic components. Diffraction patterns produced by crystallographic techniques are excellent for revealing data on the structure of substances because of the repeating and organized character of crystal lattices.

### **Technique of crystallography**

A steady crystal must first be made. Since many biological compounds don't form crystals spontaneously, crystallographers use a number of methods. Different chemicals crystallize at different rates. The molecule is kept in a solution, and a buffer, precipitants, and the molecule are all contained inside a reservoir to create the crystal. Crystallization is accomplished by the slow precipitation of the molecule-containing solution into the reservoir, which contains a hygroscopic solution. A proper crystal may form if the process is carried out too quickly. A stable crystal is supplied to the crystallographic apparatus after it has formed. A beam is then pointed towards it. The most frequent source of the beam is a synchrotron because of the radiation's high purity. Additionally, they generate the most thorough diffraction patterns. Although there are other sources, synchrotrons continue to be the norm.

Extremely sophisticated mathematics are utilized to examine the diffraction patterns that are created. A statistically predicted pattern is contrasted with two randomly created patterns. Before the real design of the crystalline is discovered, the procedure is refined multiple times. Revisions are no longer nearly as necessary thanks to modern tools. Without software, revealing the crystals' morphology may be a very time-consuming and arduous procedure. Due to an underlying degree of order, the diffraction pattern produced by these kinds of substances can

nevertheless offer important information. As an illustration, consider how the diffraction pattern that showed the double-helical structure of DNA was acquired from a fiber sample.

### Applications

X-ray crystallography has a wide range of scientific applications. When it was first proven to be an effective method, it was primarily applied to fundamental science problems, such as figuring out how big atoms are, how long and different kinds of chemical bonds are, how materials are arranged atomically, how different they are from one another, and how alloys and minerals' crystalline impartiality, grain orientation, grain boundaries, film thickness, and interface roughness.

Science has advanced significantly, and while these fields are still crucial for examining novel materials, they are now frequently used to determine the structural characteristics of various bioactive molecules, supplements, pharmaceuticals, thin-film materials, and multi-layered materials. Because of its nondestructive nature, high accuracy, and precision, it has emerged as one of the industry standards for testing materials if the structure is unknown in the geological, environmental, industrial, material science, and pharmaceutical sectors (among many others). A few of the specific areas that now can be investigated with X-ray crystallography entail assessing the surface area of films, identify critical crystal phases and sexualities that can assist in assessing the catalytic activity of substances, defining the purity of a sample, understanding how a drug may interact with particular proteins and how the substance can indeed be improved, examining how enzymes converse with other proteins, investigating crystallites, and for analyzing. These are only a few particular uses of X-ray crystallography; there are many more

### Unit cell

The identical unit cells are defined in a manner as they take up space without touching one another. A crystal's internal 3D structure of atoms, molecules, or ions is known as its lattice. It consists of a large number of unit cells. Every point of the lattice is occupied by a single of the three component particles.

### Types of Unit Cell

Primitive cubic, body-centered cubic (BCC), or face-centered cubic are the three types of unit cells (FCC). The three different sorts of unit cells will be thoroughly covered in this section.

### Primitive Cubic Unit Cell

In Primitive Cubic Unit Cell Only the corners of the original cubic unit cell contain atoms. Eight neighboring unit cells share each atom at the corner. Both the higher (or lower) layer and the same layer have four unit cells each. Consequently, a specific unit cell only contains 1/8th of such an atom. In the accompanying illustration, each tiny sphere denotes the center of both a particle, not its size, in that specific location. This building is referred to as an open structure.

1. Only the corners of the simple cubic unit cell contain atoms.
2. Eight neighboring unit cells share each atom at the corner.
3. There are four unit cells in the same layer.
4. Upper/lower layer four unit cell.
5. Consequently, a specific unit cell only contains 1/8th of an atom.
6. In the accompanying diagram, each tiny sphere indicates the location of a particle's center rather than its size.

At the corners of the each cubic cell are 8 atoms. Consequently, there are atoms in a unit cell total of

$$8 \times 1/8 = 1 \text{ atom.}$$

### **Body-centered Cubic Unit Cell (BCC)**

A BCC unit cell has an atom in the middle of the structure and atoms at each corners of the cube. The illustration that follows is just an open structure. This structure states that the atom in the center of the body is entirely a part of the unit cell that it is located.

1. Every corner of the BCC unit cell contains atoms.
2. The center of both the structure contains one atom.
3. An open structure.
4. This structure states that each atom at the body's centers is completely a part of the unit cell it is located in.

### **Face-centered Cubic Unit Cell (FCC)**

Atoms may be found in an FCC unit cell at the cube's center and on each of the crystal lattice's four corners. Only half of each atom which is shared by the face-centered atom and two neighboring unit cells belongs to a single cell.

1. Atoms are found in every corner of both the crystal lattice in an FCC unit cell.
2. Furthermore, each face of both the cube has one atom in its center.
3. Two neighboring unit cells share this face-center atom.
4. Each atom is limited to 12 in a unit cell.

### **Bravais Lattice**

The 14 distinct 3-dimensional configurations that atoms can be organized in crystals are known as the Bravais Lattice. A unit cell is the smallest collection of symmetrically positioned atoms that may be reproduced in an assembly to form the whole crystal.

A lattice can be explained in a variety of ways. The Bravais lattice is considered to be the most basic explanation. A Bravais lattice is, in other words, a collection of discrete points that, from any discrete point, have the same arrangement and orientation, making the points of the lattice identical.

### **Metallic Crystal Structure**

At normal temperature, all metallic elements are crystalline solids with the exception of Cs, Ga, and Hg. Metals and alloys, like ionic solids, have a particularly strong tendency to crystallize, regardless of whether they are produced thermally or by alternative processes like solution reduction or etching.

Metals rapidly form crystals, and even with extremely quick cooling it is challenging to create a glassy metal. The identical (almost spherical) atoms may pack into a crystal extremely quickly because molten metals possess low viscosity.

However, alloys can be quickly cooled to produce glassy metals, especially if the individual atoms are of different sizes. Because the many atoms cannot fit into a straightforward unit cell, crystallization can occasionally be so slow that glass is formed.

## Crystal Structures

The three most prevalent crystal forms for metals and alloys are body-centered cubic (BCC), hexagonal nearer packed (HCP), and cubic closely packed (ccp, also called face centered cubic, fcc). The electron configuration of the metal atoms in all three structures i.e., the total number of equidistant closest neighbors is rather significant: 8 for bcc and 12 for hcp and ccp. This can be contrasted the with low complexes (i.e., low valences) present in nonmetals, such as 2 for O, 3 for N, and 4 for C. The closest neighbors of the atom in the middle of the bcc structure are at the cube's four corners.

## Periodic trends in structure and metallic behavior

Elements progressively transition from metals and non - metals to metalloids to metal by terms of their characteristics. The transition is effectively shown by the carbon group. The two stable allotropes of the element carbon are graphite and diamond, starting at the top. Four electron bonds are formed to nearby atoms in each of them, perfectly satisfying the valence of the carbon atoms. Each carbon in graphite has three closest neighbor's, resulting in two bonds and a double bond. There is only one link between each of the four nearest neighbor's in a diamond, which are located at the vertex of a tetrahedron. Diamond structure is also present in the two elements in the periodic table immediately under carbon (silicon and germanium) Silicon and germanium are both semiconductors, despite the fact that diamond is a superb insulator (i.e., metalloids). They have the mechanical toughness of a diamond. Similar to carbon, each molecule of Si and Ge forms single bonds with its four close neighbor's to fulfil its valence of four.

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## CHAPTER 9

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### Crystalline Materials

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The configurations of molecular chains are very precise and predictable in crystalline materials. These substances frequently have high melting points. Diamond, salt, ice, sweets, and most metals are a few typical examples. Any arrangement of ions, polymers, or atoms that is kept together in an organized, three-dimensional space is referred to as a crystalline structure. The other sort of physical ordering of atoms, known as amorphous structure, is different from crystallinity. The ordering of structure is what distinguishes crystalline from amorphous structures. While an amorphous nature is erratic and lacks the repeated theme of a crystal lattice, crystalline structure may be regarded of as the maximum amount of order that really can exist in a material. Physiologically active compounds in crystalline materials, groups of organic heterocycles, such as coumarin derivatives, which may be found in the plant world, arise. The synthesis and structural characterisation of these materials is a huge topic of study in which many labs across the globe are active. Natural and synthesised chemicals are in high demand due to their biological and pharmacological properties. These compounds have been utilised in a variety of applications, including food additives and colours, as well as cosmetics. In reality, these phases are potent antioxidants with antibacterial, hypolipidemic, cholesterol-lowering, and anticarcinogenic characteristics, making them very valuable in the pharmaceutical industry. Some materials with intrinsic photochemical properties, adequate stability, and high solubility are required by charge transfer agents, solar energy collectors, and non-linear optical materials.

Because of the massive growth in industrial activity, massive amounts of toxic chemical waste are spreading in the air, land, and water. In reality, more than 2 million gallons of dyestuffs are used each year, with more than 10% of them ending up in waterways. The concentration of organic compounds, undesirable metals, and colour waste, on the other hand, need treatment before use. In this context, photocatalytic water treatment is one of the treatments employed because of the high accuracy of organic compound mineralization compounds and the convenience of the process, as well as the benefits of replacing filters with all of the difficulties. Their usage is related with regeneration and fouling. Several crystalline materials have been added into the catalytic treatment filters [15, 16]. These materials are often used to remove different contaminants, including organic chemicals, heavy metals, and others.

#### Non- Crystalline materials

When the observed X-ray powder diffraction (XRPD) distribution is largely continuous, the substance is said to be non-crystalline (or amorphous). They are repeatedly alluded to as "X-ray amorphous" powder patterns. Groups of organic heterocycles, including coumarin derivatives found in the plant kingdom, occur as part of the hunt for physiologically active compounds in crystalline materials. Numerous laboratories throughout the world are engaged in the extensive



field of study known as the synthesizing and structural characterization of these materials. For its biological and pharmacological properties, natural or synthesized substances are especially sought after.

These substances have been applied in a variety of industries, including the cosmetics industry as well as as dietary supplements and colours. These compounds have a significant role in the pharmaceutical industry due to their potent antioxidant, bactericidal, hypolipidemic, hdl, and anti - carcinogenic effects. Materials having built-in photochemical properties, adequate stability, and high solubility are necessary for charge transport agents, solar energy collectors, and non-linear optical materials.

### **Difference between Crystalline and Non-crystalline Solids**

Atoms, molecules, or ions that make up crystalline solids are arranged in a periodic three-dimensional space. Non-crystalline solids lack a regular pattern of particle arrangement. Therefore, amorphous solids are non-crystalline substances. Since the unit cells are arranged in a regular pattern, crystalline solids possess a distinct geometrical shape as opposed to non-crystalline solids, which lack a geometrical shape. Additionally, non-crystalline solids have quite a short - range wireless order, whereas crystalline solids have such a long range order. Crystalline solids get a defined heat of fusion value that is high and a known melting point. Non-crystalline solids, on the other hand, have a variable heat of fusion and melt over a wide temperature range. Crystalline solids are real solids, as well. They display every solid's property. Contrarily, non-crystalline solids need not exhibit all of a solid's qualities. They are referred to be "pseudo solids" as a result. Crystalline solids have less energy than non-crystalline substances.

### **Single crystal**

A single crystal, also known as a single-crystal solid or a monocrystalline solid, is a substance that has no grain boundaries and a continuous crystal lattice that extends to the sample's borders. Nanocrystals may possess special mechanical, optical, and electrical characteristics that are anisotropic dependent on the kind of crystallographic structure due to the lack of the defects connected to grain boundaries. In addition to rendering some diamonds valuable, these characteristics have practical uses, particularly within optics and electronics.

Perfect single crystals of significant size are incredibly uncommon in nature because entropic processes encourage the presence of various faults in the micro of solids, such as contaminants, inhomogeneous strain, and crystallographic defects like dislocations. The cost of manufacturing is frequently increased by the required laboratory settings. However, in nature, defective single crystals may grow to huge sizes. For example, it is known that several mineral species, including feldspar, gypsum, and beryl, have created crystals that are several meters wide.

### **Polycrystalline Materials**

Solids called polycrystalline materials are made up of several tiny crystals, or "grains." Grain boundaries divide the grains, which often have variable crystallographic orientations. The granules' sizes might range from a few nanometers to many millimeters. Small nuclei with haphazard crystallographic orientations first develop at various locations in the liquid during in the densification of polycrystalline materials. The atoms in the nearby liquid are absorbed by these nuclei, causing them to develop into bigger crystals. The crystals eventually collide with one another to produce a granulated or polycrystalline structure. An area that has emerged from the nucleus of such a structure with the same crystalline phase is known as a grain.

## Miller Indices

The alignment of a line or series of parallel lines of atoms within a crystal is indicated by a group of three integers called the Miller indices. The Miller indices are calculated by the intersection of the plane with the crystallographic axes. If each atom in the crystal would be represented by a point and these coordinates are attached by lines, the resulting lattice may well be split into a number of identical blocks, or electronic structures; the intersecting edges of the one of the monolayers defines a set of crystalline axes. To obtain the three Miller indices, the place between different of these wiretaps are computed and fractions are removed (hkl). Miller indices, for instance, are (100), (010), or (001) for a plane that is parallel to two axes but only cuts its third axis at a length equal to one edge of a unit cell; a plane that cuts all three factors at lengths corresponding to the edges of an atom has Miller indices of (100), (010), or (001). (111).

