



COMMUNICATION SYSTEM

Ryan Dias
Dr. Sudhir Kumar Sharma



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CHAPTER 1

Introduction to Communication System

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A communications system is a group of communication devices that have been integrated into a logical whole. These make it possible for various individuals to communicate across a geographical system. Response to disasters is one important use. Firefighters, police, and physicians can coordinate their operations with other government authorities thanks to a communications infrastructure [1], [2]. An effective model of communications devices is referred to as a communications system. This may comprise data terminal equipment, broadcasts equipment, network nodes, tributary stations, and more. Even other communication systems may be a part of a communications system. Several cities may react to a crisis by combining the systems they have deployed for their respective police and firemen thanks to a metropolitan emergency reaction communications infrastructure that links them. Communication is sent through a data transmission from its originator to a distant destination. We cannot try to cover every form of application for communication systems, nor can we go into great depth on every component that makes up a particular system. Circuits, electronics, electromagnetics, data analysis, microcontrollers, and communications technology, to mention a few of the related subjects, are only a few of the many components that make up a typical system. A piecemeal approach would also obfuscate the crucial fact that a communication network is an interconnected totality that really transcends the sum of its parts.

So, we approach the topic from a broader perspective. We will look for and isolate the foundations and issues of transmitting information in electrical form, keeping in mind that all communications have the same fundamental purpose of information transmission. These will be thoroughly investigated in order to provide analysis and design techniques suitable for a variety of applications. This essay focuses on communication networks as systems, to put it briefly. Optical communication networks, such as dispersion cables, radio, and even power line telecommunications are examples of communication systems. These many media kinds may be combined and matched by a complex system. Duplex communications is another way to separate the many forms of communication. Both sides are able to interact with each other simultaneously thanks to duplex communications. Examples of operational communications systems include situational networking that enable military troops to safely communicate with central command. Emergency communications systems, such as the U.S. Emergency Alert System (EAS) and outdoor warning sirens, enable authorities and first responders to communicate with one another and the general public.

Over the last 25 years, channel modelling has been at the centre of cellular system design. As a result of their comprehension of fading channel models, system designers and operators were able to maximise the commercial launch of base stations and expand them to accommodate more

users. As a result of recent spectrum allocations, interest in wireless systems is increasing. For instance, new applications such as local area network (LAN) networking and high-speed wireless HDMI are being stimulated by the unlicensed UNII spectrum in the 5- and 60-GHz frequency. Similar to this, innovative designs for mobile high-speed data are encouraged by global allocations of licenced spectrum for WiMAX and Third/Fourth Generation systems. The evaluation of the channel models comes first and foremost when designing digital communications for new frequency bands. A channel model considers the frequency band and its propagation properties, as well as the various usage scenarios whether it is indoors or outdoors, mobile or portable, and whether devices used have a high-gain antenna or a good low-noise amplifier, for example. It also considers the different usage scenarios. The majority of these channel types exhibit some kind of fading statistics, with satellite or fixed wireless broadband employing high-gain antennas perhaps being the exception. The study of fading is still being conducted. Different models will probably be required by new allocations shown below.

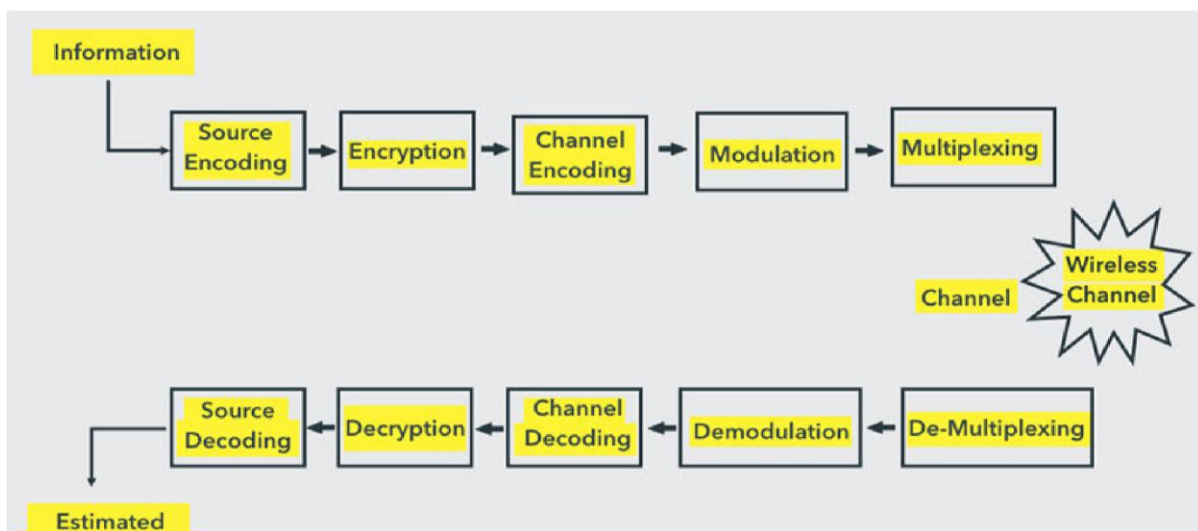


Figure 1.1 shows the different allocation models.

There are several works that go into depth with the temporal and spatial (statistical) aspects of fading; are just a few examples. The book under review, in contrast to previous volumes, focuses on performance assessment methods for wireless systems under fading. The moment generating function (MGF) methodology is highlighted by the authors as a unified technique for assessing the performance of wireless systems. The book demonstrates several instances in which closedform expressions are feasible in terms of the MGF.

The metrics of system performance, fading types experienced by wireless systems, and the fundamental forms of communication are all introduced in the first section of the book (coherent, partially coherent, and noncoherent). The average signal-to-noise ratio (SNR), outage probability (a useful metric for multiuser networks), average bit error probability, degree of fading, and average outage time are among the performance metrics that are highlighted throughout the book. The final two criteria are seldom discussed in other works, despite the fact that the first three are significant and often used.

The top networking layers, in particular the TCP layer, session layer, and sometimes the application layer, are directly impacted by the amount of fade and, more specifically, the average

outage length. Idea these metrics should provide one a fair understanding of how wireless networks run and behave.

Cross-layer research has a lot of potential in this field.

The book covers a wide range of fading types, including multipath characterised by Rayleigh (as assumed in cellular scenarios), a combination of direct line of sight and multipath characterised by Rician (as assumed in most satellite systems or when a user is in direct line of sight to a cellular base station), more complex fading models (such as Nakagami), and blockage (lognormal) fading. This is enough to address a variety of wireless channel modelling applications. For low orbit mobile satellite systems like ICO, Iridium, or Globalstar, I have come across one channel model that does not seem to have made it into the public literature; this model contains a straight line of sight and one extra strong multipath in addition to diffuse scatters. Its absence from the book is unlikely to have a significant impact.

The book's second section focuses on mathematical techniques helpful in performance assessment. The bit error probability calculations over additive white Gaussian noise (AWGN) channels begin with alternate representations of the Gaussian Q-function and the Marcum Qfunction. The conventional method requires difficult integration when fading is taken into account. When the fading statistics are averaged across the different representations, closed-form expressions are possible. The mathematical techniques are then shown by calculating the symbol-error-rate for multiple phase-shift keying (MPSK) modulation in fading channels, followed by helpful expressions seen in bit error probability. In order to assess the bit error probability of MPSK modulation over channel MRC reception, 's development of an intriguing, should have been cited. Expressions for probability density functions for use in correlative fading, specifically for Rayleigh, Nakagami, and log-normal channels, are provided at the conclusion of this section of the book.

The final half of the book deals with a thorough and exhaustive performance assessment for various receptions, many channel models, and the performance metrics mentioned before. For multichannel diversity receivers [maximum ratio combining (MRC), equal gain combining, selection combining, and switching diversity], in particular, the beauty of the MGF technique is shown. The focus of the book is this coverage. There are instances when the standard technique and the MGF approach use different phrases. Also covered are suboptimum receivers, in which it is impossible to derive simple for the MGF technique. The book demonstrates that an MGF approach exists that makes performance assessment simple for a wide range of modulation/detection methods and real-world fading channels. The MGF method includes a unified framework in the majority of these situations, enabling the creation of a collection of general tools that may take the place of case-by-case investigations. In many instances, the resultant expressions are made up of an integrand made up of simple functions and a single integral with limited bounds. The usage of a partial MGF technique to get around a computationally challenging MGF expression with multidimensional integrals in the generalised selection combining situation is also covered in the book.

The first three sections previously mentioned are for uncoded, one user, flat fading communication systems across a range of fading models. Uncoded multiuser communications are covered in the fourth section. To evaluate the effectiveness of co-channel interference limiting, multiuser communication in fading channels, outage probability is a crucial requirement. This section looks at the likelihood of outages for various fading statistics with co-

channel interference and noise. The chance of an outage is then calculated, with an outage being presumed when the signal power to total interference power (S/I) or the signal power to thermal noise power (S/N) falls below the threshold for an outage. The findings in this section account for fading, but they do not include shadowing's effects, which may be added by further averaging. The coverage of optimal combining (OC) caught my attention since I thought it was quite intriguing.

Maximizing signal power to thermal noise power and overall interference power (SINR). It is well known that this method performs more effectively than MRC. For instance, greater channel capacity may be one way this shows up. In slow fading and pure AWGN, adaptive antenna array approaches have been investigated for maximising SINR. In this section of the book, the unified MGF framework is once again used to assess the performance of OC, taking into account issues such channel correlation owing to non-ideal spatial separation and the number of interferers as a function of antenna components. A short chapter on single carrier and multicarrier direct sequence code division multiple access (CDMA) in fading is the book's last section.

The fifth and last chapter of the book discusses fading digital communication using codes. However, only MPSK with trellis-coded modulation is included. This section focuses on determining a union bound by computing the pairwise error probability using the transfer function bound. Included are the two scenarios of perfect channel state information (CSI) and no CSI. The assumption of perfect interleaving throughout yields decision statistics like those obtained with diversity combining in uncoded systems. As a result, programmed memoryless channels may simply implement the unified method utilising MGFs.

There are fewer numerical findings in this section of the book than in the prior ones. Additionally, it doesn't provide a clear contrast with uncoded systems. The portion on multichannel broadcasting, however, seemed straightforward and simple to understand. The thorough description of Alamouti's diversification approach serves as an illustration of this. The foundations of space-time coding and the capacity of fading channels are covered simply and briefly to wrap up this section. This book is quite helpful as a reference but is not meant to be used as a college textbook, in my opinion. When employing the MGF technique, the recipes in the book provide expressions, tools, and a wide range of performance numerical outcomes; the authors make it clear when this is not feasible. Additionally, the book offers a wide range of references.

There are a few nitpicks that may be made. The new version of the book should utilise bit error probability rather than terms like symbol error rate and probability. For references, only one notation should be used. There is a caption for certain plots but not for others. Additionally, I saw that μ was used in place of MGF. Despite these complaints, the work is a valuable and thorough contribution to the literature on communication theory. An automated call distributor is yet another sort of communication system that places calls from outside from organization in a queue and routes them to certain individuals. Normally, call centres notice these. A notion that is maintained in the mind is useless except if and until it is communicated to other people and the public at large. No matter how good the concept, it must be implemented well for it to be useful to everyone. The person has a primary obligation to communicate his ideas and opinions to others.

The communication system makes it possible for humans to successfully transmit ideas or any other crucial information. The original thinker meticulously transforms his thoughts into

comprehensible material that is now prepared to be disseminated with anyone and everyone. The other person who gets the communication from him is known as the receipt or the recipient, and he is repeatedly alluded to as the sender. The communication system allows information to freely flow between the recipient and sender. Information may be exchanged between two people. Information may go from a person to a machine, a machine to another person, as well as between two machines. A kind of communication system is also provided by machines connected by networks that provide signals for people to reply to. For the persons to effectively decode the information, all the devices in the aforementioned situations must operate along the same lines and patterns, be technically compatible, and deliver the same data [3]–[5].

In essence, a communication system aids in the transmission of data over an appropriate medium or channel from one end to the other. The system is divided into two domains in accordance with the direction of communication and reception. The word "communications" broadly refers to the electronic transmission, reception, and processing of information. Beginning with wire telegraphy in the 1840s, communication progressed to include telephony a few decades later and radio around the turn of the 20th century. The research conducted during World War I significantly enhanced radio transmission, which was made possible by the creation of the triode tube. The development of the transistor, integrated circuits, and other semiconductor devices led to an increase in their application and refinement.

Systems for electronic communication

Three different sages that are distinguishable from one another. These might be single words, word clusters, code symbols, or any other ordered parts. The thing that is delivered is the information itself. Depending on how many decisions must be taken, the quantity of information in each particular message may be expressed in bits or dits, which are discussed in Chapter 1. The quantity of information presented increases as the overall number of options increases. It may be sufficient to mention a word is on the top, bottom, left, or right side of this page to identify its location, i.e., two consecutive selections from one of two options. It is now important to specify which of the two pages this term may occur on, and further details must be provided. According to this point of view, just the amount of the information matters, not its meaning (or lack thereof). Realization must be reached that a redundant (i.e., completely predictable) message doesn't really communicate any information. Redundancy is not always a waste of resources. In addition to its obvious use in entertainment, education, and any kind of emotional appeal, it also aids in keeping a message understandable in challenging or loud environments [6]–[12].

Transmitter

The message from the information source won't be acceptable for instant transmission unless it is electrical in nature. Even still, much effort still has to be done to make such a message appropriate. This may be seen in single-sideband modulation, which requires that the entering sound signals be converted into electrical variations before the audio frequencies are constrained and their amplitude range is compressed. All of this is completed prior to modulation. Wire telephony does not need any processing. In long-distance communications, a transmitter is necessary to transform the incoming data into a format that is appropriate for transmission and subsequent reception.

Eventually, in a transmitter, the data superimposes itself over a high-frequency sine wave to modulate the carrier. The exact modulation technique differs from system to system. Depending

on the needs, modulation may be high level or low level, and the system itself may be pulse, frequency, or amplitude modulation, or any variation or combination of these displays a highlevel amplitude-modulated broadcast transmitter of the kind covered in Chapter in more detail. RF crystal buffer amplifiers for RF oscillator voltage and power. Modification Modulation processing voltage power amplifiers with modulation.

Channel-Noise

Shouting is not employed for long-distance communication, and before the invention of the laser, neither was the visual channel. Radio, cable, and fibre optic channels will be considered "communications" in this sense. It is also important to keep in mind that the word "channel" is often used to refer to the frequency range designated for a certain service or transmission, such as a television channel the permitted carrier bandwidth with modulation. As a consequence of system distortion or the introduction of noise, which is unwanted energy that is often random and present in a transmission system owing to a number of factors, the signal will inevitably degrade throughout the process of transmission and reception. The transmission system as a whole is constrained since noise will be received alongside the signal. When noise is bad enough, it may obscure a signal to the point where it's worthless and incomprehensible. Only one source of noise not because there is only one, but rather to make the block diagram simpler.