## Imperfections or Defects in a Solid

A disorder or flaw is any departure from the harmonious arrangement of a crystal's component components. Therefore, any anomaly in the structure of crystal organization in solids is referred to as an imperfection. Faults grow when crystals grow.

### Point Defects

Point faults describe the many forms of point defects as well as the flaws in solids. Crystalline solids are created by fusing several tiny crystals together. Crystals have a variety of flaws following the crystallization process.

When the crystallization process proceeds at a very rapid pace, point imperfections are taken into account. These flaws are mostly caused by variations in the organization of the constituent particles. A point defect occurs when the perfect configuration of solids in such a crystalline solid is distorted around an atom or nucleus. Line flaws, point defects, volume defects, and surface defects are the four categories into which faults or irregularities in crystalline can be subdivided. Ionic crystals, which were significantly more complex than metal crystals, were historically where crystalline utilizes descriptive were first observed.

### Types of Point Defect

In Point defect the point defect are categories into three categories which are illustrated below:

#### Stoichiometric defect

Stoichiometric defects are inherent flaws in which the molecular formula's representation of the ratios of cations to anions stays precisely the same. They fall into one of two categories: Vacancy defects, which occur when an atom is absent from one of its lattice positions, leaving the site unoccupied and resulting in a vacancy defect. This type of defect are categories into two types

- **Vacancy defect:** The lattice sites become unoccupied and result in a vacancy defect when an atom is indeed not represented there. A substance's density reduces as a result.
- **Interstitial defect:** It is a flaw in crystals when a molecule or atom fills the gaps between molecules. The material becomes denser due to this flaw.

#### Frenkel Defect

Whenever an atom or small ion typically a covalent bond the lattice, leaving a vacancy, and settles in the vicinity to produce an interstitial. The lattice now has a gap as a result. Frenkel

defect is the name given to this kind of flaw. Soviet scientist Yakov Frenkel made the find. It is a particular kind of point defect also referred to as a dislocation defect.

The smaller ion (cation) in ionic solids displaces the larger ion (anions) and fills an intermolecular gap. In this instance, the intermittent defect is encountered at the new place while the vacancy defect is formed at the original position.

1. It also goes by the name "dislocation defect."
2. A substance's density doesn't alter.
3. When there is a significant disparity between the sizes of anions and cations, it occurs.

### **Schottky Defect**

A Schottky hole is a specific kind of leaving group or flaw in solids that results from an empty place being created inside a crystal lattice as a result of atoms or ions travelling from the crystal's interior to its surface.

Ionic Solids include these kinds of vacancy flaws. However, in electrolytes, we must balance the compound's electrical neutrality such that an equal amount of cations and ions will indeed be absent.

1. It lessens the substance's density.
2. Cations and anions in this are approximately the same size.

### **Impurity Defect**

Impurity defects impact the electrical performance of semiconductor, which are the building blocks for circuit boards and other electronic devices. Impurity defects are alien atoms that replace part of the atoms that make up the solid or sneak into the interstices.

### **Non-Stoichiometric Defect**

Since the anion and cation ratios are not equal, and there are numerous both negative and positive electrons present, this non-stoichiometric defect is a sort of point defect. Metal excess deficiency and metal deficient defect are the other two forms of non-stoichiometric defects.

The definition of a solid seems to be self-evident; a solid is commonly regarded to be hard and firm. However, with closer examination, the term becomes less clear. A cube of butter, for one, becomes hard after being refrigerated and is plainly a solid.

The same cube gets rather mushy after a day on the kitchen counter, and it is uncertain if the fat should still be regarded a solid. Many crystals, like butter, are hard at cold pressures but soft at high temperatures. At all temperatures below their melting point, they are referred to as solids. A solid may be defined as an item that preserves its form when not disturbed. The important question is how long the thing retains its form. An extremely viscous fluid can keep its form for an hour but not for a year. A solid must hold its form for a longer period of time.

### **Solid fundamental units**

Atoms or atoms that have bonded to form molecules are the fundamental units of solids. An atom's electrons travel in orbits that create a shell structure around the nucleus. The shells be filled in a methodical sequence, with each shell holding just a few electrons. The amount of electrons in each atom varies, and they are dispersed in a distinctive electronic structure of full and partly filled shells. The chemical characteristics of an atom are determined by the

arrangement of its electrons. Solid qualities are typically foreseeable from the properties of their component atoms and molecules, and the varied shell shapes of atoms are hence responsible for solid variety.

The argon (Ar) atom, for example, has all of its occupied shells filled, resulting in a spherical atomic form. Atoms in solid argon are grouped in the tightest packing of these spheres. In contrast, the iron (Fe) atom contains one electron shell that is only half filled, resulting in a net magnetic moment. As a result, crystalline iron is a magnet. The strongest link discovered in nature is the covalent connection formed by two carbon (C) atoms. This tight connection is what makes diamond a hardest solid.

If a solid exhibits long-range order, it is crystalline. Once the locations of an atom and its neighbours are determined at one point, the exact location of each atom across the crystal is known. Most liquids do not exhibit long-range control, although many do have short-range order. Short range is defined as an atom's first or second closest neighbours. Many liquids have the same arrangement of first-neighbor atoms as the equivalent solid phase. However, when the atoms are separated by numerous atoms, their locations become uncorrelated. Water, for example, has short-range order but no long-range order. Certain liquids may exhibit short-range order in one axis and long-range order in the other; these unique liquids are known as liquid crystals. Solid crystals exhibit both short- and long-range order.

Amorphous solids are those that have short-range order but no long-range organisation. By rapidly solidifying from the melt, almost any material may be rendered amorphous (molten state). This is an unstable state, and the solid will crystallise over time. If the crystallisation timeframe is years, the amorphous state seems to be stable. Glass is an example of an amorphous solid. Each atom in crystalline silicon (Si) is tetrahedrally linked to four neighbours. The same short-range order occurs in amorphous silicon (a-Si), but the bond orientations shift as one moves away from any atom. Glass is a kind of amorphous silicon. Another form of solid that lacks long-range organisation is quasicrystals.

The majority of solid minerals found in nature are polycrystalline rather than single crystals. They are made up of millions of grains (tiny crystals) packed together to occupy every available area. Each grain is oriented differently than its neighbours. Although long-range order occurs inside a grain, the ordering switches direction at the grain border. A typical iron or bronze (Cu) chunk is polycrystalline. Metal single crystals are soft and pliable, but polycrystalline metals are tougher and stronger, making them more valuable in industry. After extensive heat treatment, most polycrystalline materials may be transformed into massive single crystals. Blacksmiths used to heat metal to render it malleable: heat causes a few grains to become huge by integrating smaller ones. The smiths would shape the softened metal and then pound it until it became polycrystalline again, boosting its strength.

### **Crystal classifications**

In general, crystals are classed as insulators, metals, electronics, and molecular solids. An insulator's solitary crystal is normally clear and resembles a piece of glass. Unless corroded, metals are gleaming. Semiconductors may be bright or translucent, but they are never rusted. Many crystals have a single sort of solid behaviour, whereas others have an intermediate behaviour. Cadmium sulphide (CdS) is a great insulator when pure; when impurities are introduced to cadmium sulphide, it becomes an intriguing semiconductor. Bismuth (Bi) seems to be a metal, although it has the same amount of electrons accessible for electrical conduction as

semiconductors. Bismuth is classified as a semimetal. Molecular solids are crystals made up of molecules or polymers. Depending on the sort of molecules in the crystal, they may be insulating, semiconducting, or metallic. New molecules are constantly being created, and many of them are crystallised. The variety of crystals available is tremendous.

Except for helium, all 92 naturally occurring elements may be crystallised under moderate circumstances, and helium can be crystallised at low temperatures requiring 25 atmospheres of pressure. Binary crystals are made up of two different elements. Sodium chloride (NaCl), alumina ( $\text{Al}_2\text{O}_3$ ), and ice are just a few examples of binary crystals ( $\text{H}_2\text{O}$ ). Crystals may also be created by the combination of three or more components.

The elements may be found in a number of crystal packing configurations. Metal lattice structures are most often formed by stacking the atomic spheres into the most compact configuration. There are two such periodic configurations that might exist. The atoms are placed into a plane-triangular lattice in each layer, with each atom having six near neighbours. This configuration is shown in Figure 2 for the atoms designated A.

In the illustration, the second layer is shaded. It has the same plane-triangular structure as the first layer, with the atoms sitting in the holes produced by the first layer. The first layer contains two sets of holes that are equal, but the atoms in the second layer can only occupy one of them. The third layer, called C, has the same structure as the first, but there are two options for determining which holes the atoms will inhabit. The third layer may be put over the first layer's atoms to create an alternative layer sequence. The hexagonal-closest-packed (hcp) structure is represented by ABABAB... This structure is used to crystallise cadmium and zinc. The second option is to arrange the atoms of the third layer over those of neither of the first two layers, but rather over the set of vacant holes in the first layer. The fourth layer is put on top of the first, resulting in a three-layer repeat ABCABCABC..., which is known as the face-centred cubic (fcc), or cubic-closest-packed, lattice. In fcc lattices, copper, silver (Ag), and gold (Au) crystallise. The spheres in the hcp and fcc structures cover 74% of the volume, representing the tightest conceivable packing of spheres. Each atom has twelve neighbours.

A unit cell contains two atoms in hcp structures and one in fcc structures. There are 32 metals with the hcp lattice and 26 with the fcc lattice. The body-centred cubic (bcc) lattice is another possibility, in which each atom has eight neighbours grouped at the corners of a cube. The cubic arrangement of cesium chloride (CsCl) is seen in Figure 3A. It is a bcc lattice if all of the atoms in this structure are of the same species. The spheres take up 68% of the capacity. The bcc arrangement contains 23 metals. Because certain elements are present in two or three of these configurations, the total of these three numbers ( $32 + 26 + 23$ ) surpasses the number of elements that make metals.

### Structures of nonmetallic elements

Covalent bonding is preferred by the elements in the fourth row of the periodic table: carbon, silicon, germanium (Ge), and -tin (-Sn). Carbon may have a variety of crystal forms. Each atom in the covalent bond has four initial neighbours, who are located at the four corners of a tetrahedron. This pattern is known as the diamond lattice, and it is seen in Figure 3C. A unit cell has two atoms and is denoted by the symbol fcc. Large diamond crystals are precious jewels. Other remarkable qualities of the crystal include having the greatest sound velocity of any solid and being the best heat conductor. Aside from diamond, the most prevalent type of carbon is graphite, a layered substance. The honeycomb lattice is formed by each carbon atom having

three coplanar close neighbours. Stacking comparable layers results in three-dimensional graphite crystals. Another kind of crystalline carbon is based on the buckminsterfullerene molecule, which has 60 carbon atoms (C<sub>60</sub>). Spherical is the molecular shape. As in graphite, each carbon is bound to three neighbours, and the spherical form is obtained via a combination of 12 rings with five sides and 20 rings with six sides. R. Buckminster Fuller, an American architect, was the first to envision such structures for geodesic domes. C<sub>60</sub> molecules, often known as buckyballs, are very strong and almost incompressible. The balls in crystals are organised in fcc lattice with a one-nanometer gap between the centres of neighbouring balls. When C<sub>70</sub> molecules are piled together, they create fcc crystal in the shape of a rugby ball. The solid fullerenes form molecular crystals with weak binding between the molecules supplied by van der Waals interactions.

Many elements, including hydrogen (H), oxygen (O), nitrogen (N), fluorine (F), chlorine (Cl), bromine (Br), and iodine, create diatomic gases (I). They solidify into diatomic molecules when cooled to a low temperature. The hcp structure is found in nitrogen, but the structure of oxygen is more complicated.

The crystal structures of elements that are neither metallic, covalent, nor diatomic are the most intriguing. Although boron (B) and sulphur (S) have various distinct crystal structures, each has a common arrangement. Twelve boron atoms combine to create an icosahedron-shaped molecule (Figure 4). The molecules are stacked to create crystals. Boron's -rhombohedral structure has seven of these icosahedral molecules in each unit cell, totaling 84 atoms. Sulfur molecules are often organised in rings, with the most common ring having eight atoms. The most common structure is -sulfur, which comprises 16 molecules or 128 atoms per unit cell. The atoms in common crystals of silicon (Se) and tellurium (Te) are organised in helical chains that stack like cordwood. However, selenium, like sulphur, builds eight-atom rings and crystals from them. Sulfur, like selenium, forms helical chains and stacks them together to form crystals.

### Structures of binary crystals

Binary crystals may be found in a variety of structures. Some element pairings produce more than one shape. Cadmium sulphide may crystallise in either the zinc blende or wurtzite structures at normal temperature. At room temperature, alumina has two potential structures: -alumina (corundum) and -alumina. At various temperatures, other binary crystals have distinct structures. Silicon dioxide (SiO<sub>2</sub>) crystals are among the most complicated, with seven distinct configurations at varying temperatures and pressures; the most frequent of these formations is quartz. Some element pairings generate a variety of crystals with varying chemical valences of their ions. The crystals Cd<sub>3</sub>P<sub>2</sub>, CdP<sub>2</sub>, CdP<sub>4</sub>, Cd<sub>7</sub>P<sub>10</sub>, and Cd<sub>6</sub>P<sub>7</sub> are made up of cadmium (Cd) and phosphorus (P). Only in the first scenario are the predicted chemical valences of Cd<sup>2+</sup> and P<sup>3-</sup> ascribed to the ions.

The binary crystals with an equal amount of the two kinds of atoms are the simplest to perceive. Sodium chloride has a cube-like shape. The sodium and chlorine atoms are arranged on opposite corners of a cube to form the lattice, and the construction is repeated (Figure 3B). The unit cell is defined by the structure of the sodium or chlorine atoms alone, which is fcc. Thus, the sodium chloride structure is composed of two interpenetrating fcc lattices. The cesium chloride lattice (Figure 3A) is based on the bcc structure, with each other atom being either cesium or chlorine. The unit cell in this example is a cube. Zinc blende is the third key structure for AB (binary) lattices (Figure 3D). It is based on the diamond structure, in which every other atom is either A



or B. Many binary semiconductors have this structure, including those with one atom from the third column of the periodic table (boron, aluminium, gallium [Ga], or indium [In]) and one from the fifth (nitrogen, phosphorus, arsenic [As], or antimony [Sb]) (GaAs, InP, etc.). The zinc blende structure is shared by the majority of cadmium and zinc chalcogenides (O, S, Se, Te) (CdTe, ZnSe, ZnTe, etc.). ZnS is the mineral zinc blende, and its unit cell is also fcc. The hcp lattice underpins the wurtzite structure, with every other atom being A or B. Most binary crystals with an equal number of cations and anions have one of these four configurations.

With alkali atoms, the fullerene molecule produces binary crystals  $M_xC_{60}$ , where M is potassium (K), rubidium (Rb), or cesium (Cs). The alkali atoms reside between the fullerene molecules, which keep their spherical form. The subscript x may have a variety of values. A chemical with  $x = 6$  (for example,  $K_6C_{60}$ ) is an insulator containing bcc fullerenes. The case  $x = 4$  is an insulator with a body-centered tetragonal structure, while the case  $x = 3$  is a metal with fcc fullerenes. At low temperatures,  $K_3C_{60}$ ,  $Rb_3C_{60}$ , and  $Cs_3C_{60}$  are superconductors.

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## CHAPTER 10

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### Crystal Defects

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A crystal is never flawless; a multitude of flaws might detract from the arrangement. A defect is a little flaw that affects just a few atoms. A vacancy is the most basic sort of defect, which is a missing atom. Extra atoms cannot be found at the lattice sites of other atoms since all atoms occupy space, but they may be found between them; such atoms are known as interstitials. Thermal vibrations may induce an atom to leave its original crystal site and relocate onto a neighbouring interstitial site, resulting in the formation of a vacancy-interstitial pair. A pure crystal has flaws such as vacancies and interstitials. Another kind of defect, known as an impurity, has an atom that is distinct from the atoms of the host crystal. Impurities may either occupy interstitial gaps or take the place of a host atom in the lattice.

There is no clear differentiation between an alloy and a crystal containing several impurities. When a sufficient amount of impurities that are soluble in the host metal are introduced, an alloy is formed. Most elements, however, are insoluble in most crystals. In general, crystals can tolerate a few contaminants per million host atoms. When too many insoluble impurities are combined, they consolidate to create their own tiny crystallite. These inclusions are known as precipitates, and they represent a significant fault. Germanium is a frequent silicon impurity. It likes the same tetrahedral bonding as silicon and may easily replace silicon atoms. In the same way, silicon is a prevalent contaminant in germanium. There can be no huge crystal without imperfections; the cleanest large crystal ever created was composed of germanium. It included around 1010 contaminants per cubic centimetre of material, which is fewer than one impurity for every trillion atoms.

Crystals are often made more useful by impurities. -alumina is colourless in the absence of contaminants. Impurities like as iron and titanium give it a blue colour, and the resultant gem-quality material is known as sapphire. The red colour typical of rubies, the other gem of -alumina, is caused by chromium impurities. At normal temperature, pure semiconductors seldom conduct electricity properly. Impurities cause their capacity to conduct electricity. In the fabrication of integrated circuits, such contaminants are purposefully introduced to silicon. Impurities in the phosphors generate visible light in fluorescent lights (luminescent materials).

Defect in the crystalline lattice. When there is a missing row of atoms, as seen in area b, an edge dislocation develops. Region and is under stress. Other flaws in crystals include a large number of atoms. Twinning is a form of grain boundary defect that occurs when a crystal is linked to its mirror counterpart. A dislocation is a kind of flaw that is a line defect that may run the length of the crystal. One sort of dislocation is caused by an additional plane of atoms introduced anywhere in the crystal structure. Figure 5 depicts another form of dislocation known as an edge dislocation. This line defect arises when one atom row is missing. The crystal arrangement in the

figure is exquisite on top and bottom. The flaw is the missing row of atoms in area b. This error runs in a perpendicular line to the page, putting pressure on area a.

When a crystal is developed, dislocations arise, and considerable care must be taken to make a crystal devoid of them. Dislocations are permanent and can last for years. They provide mechanical stress relief. When a crystal is pressed, it accommodates the produced stress by producing dislocations at the surface that eventually slide inside. Dislocations increase the mechanical hardness of a crystal. Dislocations and grain boundaries are introduced when a metal bar is cold-worked by rolling or hammering, which produces hardening.

### Identifying crystal structures

Scattering tests employing a part of the crystal as the target discover crystal structures. When a particle beam strikes the target, some of the particles disperse off the crystal and ricochet in different directions. A measurement of the dispersed particles yields raw data, which is then processed by a computer to provide an image of the atomic groupings. The locations are then calculated based on the computer-analyzed data.

Max von Laue proposed in 1912 that this measurement might be performed using X rays, which are high-frequency electromagnetic radiation. Because these waves have a small wavelength, high frequencies are required. Von Laue discovered that atoms are just a few angstroms apart (1 angstrom [Å] is  $10^{-10}$  metres, or  $3.94 \times 10^{-9}$  inch). To detect atomic arrangements, the particles scattering off the target must also have a few angstroms of wavelength. When the beam contains electromagnetic energy, X-rays are necessary.

The X rays only scatter in particular ways, and each direction has several X rays connected with it. The dispersed particles emerge at places where scattering from each identical atom provides an outward wave with all wavelengths in phase. depicts the phase of incoming waves. The scattering route from atom A2 is longer than the distance from atom A1. If the length of this extra route (AB + BC) is an exact multiple of the wavelength, the two outgoing waves are in phase and reinforce each other. When the dispersion angle is slightly adjusted, the waves no longer accumulate coherently and begin to cancel each other. When the scattered radiation from all of the atoms in the crystal is combined, all of the outgoing waves sum coherently in particular directions, resulting in a strong signal in the scattered wave.

If the additional route length (AB + BC) is five wavelengths, the spot appears just once. The location is somewhere else if it is six wavelengths. As a result, the individual spots correspond to different multiples of the X-ray wavelength. The measurement yields two pieces of data: the location of the dots and their intensity. However, this information is inadequate to determine the precise crystal structure since there is no technique that allows the computer to jump straight from the data to the structure. The crystallographer must suggest several structures and calculate how they will scatter the X-rays. The theoretical findings are compared to the observed results, and the theoretical arrangement that best matches the data is selected. Although this method is quick when there are just a few atoms in a unit cell, larger structures might take months or years. Some protein molecules, for example, include hundreds of atoms. Protein crystals are produced, and the structure is determined using X-rays. The aim is to figure out how the atoms in the protein are ordered, not how the proteins are arranged in the crystal.

Neutron beams may also be utilised to determine crystal structure. A neutron beam is created by boring a hole in the side of a nuclear reactor. Nuclear fission produces powerful neutrons, which

escape through the hole. The motion of constituent particles is regulated by quantum mechanics, often known as wave mechanics. The wavelength of each neutron is determined by its momentum. As with X rays, the scattering directions are dictated by the wavelength. The wavelengths of neutrons emitted by a reactor are appropriate for measuring crystal formations.

X-rays and neutrons serve as the foundation for two rival crystallographic methods. Although they are similar in theory, the two approaches vary in significant ways. X-rays scatter from electrons in atoms, therefore the more electrons there are, the more scattering. X-rays can quickly identify atoms with a high atomic number and numerous electrons, but they cannot easily discover atoms with few electrons. X-rays cannot detect protons in hydrogen-bonded crystals. In contrast, neutrons scatter from the atomic nucleus. They are good for evaluating the structure of hydrogen-bonded materials because they scatter quickly from protons. One disadvantage of this strategy is that certain nuclei entirely absorb neutrons, resulting in minimal scattering from these targets.

Because energetic electrons have a wavelength that is suited for such studies, electron beams may also be employed to measure crystal structure. The issue with electrons is that they scatter significantly from atoms. To properly understand the experimental data, an electron must scatter from just one atom and then depart the crystal without scattering again. Low-energy electrons scatter several times, and the interpretation must take this into account. The method of low-energy electron diffraction (LEED) involves directing an electron beam toward the surface. The dispersed electrons that return from the surface are measured. They disperse numerous times before returning backward, but mostly in a few directions that show up as "spots" in the measurements. The crystalline arrangement is revealed by analysing the various places. Because electrons are extensively dispersed by the atoms in the first few layers of the surface, the measurement only provides the atomic configurations in these layers. The same structure is supposed to be replicated throughout the crystal. Another scattering experiment includes very high-energy electrons. The scattering rate reduces with increasing electron energy, therefore extremely energetic electrons generally scatter just once. Several electron microscopes are built on this idea.

### **Ionic bonds**

Ionic bonding occurs in sodium chloride. The sodium atom possesses a single electron in its outermost shell, while chlorine requires one electron. Sodium gives one electron to chlorine, resulting in the formation of a sodium ion ( $\text{Na}^+$ ) and a chlorine ion ( $\text{Cl}^-$ ). As a result, each ion develops a closed outer layer of electrons and takes on a spherical form. Ions in an ionic metal have integer valence in addition to full shells and a spherical form.

A cation is an ion having positive valence. Cations in an ionic solid are surrounded by anions, which have a negative valence. Similarly, cations surround each anion. Because opposing charges attract, the preferred bonding occurs when each ion has as many neighbours as feasible, as determined by the ion radii. Six or eight closest neighbours are normal; the number is determined by the ion size rather than the bond angles. Alkali halide crystals are AH binaries, with A being an alkali ion (lithium [Li], sodium, potassium, rubidium, or cesium) and H being a halide ion (fluorine, chlorine, bromine, or iodine). Ionic bonding exists in the crystals, and each ion has six or eight neighbours. Of ionic crystals, metal ions in the alkaline earth series (magnesium [Mg], calcium [Ca], barium [Ba], and strontium [Sr]) contain two electrons in their outer shells and form divalent cations.

To fill their outer p-shell, the chalcogenides (oxygen, sulphur, selenium, and tellurium) need two electrons. (Electron shells are subdivided into subshells denoted as s, p, d, f, g, and so on. Each subshell is further subdivided into orbitals.) Two electrons are transferred from cations to anions, resulting in each having a closed shell. The alkaline earth chalcogenides, such as barium oxide (BaO), calcium sulphide (CaS), barium selenide (BaSe), and strontium oxide, produce ionic binary crystals (SrO). They have the same structure as sodium chloride, with six neighbours for each atom. Oxygen may be coupled with a wide range of cations to generate a wide range of ionically bound solids.

### Covalent bonds

Covalently bound solids are formed by silicon, carbon, germanium, and a few additional elements. In these elements, the outer sp-shell is half filled with four electrons. (The sp-shell is a hybrid of a s and a p subshell.) A covalent bond occurs when an atom shares one valence (outer-shell) electron with each of its four closest neighbours. The bonds are very directed and like to be arranged in a tetrahedral configuration. Two electrons—one of each atom—located in orbitals here between ions create a covalent connection. Insulators, on the other hand, have all of their electrons contained inside shells within the atoms.

The constant spin of a proton is a crucial property of a covalent bond. Counterclockwise rotation is termed spin-up from a view point above the spinning particle, whereas clockwise rotation is designated spin-down. The Pauli Exclusion Principle, which asserts that no two electrons may occupy the same position in space at the same moment with the same spin orientation, is a basic rule of quantum physics. Because two electrons in a covalent bond always occupy the same little amount of space (i.e., the same orbital), they must have opposing spin: one up and one down. The inclusion principle is then met, resulting in a strong relationship.

Carbon atoms are organised in parallel sheets in graphite, with each atom having just three close neighbours. Bonds refer to the covalent bonds that exist between neighbouring carbons inside each layer. The orbital of the fourth valence electron in carbon is perpendicular to the plane. This orbital forms weak connections with the comparable orbitals from all three neighbours. In the graphite structure, the four bonds for each carbon chain are not grouped in a tetrahedron; instead, three are placed in a plane. The planar structure produces strong bonding, although not as strong as the diamond configuration. The van der Waals interaction causes the bonding between layers to be relatively weak; there is a lot of slippage transverse to the layers. Diamond and graphite contrast interestingly: diamond is the hardest mineral in nature and is employed as an irritant, while graphite is utilised as a lubricant.

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## CHAPTER 11

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### Reason of Frenkel

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Frenkel Defect arises when anions have a substantially greater ionic compound size than cations. Ions sit in the lattice's interstices because of the size disparity between them. Frenkel flaws on ionic crystals do not change their natural state. Because there are the same number of anions and cations. As a result, it may be claimed that ionic materials with significant cation–anion size disparities exhibit Frenkel flaws.

Due to ion migration occurring within the crystal, the Frenkel defect has no effect on the crystal's density, mass, or volume. Therefore, despite possessing a Frenkel defect, the ionic crystal's volume, mass, and volume are unchanged.