At any point in a communications system, noise may interfere with the signal, but it will be most noticeable when the signal is weakest. Accordingly, the noise that is most audible is in the channel or at the receiver's input. In communications systems, there are many different types of receivers since the precise design of a given receiver is determined by a wide range of needs. The sort of display needed, which in turn relies on the location of the intelligence received, the operating frequency and its range, and the modulation scheme used are some of the most crucial criteria. Like the straightforward broadcast receiver whose block diagram is illustrated in., most receivers largely adhere to the superheterodyne type [13]–[18]. Receivers come in a wide variety of sophistication. They may be as basic as a crystal receiver with headphones or as complicated as a radar receiver with intricate antenna configurations and a visual display system. No matter the receiver, demodulation is its most crucial feature sometimes also decoding). Both of these procedures, which are covered in the following chapters, are the reverse of the equivalent transmitter modulation procedures.

As was earlier mentioned, the function of a receiver and the nature of its output have an equal impact on its structure as the sort of modulation method used. The output of a receiver may be connected to a computer, pen recorder, television image tube, teletypewriter, loudspeaker, video display unit, and different radar displays. Different arrangements must be made in each situation, each of which has an impact on the receiver design. Keep in mind that the coding and modulation techniques must be compatible between the transmitter and receiver and also timing or synchronization in some systems.

The most popular method of communication up to the development of the technique for superimposing a low-frequency (long-wave) speech information component on a high-frequency (short-wave) carrier signal was a system based on the transmission of a continuous-wave (CW) signal. With this technology, a coded message was produced by intermittently interrupting the transmission (Morse code). Because the CW method needed such extensive training and knowledge on the part of the individuals engaged in sending and receiving the signals, the field was only populated by a small number of professionals.

A whole new age of communications emerged with the advent of modulation, and its effects are still evident today. Now, let's look more closely at the modulation process. When sending messages over a radio channel, there are two alternatives to using a modulated carrier. Either utilise an unmodulated carrier or attempt to deliver the (modulating) signal directly. First, it will be shown that sending the signal itself is impossible. Although it hasn't been covered yet, there are a number of challenges with electromagnetic wave propagation at audio frequencies below 20 kilohertz (20 kHz). The transmitting and receiving antennas would need to be similar in length to a quarter-wavelength of the frequency employed for effective radiation and reception. In the broadcast spectrum, this is 75 metres (75 m) at 1 megahertz (1 MHz), but at 15 kHz, it has grown to 5000 m (or slightly over 16,000 ft)! This large vertical antenna is not practical [19]–[27]. A stronger reason against sending signal frequencies directly is that because all sound is concentrated between 20 Hz and 20 kHz, all signals from all sources would be utterly and irretrievably jumbled together. The transmitting stations alone would entirely cover the "air" in each city, however they only make up a relatively minor part of all active transmitters.

It is important to convert each signal to a distinct region of the electromagnetic spectrum in order to separate the individual signals. Each has to have a unique frequency location. Additionally, this solves the problem of weak radiation at low frequencies. SYSTEMS filters out interference and lowers it. After the signals have been translated, the front end of the receiver uses a tuned circuit to ensure that only the required portion of the spectrum is allowed and all undesirable ones are excluded. In order enable the receiver to pick any desired transmission within a predefined range, such as the very high frequency (VHF) broadcast band used for frequency modulation, the tuning of such a circuit is often made variable and coupled to the tuning control (FM). Although some of the issues with modulation have been resolved by this separation of signals, it is still true that unmodulated carriers of different frequencies cannot be used to convey intelligence on their own.

An unmodulated carrier has a constant phase relationship with regard to a reference, a constant frequency, and a constant amplitude. A message is made up of constantly changing amounts. For instance, the amplitude (volume) and frequency of speech fluctuate quickly and unpredictably (pitch). An unmodulated carrier cannot be utilised to transmit information since it is impossible to express these two variables by a set of three constant parameters. The message alters one of the carrier's characteristics in a continuous-wave modulation system amplitude or frequency modulation, but not pulse modulation. 'As a result, the signal's departure from its unmodulated value resting frequency is proportional to the instantaneous amplitude of the modulating voltage at any given time, and the rate at which this deviation occurs is equal to the signal's frequency. This way, the receiver receives enough details about the instantaneous amplitude and frequency to be able to reproduce the original message.

Requirements for Bandwidth

It makes sense to assume that the frequency range (also known as bandwidth) needed for a certain transmission will depend on how much bandwidth the modulation signals themselves need. A bandwidth of 300 to 3400 Hz is sufficient for a phone call, while a range of 50 to 15,000 Hz is needed for high-fidelity audio signals. A larger bandwidth will be needed for the highfidelity (hi-fi) transmission when a carrier has been modulated identically with each. It is important to note that the transmitted bandwidth need not precisely match the original signal's

bandwidth for reasons related to the modulating systems. In Chapters 3 through 5, this will be made plain.

Knowing the bandwidth used by the modulating signal is crucial before attempting to determine the bandwidth of a modulated transmission. If they are sinusoidal signals, then there won't be any issues; the occupied bandwidth will just be the range of frequencies between the lowest and highest sine-wave signal. However, a considerably more complicated scenario arises if the modulating signals are nonsinusoidal. The frequency requirements of such nonsinusoidal waves will be covered in Section 1-4 since they are used as modifying signals in communications very often.

A sine wave would appear on the CRT screen if the voltage waveform given by this formula were supplied to the vertical input of an oscilloscope. The frequency of the sine wave signal is represented by the symbol f_m , (1-1). The Fourier transform and the Fourier series, which are used to describe periodic time functions in the frequency domain and nonperiodic time domain functions in the frequency domain, respectively, will next be discussed. We shall explain the words of the expressions and provide examples to clarify these subjects in order to further the discussion of bandwidth needs.

A periodic waveform repeats itself and has an amplitude over a certain time T . Sine, square, rectangle, triangular, and sawtooth waveforms are a few examples. A rectangular wave is shown, 1-4 as an example, where A stands for amplitude, T for time, and τ for pulse width. The purpose of this condensed review of the Fourier series is to refresh the student's memory of the since not all waveforms are periodic and knowledge of these nonperiodic waveforms is crucial to the study of communications, the Fourier transform review material is included here. Although a thorough examination and derivation of the series and transform are beyond the purview of this work, the student may find the following review useful in comprehending these ideas: 1-5, Sine in Radians,

It is crucial to understand that any non-sinusoidal wave may be broken down into its component sine waves if it is intended for a communications system to broadcast any non-sinusoidal waves, such as square waves. As a result, the bandwidth needed will be far larger than what may have been predicted based only on the wave's repetition rate. Any nonsinusoidal, single-valued repeated waveform may be proven to consist of sine and/or cosine waves. The repetition rate of the nonsinusoidal waveform is equal to the frequency of the lowest-frequency sine wave, or fundamental, and all other sine waves are harmonics of the fundamental. Such harmonics are infinitely many. A non-sine wave with a 200 Hz repetition rate will have a 200 Hz fundamental sine wave as well as harmonics at 400, 600, 800, and so on [28]–[36].

Only the even or sometimes only the odd harmonics will be present for certain waveforms. The higher the harmonic, the lower its energy level, hence as a general rule, the highest harmonics are often disregarded in bandwidth calculations. Any one of three methods can be used to confirm the aforementioned claim. By using Fourier analysis and possibly graph synthesis, it can be mathematically demonstrated. In this instance, proving the proposition is true by adding the proper sine-wave components using a formula determined by Fourier analysis. This approach also has the additional benefit of allowing us to see the impact that some of the components, such as the higher harmonics, have on the overall waveform.

Finally, a wave analyzer, which is essentially a high-gain tunable amplifier with a restricted bandpass, may be used to tune to each component sine wave and measure its amplitude to show

that the component sine waves are present in the proper proportions. Here are a few formulae for regularly occurring nonsinusoidal waves; handbooks provide more. The nonsinusoidal wave may be expressed as follows if its amplitude is A and its repetition rate is $w/2$ per second: Each time, a number of the harmonics will also be necessary in addition to the fundamental frequency if the wave is to be accurately (i.e., with acceptable levels of distortion) represented. The necessary bandwidth will undoubtedly grow significantly as a result. Following each of the following multiple-choice questions are four options that each include an incomplete statement (a, b, c, and d). Mark the letter that comes before the line that each sentence's right conclusion is on.

1. In a communications system, noise is most likely to interfere with the signal at the transmitter, in the channel, at the information source, and at the receiver.
2. Identify the untrue assertion. A sawtooth wave is composed of fundamental and sub-harmonic sine waves, according to Fourier analysis.
3. A fundamental sine wave and an unlimited number of harmonics C. fundamental and harmonic sine waves, the amplitude of which declines with the harmonic number D. Sinusoidal voltages, some of which are small enough to disregard in practise
4. Identify the untrue assertion. To guarantee that intelligence can be transferred across long distances, to segregate different transmissions, to limit the amount of bandwidth required, and to enable the use of practical antennas, modulation is utilised.
5. Identify the untrue assertion. The signal degradation from the transmitter is often caused by noise that is: unwanted energy predictable in form
6. Present in the transmitter
7. Owing to any source

The majority of receivers belong to one of the following groups: tuned radio frequency receiver group, superhetrodyne group, amplitude-modulated group, and frequency-modulated group. Identify the untrue statement. The following is the best illustration of the need for modulation. Antenna lengths will be around $\lambda/4$ inches long. A common broad-band AM antenna is 16,000 feet in height. The frequency range of all sound is 20 Hz to 20 kHz d. Unpredictable changes in amplitude and frequency make up a message. Identify the actual situation. The sending and receiving process began as early as the middle of the 1930s, 1850, the beginning of the 20th century, and the 1840s. Which of the below processes is not a part of the receiving process? Decoding, encoding, storage, and interpretation are all possible. Plot and add the appropriate sine waves graphically, in each case using the first four components, to synthesise a square wave, a sawtooth wave. List the fundamental functions of a radio transmitter and the corresponding functions of the receiver.

Noise

No matter what their area of expertise, everyone in electronics and telecommunications should be knowledgeable about noise. Noise is created when electrical disturbances interfere with transmissions. It is constant and hinders the functioning of the majority of systems. It is quite difficult to quantify noise and its consequences since practically everyone uses a different approach. You need to be acquainted with the many forms and causes of noise after reading this chapter. Both the techniques for calculating the noise generated by diverse sources and those for

incorporating such noise will be taught. The extremely crucial noise quantities, signal-to-noise ratio, noise, and noise temperature, as well as noise measurement techniques, will have been thoroughly explored.

List at least six distinct noise categories.

Utilizing the text's formulae, determine the noise levels under various scenarios. Show that you are familiar with the formulae behind the signal-to-noise (SIN) concept issues at work involving resistance- and temperature-induced noise. Electrically speaking, noise is any erroneous energy introduction that tends to obstruct the accurate receipt and replication of sent signals.

Numerous electrical disturbances cause receivers to emit noise, which unintentionally modifies the signal. Hissing may be produced by noise in the loudspeaker output of radio receivers. In TV shows, Ryanceives "The word "confetti" or "Inow" (coloured sno") is placed over the image. Noise in pulse communication systems may result in undesired pulses or even cancel out desired pulses. It could result in significant mathematical errors. For a given transmission power, noise may reduce system range. It limits the strength of the weakest signals that may be amplified, which has an impact on the sensitivity of receivers.

There are several methods for categorising noise. Depending on the situation, it may be categorised into several categories based on the nature, source, impact, or relationship to the recipient. It is most practical to categorise the noise into two main categories here: noise that comes from sources outside the receiver and noise that is produced within the receiver. Outside of transferring the system to a different location, there is often nothing that can be done to reduce external noise quantitatively. Take note of the fact that radio telescopes are always situated far from the industry, whose operations produce so much electrical noise. Wherever feasible, international satellite earth stations are placed in quiet valleys. Internal noise is easier to quantify and may be reduced with the right receiver design. It is crucial for everyone involved in communications to be knowledgeable about noise and its consequences since noise has such a limiting influence and because it is often feasible to mitigate its effects via intelligent circuit usage and design. The term "external noise" refers to the many noises produced outside the receiver, including ambient, extraterrestrial, and industrial noise.

Ambient Noise

Listening to shortwaves on a receiver that isn't well suited to receiving them is perhaps the greatest method to get to know atmospheric noise. You'll hear a startling assortment of weird noises that all tend to obstruct the programme. The majority of these noises are caused by erroneous radio waves that cause voltages to be induced in the antenna. Most of these radio waves originate from erratic natural sources. Lightning strikes during thunderstorms and other naturally occurring electromagnetic disturbances in the environment are what produce static. It comes from amplitude-modulated impulses and spreads throughout the majority of the RF band typically utilised for broadcasting since such processes are random in nature. Radio transmissions with components spread over a broad frequency range make up atmospheric noise. Since it travels across the globe in a similar manner to regular radio waves of the same frequencies, static from both nearby and far-off thunderstorms may be picked up at any location on the ground. If the storm is local, the static will probably be more severe but less frequent. Since field strength and frequency have an inverse relationship, this noise will disrupt television reception more so than radio.

The intensity of static from distant sources will fluctuate in accordance with changes in the propagating conditions. Both broadcast and shortwave frequencies typically experience an increase in it at night. Due to two distinct factors, atmospheric noise becomes less severe at frequencies above about 30 MHz. Second, the mechanism that produces this noise is designed in such a way that very little of it is produced in the VHF range and above. It is safe to say that the number of different types of space noise is almost equal to the number of sources.

A division into two subgroups will do for the sake of convenience solar roar We shouldn't be shocked to learn that noise is apparent among them, again there are two sorts, since the radiates so many things our way. Due of the sun's size and extreme heat (about 6000°C on its surface), there is ongoing noise radiation from it even when it is "silent" outside. As a result, it radiates across a very wide frequency range, including those that are used for communications. The sun, however, is a continuously changing star that passes through periods of peak activity from which electrical disturbances like corona flares and sunspots emerge. Even while the extra noise is only coming from a small area of the sun's surface, it may nonetheless be orders of magnitude more intense than the noise you would normally hear from the sun. A supercycle is also observed to be in operation if a line is made to connect these 11-year peaks, with the peaks reaching an even greater maximum every 100 years or so. Finally, the strength of these 100-year peaks seems to be rising. It has been able to date tree growth rings back to the beginning of the eighteenth century since there is a link between solar disturbance peaks and tree growth rings. Evidence suggests that 1957 was not only a peak, but also the greatest peak of its kind ever recorded.

cosmic clamour Since far-off stars are also suns and have high temperatures, they emit RF noise similarly to our sun, making up for their lack of proximity with numbers that, when added together, can have a significant impact. The noise that is picked up is known as thermal (or black-body) noise, and it is dispersed fairly evenly across the entire sky. We also pick up noise from other galaxies, the Milky Way galaxy's centre, and other virtual point sources like "quasars" and "pulsars." Although the sources of this intense galactic noise are only isolated stars, they are still only points in the sky. Cassiopeia A and Cygnus A are two of the most powerful sources, and they were also two of the first discovered. Note that while speaking with radio astronomers, it is not recommended to refer to the prior claims as "noise sources".