### Defect Dislocation Defect

Line flaws called dislocations distinguish slipping from non-slipping crystallographic areas. Similar to how point defects are crucial for diffusion, their motion through glide and climbing is at the heart of deformation in the majority of crystalline materials. Downturns are not equilibrium flaws, in contrast to point defects.

The creation of a dislocation causes a significant change in enthalpy, but a much smaller change in entropy. In a crude example, the former may be compared to the change in enthalpy brought about by the development of  $N$  vacancies, where its vacancies form a row that is the same length as the route. As opposed to the development of  $N$  vacancies that are arbitrarily dispersed throughout a crystal, the production of  $N$  vacancies that are restricted to reside along a line will result in a large reduction in entropy.

### Linear Defect

Line defects, also known as dislocations, are lines where entire rows of atoms are ordered abnormally in a solid. The ensuing spacing irregularity is most pronounced along a line known as line of dislocation. Solids can be strengthened or weakened by line faults. Line defects, also known as dislocations, are lines around which whole rows of atoms are abnormally ordered in a solid. Along a line known as the line of dislocation, the ensuing variation in spacing is most pronounced. Solids may be made stronger or weaker by line faults.

### Edge Dislocations

Edge dislocations is a simple to imagine the edge defect as an entire extra of atoms in some kind of a lattice. Since this locus of faulty points the dislocation produces in the lattice lies along a line, the defect is known as a line defect. The additional half-top plane's is parallel to this line. Only in the immediate region of the dislocation line are the interatomic bonds considerably disrupted.



## Screw Dislocations

Screw dislocation is a second fundamental form of dislocation. A little greater visualization difficulty exists with the screw dislocation. Shear stress also causes a screw dislocation to move, but this time the defect line moves perpendicularly to the direction of a stress and the displacement of the atoms rather than parallel.

## Difference between Edge and Screw Dislocations

a screw displacement moves inside a perpendicular direction to the Burgers direction, whereas an edge dislocation moves in the line of both the Burgers vector. As it passes through the lattice, the screw instability 'unzips' it, forming a 'screw' or helical set of atoms from around core. An extra half-plane of atoms in the middle of the crystal lattice causes the edge dislocation, a type of line defect, to form. In contrast, the screw dislocation is also a type of line defect, but it develops when the jets of atoms in the crystal lattice follow a helical trail around the dislocation line.

## Interfacial defects

External surfaces, intergranular, or stacking faults are examples of interfacial defects, often known as "planar defects." There are two main categories of interfacial defects: grain borders and stacking faults. Polycrystalline materials (where "grains" refers to individual crystals) have grain boundaries. Interfacial flaws are lines that often divide areas of materials with various crystalline structure and/or crystallographic orientations. One of the crystal structure's most evident boundaries is its external surface.

## Bulk or volume defects

Pores, fissures, and foreign intrusions in crystalline materials are examples of bulk or volume flaws. When several point flaws come together to produce a three-dimensional imperfection, pores may develop. The efficiency of material is significantly impacted by these kinds of flaws. Bulk faults are three-dimensional macroscopic flaws. Unlike the tiny flaws, they often happen on a much greater scale. These large flaws are typically added to a materials during manufacturing or refining procedures from its raw condition. These consist of pores, fissures, foreign inclusions, and various stages. Metals can develop fractures during the forging and working processes that function as fatigue cracks and degrade the metal. Bulk faults can also be defined as any flaws in the welding or joining process.

1. Macro- or bulk flaws that are three-dimensional, such pores, fissures, or inclusions.
2. Voids are discrete areas devoid of atoms; they can be seen as collections of vacancies.
3. Small patches of a distinct phase can occur when impurities collect together in a cluster. These are frequently known as precipitates.

Crystallographic imperfections come in the form of line defects. These flaws come in two different varieties: screw and edge dislocations. In contrast to screw dislocation, which happens when atoms within crystal lattice follow a helical path from around dislocation line, edge dislocation happens when an extra half of atoms exists in the center of the crystal. It becomes clear what a dislocation is as a line fault. The dislocation line follows the dislocation's center, which has the most distortion in comparison to the ideal lattice.

Three-dimensional dislocations come in two different flavors. The Burgers vector of an edge dislocation is parallel towards the dislocation line. The simplest way to picture edge dislocations is as an additional atom-filled half-plane. The Burgers vector is perpendicular to the route in a

screw dislocation, making it more complicated. There are also mixed dislocations, in which the Burgers vector forms an acute angle with the dislocation line. Only edge dislocations are capable of existing in a 2D form like the bubble raft. A dislocation can be moved by gliding and climbing. One of two motions are possible for an edge dislocation. An edge dislocation travels conservatively if it moves with in glide plane specified by  $b \perp l$ . The process is neoconservative, however, if an edge dislocation travels perpendicular to its glide plane because lattice molecules were added to or removed from the route by diffusion, causing the dislocation to climb out of its glide plane. Since  $b$  and  $l$  are parallel to one another, a screw dislocation lacks a defined glide plane. A screw dislocation hence often moves along the plane that has the least amount of resistance to its movement.

### **Mechanical Properties of Metals**

The ability of a material to withstand various external pressures, like shear stresses, loads, environmental factors, and time, is known as its mechanical property. The metal's resistance to shearing, stretching, twisting, compression, or breaking under a specific set of circumstances may be measured by mechanical engineers. The parts of a material that respond to an applied load are referred to as its mechanical characteristics. The ability to define a material's resistance to deformation is a crucial aspect of all mechanical qualities.

### **Elastic Deformation**

Elastic deformation is a brief change in a material's structure that returns to its original state once the force or load is removed. When a force is applied within a material's elastic limit, elastic deformation occurs, changing the shape of the substance. This physical characteristic guarantees that ductile materials will expand back to their original size when the applied load has been released. In this case, distortion is temporary and reversible. Metals and ceramics frequently exhibit elastic deformation at low stresses, and their elastic behavior is typically linear.

Metals will deform when subjected to light loads or pressures. Metals revert to their normal form when the imposed stresses are removed. Elastic deformation is the term used to describe this brief deformation of metals. The brief stretching or twisting of links between atoms is referred to as elastic deformation. For instance, just a small percentage of the bonds are twisted or stretched while folding a steel sheet, yet the atoms need not slide past one another. By applying compression stress or tension/compression stress, elastic deformation may result. However, when these forces are high enough to permanently damage the metal, plastic deformation takes place.

The displacement of atoms during plastic deformation results in the breakage of bonds. They may recover from pressure and revert to their regular functions thanks to the deformation of material. However, these qualities deteriorate over time, and under particular circumstances the material might lose its ductility and brittleness. When materials get chilled or are exposed to substances that harden them, they lose some of their pliability. Some softening agents are included in to maintain or improve a material's flexibility. To enable polymer polymers to bend and yield under pressure without significantly changing their form, for instance, specific softening ingredients can be added to the mixture.

### **Plastic Deformation**

When an item undergoes plastic deformation, the applied force causes an irreversible change to its size or shape. The form does not change even after the force has been removed. For instance,

steel rocks may flex. When a material experiences tensile, tensile, bending, or torsion loads that are greater than its yield strength, causing it to stretch, compression, buckle, bend, or twist, this irreversible distortion is known as plastic deformation. There are many different ways that plastic deformation is caused. While still in brittle materials like concrete, rock, and bone, plasticity results from the sliding of micro cracks, dislocations are the cause of plasticity in metals. In metals, there are two main processes for plastic deformation:

- Slip
- Twinning

### **Slip and Twinning**

The primary process of displacement in metals is slip. A slip is the movement of crystal blocks over one another along various crystallographic planes referred to as slip planes. In twinning, a section of the crystals adopts an orientation that is clearly and symmetrically connected to the direction of the remaining untwined lattice. To mound items into the appropriate shape, pressure and warmth are utilized. Rapid material changes are brought on by the rapidity of stress, and occasionally a material that is unable to adapt to structural changes may shatter. Under regulated heat and pressure, plastic deformation is employed in the production of goods, permitting the material to react to structural changes and gradually bending until the desired shape is attained. The ranges of plastic deformation in hard thermo-setting polymers, crystals, and ceramics are quite small.

### **Yield criterion**

Under every combination of stresses, the yield criteria specifies the elasticity limit (or the beginning of plastic flow). A material failure with structural plasticity is described by a yield condition called yield criteria. It specifies the point at which a material transitions from elastic to plastic or hard failure deformations. When designing a structure, it is crucial to choose the right yield criterion.

### **Yield surface**

In the eighth space of stresses, an elastic region is a five-dimensional surface. The surface is typically convex, and the internal stress condition is elastic. The material is considered to have achieved its ductility and has become plastic when the stress condition is on the surface. Even if the size and shape of the yield surface may alter as the deformations progresses, further material deformation causes the maximum stress to remain there.

### **Plastic Deformation of Metals**

Springs are used to study plastic deformation. In order to distinguish between plastic and stretchy materials, the causes of plastic deformation are numerous. Metals exhibit dislocation plasticity, whereas brittle materials such as concrete, stone, and bone exhibit micro crack slippage plasticity. The plastic deformation and tensile stress are dimensional changes that persist even after the originating load is eliminated. If the load exceeds the permitted limit, the body will continue to deform even after the weight has been removed. The solid body deforms when the applied stress reaches the yield stress or elastic limit. This is a result of an atomic level slide or dislocation process.

Understanding certain key and often used terms in the field of plasticity and viscoelastic modelling is required in order to move forward. There are six independent sections to the stress

tensor, which may be divided into cubic (or hydrostatic) and deformation portions. The analogue strains can also be obtained by decomposing the strain tensor similarly. The volumetric tension and stress are mathematically described as the trace of both the stress and tension tensor divided by three. The deviatoric stress results from the differential.

### **Deviatoric energy**

It is crucial to comprehend several key and often used terms in the field of flexibility and viscoelastic modelling in order to move forward. The stress tensor is made up of six separate portions that may be divided into hydrostatic (or hydraulic) and deviator stress parts. Similar to how the strain tensor may be broken down into analogue strains. The volumetric pressure and pressure are mathematically defined as being equal with one of a trace of strain and tension tensor. Deviatoric stress is produced by the difference.

### **Tensile properties of materials**

Tensile testing, which yields a load against elongation curve that is subsequently transformed into a stress vs strain curve, is used to determine the tensile characteristics of various materials. Tensile testing, which is often detailed by a Standard astm test, is typically used to determine the tensile qualities of materials. Tensile characteristics reveal how a material will respond to tension-based pressures. A general machine test called a tensile test involves loading a well prepared specimen under extremely controlled conditions while measuring both applied load and the specimen's elongation over a predetermined distance. Tensile tests are used to identify several tensile qualities such as the elastic limit, yield point, elongation, proportional limit, decrease in area, and modulus of elasticity.

A load against elongation curve from a mechanical testing is the principal output, which is subsequently transformed into a stress vs strain curve. The load-elongation curve will be the same shape as that of the engineering stress-strain curve since the engineering stress and strain are both calculated by dividing the load and elongation by known values (specimen geometry information). Each material has a distinct stress-strain curve that connects the shear load to the resultant strain. Below is a typical industrial stress-strain curve. The stress-strain curve is observed to grow continuously up to fracture if the genuine stress, based on the specimen's actual cross-sectional area, is employed.

### **Linear-Elastic Region and Elastic Constants**

At first, there is a linear rise in the stress and strain. This area of the curve is linear-elastic, and it shows that no deformations has taken place. When the tension is relieved in this area of the curve, the material will take on its original form. In this linear area, whenever the stress-to-strain ratio to strains is a constant, the line follows the relationship known as Hooke's Law. The Young's modulus, or modulus of elasticity, is the slope of this line in this area where stress and strain are proportionate. A material's characteristics under tension, during deformation, and when the stress is removed are determined by its modulus of elasticity (E). It is a way to gauge how stiff a certain material is. Divide the tension by the material's strain to determine the elastic modulus. The flexural will use the same units also as tension, such like kpi or MPa, because strain has no units. Depending on how the material is now being extended, bent, or otherwise deformed, there are several types of moduli. The shear modulus defines the linear-elastic stress-strain connection that whenever a component is subject to pure shear, such as when a cylindrical bar is being torsion ally loaded.

### **Poisson's ratio**

In the two different directions that are right angles to the axial strain, lateral strains of the opposite sign are always present together with the axial strain. Positive (+) strains are those that result in an increase in length, whereas negative (-) strains lead to a reduction in length (-). The inverse of the laterally strain to axial strain ratio for a uniaxial stress condition is known as the Poisson's ratio. The values of axial and lateral strain are occasionally used to define Poisson's ratio.

Since both strain are unitless, this ratio is also unit less. This ratio is roughly constant for stresses inside this elastic range. Poisson's Ratio is 0.25 for a fully isotropic elastic material, however for the majority of materials, the value ranges from the area of 0.28 to 0.33. Poisson's ratio typically has a value of about 0.3 for steels. Accordingly, if there is an inch of deformation for every inch of stress produced, it will result in 0.3 inch of distortion for every inch of force applied in the opposite direction. The bulk modulus (K) and Lamé's constants ( $\lambda$  and  $\mu$ ) are two more elastic constants that may be encountered. When a material piece is under increased pressure on all sides, the aggregate modulus is employed to characterize the condition. The bulk modulus describes the connection between a change in the pressure and the associated strain. The Poisson's ratio and the modulus of elasticity are used to get Lamé's constants.

### **Ultimate Tensile Strength**

The highest engineering stress level attained during a tension test is known as the maximum stress (UTS), or simply the tensile strength. The capacity of a substance to endure foreign environment without breaking is referred to as strength. In brittle fracture, the UTS will be at the elastic limit or towards the end of the spline section of the stress-strain curve. The UTS of the cause's progressive in ductile materials will be substantially beyond the elastic section and within the plastic portion.