In conclusion, space noise is detectable at frequencies between 8 MHz and 1.43 GHz, the latter frequency being associated with the 21-cm hydrogen "line." It is the strongest component throughout the range of about 20 to 120 MHz, apart from artificial noise. At frequencies over 1.5 GHz, its ultimate demise is likely regulated by the processes creating it as well as its absorption by hydrogen in interstellar space. Very little of it reaches the ionosphere below 20 MHz.

Industrial Noise

The intensity of noise produced by people between 1 and 600 MHz (in urban, suburban, and other industrial regions) often surpasses that produced by any other source, whether internal or external to the receiver. This category includes a variety of large electric devices as well as sources such as auto-NOISE 17 mobile and aeroplane ignition, electric motors and switching equipment, leakage from high-voltage lines, and more.

Another potent source of this noise is fluorescent lighting, which is why it should never be used for testing or sensitive receiver reception. Due to the arc discharge present in all of these actions, the noise is created, hence it makes sense that it would be loudest in industrial and heavily

inhabited locations. As proved by Marconi in 1901 in St. John's, Newfoundland, industrial noise caused by spark discharge may, under some circumstances, even cross oceans. Industrial noise is so varied in nature that it is difficult to assess it using anything other than statistical methods. However, it adheres to the basic rule that received noise rises as receiver bandwidth increases.

Domestic Noise

We cover noise produced by any active or passive receiver components under the topic of internal noise. Such noise is often random, cannot be handled on a voltage-by-voltage basis, but is simple to monitor and statistically characterise. There is, on average, the same amount of noise at one frequency as there is at any other since it is randomly spread over the whole radio spectrum. The strength of random noise varies with the measurement bandwidth. Thermal Agitation white, or Johnson noise are all terms for the random noise produced in a resistive component or resistance. It is caused by the molecules atoms and electrons moving rapidly and randomly inside the component itself.

According to kinetic theory, a particle's temperature may be thought of as an expression of its internal kinetic energy in thermodynamics. Therefore, the statistical root mean square (rms) value of the particle velocity of a body is its "temperature." According to the hypothesis, at absolute zero, which is measured in OK (kelvins, previously known as degrees Kelvin) and very nearly equals -273°C , these particles' kinetic energy approaches zero and they stop moving. It becomes clear that the noise produced by a resistor, in addition to being proportional to the bandwidth across which the noise is to be measured, is proportional to its absolute temperature. $P_n \propto T \Delta f$ hence equals $kT \Delta f$, where k is the proper proportionality constant, 1.38×10^{-23} J(joules)/K, or Boltzmann's constant. $K = 273 + ^{\circ}\text{C}$ in this instance when $T =$ absolute temperature [37]–[45].

One may initially believe that there is no voltage to be measured across an ordinary resistor when it is kept at the standard temperature of 17°C (290 K) and is not connected to any voltage source. That is true if using a direct current (dc) voltmeter as the measuring device, but if using a very sensitive electronic voltmeter, it is false. The resistor generates noise, and there may even be a significant voltage applied across it. Only the alternating current (ac) meter will record a reading because it is random and has a finite rms value but no dc component. The current, which is the result of the random movement of electrons inside the resistor, is what generates this noise voltage. It is accurate to say that over any extended period of time, an equal number of electrons arrive at one end of the resistor as do at the other. Because electrons move randomly, there will always be more electrons arriving at one end than the other at any given moment. As a result, both the potential difference between the two ends of the resistor and the rate at which electrons arrive at either end fluctuate arbitrarily. There is undoubtedly a random voltage across the resistor, and it is calculable and measurable.

It is important to understand that any calculations pertaining to random noise only apply to the rms value of the noise, not to its unexpected instantaneous value. All that can be said about peak noise voltages is that they are not likely to be greater than 10 times the rms value. , shows that the square of the terms noise voltage associated with a resistor is proportional to the resistor's absolute temperature, the value of its resistance, and the measurement bandwidth for noise. Particularly noteworthy is the fact that the noise voltage generated is largely unaffected by the measurement frequency. This is due to the randomness of it, which causes it to be uniformly dispersed over the frequency range.

Receivers may produce noise from a variety of sources, not only thermal agitation. The shot effect, which causes shot noise in all amplifying devices and almost all active devices, is the most significant of all the other sources. It manifests as a randomly fluctuating noise current overlaid on the output and is created by random changes in the arrival of electrons (or holes) to the output electrode of an amplifying device. It is intended to sound magnified like a rain of lead shot landing on a metal sheet. Thus, shooting noise gets its name.

Although the different bias voltages control the average output current of a device, the number of electrons arriving at the output electrode at any one moment may be more or smaller. This is mostly caused by the random drift of the discrete current carriers across the junctions of bipolar transistors. Since the routes taken are random, they are not equal. Consequently, even if the collector current is constant on average, there are slight deviations. Shot noise operates similarly to thermal agitation noise, with the exception that its source is different [46]–[54].

Since there are several factors at play while creating this noise in the different amplifying devices, approximate formulas are often used to describe it. For all devices except the diode, shot-noise formulae are often simplified since it may be a bit tricky to add shot-noise current to thermal noise voltage in calculations. The precise formula is $V_{2eip} S_f (2-3)$ for a diode, where e is the charge on an electron, which is equal to $1.6 \times 10^{-19} \text{ C}$, i_P is the direct diode current, and S_f is the bandwidth. System of It can be shown that, only holds true for vacuum tube diodes under so-called temperature limited circumstances, in which the "virtual cathode" has not yet formed. In all other cases, the formula is not only oversimplified but it also does not represent shot-noise current. The most practical way to deal with shot.

To get the value or formula for an equivalent input-noise resistor. This comes before the device, which is now considered to be noiseless, and has a value such that the corresponding system's output has the same amount of noise that the practical amplifier does. It is now simpler to combine shot noise with thermal noise since the noise current has been swapped out for a resistance. As will be shown, it has also been mentioned in relation to the amplifier's input, which is a far more practical location.

The corresponding shot-noise resistance value in most cases, a device's requirements are listed in the manufacturer's specs. There are additional approximate calculations for equivalent shot noise resistances. They all demonstrate that such noise is exactly proportional to output current and inversely proportional to Trans conductance. Regarding the usage of R_{eq} , it's crucial to understand that it is a fake resistance created only for the purpose of making calculations concerning shot noise easier. This resistance is exclusively used for noise generation and is connected in series with the device's input electrode while operating at the same temperature as all the other resistors.

Noise during Transit

The so-called transit-time effect occurs, increasing the transistor's noise input admittance, when the time it takes an electron to move from an emitter to a collector of a transistor becomes significant to the period of the signal being amplified, which occurs at frequencies in the upper VHF range and beyond. At such frequencies, the little currents brought about in the device's input by random variations in the output current become quite significant and produce random noise frequency distortion.

As soon as this high-frequency noise becomes audible, it continues to grow in frequency at a pace that fast reaches 6 decibels (6 dB) per octave, and this random noise then quickly takes precedence over the other types. As a consequence, it is better to measure noise at such high frequencies as opposed to attempting to determine an input equivalent noise resistance for it. The noise levels of radio frequency (RF) transistors are exceptionally low. With transistor amplifiers, noise, s as low as 1 dB are achievable deep into the UHF band.

Different Noise Flicker Transistors exhibit flicker or modulation noise at low audio frequencies, a kind of noise that is poorly understood. It is inversely proportional to frequency above around 500 Hz, although it is inversely proportional to emitter current and junction temperature. It's not as serious anymore. Resistance Transistors also include thermal noise, often known as resistance noise. It is caused by the internal resistances of the base, emitter, and collector, with the base resistance often making the biggest contribution. Transistor noise is largely constant above 500 Hz and up to around $f_{ab}/5$, allowing for the unrestricted use of an equivalent input resistance for thermal and shot noise.

Mixers' noise except at microwave frequencies, when the situation is quite complicated, mixers (nonlinear amplifying circuits) are substantially noisier than amplifiers employing equivalent elements. In mixers, there is a high level of noise that is brought on by two distinct effects. First, the conversion Tran's conductance of mixers is substantially lower than the trans conductance of amplifiers, and second, noise related with the image frequency will be accepted if image frequency rejection is insufficient, as is often the case at shortwave frequencies.

CHAPTER 2

Types of Communication System

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Information or ideas are exchanged between two entities using connectivity. Gathering, transmitting, and processing information are all parts of the communication process, which includes the interchange of both formal and informal input. Employees and managers may communicate with one another within or outside of the company. It might be spoken, nonverbal, written, or pictorial. The essential effective is to communicate ideas, transmit information, and comprehend other things. As a result, information is sent from one location to another, or from the transmitter to the receiver.

System of optical communication

"Optical" is the term for light. The optical communication system relies on light as the communication channel, as the name already indicates. In an optical communication system, the transmitter transforms the data into an optical signal (a signal that is represented by light), which is then sent to the receiver. Following signal decoding, the receiver reacts appropriately. Light aids in the exchange of information in an optical system. The aforementioned idea underlies both helicopter and aero plane safe landings. The pilots choose their next course of action after receiving electronic waves from the base. On the road, a red light signals an instant halt, whereas a green light signals an immediate forward motion [55]–[57]. The optical fiber is used for light transmission in this kind of communication.

When compared to other media, fibre optic cables are much lighter, have a smaller diameter, and can withstand corrosion and rust because of their non-metallic structure. With these qualities, fibre optics tops the list of communication technologies in use today. Our capacity to communicate and convey information quickly from one location to another powers the world we live in. The power of many technologies would be meaningless without a way to transmit data back and forth. Fiber optics is one of the most potent communication technologies available today. Fiber optic communication uses light to carry data instead of electricity, as traditional cables and cabling do. The greatest applications for fibre optic cables are in the fields of telephone, Internet, and television. There are three essential components to any fibre optic system: Cable with a fibre optic transmitter

Receiver

In order to transmit data via a light source, the transmitter translates analogue or digital information into digital pulses. This light source is linked to a fibre optic cable that sends light pulses, or the signal, to the receiver. In order to receive a digital or analogue signal, the receiver contains a light detector that interprets the incoming light pulses and amplifies them.

When compared to alternative data transport techniques, including copper cable, fibre optic communication offers a plethora of advantages.

Speed

To begin with, fibre optics enable data transfer rates that were unheard of in earlier technologies. The maximum data transmission rate for copper Internet connections is about 50 Mbps, whereas fibre optics can easily reach rates of over 1 Gbps and have been successfully tested at speeds over 1000 times this (Pilot Fiber).

Distance

Fiber optics are the best when it comes to transmission distance since they can transfer data tens of kilometres away with very little signal loss. Amplification is quite straightforward and quick to do in the event that a distance results in a considerable signal loss. Interference does not occur since these wires employ light rather than electricity. Electric fields may interfere with normal electrical transmission, but light is unaffected by this kind of interference.

Physical Features

When compared to other media, fibre optic cables are lighter, have a smaller diameter, and are more resistant to corrosion and rust since they are made of non-metallic materials. With these qualities, fibre optics tops the list of communication technologies in use today. Communication infrastructures must keep up as new technologies advance at quicker rates, and fibre optics enable this. Without this technology, the world would be severely constrained, yet fibre optics has opened up a world of possibilities.

System for Radio Communication

A radio is used in the telecommunications system to transmit and receive information. The transmitter and receiver of a radio communication system each have an antenna, which is necessary for the system to function. The transmitter generates signals that are sent through radio carrier waves with the aid of an antenna. The signal is also picked up by the receiver with the use of an antenna. Electronic filters assist in separating electromagnetic radiation from other undesired signals, which are then amplified to the desired level. Some information is unnecessary and must be deleted. In order for people to react appropriately, the signals are finally translated into information they can readily understand.

The market's emergence of new wireless services and goods has significantly boosted the demand for spectral resources recently. The frequency allocation charts, however, show that practically all of the available frequency bands have already been allotted, and the old static spectrum distribution procedures are to blame for gaps in the timing and location of spectrum utilisation in the authorised bands. But it's conceivable that at certain points in time or a specific area, portion of the spectrum allotted to a particular service is not being used, and because of the fixed spectrum allocation method, the other user or service provider is unable to access this unutilized spectrum. Therefore, the issue of spectrum scarcity is caused by the improper use of the assigned spectrum rather than a shortage of spectrum itself.

In, the restrictions of the fixed spectrum allocation based approach are covered in depth. The concepts of dynamic spectrum access (DSA) and opportunistic spectrum access (OSA) have been introduced to address the aforementioned drawbacks of the fixed spectrum allocation scheme. These concepts define a set of techniques and models to support the dynamic

management of the spectrum for wireless communications systems. As a result, cognitive radio emerged as a method to optimise spectrum consumption overall by using spectrum possibilities in both licenced and unlicensed bands. It all begins with the radio frequency (RF) medium being sensed; radios may use data from the wireless environment to keep track of the local and temporal spectrum utilisation.

In order to prevent unwanted interference amongst competing cognitive users, opportunistic users may dynamically choose the appropriate channels and adjust their transmission settings locating the spectrum's unused spectrum. To accomplish optimum frequency band utilisation and establish communication while ensuring that the licenced or principal users of the spectrum are not impacted, it observes, learns, optimises, and intelligently adjusts. While supporting the growing number of services and applications in wireless communication systems, it may operate in numerous frequency bands and make the most use of the scarce radio spectrum.

The Federal Communication Commission (FCC new)'s spectrum licencing procedures, which are more flexible and permit unlicensed (or secondary or cognitive) users to access the spectrum so long as the licenced (primary) users are not interfered with by the unlicensed users, are the driving force behind cognitive radio technology . The usage of the frequency band is much improved by this new approach of spectrum licencing, which also increases the functionality of wireless communication devices. However, multiple standardisation initiatives backed by the IEEE and instructions from spectrum regulatory authorities have increased the potential implementation of cognitive radio networks. The aforementioned standardisation initiatives made some of the spectrum available for opportunistic access and established guidelines for spectrum sharing that could be used for a variety of cutting-edge and promising applications, including smart grid, machine-to-machine, vehicular networks, public safety networks, and emergency networks.

The term "cognitive radio" is defined differently by various research groups, and each community has its own distinctive viewpoint and distinguishing characteristics. Communication theorists believe that cognitive radio is primarily concerned with dynamic spectrum sharing; networking and information technology researchers see it as a device capable of cross-layer optimization; computer scientists see it as a device capable of learning and adapting with presumptive capabilities; and the hardware and radio frequency community frequently sees it as an evolutionary step from Software Defined Radio. The SDR, which operates on various frequency bands without any hardware modifications, is basically where cognitive radio got its basic idea from. However, the user still controls the frequency band and operational settings manually via the software. Contrary to cognitive radio, which is software defined radio with the ability to sense their environment and make decisions such as about modulation scheme, transmission power, etc. without human intervention, the artificial intelligence component for learning and decision making is not available in SDR. A primary network does not understand the activity of a cognitive network and does not need any special capability to cohabit with one.

Because their broadcasts shouldn't harm the main user's quality of service, cognitive users must move quickly in order to change their RF power, rate, codebook, utilised channel, etc. when a primary user is discovered (QoS). Additionally, the cognitive users must coordinate their usage of the available spectrum and channels to prevent conflicts between various cognitive radios. A variety of applications, including television, microwave point-to-point communications, and land mobile radio, have been suggested for the implementation of cognitive radio networks on a

coexisting/shared basis because of their generally underused spectrum and enables the coexistence of television users and cognitive radio users for wireless internet access.

When the television band is not in use, cognitive radio users in rural areas can use it for Internet applications. It is advantageous to have broadband internet access over these television white spaces, as separate broadband network deployment in rural areas might be challenging and expensive otherwise have also reviewed several spectrum sensing methods and briefly examined the spectrum sharing domain. In order to improve spectral efficiency and user fairness, we specifically addressed possible concerns with developing communication system applications in this study.

We also provided a technical review of the state-of-the-art of different spectrum sharing/management strategies. Cognitive users or networks apply the following sharing techniques power control method; game theory; multiple antennas; and medium access control (MAC) protocol. In particular outlines the cognitive radio network's spectrum sharing approach. Additionally, Section 3 describes the various realms of spectrum sharing. Section 4 details the associated research that has been done by scientists to improve the cognitive radio system's throughput and capacity, and Section 5 wraps up the study and considers its potential use in the future.

Model of the system for sharing spectrum

Since wireless channels are shared, cognitive users must coordinate their efforts at transmission. However, the three kinds of primary cognitive radio functions are spectrum sensing, spectrum sharing/management, and spectrum mobility. The authors in have investigated three possible ways, including database registry, beacon signals, and spectrum sensing, to identify the spectrum possibilities using Wireless Netw 123 as a reference and knowledge of frequency band use. The database registry technique uses the GPS (global positioning system) placed on unlicensed devices to pinpoint their location before accessing the principal network's database to find any licenced channels that are open at that specific area.

However, there are some potential issues with the database registry method to identify spectrum opportunities, including: the requirement for a new commercial entity to build and maintain the database; the requirement for cognitive devices to know their locations with prescribed accuracy, which is challenging for indoor GPS-enabled devices; and the requirement for devices to have additional connectivity in a different frequency band in order to be able to access the database prior to any transmission. Additionally, finding unutilized channels inside the service region and unlicensed devices transmitting if they have received a beacon (control) signal provide possible challenges for discovering spectrum gaps with beacon signals. However, in the event of a concealed terminal issue, unlicensed users must wait while the licenced spectrum is not in use until the beacon signal is received. Additionally, the beacon infrastructure must be maintained, either by a licenced operator or by another operator, adding to the overall cost. The spectrum sensing strategy, however, outperforms the other options in terms of finding the unused channel since unlicensed users may do it on their own and there is no need to change the infrastructure of a licenced system. As a result, historical wireless communications systems are compatible with dynamic spectrum access through spectrum sensing.

In many situations, the database registry technique is used in conjunction with the spectrum sensing methodology to determine how the licenced channels are utilised. Spectrum sensing

refers to the ability of cognitive radio to identify the open channels within the pre-existing systems (licensed bands/primary users band), and various aspects of the sensing, including time, space, angle-of-arrival, code, and frequency, have been investigated for full-spectrum awareness. For instance, in the time-dimension, it is necessary to detect the possibility of a particular spectrum band being left unoccupied by licensed users at a specific time; in the space-dimension, it is necessary to detect the possibility of a particular band being left unoccupied by licensed users in a particular geographic area; and in the code-dimension, it is possible for cognitive radio users to use a band even if it is occupied by licensed users in the time, frequency, and space dimensions by using free spreading code or hopping. When a principal user shows up during a cognitive radio conversation, spectrum mobility enables users to move to another unoccupied frequency band.

Spectrum sharing, which is responsible for an effective and equitable spectrum allocation or scheduling solutions among the licensed users and cognitive users, is a critical element of dynamic spectrum access in cognitive radio technology. The main user network and the cognitive user network share the radio airwaves concurrently under the spectrum sharing concept.

The radio spectrum may, however, be opportunistically accessed by unlicensed or cognitive users if it is not completely exploited or occupied by the major users. In other words, the unlicensed user is permitted to use the spectrum and it is transparent to the primary user as long as they do not interfere with them by keeping the collision probability below the specified threshold. The transmissions of cognitive users have little effect on the operational circumstances for which the main user devices are built, therefore such sharing occurs without the primary users being aware of cognitive users. This spectrum sharing concept is appealing because it ensures the coexistence with current legacy systems and improves spectrum access and usage. However, Fig. 1 depicts a number of factors for the cognitive network system model for spectrum sharing, and they are as follows.

Architecture of cognitive radio networks

The design of the cognitive radio network is crucial for allowing several cognitive users to share the licensed spectrum. According to, there are primarily two kinds of cognitive radio network design.

Centralized network for cognitive radio

A central controller, such as a base station, controls spectrum allocation and cognitive users' access to a certain regime of the spectrum in the centralized cognitive radio network. Additionally, all communications between cognitive users are monitored by this central controller, and the cognitive user's choices about spectrum access, such as the length of the spectrum allotment and transmit power, are managed by the central base station.

The central controller must gather data for this reason about the cognitive users' spectrum requirements as well as data regarding the licensed users' spectrum consumption. Based on this data, an ideal solution may be found that increases overall network throughput, offers QoS, lowers latency, etc. All cognitive users in the network are informed of the central controller's choices.

However, there is a significant overhead associated with the information gathering and interchange to and from the cognitive users and the central controller.

Network of distributed cognitive radios

The distributed cognitive radio network enables peer-to-peer communication between cognitive users without the need for a base station or centralized controller. However, the cognitive user has the autonomy and independence to choose their own spectrum access. Each cognitive user's cognitive radio transceiver needs more processing resources than those needed in the centralized network because each cognitive user must gather knowledge about the local radio environment before making a decision. The communications overhead would be less in this scenario, however. Cognitive users may sometimes be taken for relay stations in multi-hop communication.

Spectrum distribution practices

Mutually beneficial spectrum sharing

Using a centralised base station or a shared control channel in either distributed or centralized cognitive radio networks, all cognitive users collaborate with one another under the cooperative sharing scheme. The cooperative spectrum sensing reduces the sensing time while improving the spectrum sensing accuracy, incurs a good degree of fairness, higher complexity, and overhead with an increase in energy consumption.

The cooperative spectrum sensing is performed by cognitive users to share the spectrum with maximum efficiency by exchanging the sensing information with each other. However, only those sensing data that are relevant in establishing the presence of the main user are employed in the cooperative spectrum sensing in order to decrease communication overhead, complexity, and power consumption.

In the cognitive radio spectrum sharing system, the communication overhead is further reduced by clustering, in which the results of the spectrum sensing are pooled and analysed locally by the cluster head. Each cluster's cluster head submits the results to a central controller, who then decides whether to provide channel access.

The simplest method is to use an OR operation between the received sensing results, while weighted data based fusion and other methods have also been proposed for sharing the spectrum by combining the spectrum sensing results of various cognitive users and making decision of sharing spectrum based on the cooperative sensing.

In, the employment of numerous antennas in conjunction with sensing and combining strategies based on maximum ratio combining (MRC) and equal gain combining (EGC) under various fading channels is studied. It is shown that this approach increases the likelihood that main users would be detected.

Spectrum sharing that isn't cooperative

In contrast to cooperative spectrum sharing, there is no information flow between the cognitive users in this approach of spectrum sharing. Although this approach of sharing benefits networks with fewer cognitive users and reduces communication cost, it severely degrades spectrum efficiency in multiuser networks due to the egotistical character of each cognitive user. Since a single user's spectrum sensing data is used to help decide whether to share the primary licenced channel, non-cooperative spectrum sharing has a much higher probability of false alarms than cooperative spectrum sharing, which lowers the performance of either the primary user or the cognitive user.

Techniques for spectrum access

In a shared-use paradigm, the cognitive user may access the spectrum in three distinct ways, including via spectrum interweaving/opportunistic spectrum access, spectrum underlay, and spectrum overlay. Each of these approaches is covered in more depth below.

Spectrum blending and opportunistic access (OSA)

If the main user of the spectrum is not using it at a specific moment, frequency, or location, the cognitive users may opportunistically access it with the aid of spectrum depicts the model of the spectrum sharing system for the Wireless Newt network access method used in the cognitive radio communication system. Therefore, the cognitive user must do spectrum sensing to find the activity of a main user in that regime in order to access the regime of spectrum using the spectrum interweave approach.

The cognitive users may access the unutilized spectrum if an inactive main user spectrum hole is discovered, as illustrated in the cognitive users must leave the spectrum once the major user commences transmission. Cognitive radio employs the spectrum interweave technique in orthogonal frequency division multiplexing (OFDM), time division multiple access (TDMA), and frequency division multiple access (FDMA) wireless communication systems.

Underlay spectrum

As seen in the cognitive users transmit alongside the main user in the spectrum underlay access technique. To ensure that the interference generated by cognitive users to the primary users stays below the interference temperature limit, the transmit power of cognitive users should be restricted.

The interference limit established at the main user's receiver up to which it may tolerate interference without impairing function is known as the interference temperature. For cognitive radio systems using code division multiple access (CDMA) or ultra-wide band (UWB) technology, the spectrum underlay approach is utilized. As a result, the spectrum underlay access approach does not need spectrum sensing to find the spectrum hole for cognitive users transmission, but it does require a threshold level to prevent interference.

Spectrum encl.

The contemporaneous main and cognitive user's transmission is permitted in the spectrum overlay mode of the spectrum access method, as illustrated in help to reduce interference at the secondary and main receiver. Although the spectrum overlay is a viable method for sharing the spectrum, it requires close coordination with key users and an understanding of their communication signals.

Additionally, by using a portion of the primary user's power for this approach and the remainder for its own data transmission, the cognitive user aids in relaying the information of the primary user. As a consequence, the main user's increased SNR from relaying is offset by the primary user's decreased SNR from cognitive user interference, resulting in the same SNR at the primary receiver without cognitive user. As a result, the cognitive user's existence is unknown to the main user. Cognitive transmitter use dirty paper coding to minimize interference at cognitive receiver shown below.

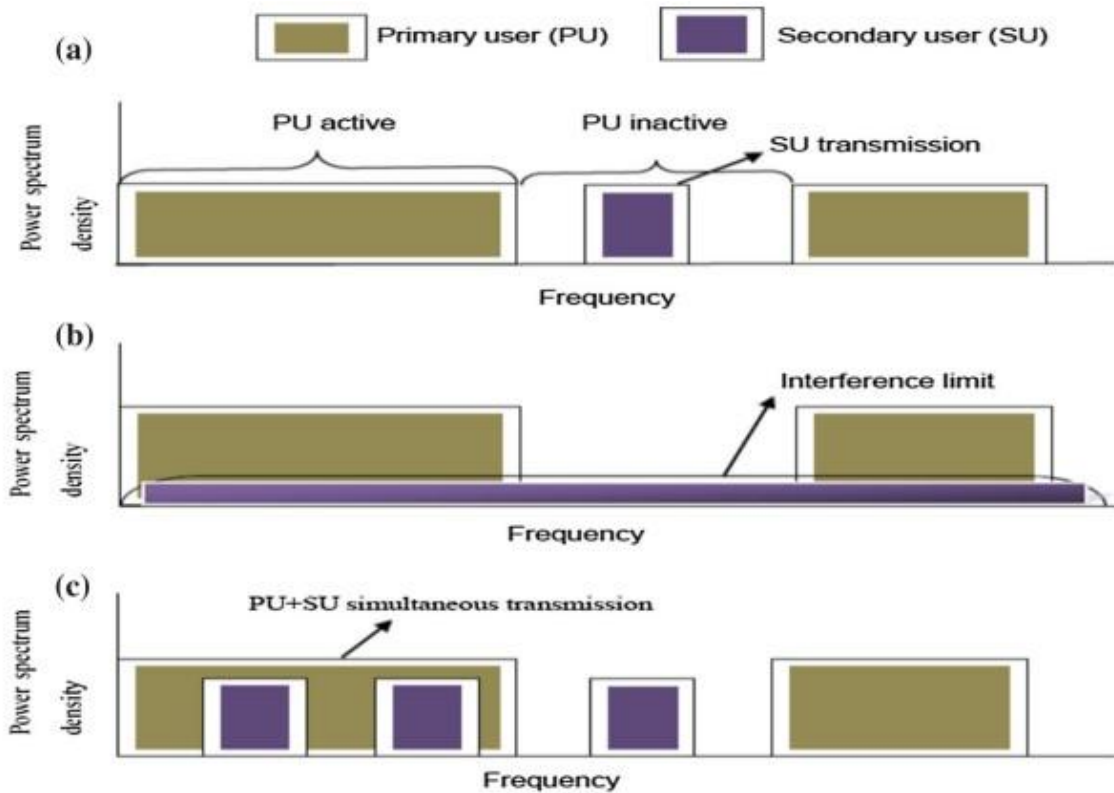


Figure 2.1 shows the interference at cognitive receiver.

System for duplex communications

Due to the simultaneous communication of two pieces of equipment in both directions, duplex communications systems get their name. You may both hear another other at the exact same time when you talk to your buddy on the phone. The transmitter delivers the signal to the receiver, who receives them immediately and provides the speaker with crucial feedback so that he may reply. Therefore, the person speaking and the receiver really communicate at the same time. Two devices may communicate simultaneously when using the duplex communication technology. In one form of communication system, the sender is responsible for transmitting signals, while the receivers are just required to listen to them and reply appropriately. Simplex communication system is another name for this kind of communication [2], [58].