The UTS is the highest mountain upon that stress-strain curve above where the line briefly becomes flat. The UTS is frequently not comparable to the breaking strength since it is dependent on the engineering stress. Although the technical stress-strain curve may suggest a decrease in the stress level to before fracture, strain hardening happens in ductile materials and the pressure will continue to rise until fracture occurs. This happens when engineering stress is calculated based on the initial cross-section area without taking into consideration the necking that frequently happens in test specimens.

Although the UTS might not even accurately reflect the maximum amount of stress that such a material can withstand, it is seldom used in the creation of components. The current design standard for ductile metals is to size static components based on yield strength. However, the UTS is helpful for defining a material and also for quality control because it is straightforward to calculate and fairly repeatable. On the other side, the design of a part for brittle materials may be dependent on the material's tensile strength.

### **Yield Strength**

Depending on the yield strength, an item will either be rigid or pliable. It is the moment at which anything turns from elastic to plastic. Based on the requirements, yield strength enables us to select the best materials for the construction. The toys we admire are made of pliable materials like plastic rather than metals since it would be difficult to mould the latter into the unique designs we so adore.

## **Yield point**

In mechanical engineering, the yield point is the load, expressed as a percentage of the original cross-sectional area, at which a solid material begins to flow or permanently change shape. It is also known as the stress present in a solid at the time of permanent deformation. The elastic behavior comes to a halt at the yield point, also known as the elastic limit, and is replaced by plastic behavior. The material recovers to its original form when stresses that are lower than the elastic modulus are eliminated. A number termed yield strength is used in place of the yield point for many substances that lack a clearly defined yield point. The stress where a material has experienced a predetermined degree of permanent deformation often 0.2 percent is known as the yield strength. A few materials begin to flow or yield at a somewhat well-defined stress (the upper yield point), and as deformation progresses, this stress rapidly decreases to a lower stable value (the lower yield point). Beyond the yield point, any stress increase results in increasing irreversible deformation and finally breakage.

## **Diffusion**

Diffusion is the net movement of anyone or anything (for example, atoms, ions, molecules, or energy) from a higher concentration region to a lower concentration region. A gradient in Gibbs free energy or chemical potential drives diffusion. It is possible to diffuse "uphill" from a low concentration zone to a high concentration region, as in spinodal decomposition.

Many domains employ the notion of diffusion, including physics (particle diffusion), chemistry, biology, sociology, economy, and finance (diffusion of people, ideas, and price values). The core principle of diffusion, however, is shared by all of these: a material or collection experiencing diffusion extends out from a place or location where that substance or collection is more concentrated. A gradient is a change in the value of one variable, such as concentration, pressure, or temperature, caused by a change in another variable, generally distance. A concentration gradient is a partial pressure over a distance, a pressure gradient is a change in pressure over a distance, and a temperature gradient is a change in temperature over a distance.

Diffusion is distinguished by the fact that it is based on particle random walk and produces mixing or mass transport without necessitating directed bulk motion. Advection is characterised by bulk motion or bulk flow. Convection is the word used to describe the confluence of two transport processes.

## **Bulk flow**

The movement/flow of a whole body caused by a pressure differential is referred to as "bulk flow" "Diffusion" refers to the progressive movement/dispersion of concentration inside a body caused by a concentration gradient, with no net matter movement. Human breathing is an example of a process that involves both bulk velocity and diffusion. The first step is a "bulk flow" technique. The lungs are placed in the thoracic cavity, which expands during external breathing. This expansion generates an increase in the capacity of the alveoli in the lungs, which results in a drop in alveolar pressure. This causes a pressure differential between air outside the body, which is generally high, and the alveoli, which is comparatively low. The air flows down the pressure gradient via the lungs' airways and into the alveoli until the pressures in the air and the alveoli are equal, at which point the movement of air by bulk flow ceases.

Second, there is a "diffusion" process. The air entering in the alveoli has a greater concentration of oxygen than the "stale" air in the alveoli. The increased oxygen concentration causes an



oxygen concentration gradient between the alveolar air and the blood in the capillaries who surround the alveoli. The oxygen then diffuses down the concentration gradient into the circulation. Another effect of air entering the alveoli is a reduction in the concentration of carbon dioxide in the alveoli. As fresh air contains a very low concentration of carbon dioxide relative to the blood in the body, this generates a concentration for carbon dioxide to diffuse from the blood into the alveoli. Finally, there is a "bulk flow" method. The blood is subsequently transported throughout the body by the heart's pumping function. The volume of the left ventricle of the heart reduces as it contracts, increasing the pressure in the ventricle. This produces a pressure differential between the heart and the capillaries, and blood flows through blood arteries via bulk flow down the gradient.

### **Concept of diffusion**

Diffusion is utilised extensively in physics (particle diffusion), chemistry, biology, society, economics, and business (diffusion of people, ideas and of price values). However, in each scenario, the substance or collection experiencing diffusion is "spreading out" from such a place or location where that substance or collection is more concentrated.

There are two approaches to introducing the concept of diffusion: a phenomenological method based on Fick's equations of diffusion and their mathematical ramifications, or a physical and atomistic approach based on the random walk of diffusing particles. Diffusion, according to the phenomenological method, is the movement of a material from a high concentration zone to a low concentration region without bulk motion. The diffusion flow is proportional to the negative gradient of concentrations, according to Fick's laws. It moves from high concentration areas to low concentration areas. Later, in the context of thermodynamics and non-equilibrium thermodynamics, numerous extensions of Fick's rules were established.

Diffusion is seen atomistically as the outcome of the random walk of the diffusing particles. Moving molecules in molecular diffusion are pushed by heat energy. Robert Brown discovered the random walk of small particles suspended in a fluid in 1827, when he discovered that minute particles suspended in a liquid medium and just large enough to be visible under an optical microscope exhibit a rapid and continuously irregular motion of particles known as Brownian movement. Albert Einstein created the theory of Brownian motion and the atomistic underpinnings of diffusion. The notion of diffusion is often used to any subject matter involving random movements among groups of humans.

Diffusion is the movement of fluid molecules in porous substances in chemistry and materials science. Molecular diffusion occurs when the collision with another molecule is more probable than the collision with the pore walls. Under these circumstances, the diffusivity is proportional to the mean open route, as it is in a non-confined environment. Knudsen diffusion occurs when the pore width is similar to or less than the molecule's mean free route across the pore. The contact with the pore walls becomes more common in this scenario, and the diffusivity decreases. Finally, configurational diffusion occurs when the molecules are of equivalent size to the pore. Diffusivity is substantially lower in this scenario compared to molecular diffusion, and minor alterations in the dynamical diameter of the molecule induce huge differences in diffusivity.

Diffusion is a process that occurs as a consequence of random mobility of molecules and results in a net movement of matter from a high concentration area to a low concentration zone. The aroma of a flower, for example, swiftly pervades the calm air of a room.

Heat conduction in fluids is the movement of thermal energy from a higher to a lower temperature. The operation of a nuclear reactor entails neutron diffusion across a material that generates widespread scattering but only infrequent neutron absorption.

The concentration gradient is found to be related to the flowrates of the diffusing material. If  $j$  is the amount of substance passing through a unit area per unit time reference surface, if the coordinate  $x$  is perpendicular to this reference area, and if the constant of proportionality is  $D$ , the rate of increase of concentration in the direction  $x$ , and the minus sign indicates the velocity of the fluid is from higher to lower concentration.  $D$  regulates the diffusion and is known as diffusivity.

### **Corrosion**

It is essentially described as a natural process that causes pure metals to convert into undesirable chemicals when they mix with substances such as water or air. This reaction produces metal degradation and disintegration, beginning with the exposed region of the metal and progressing to the total mass of the metal.

Corrosion is often an unfavorable phenomena since it interferes with the beneficial qualities of the metal. Iron, for example, is known to have high tensile strength and stiffness. Rusting, on the other hand, causes iron items to become brittle, flaky, and structurally unstable. Corrosion, on the other hand, is a diffusion-controlled process that happens mostly on exposed surfaces. As a result, in certain situations, measures are made to limit the activity of both the exposed surface and raise the corrosion resistance of a material. Passivation, chromate conversion are examples of processes employed. Some corrosion processes, on the other hand, are not always observable and much less predictable. Corrosion may also be classed as an electrolytic method since it often includes redox interactions between the metal and specific atmospheric chemicals such as water, oxygen, sulphur dioxide, and so on.

Metals higher in the reactivity series, such as iron and zinc, corrode quickly, while metals lower in the reactivity series, such as gold, platinum, and palladium, do not corrode. The reason for this is because corrosion requires the combustion of metals.

### **Factors Affecting Corrosion**

- Metals exposed to air containing gases such as  $\text{CO}_2$ ,  $\text{SO}_2$ ,  $\text{SO}_3$ , and oth
- Metals exposed to moisture, particularly salt water (which increases the rate of corrosion).
- The presence of contaminants such as salt (eg.  $\text{NaCl}$ ).
- Temperature: As the temperature rises, so does corrosion
- . The nature of the initial oxide layer formed: Some oxides, such as  $\text{Al}_2\text{O}_3$ , generate an impervious protective layer that prevents further corrosion. Others, such as rust, quickly crumble and reveal the remaining metal.
- Acid in the ambience: Acids may readily increase the rusting process.

### **Rate of Corrosion**

To explain the creation of an oxide layer, the Deal-Grove model is often utilised. This model aids in the prediction and management of oxide layer production in a wide range of conditions. Corrosion may also be measured using the weight loss approach. In this procedure, a clean, weighed piece of metal or alloy is exposed to a corrosive environment for a certain period of

time. The corrosion compounds are then removed during the cleaning procedure. The portion is then weighed to calculate the weight decrease.

The corrosion rate ( $R$ ) is computed as follows:

Where,

$k$  is a constant.

$W$  = metal weight reduction in time  $t$ ,

$A$  = exposed metal surface area,

$\rho$  is the metal's density (in  $\text{g/cm}^3$ ).

## Types of Corrosion

### Crevice Corrosion

A limited kind of corrosion known as crevice corrosion may occur whenever there is a difference in ionic strength between any two small locations of a metal. For example, this kind of corrosion is particularly common in tight places (crevices). Gaskets, the undersurface of nuts, and bolt heads are examples of crevice corrosion-prone locations. Crevice corrosion affects all grades of aluminium and stainless steels. This is mostly due to the establishment of a variable aeration cell, which causes corrosion to occur inside the cracks.

### Stress Corrosion Cracking

Corrosion Due to Stress Cracking, abbreviated as 'SCC,' refers to metal cracking caused by corrosive environments and tensile stresses applied on the metal. It often happens at high temperatures. Stress corrosion cracking of the austenitic stainless steel in chloride solution is one example.

### Intergranular Corrosion

The presence of contaminants in the grain boundaries that divide the grain generated during the crystallisation of the metal alloy causes intergranular corrosion. It may also happen because to alloy depletion or enrichment at these grain boundaries.

IGC, for example, has an impact on aluminum-based alloys.

### Galvanic corrosion

Galvanic corrosion may occur when an electric contact develops between two metals that are electrochemically different and are in an electrolytic environment. It describes the deterioration of one of these metals at a joint or junction. A notable illustration of this form of corrosion is the deterioration that happens when copper comes into contact with steel in a salt-water environment.

When aluminium and carbon steel are combined and submerged in saltwater, the aluminium corrodes quicker while the steel is protected.

### Corrosion of Pitting

Pitting Corrosion is unexpected and hence difficult to detect. It is regarded as one of the most hazardous kinds of corrosion. It begins at a single location and progresses to the production of an oxide layer surrounded by the regular metallic surface. Once established, this 'Pit' continues to

expand and may take on numerous forms. If left uncontrolled, the pit steadily penetrates metal from the surface in a vertical direction, ultimately leading to structural collapse.

Consider a dollop of water on a steel surface; pitting will begin near the water droplet's centre (anodic site).

### **Uneven Corrosion**

This is considered the most prevalent kind of corrosion, in which the environment attacks the metal's surface. The degree of the rusting is readily apparent. This sort of corrosion has a little influence on the material's performance.

A piece of zinc and steel submerged in diluted sulfuric acid would normally dissolve at a consistent pace throughout its whole surface.

### **Grooving with Hydrogen**

This is pipeline corrosion caused by grooves generated by the interaction of a corrosive substance, corroded pipe components, and hydrogen gas bubbles. When the bubbles come into touch with the substance, they normally destroy the protective layer.

### **Metal Dusting**

Metal dusting is a kind of corrosion that happens when sensitive materials are exposed to high-carbon conditions, such as synthesis gas. Corrosion causes the breakdown of bulk metal into metal powder. Corrosion occurs when a graphite layer is produced on the surface of metals from the vapour phase of carbon monoxide (CO). This graphite layer subsequently forms meta-stable M<sub>3</sub>C species (where M is the metal) that typically migrate away from the metal surface. In rare circumstances, no M<sub>3</sub>C species are found. This signifies that the metal atoms have been transported straight into the graphite layer.

### **Microbial Corrosion**

Microbiologically influenced corrosion (MIC), often known as microbial corrosion, is a kind of corrosion induced by microorganisms. Chemoautotrophs are the most frequent. This corrosion may harm both metallic and nonmetallic objects in the presence or absence of oxygen.