System for Half-Duplex Communication

Both sides cannot connect at the same time in a half-duplex system. Only the receiver may reply once the sender stops delivering signals to that person. A walkie talkie uses a half-duplex communication mechanism to communicate. When speaking to one another, military personnel must first announce "Over" before the other person may reply. When the other person to talk, he must properly pronounce the security code. Until the data is full and accurate, the opposite side will not communicate.

System of Tactical Communication

The tactical way of communication is an additional method. According to changes in the surrounding circumstances and other factors, communication in this form fluctuates. All of the

communication methods mentioned above serve the same purpose, which is to send information from one side to the other. The numerous communication system models enable us to comprehend the path that abilities to manage out from provider to the receivers via a particular channel.

CHAPTER 3

Power Control

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Power Management

The administration of protocol as well as a trustworthy and scalable method that enables a cognitive user to obey the rules are necessary. Cognitive radios must abide by the rules and constraints in order to access the spectrum. However, if the protocols are broken, then power control strategies that are proactive and reactive are utilised to stop this bad conduct. A proactive strategy contains a regulation (such as a maximum power restriction) and an enforcement mechanism (such as power allocation), but it is implemented before cognitive radio users begin acting inappropriately, or before they violate the spectrum access rules. On the other hand, the misbehaving cognitive radio has to be punished using a reactive strategy. A channel's transmission power restrictions alone may not be adequate when cognitive users coexist with main users in an operational spectrum. It is necessary to limit the demand for signal power transmission on an available channel for minimal neighbouring channel interference since key users are present on the adjacent channels.

As a result, the occupancy of the adjacent channels is a crucial factor in transmit power mode for optimal spectrum sharing. Additionally, the cognitive user may only broadcast in the opportunistic spectrum access transmission model when it identifies the spectrum gaps, which is the period of time when the main user is not transmitting across the band. The authors of nevertheless developed a novel transmission model for sharing the spectrum in which the cognitive user may broadcast at any time without determining whether the main user is active or not, but it must limit its transmission strength to prevent detrimental interference at the primary user.

This is a good consideration since it operates similarly to ultra-wide band even in the absence of precise channel state information (UWB). The limitation on transmit power, however, reduces the cognitive radio user's data transmission range and prevents them from fully using available permitted spectrum where they may send at their maximum capacity. The authors of have thus suggested that sensing be used to change the cognitive user's transmission power such that, while the main user is active, the cognitive user broadcasts at a low power to prevent interference at the primary user, and vice versa. Additionally, incorrect or incomplete channel information causes the functionality of the cognitive radio system to degrade.

Additionally, explore how transmission power and rate may be adjusted in response to fading circumstances. Kang has calculated the ergodic and outage capacity closed-form expressions and has found the best power allocation to cognitive users in a Rayleigh fading environment under the premise that cognitive users have access to channel state information (CSI). The interference transmission ratio (ITR), which is the ratio of main to secondary channel gain, has also been

identified as an essential metric that determines which cognitive user has precedence to transmit over other cognitive users. Because cognitive radio users and main users live side by side, researchers and scientists are also making use of OFDM-based cognitive radio networks.

Several authors have outlined several ways for allocating the best power to the subcarriers of cognitive radio users. To begin with, the power loading technique was created for the OFDM cognitive radio network to distribute the best amount of power to the subcarriers while satisfying the interference restriction and using the secondary subcarrier's placement in relation to the main users. The gradient descent technique has been taken into consideration when deciding how much power to supply subcarriers in an OFDM cognitive radio network in order to maximise capacity under the specified interference temperature restriction. Additionally, have taken into account two constraints in an OFDM cognitive radio network for the best power distribution, namely the co-channel and adjacent channel interference constraints, at the cost of high complexity $O(N \log N)$? $O(LM)$ (where N is the number of cognitive user subcarriers and L is the number of primary user transmitter receiver pairs), as opposed to the gradient based approach taking into account only the adjacent channel interference and $h_a(N)$.

The channel circumstances, interference temperature, and necessary signal-to-interference noise ratio (SINR) in the centralised cognitive radio network were also taken into account by while using the geometrical programming technique for power allocation. However, the author has only taken into account the primary user's single licenced channel, which is concurrently shared by many cognitive users using the CDMA method. Their major goal is to save power by capping the transmit power of the cognitive users. Chan and Zhang on the other hand, have only taken into account a single cognitive user and numerous primary users, and they have provided an iteration minimum technique to find the ideal sensing time and transmit power for all licenced channels in order to optimise channel usage.

Finds the best solution after two iterations compares several power distribution techniques used in OFDM-based cognitive radio networks. have taken into account the fairness of the cognitive users in the OFDM-based cognitive radio network and have proposed fast optimal power and simple power distribution algorithms with complexities of respectively. This is because fairness is one of the important parameters considered for the network Wireless 123 performance. Additionally, the interference, fairness, and total power limits have been taken into consideration in the solution of the cognitive user's capacity optimization issue. Additionally, in a max-min and proportional fairness scenario has been taken into consideration for the joint rate and power optimization issue.

Results showed that proportional fairness outperformed the max-min fairness criterion in terms of throughput but at the expense of some injustice additionally, in order to maximise usage and fairness, the authors of suggested an algorithm for allocating spectrum using both centralised and distributed techniques. The proposed algorithm increased throughput while reducing complexity and interference. Taking into mind the fairness of cognitive users in the network under peak transmit power and average interference power constraints, the SINR balancing issue has been taken into consideration in.

In order to obtain the best solution, the multiple constraint optimization problems in have been split into single constraint sub-problems. Additionally, have suggested a quick method for an OFDM-based cognitive radio network in an effort to tackle the computing complexity issue in cognitive radio networks. A filter bank multicarrier (FBMC) technique rather than an OFDM

scheme has also been suggested in for multicarrier communication in cognitive radio networks with low complexity power allocation. However, the dynamic resource allocation strategy, as explained in has helped to lessen the computational complexity of power and spectrum allocation difficulties in cognitive radio heterogeneous networks shown below.

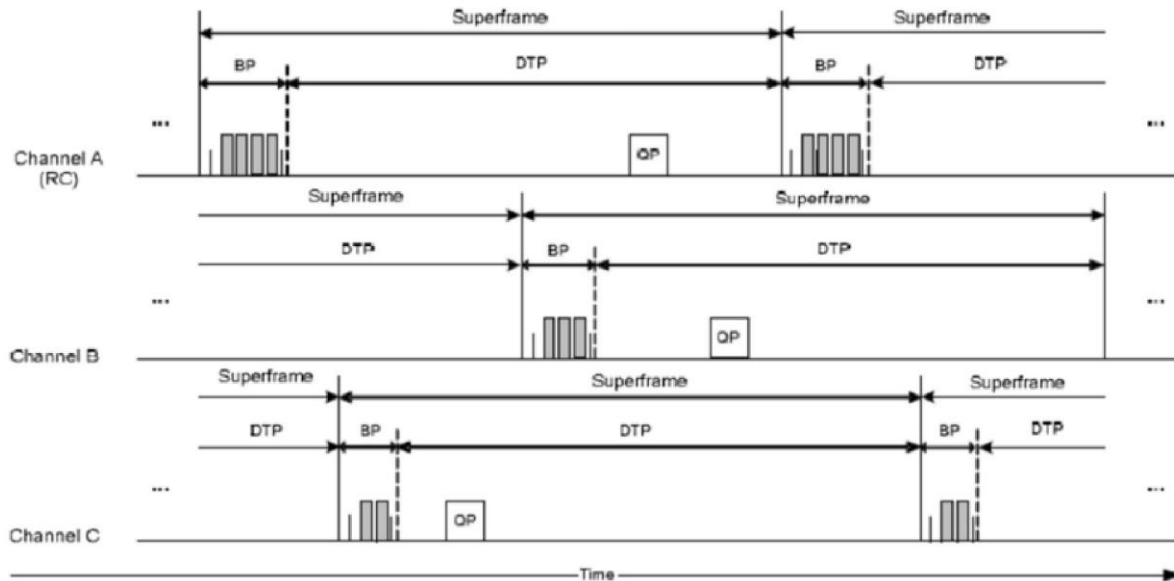


Figure 3.1 shows the cognitive radio heterogeneous networks,

The non-orthogonal multiple access (NOMA) approach of sharing power domain spectrum has recently been studied by researchers and scientists NOMA provides a number of benefits, including better performance than OFDM faster throughput owing to the broad bandwidth, and the use of channel gain for efficient power utilisation. It also helps with spectrum sharing in cognitive radio. In contrast to OFDMA, which divides the available bandwidth into subcarriers to increase throughput, all NOMA users use the entire bandwidth and the power allocation to cognitive users takes into account the channel conditions, with more transmit power allocated to the user with favourable channel conditions compared to the user with a more challenging environment. Since everyone using NOMA uses the same frequency for transmission, the receiver must be able to properly interpret its signal and reduce co-channel interference. As a result, this system's receiver decoding algorithm is more complicated than that of OFDM. Because it prevents rivalry among cognitive users for a particular channel among all the available channels and simply requires power regulation in accordance with the environment, NOMA is an effective method of spectrum sharing in cognitive radio. The power distribution to various users is managed by the base station or central coordinator, however research on the NOMA concept in remote environments is currently ongoing.

Therefore, using game theory to spectrum management inside the cognitive network might effectively ensure its fairness and rationality. The OODA (orient-observe-decide-and-act) strategy, which the authors previously suggested in, takes into consideration the behaviour modelling of the cognitive users and allows several heterogeneous cognitive networks with varying QoS needs to share the spectrum of the core network. Additionally, two significant game theory-based possibilities for spectrum sharing in diverse cognitive networks are explored below.

Where there are more primary networks than cognitive networks and there are more primary networks than cognitive networks

The major and secondary networks' harmonic utility functions are the only ones specified, however. Additionally, the authors in took into account the utility function and the varying bandwidth subcarriers of the multicarrier communication network allocated to the cognitive user with the goal of maximising the data rate of cognitive users while defining the constraints on resources like power, spectrum, and bandwidth. The primary contribution of this study is the formulation of utility function, which is based on harmonic mean fairness, maximum/minimum fairness with allocation difficulties, and proportional fairness. In addition, the channel circumstances are taken into account while allocating resources among competing cognitive users.

Although the authors in made the same assumption that a node cannot transmit and receive on the same channel simultaneously, they solved the convex optimization problem in and used the connectivity graph colouring method in to distribute resources among competing users in the adhoc network. The approach described in has an advantage over the connection graph in that it requires much less iterations and offers significantly higher throughput. However, in all of the methods described in, there is just one homogeneous primary user network that the cognitive users use, disregarding the primary user system's heterogeneity. By using the incremental subgradient optimization technique for both situations with and without the fairness restrictions and making the assumption that each cognitive radio user is half-duplex, the authors in were able to optimise the capabilities of the cognitive radio connections.

The resource allocation optimization issue takes into account the occupied probability of each subcarrier as well as the constant bandwidth of each OFDM subcarrier that the cognitive users are using. To reduce interference and increase spectrum efficiency, the whole spectrum from the spectrum pool is separated into orthogonal subcarriers for the OFDM access strategy in the aforementioned references have performed the sharing of licenced spectrum using TDMA mode in the centralised cognitive network, where all of the available bandwidth is accessed by multiple cognitive users at various times, using the game theoretical spectrum sharing using OFDM access scheme in ad-hoc cognitive network.

The throughput suffers when compared to the multicarrier OFDM access approach, despite the fact that this technique is simpler than multicarrier communication. The many aspects of spectrum trading between main and secondary users have been highlighted by .After spectrum sensing, a mechanism called spectrum trading is required in order to exchange the observed unused channels. Three types of trade markets monopoly, oligopoly, and exchange market are described in the literature and are covered in depth in have looked at the design of cooperative and non-cooperative channel sharing etiquette for cognitive radio networks in .

The cognitive radios are the players in the game of spectrum sharing in the cognitive radio network, and their tactics include the choice of new transmission parameters and new transmission frequencies, which have an impact on both their own performance and the performance of the nearby players. In , the authors also put forth two additional utility functions for the self-centered cognitive user, which adapts to the channel for transmission by causing little interference on that channel; and for the cooperative cognitive user, which adapts to the channel and causes little interference on both that channel and on nearby nodes/channels. Since the second sort of utility function depends on user participation, it is better than the former but

comes at a higher cost in overhead. The utility function of the cognitive user is application dependent. In time-critical applications, for instance, a brief delay or minimal jitter are crucial requirements; alternatively, a low bit-error-rate may be significantly more significant than time criticality. The utility functions that the user wants to improve will take these aspects into account. The effectiveness of the network-level bandwidth allocation, connection-level bandwidth allocation, capacity reserve, and admission control functions of the game theoretical framework for radio resource management has been thoroughly examined in. Additionally, explores the idea of spectrum sharing between different main and secondary users depending on the price and quantity of needed bandwidth.

Additionally, the auction theory in cognitive radio spectrum sharing through interaction between the cognitive users and main users is provided in where it is the most popular use of game theory discusses the optimality approach for achieving the equilibrium between supply and demand for the auctioned spectrum. In addition, it has been shown that the Nash equilibrium Wireless is used for non-cooperative game theory to distribute the spectrum among many cognitive users, while the Nash bargaining solution is for cooperative game between cognitive and licensed users. The static game spectrum sharing method used for spectrum allocation in has, however, decreased the efficiency of wireless networks due to the inefficient Nash equilibrium outcomes brought on by the user's selfishness in seeking its own benefit at the expense of equitable and overall spectrum sharing.

Additionally, the ideal solution is provided by taking into account the interests of each cognitive user in the linear proportional fairness approach of spectrum sharing, which applies cooperative game theory to the sharing of the spectrum. The most popular auction techniques in environments with competing multiple cognitive users are sequential auctions or however Vickrey auctions are preferable to sequential auctions for distributing spectrum among cognitive users due to the time-definite assignment of spectrum. Additionally, the categorization of auction procedures also includes the single and double auction methods.

One seller and several buyers participate in the single auction trade technique, and the item is won by the bidder who made the highest offer. However, a twofold auction is an effective way for exchanging spectrum if both buyers and sellers become numerous. The auctioneer (spectrum broker) decides to allocate the spectrum to the specific buyer at a price higher than that requested by the specific seller to make a profit for itself in a double auction in which the sellers and buyers submit their selling and buying prices to the auctioneer.