### **Corrosion at High Temperatures**

As the name implies, high-temperature corrosion is a form of corrosion caused by heating of materials (mainly metals). A heated environment including gases such as oxygen, sulphur, or other chemicals may cause chemical degradation of metal. These chemicals may quickly oxidise the materials (metals in this example). Materials used in automobile engines, for example, must be able to withstand prolonged durations of high temperatures in an environment containing corrosive combustion products.

### **Prevention of Corrosion**

Corrosion prevention is critical in order to avoid massive losses. Metals are used in the bulk of the buildings we see and utilise. This includes bridges, autos, machines, and home items such as window grills, doors, and railway lines. While this is a serious problem, numerous treatments are available to help reduce or prevent rust to metallic things. This is particularly true for materials that are constantly exposed to the elements, such as seawater, acids, or other harsh conditions. Some prominent corrosion prevention strategies include:

1. Electroplating Galvanization
2. Passivation
3. Anti-Corrosion
4. Protective Coatings Biofilm Coatings
5. Painting and lubrication
6. Application of corrosion inhibitors or drying agents
7. Metal surface cleaning on a regular basis

Corrosion is described as the chemical and electrochemical destruction of metals or alloys by the surroundings damp and humid environment. Corrosion occurs in the presence of O<sub>2</sub> gas, making it an oxidation process. Almost all metals corrode, however the rate of corrosion varies per metal. Corrosion is a spontaneous and irreversible process in which metals generate stable compounds such as oxides, hydroxide ions, and sulphides.

### **Factors Impacting Corrosion**

Metal positions in the electrochemical series - The electrochemical series is important in corrosion. More reactive metals undergo oxidation more rapidly and corrode more quickly. Iron, for example, oxidises readily, but silver does not because gold is less reactive than iron.

Metal impurities - The contaminants in metals often increase the corrosion rate because these impurities operate as a miniature electrochemical cell, causing corrosion.

The presence of electrolytes - Because dissolved salts transmit ions, they act as an electrolyte. The presence of electrolyte in water speeds up corrosion.

The concentration of oxygen - As the concentration of oxygen increases, so does the rate of corrosion. Areas with lower oxygen concentrations serve as anodes, whereas regions with higher oxygen concentrations serve as cathodes. As a result, rusting develops.

Weather humidity - When the weather is humid, the combination of moisture and high temperature accelerates corrosion because ions acquire energy and begin moving quicker in higher temperatures, colliding more often.

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## CHAPTER 12

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### Polymer Degradation

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Polymer degradation is the loss of a polymer's physical qualities, such as strength, due to changes in its chemical makeup. Polymers, especially plastics, degrade at every step of their product life cycle, including original production, usage, disposal into the environment, and recycling. Biodegradation may take decades, but other commercial techniques can totally dissolve a polymer in hours. Technologies to either prevent or promote deterioration have been developed. Polymer stabilisers, for example, guarantee that plastic objects have the necessary qualities, lengthen their useful lives, and make recycling easier. Biodegradable additives, on the other hand, hasten the decomposition of plastic waste by boosting its biodegradability. Some types of plastic recycling include the full breakdown of a polymer into monomers or other compounds.

In general, the most important variables in the deterioration of plastic polymers are heat, light, air, and water. The key chemical changes are oxidation and chain scission, which result in a decrease in the polymer's molecular weight and degree of polymerization. These modifications have an impact on physical qualities like as strength, malleability, melt flow index, appearance, and colour. The changes in attributes are typically labelled "ageing".

Polymer degradation is defined as a change in the qualities of a polymer, such as tensile strength, colour, form, and molecular weight, or of a polymer-based product caused by one or more environmental elements such as heat, light, solvents, or any other applied force.

#### Thermal-Oxidative Degradation

It consists of the active oxygen attacking the polymer; at its core, it is an organic oxidation-reduction process. As with heat degradation, oxygen generates free radicals in the polymerization, which may result in a variety of damaging side reactions. Because of the reactivity of aryl and tertiary carbons, diene or tertiary carbon polymers are the least immune to radical oxygen. This sort of breakdown has been extensively researched in polyolefins and is obviously dependent on O<sub>2</sub> concentration. In the first step, oxygen binds to the vulnerable carbons in the chain, forming a peroxide that decomposes to ethanol or aldehyde.

#### Hydrolytic Degradation

It consists of active oxygen attacking the polymer; at its core, it is an organic oxidation-reduction process. As with heat degradation, oxygen creates free radicals in the polymer, which may lead to a variety of damaging side reactions. Due to the reactivity of aryl and tertiary carbons, diene or tertiary carbon polymers are the least resistant to radical oxygen. This sort of breakdown has been extensively researched in polyolefins and is obviously dependent on O<sub>2</sub> concentration. In



the first step, oxygen binds to the vulnerable carbons in the chain, forming peroxide, which decomposes to acetone or aldehyde.

Biodegradation starts with bacteria and fungus colonising the polymer surface. Surface tension, porosity, and surface roughness all influence bonding to its surface. Because enzymes are less accessible to hydrolyzable groups in compact polymers, they are less biodegradable.

Enzyme-based plastic hydrolysis consists of two steps: The enzymes first connect to the polymer substrate, followed by hydrolytic division. Polymer degradation products, such as oligomers, dimers, and monomers, have very low molecular weight. This oligomer is subjected to a new breakdown by microorganism enzymes. Under aerobic circumstances, bacteria employ oxygen as an electron acceptor, followed by the production of tinier organic molecules, resulting in  $\text{CO}_2$  and water as end products. Microorganisms shatter polymers in the absence of oxygen in anaerobic circumstances. Anaerobic bacteria utilisesulphate, nitrate, iron, carbon dioxide, and manganese as electron acceptors.

### **Thin film**

A thin film is a layer of material that ranges in thickness from fractions of a nanometer (monolayer) to a few micrometres. The controlled production of materials as thin films (also known as deposition) is a critical step in many applications. The home mirror is a well-known example, with a thin metal coating on the back of a glass panel to generate a reflecting contact. Silvering was previously a typical method for producing mirrors, but more recently, the metal layer is created using processes such as sputtering. During the twentieth century, advances in thin film deposition techniques enabled a wide set of technical breakthroughs in areas such as magnetic recording media, electronic semiconductors, integrated passive devices, LEDs, optical coatings (such as antireflective coatings), hard coatings on cutting tools, and energy generation (e.g. thin-film solar cells) (thin-film batteries). Thin-film medication delivery is also being used in pharmaceuticals. A multilayer is a stack of thin films. Thin films are vital in the creation and research of materials with novel and distinctive characteristics, in addition to their application appeal. Multiferroic materials and superlattices, for example, enable the investigation of quantum processes.

### **Adsorption and desorption**

The contact of a vapour atom or molecule with a substrate surface is known as adsorption. The sticking coefficient, or the proportion of entering species thermally equilibrated with the surface, characterises the interaction. Desorption is the process by which a previously adsorbed molecules overcomes the binding energy and departs the surface of the substrate. The intensity of atomic interactions distinguishes the two forms of adsorptions, physisorption and chemisorption. The Van der Waals forces or methods bonding between a stretched or bent molecule and the surface is described by physisorption, which is defined by the adsorption energy  $E_p$ . Evaporated molecules lose kinetic energy quickly and lower their free energy by interacting with surface atoms.

Chemisorption is defined as the strong electron transfer (ionic or covalent link) of a molecule with substrate atoms, which is characterised by the adsorption energy  $E_c$ . The potential energy as a function of distance may be used to depict the process of physisorption and chemisorption. The equilibrium distance for physisorption is greater than that for chemisorption. The effective energy barrier  $E_a$  governs the shift from physisorbed to chemisorbed states.

**Crystal surfaces have distinct bonding sites with bigger molecules.**

These values that would be preferentially filled by vapour molecules in order to lower total free energy. These stable places are often discovered on step edges, voids, and screw dislocations. When the most stable sites have been occupied, the adatom-adatom (vapour molecule) interaction becomes significant.

**Deposition**

Thin-film deposition is the process of putting a thin film to a surface. It refers to any method for depositing a thin film of material upon a substrate or onto previously placed layers. Although "thin" is a relative word, most deposition processes limit layer thickness to tens of nanometres. Molecular beam epitaxy, the Langmuir-Blodgett technique, atomic layer deposition, and molecular layer deposition all allow for the deposition of a single layer of molecules or atoms at a time.

It is used in optics (for reflective, anti-reflection coatings, or self-cleaning glass, for example), electronics (layers of insulators, semiconductor, and conductors create integrated circuits), packaging (for example, aluminum-coated PET film), and modern art (see the work of Larry Bell). Where thickness is not an issue, similar procedures are utilised, such as electroplating for copper purification and CVD-like deposition of silicon and enriched uranium following gas-phase processing.

**Chemical deposition**

A fluid precursor undergoes a chemical transformation at a solid surface, resulting in the formation of a solid layer. The production of soot on a cold item when put within a flame is a common example.

Because the fluid covers the solid object, deposition occurs on all surfaces with little concern for direction; chemical deposition thin films tend to be conformal rather than directional. Chemical depositing is further classified according on the phase of the precursor:

Plating is dependent on liquid precursors, which are typically a solution of water and a salt of the metal to be deposited. Some plating techniques are totally driven by chemicals in the solution (typically for noble metals), although electroplating is by far the most economically relevant process. An improved kind of electroplating known as electrochemical deposition is currently utilised in semiconductor production to manufacture copper conductive wires in advanced chips, replacing the chemical and physical deposition procedures employed in prior chip generations for aluminium wires

Chemical solution deposition (CSD) or chemical bath deposition (CBD) employs a liquid precursor, often an organometallic powder solution soaked in an organic solvent. This is a low-cost, simple thin-film method that yields stoichiometrically correct crystalline phases. Because the 'sol' (or solution) eventually progresses towards the production of a gel-like diphasic system, this approach is also known as the sol-gel method.

The Langmuir-Blodgett technique involves floating molecules on top of an aqueous subphase. The molecular packing density is regulated, and the packed monolayer is transferred to a solid substrate by controlled removal of the solid substrate from the subphase. Thin films of diverse molecules, such as nanoparticles, polymers, and lipids, may be created with controlled particle packing density and layer thickness. Spin coating, also known as spin casting, involves depositing

a liquid or sol-gel precursor onto a smooth, flat substrate, which is then spun at high speeds to centrifugally disseminate the solution across the substrate. The eventual thickness of the deposited film is determined by the speed at which the solution is spun and the viscosity of the sol. Depositions may be repeated as needed to enhance the thickness of films. Thermal treatment is often used to crystallise the amorphous spin coated film. After crystallisation on single crystal substrates, such crystalline films may display certain preferred orientations.

Dip coating is similar to spin coating in that a liquid or sol-gel precursor is placed on a substrate, but the substrate is entirely immersed in the solution and subsequently removed under controlled circumstances. The film thickness, homogeneity, and nanoscopic shape are regulated by regulating the withdrawal speed, evaporation conditions (primarily humidity and temperature), and solvent volatility/viscosity. There are two evaporation regimes: the capillary zone, which evaporates at extremely low withdrawal speeds, and the draining zone, which evaporates at higher rates.

Chemical vapour deposition (CVD) often employs a gas-phase precursor, which is frequently a halide or hydride of the element being deposited. MOCVD employs the utilisation of an organometallic gas. Commercial procedures often use relatively low precursor gas pressures.

As a precursor, an ionised vapour, or plasma, is used in plasma enhanced CVD (PECVD). Unlike the soot example above, commercial PECVD uses electromagnetic techniques (electric current, microwave stimulation) to form a plasma rather than a chemical process.

Atomic layer deposition (ALD), like its sister technology molecular films deposited (MLD), deposits conformal thin films one layer at a time using a gaseous precursor. To achieve complete layer saturation before commencing the next layer, the procedure is divided into two half reactions that are conducted in succession and repeated for each layer. As a result, one reactant is deposited first, followed by the second, and a chemical reaction occurs mostly on substrate, generating the desired composition. Because of the incremental nature of the process, it is slower than CVD, but it may be operated at lower temperatures, unlike CVD.

### **Physical deposition**

Physical deposition creates a thin solid coating using mechanical, electromechanical, or thermodynamic processes. Frost formation is a daily example. Because most engineering materials are held together by relatively high energies and chemical reactions are not used to store these energies, advertisement physical deposition systems typically require a low-pressure vapors environment to function properly; the majority can be classified as physical vapors deposition (PVD).

The material to be deposited is put in an energetic, entropic environment, allowing material particles to escape from its surface. A colder surface faces this source, drawing energy from the particles as they arrive, enabling them to form a solid layer. To enable the particles to migrate as easily as possible, the whole system is maintained in a vapor deposition chamber. Because particles prefer to follow a straight route, films formed by physical methods are often directional rather than conformal.

A thermal evaporator that melts the material and raises its vapour pressure to a desirable range using an electric resistance heater. This is done at a high vacuum to enable the vapour to reach the substrate without interacting with or scattering against other different atoms in the chamber, as well as to decrease impurity incorporation from the remaining gas in the vacuum chamber.

Only materials with much greater vapour pressures than the heating element may be deposited without contaminating the film. Molecular beam epitaxy is a very advanced kind of thermal evaporation.

An electron beam evaporator uses an electron cannon to fire a high-energy beam to boil a tiny patch of substance; since the warming is not uniform, lower vapour pressure materials may be deposited. The beam is often curved at a  $270^\circ$  angle to prevent the gun filament from being directly exposed to the evaporant flow. Typical electron beam evaporation deposition rates vary from 1 to 10 nanometres per second.

Slow streams of an element may be directed towards the substrate in molecular beam epitaxy (MBE), allowing material to deposit one atomic layer at a time. Compounds such as gallium arsenide are often formed by repeatedly depositing a layer of one element (e.g., gallium), followed by a layer of the other (e.g., arsenic), resulting in a chemical as well as physical process; this is also known as atomic layer deposition.

When organic precursors are used, the process is known as molecular layer deposition. The material beam may be produced either physically (through a furnace) or chemically (by a chemical reaction) (chemical beam epitaxy).

Sputtering uses a plasma (often a noble gas like argon) to knock material off a "target" a few atoms at a time. Because the procedure does not include evaporation, the target may be held at a relatively low temperature, making this one of the most adaptable deposition processes. It is particularly beneficial for compounds or mixes in which distinct components would ordinarily evaporate at different speeds.

It should be noted that the step coverage of sputtering is more or less conformal. It's also common in optical media. This process is used in the manufacture of all CD, DVD, and BD formats. It is a quick approach that also gives exceptional thickness control. Nitrogen and oxygen gases are now employed in sputtering.

The ablation technique is used by pulsed laser deposition devices. Pulses of concentrated laser light evaporate the target material's surface and convert it to plasma; this plasma often reverts to a gas before reaching the substrate.

Cathodic arc deposition (arc-PVD) is a kind of ion beam deposition in which an electrical arc creates a blast of ions from the cathode. The arc has a high power density, which results in a high amount of ionisation (30-100%), multiple charged ions, neutral particles, clusters, and macro-particles (droplets). When a reactive gas is injected during the evaporation process, dissociation, ionisation, and excitation may occur during contact with the ion flux, resulting in the formation of a compound film.

Electrohydrodynamic deposition (electrospray deposition) is a revolutionary thin-film deposition method. The liquid to be deposited is supplied through a tiny capillary nozzle (often metallic) that is linked to a high voltage. The substrate on which the film must be placed is grounded. The liquid pouring out of the nozzle adopts a conical form (Taylor cone) under the effect of the electric field, and at the apex of the cone a thin jet emerges, which disintegrates into extremely fine and minuscule positively charged droplets under the influence of the Rayleigh charge limit. The droplets get smaller and smaller until they are deposited on the substrate as a homogeneous thin layer.

## Applications

### Decorative coatings

Thin films' use for ornamental coatings is perhaps its earliest use. This includes 100 nm thin gold leaf that were employed in ancient India around 5000 years ago. It may also refer to any kind of painting, albeit this type of work is often regarded as an art form rather than an engineering or scientific field. Today, thin-film materials with variable thickness and a high refractive index, such as titanium dioxide, are often used for ornamental coatings on glass, resulting in a rainbow-colored effect similar to oil on water. Furthermore, in transparent gold-colored surfaces may be created by sputtering gold or titanium nitride.

### Optical coatings

These layers have use in both reflecting and refractive systems. Large-area (reflective) mirrors were accessible in the nineteenth century, thanks to the sputtering of metallic silver or aluminium on glass. Aberrations, or non-ideal refractive behaviour, are common in refractive lenses used in optical devices such as cameras and microscopes. Previously, enormous sets of lenses had to be lined up along the optical path; however, covering optical lenses with transparent multilayers of titanium dioxide, silicon nitride, or silicon oxide, among other materials, may now correct[dubious - discuss] these aberrations. The few mm broad lens in smart phone cameras is a well-known example of thin-film technology's breakthrough in optical systems. Anti-reflective coatings on eyeglasses and solar panels are two further examples.

### Coatings for protection

Thin coatings are often deposited to shield an underlying work item from outside effects. The protection may function by reducing contact with the external medium in order to minimise diffusion from the medium to the work piece or vice versa. Plastic lemonade bottles, for example, are typically covered with anti-diffusion coatings to prevent the out-diffusion of  $\text{CO}_2$ , into which carbonic acid decomposes after being put into the beverage under high pressure. Another example is thin TiN layers in microelectronic circuits that separate electrically conducting aluminium lines from the embedding insulator  $\text{SiO}_2$  to prevent  $\text{Al}_2\text{O}_3$  production. Thin coatings are often used to shield mechanically moving components from abrasion. Diamond-like carbon (DLC) layers used in automobile engines are examples of the latter use, as are thin films built of nanocomposites.

### Electrically operating coatings

Thin layers of elemental metals such as copper, aluminium, gold, or silver, among others, and alloys have several uses in electrical devices. They can convey electrical currents or provide voltages due to their high electrical conductivity. Thin metal layers are used in traditional electrical systems as Cu layers on printed circuit boards, as the outside ground conductor in coaxial cables, and in numerous other forms such as sensors. Their usage in integrated passive devices and integrated circuits[23], where the electrical network between active and passive devices like as transistors and capacitors is built up from thin Al or Cu layers, became a prominent area of application. These layers have thicknesses ranging from a few hundred nm to a few  $\mu\text{m}$ , and they are often encased in a few nm thin titanium nitride layers to prevent a chemical interaction with the underlying dielectric, such as  $\text{SiO}_2$ . A micrograph of a laterally constructed TiN/Al/TiN metal stack in a microelectronic

Electrons may be bonded to a sub-nanometric layer in heterostructures of gallium nitride and related semiconductors, thereby acting as a two-dimensional electron gas. Quantum effects in such thin films may greatly increase electron mobility as compared to bulk crystals used in high-electron-mobility transistors.

### Perovskite solar cell

Thin layers of elemental metals such as copper, aluminium, gold, or silver, among others, and alloys have several uses in electrical devices. They can convey electrical currents or provide voltages due to their high electrical conductivity. Thin metal layers are used in traditional electrical systems as Cu layers on the printed circuit boards, as the outside ground conductor in coaxial cables, and in numerous other forms such as sensors. Their usage in integrated passive devices and integrated circuits[23], where the electromagnetic network between active and passive devices like as transistors and capacitors is built up from thin Al or Cu layers, became a prominent area of application. These layers have thicknesses ranging from a few hundred nm to a few  $\mu\text{m}$ , and they are often encased in a few nm thin titanium nitride layers to prevent a chemical interaction with the underlying dielectric, such as  $\text{SiO}_2$ .

A micrograph of a laterally constructed TiN/Al/TiN metal stack in a microelectronic device is shown. Electrons may be bonded to a sub-nanometric layer in heterostructures of gallium nitride and related semiconductors, thereby acting as a two-dimensional electron gas. Quantum effects in such thin films may greatly increase electron mobility as compared to bulk crystals used in high-electron-mobility transistors.

Both the raw materials utilised and the production processes available (such as different printing techniques) are inexpensive. Because of their high absorption coefficient, ultrathin films of roughly 500 nm may absorb the whole visible sun spectrum. When these properties are combined, it is possible to produce low-cost, high-efficiency, thin, lightweight, and flexible solar modules. Perovskite solar cells have been used to power prototypes of low-power wireless devices for ambient-powered Internet of things applications, and they may aid in climate change mitigation. The term "perovskite solar cell" is derived from the absorber materials'  $\text{ABX}_3$  crystal structure, also known as the perovskite structure, in which A and B are cations and X is an anion.

A cations with radii ranging from 1.60 to 2.50 Å have been discovered to form perovskite structures. The optical bandgap of methylammonium lead trihalide ( $\text{CH}_3\text{NH}_3\text{PbX}_3$ , where X is a halogen ion such as iodide, bromide, or chloride) varies between 1.55 and 2.3 eV depending on the halide concentration. Formamidinium lead trihalide ( $\text{H}_2\text{NCHNH}_2\text{PbX}_3$ ) has also shown potential, with bandgaps ranging from 1.48 to 2.2 eV. Its lowest bandgap is closer to that of a single-junction cell than methylammonium lead trihalide, hence it should be more efficient. Perovskite was originally used in a solid-state solar cell in a dye-sensitized cell using  $\text{CsSnI}_3$  as a p-type hole transport layer and absorber. [16] The incorporation of lead as a component of perovskite materials is a typical source of worry; solar cells built of tin-based perovskite absorbers such as  $\text{CH}_3\text{NH}_3\text{SnI}_3$  have also been reported, however with inferior power-conversion efficiency.

Perovskite cells have various opt electrical features that make them useful in solar cells. The exciton binding energy, for example, is low. This enables electron holes and electrons to be readily separated upon photon absorption. Furthermore, the charge carrier's long diffusion distance and high diffusivity - the rate of diffusion - enable the charge carriers to traverse extended distances inside the perovskite solar cell, increasing the chances of it being absorbed



and converted to electricity. Finally, perovskite cells have broad absorption ranges and high absorption coefficients, which boost the power efficiency of the solar cell by broadening the range of photon energy absorbed.

Multi-junction solar cells have a greater power conversion efficiency (PCE), allowing them to exceed the thermodynamic limitation imposed by the Shockley-Queisser limit for single junction cells. The presence of several bandgaps in a single cell prevents photons from being lost above or below the band gap energy of a single junction solar cell. PCE of 31.1% has been measured in tandem (double) junction solar cells, rising to 37.9% in triple junction solar cells and 38.8% in quadruple junction solar cells. However, the metal organic chemical vapour deposition (MOCVD) procedure required to create lattice-matched and crystalline solar cells with more than one junction is prohibitively costly, making it a poor option for general deployment.

Perovskite semiconductors provide an alternative that has the potential to challenge the efficiency of multi-junction solar cells while being much cheaper to produce under more common circumstances. All-perovskite tandem cells with a maximum PCE of 31.9%, all-perovskite triple-junction cells with a maximum PCE of 33.1%, and perovskite-Si triple-junction cells with a maximum PCE of 35.3% compete with the double, triple, and quadruple junction solar cells described above. These multi-junction perovskite solar cells, in addition to being cost-effective to produce, also retain high PCE across varied weather conditions, making them applicable globally.

### **Mechanical properties**

Understanding the intrinsic mechanical characteristics of the materials is a primary responsibility in order to produce mechanically robust products. Mechanical characteristics, like those of other 2D materials, are evaluated computationally and validated experimentally.

Nanoindentation is a popular method for determining the mechanical characteristics of 2D materials. The anisotropy in the Young's modulus in multiple plane directions is shown by nanoindentation results in 2D HOIP (100, 001, and 110). [30] Gao et al. discovered that single-crystal  $(\text{C}_6\text{H}_5\text{CH}_2\text{NH}_3)_2\text{PbCl}_4$  possessed mid-range anisotropy in these directions due to crystal structure corner sharing. The direction, which is perpendicular to the inorganic layers, was the strongest. In general, there is a strong association between increasing Pb-X (extremely common cation) bond strength and Young's moduli in many 2D HOIPs. Another nanoindentation investigation discovered that altering the A ion from organic  $\text{CH}_3\text{NH}_3^+$  to inorganic  $\text{Cs}^+$  had minor impact on the Young's modulus, but the Pb-X strength has a dominant influence. [32] Nanoindentation reveals that 2D HOIP structures with thicker and more densely packed inorganic layers have improved Young's moduli and stability due to the increased mechanical stability of the inorganic layers.

Used nanoindentation to evaluate mechanical characteristics on a basic lead iodide system to examine the influence of the number and length of subunits (organic layer) on the out of plane Young's modulus. Due to a transition from covalent/ionic bonding to van der Waals bonding, this research discovered that 2D HOIPs are softer than 3D counterparts. Furthermore, increasing the number of subunits "n" from 1 to 5 raises Young's modulus and hardness until 3D standard values are reached. The length of the organic chain diminishes and the Young's modulus plateaus. When developing perovskites solar cells for specific purposes, these parameters may be modified.

2D HOIP are also vulnerable to the negative Poisson's ratio phenomenon, which occurs when a material contracts laterally when stretched and expands laterally when compressed. This phenomenon is frequent in 2D materials, and the Poisson's ratio in the 2D HOIP chemistry may be adjusted by altering the "X" halide. Because halides with lower electronegativity form weaker bonds with the "B" cation, the negative Poisson ratio increases (in magnitude).

### **Absorption (electromagnetic radiation)**

Transmission is when an electromagnetic wave passes right through an object. If an object is transparent, that's because the light passes through it. So window glass is transparent to visible light. Now, transmitted light can experience two important and related effects. First of all, the waves are often slightly bent.

This is the phenomenon known as refraction. Refraction of light by a glass is the basis of all sorts of eyeglasses and optical devices, and you can see this phenomenon, of course, through a magnifying lens that you bend light, and therefore change the appearance of the object behind that lens. We also use telescopes and microscopes, very important sort of devices. The electrons of the atom prefer to oscillate at certain frequencies. When a light beam of the same natural frequency strikes an atom, the electrons in that atom begin to vibrate. During vibration, incident electron with neighboring atoms in such a way that the vibrational energy is converted into thermal energy. As a result, we may deduce that selective absorption of light happens when the frequency of the light matches the vibration of the electrons in the atoms. Because various atoms and molecules have different inherent frequencies of vibration, they will absorb different frequencies of light waves preferentially.

### **Light Transmission and Reflection**

In contrast to absorption, transmission and light reflection occur when the inherent frequency of electron oscillation does not match the frequencies of incoming light. When a light wave impacts an item in this scenario, the electrons begin to vibrate. The electrons vibrate briefly with a tiny amplitude before re-emitting the energy as a light wave. If the item under investigation is transparent, the electron vibrations are transmitted to neighbouring atoms and re-emitted from of the opposite side of the object. The light is considered to be transferred in such instances. If the item is opaque, the electrons' vibrations are not transferred in bulk; rather, the electrons of the atoms vibrate for a limited amount of time before being re-emitted as a light reflected wave from the object's surface.