A detailed discussion of the equilibrium in single and double auction procedures may be found in. The bidding process for the internet has also been explored in with the method creating ideal Bayesian equilibrium. The double auction in the primary and cognitive radio networks, with the primary and cognitive users being the bids of the available channels, is covered by the authors in The authors of have taken into account the possibility that the broker would distribute a single channel among a single main user network, a single or many cognitive user networks, and both, with the primary network receiving a higher priority than the cognitive user networks. In addition, algorithms have been suggested in for situations when there are both single and multiple cognitive user networks on a single channel.

Furthermore, in the double spectrum allocation issue was developed for the distribution of spectrum to primary and cognitive users, and in the suggested scheme, the requirement from the cognitive users is fulfilled. Moreover, the true online double auction (TODA) method, which is

intended for both primary and cognitive users, has been presented additionally, the quantity of spectrum traded to the cognitive network and the duration of the spectrum allotment determine the benefits that the main user network will get. The principal network shouldn't, however, degrade the services it provides to its own users in order to gain greater advantages. In order to guarantee optimal allocation, Chang and Chen in took into account the QoS of principal users via its blocking rate.

A super-frame structure of cognitive users for competitive interaction is studied in after the advantages of main users, cognitive users, regulatory system, and service provider have been taken into account. Also mentioned in is the Vickrey auction system based on SINR and power, and the min-max fair SINR allocation is carried out for the spectrum allocation for cognitive games. The revenue-based sharing model is suggested in as an alternative to pricing and auction theory, where the income shared by the main user network is dependent on how resources are distributed among the primary and cognitive users. Furthermore, as stated in where the authors presented an auction procedure that cannot be performed in polynomial time, the allocation of spectrum to cognitive users by the main service provider is thought to be an NP-hard task.

A number of antennas

Due to the throughput improvement and interference cancellation, the idea of numerous antennas has also been explored as a viable approach for spectrum sharing in the cognitive radio communication system. Multiple antennas are implemented at the cognitive user transmitter in a system model for the cognitive radio network that is provided which significantly increases the channel capacity compared to the single antenna at the cognitive user transmitter. Due to the beam-forming of the many antennas, it is also capable of transmitting on the same spectrum that the main user is now utilising. Additionally, in a cognitive radio network, the multiple antennas are used to distribute the transmit dimensions in space, giving the cognitive transmitter more degrees of freedom in space in addition to the time and frequency to balance between maximising its own transmit rate and minimising the interference powers at the primary receivers.

However, two techniques are suggested in projected-channel SVD (P-SVD) and direct-channel singular value decomposition (D-SVD), which improve the cognitive radio user's capacity and reduce interference at the main receiver by beam-forming null to the primary receiver, respectively. While secondary radio receivers utilise adaptive approaches to decode in the face of interference from main users, used antenna weights to establish nulls at the primary receivers. Through feedback from the main receivers, the channel estimation is carried out to acquire the antenna weights, and the Wireless Netw 123 suitable antenna weight is computed using these estimations. The cognitive radio transmitter antennas then adjust the antenna weights to generate the radiation pattern that cancels out interference at the main reception and offers effective communication to its corresponding cognitive radio receiver.

Additionally, the authors of have spoken about the characteristic function and how it may be used to calculate channel capacity in a fading environment. In the error rate and channel capacity are calculated using the moment generating function (MGF) and characteristic function (CF). The formulation of the fading channel capacity utilising the MGF technique in the context of numerous antennas and varying correlation coefficients in fading settings can be found in .The authors in took into account the cognitive radio spectrum sharing scenario without conventional constraints in the sharing environment that is on the cognitive users transmit power and primary

user received interference power, and they concluded that this results in no degradation of the secondary or primary services due to the linear processing of the channel gains in multiple antennas spatial domain.

The influence of poor channel state information (CSI) on system performance has also been taken into account by the authors, although the suggested solution is not appropriate for cognitive users who share a full-duplex main user spectrum. Additionally, the interference restriction at the main receiver was taken into account by the authors of while calculating the single cognitive user system capacity, which led to the need of limiting its transmit power. Multiple antennas are also taken into account for both secondary and main users. For cognitive users, pre-whitening rather than post-whitening multi-antenna spectrum sharing is taken into consideration since it has less interference at the main receiver than the post-whitening scheme.

Additionally, the underlay multicast method of cognitive radio spectrum sharing has been proposed in .This method uses multiple antennas only at the cognitive access point to broadcast the same information to all cognitive receivers with beam-steering while limiting the side-lobe power to the primary receiver. The presence of cognitive and primary users on the same spectrum, however, may worsen both the primary and cognitive users' performance, necessitating the perfect With CSI information at the cognitive user, (MCC) capacity. However, there is a transmit power restriction at both the main and secondary transmitter, and Lagrange's optimization is used to optimise MCC capacity by taking these two transmit power constraints into account at both the transmitter. The main user transmit power limitation is not a workable option to improve the performance of the cognitive radio system since the cognitive user system does not wish to alter the primary user network and should not place any restrictions on it. The distribution of transmission time and power to diverse cognitive users in centralised and distributed cognitive networks has been jointly explored by Additionally, the authors have taken into account the advantages of many antennas while keeping in mind the need for resource allocation equity in diverse cognitive user networks. In place of the traditional interference channel, a novel multiple antenna channel model dubbed cognitive interference channel has recently been taken into consideration where the cognitive transmitter is given access to the principal user data. The additional information at the cognitive transmitter aids in learning about the nearby nodes.

MAC protocol, or medium access control

Traditionally, the medium access control (MAC) protocol has been used by users to access the channel during spectrum sharing. In contrast to conventional MAC protocols, which need multiple cognitive users to share a single channel, cognitive radio systems require multiple cognitive users to share several channels. This is the primary distinction between conventional MAC protocols and cognitive radio systems. Furthermore, cognitive users must distinguish between main user transmission and cognitive user transmission; as a result, they must choose whether to halt transmission to protect the primary user or to retransmit in the event of interference from other cognitive users. Each cognitive user does not have a set number of channels for transmission since the permitted channels for communication fluctuate with time and place.

All of these functions must be implemented into the cognitive radio communication system's MAC protocol. The sensing and switching feature must be included in the cognitive radio MAC protocol spectrum sharing approach because the cognitive user is intelligent and has the capacity

to switch between several channels. Additionally, there can be several cognitive radio users attempting to access the spectrum; as a result, the cognitive radio network MAC protocol access has to be coordinated to avoid interference between users in the spectrum's overlapping regions. To overcome layered protocol and structural restrictions, cross-layer design and optimization approaches for cognitive radio have been presented. For the design of a communication system, the physical layer must pay close attention to the physical environment and channel that the MAC layer follows. Other various parameters of this layer include frame type, frame size, data rate, channel/time slot allocation, scheduling scheme, retransmission probability, etc. All of these Wireless Netw 123 MAC layer characteristics make up the MAC protocol and are in charge of making choices about spectrum sensing and access. The main goals of cognitive MAC protocol designs are to. Optimize spectrum sensing and access decision-making, Regulate multiuser access in multichannel networks, and allocate radio spectrum and schedule traffic transmission.

The MAC protocols created for conventional wireless networks must be changed to enable spectrum sensing and spectrum access for DSA-based cognitive radio networks. The requirement for the coexistence of cognitive users with licenced users makes the design of MAC protocols for cognitive radios a very difficult task. Such a protocol must achieve the highest spectrum utilisation by accurately detecting all spectrum opportunities to access the spectrum in order to minimise collisions with other cognitive users. The MAC level may, however, change the transmission parameters, such as modulation and coding level, dependent on the channel quality. Numerous approaches to using an optimization model to improve spectrum sensing and access decisions have been presented [94–96]. Kim and Shin have described the technique for cognitive users to optimise their sensing periods and reduce idle channel finding delays in.

However, POMDP (partially observable Markov decision process) is used in to allow cognitive users to access the licenced channels. The cognitive radio user chooses which channel to access for the data transmission depending on the multiple channels' outcomes of sensing. The MAC protocol must choose the best accessible channels to sense. This choice is based on the goal of maximising transmission rate, with restrictions such the need that the chance of a collision with a licenced user be below a threshold. The hardware constraint-MAC (HC-MAC) has been presented for an effective spectrum sensing and access decision, taking into account hardware restrictions such single radio, partial spectrum sensing, and spectrum aggregation limit. The model may be used with one or more channels and one or more users, although it has a multichannel concealed terminal issue.

Additionally, describe the MAC protocol for multichannel and multiuser cognitive radio systems. These systems' primary goals also include performing agreements amongst cognitive users for spectrum availability in multichannel situations and preventing collisions brought by by simultaneous broadcasts. For the dispersed cognitive radio network shown in the cognitive MAC (C-MAC) protocol is suggested. In this network, no base station or other centralised entity is provided for the coordination of the cognitive radio terminals. Each licenced channel that is available is planned in C-MAC and is broken up into super-frames, which are blocks of consecutive beacon and data transmission times. In order to synchronise and coordinate cognitive users over non-overlapping beacon intervals, a rendezvous channel (RC) is presumptively accessible throughout network operation.

In case the main user shows up, the backup channel, which is also recognised during sensing, is utilised to rapidly provide an option of an alternative spectrum band. Each cognitive radio user

visits the RC on a regular basis to share information about the load of each band for the purposes of synchronisation, information gathering about primary and secondary user discovery, avoiding hidden node problems, and exchanging schedules for beacon periods to prevent beacons from being sent simultaneously across all spectrum bands. Additionally, before transmitting data across a defined channel to its intended recipient, each cognitive terminal must first broadcast a beacon signal during the allocated beacon slot, coordinate with other users, and then send the data to the intended receiver.

To ensure that other cognitive users are aware of any spectrum changes made by the cognitive terminal in C-MAC, these changes must first be notified over the RC. Setting up an RC that is accessible throughout the whole cognitive network is thus a crucial challenge. The establishment of a non-overlapping beacon, the absence of any centralised entities during calm times, and RC availability are some of the technical challenges with this protocol. Additionally, the network synchronisation requirements necessary for beacon control infrastructure and C-MAC add to the complexity. It does not, however, have the concealed terminal issue that HC-MAC does. The cognitive radio enabled multi-channel (CREAM) MAC protocol, which is free from hidden terminal problems and network synchronisation but has a significant communication overhead, has also been explored in.

Wireless communications are becoming more and more important, necessitating a flexible and effective use of the spectrum resources. The previous technology-specific spectrum allotment cannot support the current wireless communication's rising demand unpredictability. Therefore, the technology-specific spectrum allocation will necessarily result in less-than-ideal spectrum allocations. The cognitive radio communication system, which offers considerably high bandwidth to mobile users through a heterogeneous wireless architecture and dynamic spectrum access strategies, has been reviewed in this study in terms of its current level of spectrum sharing and management. It creates a number of issues because of the shifting nature of the accessible spectrum and the differing quality-of-service requirements for different applications. When focusing on how closely the MAC protocol design is connected to the other levels of the protocol stack, the key difficulties and potential research topics have been highlighted.

The possible difficulties in implementing the dynamic spectrum access principles are those that need considerably increasing the efficiency of spectrum usage without sacrificing the benefits of the static spectrum distribution system. The development of wireless networks and devices that can opportunistically operate in various frequency bands is the first challenge, and other issues in the field of spectrum policy include the need to create regulations for dynamic spectrum access that promote effective spectrum use, safeguard the rights of licence holders, and preserve service quality. In addition, there are important economic factors to take into account, such as rules that must safeguard the interests of main users who have made substantial infrastructure expenditures. Additionally, it must be economically advantageous for manufacturers and service providers to create and implement the equipment necessary for cognitive users to use the spectrum opportunistically.

The significance of spectrum trading is influenced by technological developments made in the spectrum, including power control, channel selection, and access behaviour. However, a crucial factor in determining the necessity for spectrum trading in the future is the equilibrium between the supply and demand of the spectrum. Technology as well as the proportion of licenced to license-exempt spectrum govern this equilibrium. Next, regardless of the future directions that

spectrum technologies take, a definition of spectrum use rights is necessary to provide a foundation for user behaviour. The cognitive users' knowledge of the location and transmit power of the main users is another crucial presumption in the previously presented study, which makes it easier to compute interference. However, in cognitive radio networks, such an assumption could not always be true. In order to fully achieve the promise of cognitive radio networks, it is necessary to encourage the academic community to create cutting-edge, contextbased approaches, strategies, and algorithms that may be influenced by other interdisciplinary study areas.

An emerging study topic is the algorithm and protocol for self-configuring cognitive radio, centralized/distributed cognitive radio networks, and radio resource management. Additionally, the channel is treated as a spectrum unit by all spectrum choice and sharing approaches, making the creation of an algorithm an essential task. In general, the common control channel makes it possible to implement numerous spectrum sharing capabilities; however, since a channel must be given up when the principal user selects it, the usage of a fixed common control channel is not practical. A channel that is shared by all users in cognitive radio networks is also highly reliant on topology and changes over time. Therefore, finding a solution to this problem is essential for cognitive radio communication systems as well. Additionally, the complexity of the cognitive radio network spectrum design has been included into the mobility of the major and secondary users.

In a certain place, the existence or absence of a licenced channel for a cognitive user who is walking or standing still will be unclear if the licenced user is moving quickly. Additionally, because the channel availability status may differ depending on the user's current location, the fast cognitive user's decision to sense a particular channel in a scenario might not be accurate. It is therefore advised for fast cognitive users to perform spectrum sensing frequently in order to reduce the likelihood of a false alarm. Additionally, the cognitive radio network's spectrum sharing is heavily reliant on the system's user base. The rivalry among cognitive users may lower the performance of the cognitive radio network if there are considerably more cognitive users. Therefore, a highly scalable cognitive radio system for sharing the spectrum is required. Additionally, an energy-efficient cognitive terminal is required for the development of a future cognitive communication network, and designing a cognitive radio communication system that incorporates energy economy is a difficult undertaking.

The MAC protocol should be designed with some kind of sleep and wake method to prevent cognitive network service deterioration. The cognitive radio spectrum sharing solutions should improve the performance with the least amount of energy consumption since the user's terminal has a limited battery life and the cognitive radio users sensing will also use energy in addition to transmitting data. The blocking probability of cognitive radio communication is significantly high, which creates a serious problem, especially for the real-time cognitive radio user's traffic. Cognitive radio communication systems operate on the underutilised licenced channels and have lower priority than the licenced users. Sharing strategies in cognitive radio networks that satisfy the quality-of-service needs of cognitive users should be carefully planned.

Additionally, one of the key responsibilities of the system designer is to address the security concerns of the cognitive radio network. Significantly more research has to be done in this area to ensure that cognitive radio users can receive data securely. The cognitive radio network has an open research field for spectrum sensing interface with database for accurate recognition of

licenced users. Cognitive machine-to-machine communication and machine learning methods are also growing challenges. Additionally, cognitive radio-based 5G communication has recently been suggested to operate at higher frequencies, such as 28 GHz and 60 GHz, however it is difficult to maintain an uninterrupted connection at such a high frequency owing to interference and a limited coverage area.