The electrons of the atom prefer to oscillate at certain frequencies. When a light beam of the same natural frequency strikes an atom, the electrons in that atom begin to vibrate. During vibration, electrons interact with neighboring atoms in such a way that the vibrational energy is converted into thermal energy. As a result, we may deduce that selective absorption of light happens when the frequency of the light matches the frequency of vibration of the electrons in the atoms. Because various atoms and molecules have different inherent frequencies of vibration, they will absorb different frequencies of visible light preferentially.

In contrast to absorption, transmission and the reflection of light occur when the inherent frequency of electron oscillation does not match the frequencies of incoming light. When a light wave impacts an item in this scenario, the electrons begin to vibrate. The electrons vibrate briefly with a tiny amplitude before re-emitting the energy as a light wave. If the item under investigation is transparent, the electron vibrations are transmitted to neighbouring atoms and re-

emitted from the opposite side of the object. The light is considered to be transferred in such instances. If the item is opaque, the electrons' vibrations are not transferred in bulk; rather, the electrons of the atoms vibrate for a limited amount of time before being re-emitted as a reflected light wave from the object's surface.

Reflection, transmission, and absorption are all modified by the wavelength of the affected light. Thus, these three processes may be measured for either monochromatic radiation (in which case the word "spectral" is appended to the relevant quantity) or a specific kind of colours radiation. The spectral distribution of the incoming radiation must be supplied for the latter. Furthermore, reflectance, transmittance, and absorptance may be affected by the polarisation and geometric distribution of the incoming light, which must be described. The ratio of reflected radiant power to incoming radiant power defines the reflectance  $r$ . The (differential) incident radiant power for a specific area element  $dA$  of both the reflecting surface is provided by the surface's irradiance  $E_e$  multiplied by the size of the surface element, so

The (differential) reflected radiant power is supplied by the exitance  $M_e$  multiplied by the surface element size:

Thus,

$$r = M_e / E_e$$

Total reflectance is further split into regular reflectance  $r_r$  and diffuse reflectance  $r_d$ , which are calculated as the ratios of regularly (or specularly) reflected radiant power to incoming radiant power. It is clear from this definition that

$$r = r_r + r_d$$

The ratio of transmitted incident radiation to incident radiant power defines a medium's transmittance  $t$ . Total transmittance is further split into regular transmittance  $t_r$  and diffuse transmittance  $t_d$ , which are obtained by the ratios of regularly (or directly) transmitted light power to incident radiant power.

$$t = t_r + t_d$$

The ratio of absorbed radiant power to incident radiant power defines a medium's absorptance  $a$ . Reflectance, transmittance, and absorptance are dimensionless since they are defined as ratios of radiant power values.

Electrochemistry is a branch of chemistry that studies the link between electrical energy and chemical reactions. Electrochemical reactions are chemical processes that include the input or creation of electric currents. These responses are roughly categorised into two types:

Electrical energy is used to produce chemical transformation. Specifically, the occurrence of electrolysis. Chemical energy is converted into electrical energy. Specifically, the creation of electricity by spontaneous redox reactions.

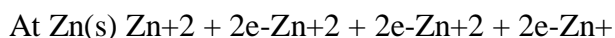
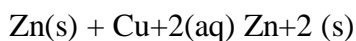
When electrons flow from one element to another in certain kinds of reactions, electricity is created (such as redox reactions). Electrochemistry often deals with the overall reactions that occur when numerous redox reactions occur concurrently, coupled by an external electric current and a suitable electrolyte. To put it another way, electrochemistry is concerned with chemical events involving charge transfer (as seen commonly in liquids such as solutions). Charge transfer

that happens homogeneously or heterogeneously across various chemical species is often involved in charge dissociation.

### Electrochemical Cell

The galvanic cell turns electrical energy from chemical energy, which is acquired via a redox reaction. Both oxidation and reduction occur in different compartments. Each compartment contains an electrolyte solution as well as a metallic conductor that serves as an electrode. Half cells are the compartments that hold the electrode and the electrolyte solution.

For example, a Daniell cell is a galvanic cell that uses zinc and copper to perform a redox reaction.



At the cathode (reduction half)



### Daniell Cell - Galvanic Cell

Salt bridges are inverted U-tubes filled with a concentrated solution of inert electrolytes. It maintains charge balance and completes the circuit by enabling ions to pass through it. It comprises a gel containing inert electrolytes such as  $\text{KNO}_3$  or  $\text{K}_2\text{SO}_4$ . Negative ions flow towards the anode and positive ions flow towards the cathode through the salt bridge, ensuring that the charge balance is maintained and the cell continues to operate.

**Electrode potential:** In a galvanic cell, when two electrodes are dipped in their respective ions, one electrode (anode) has a propensity to oxidise, whilst the ion of the other electrode (cathode) has a tendency to acquire an electron. This propensity to lose electrons (oxidation) or acquire electrons (reduction) is referred to as electrode potential.

**Standard electrode potential ( $E^0$ ):** The electrode potential of an electrode relative to a standard hydrogen electrode under standard circumstances is known as the standard electrode potential. The following are the standard conditions:

Each ion in the solution has a 1 molar concentration. A 298 K temperature. One bar of pressure.

### Series Electrochemical

By comparing the potential of different electrodes vs the standard hydrogen electrode, a series of standard electrodes has been constructed (SHE). The electrochemical series is formed when the electrodes (metals and nonmetals) in contact with their ions are organised based on the values of the standard reduction potentials or standard oxidation potentials.

### Oxidation and reduction

Redox is an abbreviation for reduction-oxidation. It refers to electromechanical processes that involve the transfer of electrons to or from a molecule or ion in order to change its oxidation state. This reaction may be triggered by an external voltage or by the release of chemical energy. The terms oxidation and reduction refer to the changes in oxidation states that occur in the atoms, ions, or proteins involved in an electrochemical process. Formally, the molecular formula is the hypothetical charge that an atom would have if all links to atoms of different elements were completely ionic. The oxidation state of an atom or ion that gives up an electron to another

atom or ion increases, while the oxidation state of the receiver of the negatively charged electron decreases. When atomic sodium combines with atomic chlorine, for example, sodium gives one electron and achieves an oxidation state of +1. Chlorine absorbs the electron, reducing its oxidation state to 1. The sign of the redox potential (positive/negative) correlates to the value of the electronic charge of each ion. The attraction of the oppositely charged sodium mixed chlorine ions causes them to form an ionic bond.

The loss of electrons from a diatomic molecule is referred to as oxidation, whereas the gain of electrons is referred to as reduction. This may be readily recalled by using mnemonic methods. "OIL RIG" (Oxidation Is Loss, Reduction Is Gain) and "LEO" the lion says "GER" are two of the most popular (Lose Electrons: Oxidation, Gain Electrons: Reduction). Oxidation and reduction are always coupled processes, with one species oxidising while another is reduced. For electrons are shared (covalent bonds) between atoms with considerable electronegativity differences, the electron is allocated to the atom with the greatest electronegativity when calculating the oxidation state.

The atom or molecule that loses electrons is known as the reducing agent, or reductant, while the substance that takes electrons is known as the oxidant. Thus, in a reaction, the oxidising agent is always reduced whereas the reducing agent is always oxidised. The most frequent oxidising agent is oxygen, although it is not the only one. An oxidation process, despite its name, does not always need the presence of oxygen. In reality, an oxidant other than oxygen may feed a fire; fluorine flames are often unquenchable because fluorine is an even stronger oxidant (it has a weaker bond and greater electronegativity, and hence receives electrons even better) than oxygen.

In oxygen-containing processes, the gain of oxygen denotes the oxidation of the atom or molecule to which the oxygen is added (and the oxygen is reduced). The loss of hydrogen in organic substances, such as butane or ethanol, suggests oxidation of the molecule from which it is lost (and the hydrogen is reduced). This is due to the fact that hydrogen provides its electron in covalent connections with nonmetals but takes the electron with it when it is removed. Loss of oxygen or gain of hydrogen, on the other hand, signifies decrease.

### **Electrochemical cell**

An electrochemical cell is a device that generates an electric current by using the energy produced by a spontaneous redox reaction. The Galvanic cell or Voltaic cell is a kind of cell named after Luigi Galvani and Luca Volta, two scientists who performed studies on chemical reactions and electric current in the late 18th century.

Two conducting electrodes are used in electrochemical cells (the anode and the cathode). The anode is the electrode where oxidation happens, while the cathode is the electrode where reduction occurs. Any suitably conducting substance, such as metals, transistors, graphite, or even conductive polymers, may be used to create an electrode. The electrolyte, which contains ions that may easily migrate, sits between these electrodes.

The galvanic cell employs two distinct metal electrodes, each immersed in an electrolyte containing positively charged ions that are the oxidized version of the electrode metal. One electrode will be oxidized (the anode), while the other will be reduced (the cathode). The anode metal will oxidise, transitioning from an oxidation state of 0 (in solid form) to a positive oxidation state and becoming an ion. The metal ion in solution will take one or more electrons

from the cathode, reducing the ion's oxidation state to 0. This results in the formation of a solid metal that electrodeposits on the cathode. The two electrodes must be electrically linked to each other, enabling electrons to flow from the metal of the anode to the ions on the cathode's surface through this connection. This flow of electrons creates an electric current, which may be utilised to perform tasks such as turning a motor or lighting a lamp.

A Daniell cell is a galvanic cell with zinc and copper electrodes immersed in zinc sulphate and copper sulphate, respectively

In a Daniell cell, the half reactions are as follows:

Anode made of zinc:  $\text{Zn(s)} \rightarrow \text{Zn}^{2+}(\text{aq}) + 2 \text{e}^{-}$

$\text{Cu}^{2+}(\text{aq}) + 2 \text{e}^{-} \rightarrow \text{Cu(s)}$  copper electrode (cathode)

A contemporary electrochemical research cell stand. The electrodes are connected to high-grade metallic wires, and the stand is connected to a potentiostat/galvanostat (not pictured). A noble gas is used to aerate a shot glass-shaped container, which is then sealed with a Teflon block.

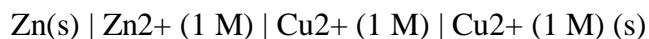
In this case, the anode is zinc metal, which is oxidised (loses electrons) to create zinc ions in solution, while copper ions absorb electrons from the copper metal electrode and deposit as an electrodeposit at the copper cathode. This cell generates a basic battery by spontaneously generating an electric current flow from the anode to the cathode through the external connection. By providing a voltage, this process may be reversed, resulting in the deposition of zinc metal at the anode and the production of copper ions at the cathode.

In addition to the electron conduction channel, an ionic conduction path between the anode and cathode electrolytes is required to produce a full electric circuit. A liquid junction is the most basic ionic conduction route. The liquid connection may be given by a porous stopper that facilitates ion movement while limiting electrolyte mixing to prevent mixing between the two electrolytes. A salt bridge, consisting of an electrolyte saturated gel in an inverted U-tube, may be utilised to further reduce electrolyte mixing. In the electrolyte, when negatively charged electrons flow in one way around this circuit, positively charged metal ions flow in the other direction.

A voltmeter can measure the difference in electrical potential between the anode and the cathode.

The voltage of an electrochemical cell is also known as the electromotive force or emf.

A cell diagram may be used to track the electrons' course in an electrochemical cell. Here's an example of a Daniell cell cell diagram:



First, write the reduced form of the metal to be oxidized at the anode (Zn). This is separated from its oxidised version by a vertical line that marks the phase boundary (oxidation changes). The saline bridge on the cell is shown by the twin vertical lines. Finally, the oxidized form of the metal to be reduced at the cathode is written, with a vertical line separating it from the reduced form. The concentration of electrolytes is mentioned since it is a key variable in calculating the precise cell potential.

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## *Questionnaire for Revision*

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1. What is material science?
2. Explain the scope of Material Science in brief.
3. Define material. State its classification
4. Explain in brief about semiconductor
5. Explain brief about material composition.
6. Explain the nano-materials .
7. Define metals, ceramics, polymers and composites materials.
8. Explain the Nature of bonding in materials
9. Define crystallography. Explain fundamental of crystallography.
10. Explain Defects in crystalline materials
11. Explain Extensive and intensive thermodynamic properties, 1
12. Solidification of pure metals and alloys
13. Explain mechanical properties of metals, ceramics, polymers.
14. Define the term specific heat, heat conduction, thermal diffusivity, thermal expansion, and thermoelectricity.
15. What is electromagnetic radiation?

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## Books for References and further studies

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1. Handbook of Solid State Batteries 2nd Edition edited by Nancy J Dudney, William C West & Jagjit Nanda
2. Crystal Chemistry From Basics to Tools for Materials Creation by Gérard Ferey
3. Innovative Thermoelectric Materials Polymer, Nanostructure and Composite Thermoelectrics edited by Howard E Katz & Theodore O Poehler
4. Industrial Applications of Ultrafast Lasers by Richard Haight & Adra V Carr
5. Materials Concepts for Solar Cells 2nd Edition by Thomas Dittrich
6. Crystal Growth for Beginners Fundamentals of Nucleation, Crystal Growth and Epitaxy (3rd Edition) by Gia Lim Tan
7. Aberration-Corrected Imaging in Transmission Electron Microscopy An Introduction 2nd Edition by Rolf Erni
8. Materials Thermodynamics With Emphasis on Chemical Approach (With CD-ROM) by Hae-Geon Lee
9. Giant Molecules Here, There, and Everywher (2nd Edition) by Alexander Y Grosberg & Alexei R Khokhlov

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