As a result, researchers and scientists have untapped potential in the actual deployment of cognitive radio in 5G. Furthermore, the OSA-MAC (opportunistic spectrum access—MAC) for distributed cognitive radio network is suggested in, and although its design is somewhat similar to that of the IEEE 802.11 ad-hoc MAC protocol, it performs differently from WLAN IEEE 802.11 MAC, as further discussed in. One specific control channel, owned by the cognitive user service provider, is provided in the OSA-MAC for the exchange of control information between cognitive users. All cognitive users are synced with the periodic beacon broadcast, which divides the duration of each channel into beacon intervals, there are three processes that make up each beacon interval: channel selection, sensing, and data transmission.

CHAPTER 4

Element of Communication System

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Information is the content that has to be sent from one person to another or from one person to another as feedback. Information may be presented in any format, including text, video, or a mix of all communication types. The information is transported through the signal. To be sent between one ending to the other the message is transformed into a signal. Wireless communications are becoming more and more important, necessitating a flexible and effective use of the spectrum resources. The previous technology-specific spectrum allotment cannot support the current wireless communication's rising demand unpredictability. Therefore, the technology-specific spectrum allocation will necessarily result in less-than-ideal spectrum allocations. The cognitive radio communication system, which offers considerably high bandwidth to mobile users through a heterogeneous wireless architecture and dynamic spectrum access strategies, has been reviewed in this study in terms of its current level of spectrum sharing and management. It creates a number of issues because of the shifting nature of the accessible spectrum and the differing quality-of-service requirements for different applications. When focusing on how closely the MAC protocol design is connected to the other levels of the protocol stack, the key difficulties and potential research topics have been highlighted.

The possible difficulties in implementing the dynamic spectrum access principles are those that need considerably increasing the efficiency of spectrum usage without sacrificing the benefits of the static spectrum distribution system. The development of wireless networks and devices that can opportunistically operate in various frequency bands is the first challenge, and other issues in the field of spectrum policy include the need to create regulations for dynamic spectrum access that promote effective spectrum use, safeguard the rights of licence holders, and preserve service quality. In addition, there are important economic factors to take into account, such as rules that must safeguard the interests of main users who have made substantial infrastructure expenditures. Additionally, it must be economically advantageous for manufacturers and service providers to create and implement the equipment necessary for cognitive users to use the spectrum opportunistically.

The significance of spectrum trading is influenced by technological developments made in the spectrum, including power control, channel selection, and access behaviour. However, a crucial factor in determining the necessity for spectrum trading in the future is the equilibrium between the supply and demand of the spectrum. Technology as well as the proportion of licenced to license-exempt spectrum govern this equilibrium. Next, regardless of the future directions that spectrum technologies take, a definition of spectrum use rights is necessary to provide a foundation for user behaviour. The cognitive users' knowledge of the location and transmit power of the main users is another crucial presumption in the previously presented study, which makes it easier to compute interference. However, in cognitive radio networks, such an assumption could not always be true. In order to fully achieve the promise of cognitive radio

networks, it is necessary to encourage the academic community to create cutting-edge, contextbased approaches, strategies, and algorithms that may be influenced by other interdisciplinary study areas.

An emerging study topic is the algorithm and protocol for self-configuring cognitive radio, centralized/distributed cognitive radio networks, and radio resource management. Additionally, the channel is treated as a spectrum unit by all spectrum choice and sharing approaches, making the creation of an algorithm an essential task. In general, the common control channel makes it possible to implement numerous spectrum sharing capabilities; however, since a channel must be given up when the principal user selects it, the usage of a fixed common control channel is not practical. A channel that is shared by all users in cognitive radio networks is also highly reliant on topology and changes over time.

Therefore, finding a solution to this problem is essential for cognitive radio communication systems as well. Additionally, the complexity of the cognitive radio network spectrum design has been included into the mobility of the major and secondary users. In a certain place, the existence or absence of a licenced channel for a cognitive user who is walking or standing still will be unclear if the licenced user is moving quickly. Additionally, because the channel availability status may differ depending on the user's current location, the fast cognitive user's decision to sense a particular channel in a scenario might not be accurate. It is therefore advised for fast cognitive users to perform spectrum sensing frequently in order to reduce the likelihood of a false alarm.

Additionally, the cognitive radio network's spectrum sharing is heavily reliant on the system's user base. The rivalry among cognitive users may lower the performance of the cognitive radio network if there are considerably more cognitive users. Therefore, a highly scalable cognitive radio system for sharing the spectrum is required. Additionally, an energy-efficient cognitive terminal is required for the development of a future cognitive communication network, and designing a cognitive radio communication system that incorporates energy economy is a difficult undertaking shown below.

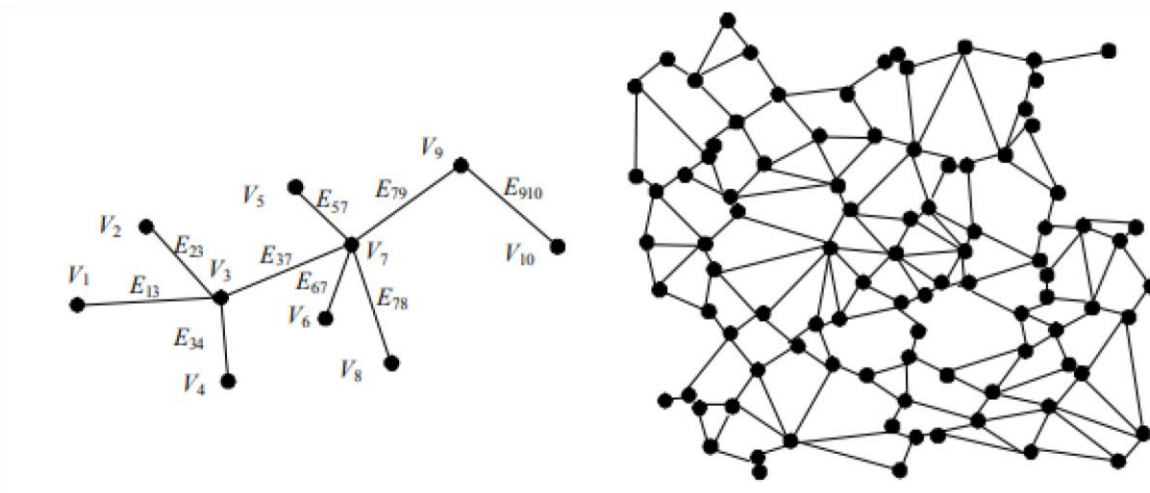


Figure 4.1 shows the cognitive radio communication system.

The MAC protocol should be designed with some kind of sleep and wake method to prevent cognitive network service deterioration. The cognitive radio spectrum sharing solutions should

improve the performance with the least amount of energy consumption since the user's terminal has a limited battery life and the cognitive radio users sensing will also use energy in addition to transmitting data. The blocking probability of cognitive radio communication is significantly high, which creates a serious problem, especially for the real-time cognitive radio user's traffic. Cognitive radio communication systems operate on the underutilized licenced channels and have lower priority than the licenced users.

Sharing strategies in cognitive radio networks that satisfy the quality-of-service needs of cognitive users should be carefully planned. Additionally, one of the key responsibilities of the system designer is to address the security concerns of the cognitive radio network. Significantly more research has to be done in this area to ensure that cognitive radio users can receive data securely. The cognitive radio network has an open research field for spectrum sensing interface with database for accurate recognition of licenced users. Cognitive machine-to-machine communication and machine learning methods are also growing challenges. Additionally, cognitive radio-based 5G communication has recently been suggested to operate at higher frequencies, such as 28 GHz and 60 GHz, however it is difficult to maintain an uninterrupted connection at such a high frequency owing to interference and a limited coverage area. As a result, researchers and scientists have untapped potential in the actual deployment of cognitive radio in 5G shown below.

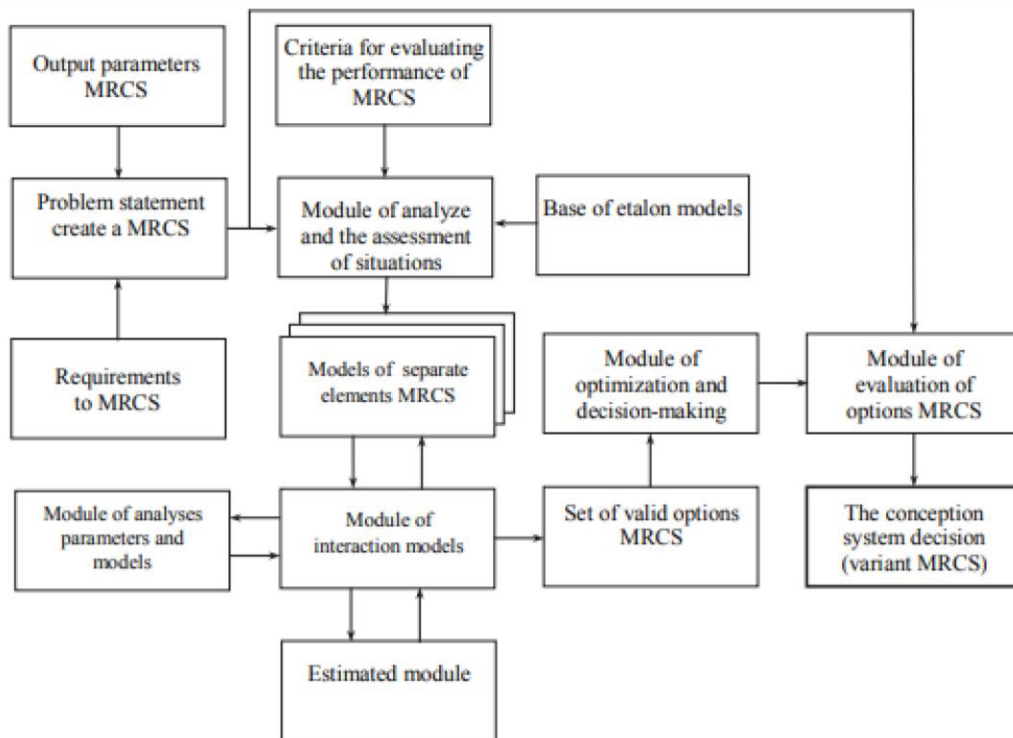


Figure 4.2 shows the cognitive radio.

Terahertz technology's potential is now sparking a lot of curiosity. Imaging methods for inspecting individuals, mail, or baggage for security purposes as well as for quality control of industrial items are possible future uses for terahertz technology. Future short-range interior communication systems could operate at a frequency of several hundred gigahertz, too. Terahertz sources and detectors need to be created in order to support each of these applications in an

effective, affordable, and small manner. Passive components including terahertz mirrors, filters, and modulators are also necessary.

Polymeric dielectric mirrors for the terahertz region have recently been put to the test. Here, we describe a much better structure that is omnidirectional, Omni directionally reflective, and has a substantially wider reflection range. The transmission and reflection of the structure are thoroughly examined from different angles. Excellent agreement exists between experimental results and model calculations. But before we discuss these findings, let's quickly go over how these mirrors could end up playing a crucial role in terahertz communication networks.

The environment greatly absorbs terahertz radiation, and free-space path losses are considerable. As a result, terahertz Pico cells will have small operating lengths and may only be able to cover one building or a single room. These systems will need high directivity antennas to make up for the significant losses incurred by the atmosphere and open space. A highly targeted transmission between a transmitter and a receiver will be the outcome.

However, because moving humans or other objects may obstruct the straight line-of-sight beam path, a functional indoor terahertz communication system must be resistant to shadowing. As a result, for dependable operation, such a system should additionally employ indirect transmission channels that include one or more wall reflections. The outcome of a ray-tracing simulation of a terahertz picocell in a typical office setting. We simulate a 30 m² space with moving furniture and humans who may obstruct the terahertz beam. The worst case signal level for the straight line-of-sight route DP and pathways that entail one or two reflections from the walls are shown at 1 m above the ground. Under the ceiling, in the centre of the room, is where you'll find the transmitter. Dark areas indicate places with inadequate signal strength. As can be seen, a terahertz connection cannot only depend on the DP since there is always the possibility that anything may obstruct the beam path.

At terahertz frequencies, traditional construction materials suffer from large reflection losses, whereas the reflective shows the worst-case signal intensity in dBm in a room that is 5.6 m² in size and furnished with conventional office furniture. The signal level resulting from the straight line-of-sight route, all pathways that include one reflection off the walls, and all paths that involve two reflections are shown in the three plots, from top to bottom. Polymeric terahertz mirrors with reflection bands adjusted to the communication system's carrier frequency might improve the ity of the walls. This would aid in lowering the antenna gain needed to set up a trustworthy terahertz communication. Fortunately, ray-tracing simulations demonstrate that just a few "hot spots," rather than the whole wall surface in a normal room, need to be covered.

Such mirrors should be highly reflective throughout a broad range of incidence angles within a certain frequency band in order to maximise performance. Omnidirectional mirrors, which are highly reflective at all incidence angles, have lately been explored in the literature. A dielectric structure must meet a number of requirements in Refs. 10–12 in order to be omnidirectionally reflective. In essence, there must be a significant difference in refractive index between the two layers. A wide reflection band is the outcome for a normal incidence angle of 0. As the incidence angle increases, this reflection band's location will blueshift and its form may somewhat alter.

A band where the structure is strongly reflective from all angles may be found if the breadth of the reflection band is sufficiently wide relative to the magnitude of this blueshift. These materials' refractive index steps are insufficient to create an omnidirectional mirror. Therefore,

additional low-absorbing materials with a higher refractive index, such as semiconductors, must be used. Here, we construct an omnidirectional terahertz mirror out of polypropylene and thin slices of silicon with high resistance.

The structure comprises of four layers of high-resistivity silicon that are 63 nm thick and four layers of polypropylene that are 150 nm thick and have a refractive index of 1.53 and 3.418, respectively. A dielectric mirror's construction often begins with the substance having the highest refractive index. However, to safeguard the delicate, tiny slices of silicon in our mirror, we added polypropylene layers as exterior layers. Both transmission and reflection measurements are carried out using a fiber-coupled terahertz time-domain spectrometer; see, for instance.

The terahertz transmission spectra across the structure for s and p polarisations, respectively. The related reflection spectra are shown in the solid lines are the output of a transfer matrix simulation, while the dots reflect the experimental data. The simulation is run using the aforementioned parameters. Between each layer of material in the simulation, there is a tiny layer of air. Because part of the beam is cut due to the shape of the sample holder, accurate results for incidence angles greater than 60° are not available. Theoretical curves in this instance indicate the transmission spectrum anticipated for grazing incidence. A wide reflection band with a frequency range of 0.247 to 0.388 THz is seen with normal incidence. As the incidence angle rises, this reflection band blueshifts for both s and p polarisations, reflecting at least 95% of the incident power.

The grey region in the diagrams represents the frequency range for which the mirror is highly reflective for both polarisations. For s-polarized waves, the omnidirectional reflection band is wider. Using thin slices of crystalline silicon does, in fact, lessen the structure's mechanical flexibility, which is one of the major benefits of polymeric mirror systems.

However, it could be conceivable to substitute these silicon layers with polymer layers whose refractive index has been significantly increased by the inclusion of high-index microparticles during a compounding process. For instance, a flexible high-index dielectric might be created by combining polypropylene with a fine, high-resistivity silicon powder. In this situation, coextrusion might be used to create the structures, which would also prevent air layers from forming between the dielectric structure's layers, improving the quality and uniformity of the mirror.

In conclusion, we have shown a polypropylene and silicon high-resistivity omnidirectional mirror for the terahertz region. Transmission spectra via the mirror structure for different angles and s-polarized terahertz waves at frequencies between. The results of a transfer matrix computation are illustrated as solid lines, while the experimental data are shown as dots 375 GHz. With regard to both s and p polarisations as well as all incidence angles, the structure is extremely reflective. Future mirrors may be created using two polymer films, one of which has been mixed with a high-index filler to increase its refractive index. The mechanical flexibility of these mirrors would allow them to be used as wall paper to increase the reflectivity of indoor terahertz picocells.

Transducer

Given that it transforms energy from one format to another, the transducer may also be referred to as a converter. The converter can turn the corresponding electrical pulses for temperature,

temperature, and force. A phone call, for instance, may transmit our speech to the sender by turning it into audio signals.

Booster

An amplifier is a device that aids in boosting the transmitted signal's intensity. Amplification is used to boost the message's transmission frequency.

Modulator

There are occasions when a message must be sent across great distances. The frequency and amplitude of these signals are typically modest. These messages are combined with high pulse, high frequency carrier waves to extend their range. Modulation is the process of encoding the message on high-frequency waves. The message to be conveyed is included in the modulation wave that results. Based on the adjustments made, there are three main sorts of modulations present:

Amplitude modulation is the process of altering the amplitude and superimposing it on a highfrequency carrier pulse. Frequency variation: In this method, the signal is motivated by a carrier wave to change frequency. Since sounds from many source materials are avoided, transmitted signal is superior to amplitude motivation. Phase modulation: The carrier wave's phase affects the signal wave's phase.

Transmitter

With the use of apparatus referred to as a transponder, the message is changed into a signal. The transmission is present at the sender's site, and there could also be a receiver at the recipient's location.

An antenna

An antenna is a tower or equipment that gathers electromagnetic delivered from the transmitter via the air. An antenna is a structure that can translate a message into waves so that it may be sent farther. The metallic antenna needs many wires to operate.

Channel

The message is converted by the antenna and sent across a channel, which might be a wire, cable, or physical space.

Noise

Noise is the obstacle that stands between the transmitter and the receiver. Noise generally interferes with or interrupts the communication that is being sent from one party to another. Physical disturbance, lightning, solar irradiance, or any other pertinent sort of distraction may all be considered forms of interference.

The external damage is either completely prevented by the channels' design or is at a minimum. Electrons in conductors may collide at random, which may cause noise. Utilizing digital technology, efforts are undertaken to lessen or eliminate internal noise [1], [3].

Diminishment

When a signal travels over a large distance via a medium, attenuation is the issue that results. The thickness of the form of media has an impact on this. The reduction in initial power is

precisely proportional to the medium's range. Comparatively speaking, digital transmissions are less susceptible to attenuation than analogue ones.

Disturbance

It's another of the channel's issues. The bandwidth and frequency of the sent message are predetermined. However, the wavelength and bandwidth are affected by this distortion.

Recipient

The receiver, which is located at the other end of the transmission system, serves as a transmitter for the sender's message. It refers to a device created to provide an outputting to the signal being received. The message is also translated by the receiver for the recipient. When two-way telecommunication is in use, the receiver also serves as a sending device, bringing the message to the original sender.

Demodulator

Demodulation serves the exact opposite purpose to modulation. When a signal is modulated, it is connected to the carrier, but when a signal is demodulated, it is uncoupled from the amplitude modulation.

Repetition

Between it receiver and transmitter, there are many repeaters. The main job of a repeater is to magnify the signal it receives and transmit it onto the next repeater without distorting the message. The communication process depends heavily on the communication systems. These technologies make it possible to share thoughts and transmit information from far-off locations. The communication process is constant throughout almost all features or kinds of communication systems, despite the system's complexity and the participation of several parts.

CHAPTER 5

Information, Message and Signal in Communication System

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It is obvious that communication relies heavily on the idea of information. Information, however, is a loaded term that implies philosophical and semantic ideas that resist clear explanation. By focusing on the message, which is the physical representation of information as provided by the source, we avoid these issues. The objective of a transmission line is to replicate at the destination an acceptable duplicate of the source message, regardless of the message's form.

There are many different forms of data carriers, including humans and robots, and communications may take many different forms. However, we may distinguish between two different types of message: analogue and digital. This difference then establishes the standards for effective communication. A physical amount that changes over time, often in a smooth and continuous manner, is called an analogue message. The sound pressure you create when you talk, the displacement of a helicopter gyro, or just the light intensity at a specific location in a television display are case studies of analogue communications. A time-varying waveform contains the information, hence an analogue communication system must convey this waveform with a certain level of accuracy.

In order to transfer the digital output from either the broadcaster to the speaker at the destination, the receiver processes the signal. Amplification is used in receivers to make up for transmission loss, while demodulation while decoding are used to undo the signal processing done in transmitters. For the reasons explained in the next section, filtering is another crucial function at the receiver.

The oscillation's initial amplitude would be inversely proportional to the magnitude of the current pulse, and its decay speed would be governed by the circuit's time constant. Since the tank circuit is being fed a train of pulses, each pulse will result in a full sine wave whose amplitude is proportional to the magnitude of this pulse. The following sine wave, corresponding to the magnitude of the subsequent applied pulse, will come after that, and so on. We can see that if the initial current pulses are made proportional to the modulating voltage, an exceptionally excellent approximation of an AM wave will arise, even when at least 10 times as many pulses each audio cycle are delivered to a real circuit. It works best with a tuned circuit whose Q is not too low and is known as the flywheel effect of the tuned circuit.

By connecting the modulating voltage in series with any of the amplifier's supply voltages, a class C amplifier's output current may be made proportional to the modulating voltage. As a result, any combination of cathode (or erilitter), grid (or base), and anode (plate or collector) modulation of a class C amplifier is feasible. Each has unique uses, benefits, and downsides. Each will be covered in detail in the next sections.

Amplitude modulation may be produced in an AM transmitter at any moment after the radio frequency source. Even a crystal oscillator could be amplitude-modulated, but doing so would

interfere unnecessarily with its capacity to maintain a stable frequency. High-level modulation refers to a transmitter's output stage that is plate-modulated (or collector-modulated in a lower-power emitter). Any other location, such as another electrode of the output, may receive low-level modulation. After the amplifier, so-called low-level modulation is created. Both methods produce the same final result, but their transmitter circuit layouts vary.

Plate modulation of the output stage of a television transmitter is not practical due to the challenge of producing high video (modulating) powers at the necessary huge bandwidths. The greatest degree of modulation used in TV transmitters is grid modulation of the output stage. In TV transmission, it is referred to as "high-level" modulation, while everything else is referred to as "low-level" modulation. An AM transmitter's typical block diagram, which may be either low-level- or high-level-modulated, is shown in Figure 1. There are several shared characteristics. Both have a reliable RF source, followed by RF power amplifiers and buffer amplifiers. Both kinds of transmitter's process or filter the audio voltage to occupy the proper bandwidth (often 10 kHz) and to some extent compress it to lessen the ratio of highest to minimum loudness. The modulator amplifier, which is the highest-power audio amplifier, is the culmination of the audio and power audio frequency (AF) amplifiers used in both modulation systems. Actually, the only difference is the location of the modulation. Here, an amplifier is shown after the modulated RF amplifier for low-level modulation, which serves to emphasize the difference. It is obvious that this amplifier must be a linear RF amplifier, or class B. Keep in mind that if the final amplifier had been the one that had the modulation, it would have been referred to as low-level modulation (or collector) [62]–[69].

As a result, more audio power is needed to create modulation at greater levels of modulation. This is undoubtedly a disadvantage for the high-level system. However, if any level other than the output stage is modulated, each stage after that must manage sideband power in addition to the carrier. These following amplifiers all need to have enough bandwidth for the sideband frequencies. All of these steps must be able to manage the amplitude changes brought on by the modulation. These stages, which must be class A, are less effective than class C amplifiers.

Low modulating power requirements in one system and much more effective RF amplification with a simpler circuit design in the other are viewed as each system's major advantages. In actual use, it has been discovered that a plate-modulated class C amplifier often exhibits higher levels of efficiency, less distortion, and superior power handling capability. Broadcast AM transmitters nowadays nearly always employ high-level modulation, while TV transmitters use grid modulation as the last step due to these factors. In low-power and other applications, AM generators, and test equipment, other techniques could be employed. With average output levels ranging from dozens to hundreds of kilowatts, broadcasting is the primary use of AM. The rest of this chapter focuses on vacuum-tube systems.

Class C amplifier with grid modulation

By adding the modulating voltage in series with the grid bias, a class C amplifier may be modified. The fixed battery bias is overlaid with the modulating voltage. As a result, the bias fluctuates at a rate equal to the modulating frequency and is proportional to the amplitude of the modulating signal. The RF input voltage overlaid on the total bias, along with this. As a consequence, the plate current flows in pulses, with each pulse's amplitude being inversely proportional to the instantaneous bias and, by extension, the instantaneous modulating voltage. When these pulses are applied to the tuned tank circuit, amplitude modulation results.

The waveform demonstrates that this system will only function distortion-free if the triode's transfer characteristic is absolutely linear. The output must be somewhat distorted since this is impossible, and it must be more so than from a plate-modulated amplifier. It turns out that the lower plate efficiency is also a result of the need to set up the input conditions which prevents grid current from flowing when full modulation is not desired (this is due to the 's geometry and is necessary so that full modulation may be obtained when desired). Reference to the class C amplifier's behaviour demonstrates that it only performs at full efficiency when the grid is pushed to its limit, which is not the case in this situation.

Because of these bias conditions, a gridmodulated amplifier's maximum output power is much lower than what the same tube can produce when it is unmodulated (or plate-modulated). The benefits of grid modulation are offset by the fact that it requires less modulating power than plate modulation. By running the amplifier in push-pull mode, the harmonics produced by the transfer characteristic's nonlinearity may be decreased. AM is not generated for transmission using grid modulation unless additional conditions are present.

Class C amplifier that is plate-modulated

The conventional and most popular technique for achieving amplitude modulation for broadcasting and other high-power transmission applications is the plate-modulated class C amplifier. A class C amplifier's plate current, which varies in accordance with the modulating sign, is connected in series with the audio voltage. The transmitter's final power amplifier is the one that receives this kind of modulation the most (more simply termed the final or the PA).

Typically, an audio output (modulating) transformer is used to apply the modulating amplifier's output to the PA. This system, which involves anode modulation of the output power amplifier and class B functioning of the modulator with transformer output, is frequently referred to as anode-I) modulation. A class B modulator is used by the transformer, which provides high audio efficiency. Since the output of the modulator may be stepped up to any needed value, it also enables 100 percent modulation to be accomplished. These factors led to the use of this modulation scheme in the great majority of AM broadcast transmitters to modulate transformers. By adding the modulator and its transformer output, the equivalent circuit shown in has been changed into the actual circuit . Since neutralization would undoubtedly be required to prevent the Miller effect in a triode at high frequencies, as it was for the grid-modulated amplifier, neutralisation is also shown. To make the explanation simpler, a shunt fed C amplifier is shown; in actual application, it may or may not be employed. To prevent RF damage to the modulation transformer, a choke is connected in series with it.

It can be observed that the PA and the modulator both utilise the same supply voltage, V_{bb} . This indicates that the peak modulator output voltage (per tube) should be kept below V_{bb} to prevent distortion, and that the ideal value is $V_{AF} = 0.1v$. The transformer turns ratio in this scenario will be 1.4:1 since the peak-to-peak modulator primary voltage is now 1.4 v and an audio voltage equal to V_{bb} is needed to provide complete modulation depicts a fixed bias supply V_{ee} , although self-bias may also be employed as leak-type bias. This fact leads to improved functioning.

The entire plate voltage provided to the class C amplifier is shown on the first waveform of, 310, and the corresponding plate current is shown on the second. When these are supplied to the tank circuit, the modulated wave of the waveform. Results of plate-modulation waveforms. Although the required train of current pulses is created using a different approach that also has the benefit

of being more linear, what occurs in this situation is plainly quite similar to what occurred with the gridmodulated amplifier.

The final three waveforms in are utilised to depict the behaviour of the circuit rather than to demonstrate how the circuit creates AM. The combined supply voltage of and the RF-modulated voltage are superimposed to create the waveform of , 3-1 Od, which depicts the total voltage that appears between the plate and cathode. The main coil of the output tank is crossed by the RF voltage in the circuit shown in, while the coupling capacitor C_c blocks the supply voltage goal is to demonstrate how much higher than V_{bb} the peak plate voltage can go. · In fact, at 100% modulation, the positive peak of the modulated C)cle climbs to double the unmodulated RF voltage peak of over $2V_b$. Thus, in the plate-modulated amplifier, the maximum plate voltage may increase to over $4 V_{bb}$. Making ensuring the tube can handle such a high voltage requires careful consideration.

Although the RF driving voltage does not change throughout the modulating cycle, the waveform shows that the modulated amplifier's grid current changes. The plate is only mildly positive when the plate supply voltage drops at the negative modulation peak, and since the grid is also driven positively, the current in the grid now climbs very noticeably. The contrary is true, as grid current decreases at the modulation's positive peak. Because of how much the present increase surpasses the current fall, the change is not sinusoidal. There are two undesirable consequences if this scenario is not resolved. First, if grid current increases, the driver can get overloaded, which would distort the output wave. Second, the PA's grid is nearly guaranteed to melt!

There are two treatments available, and displays the outcome of the most effective of the two. The best remedy is to employ grid leak bias to accomplish limitation similar to that used by the amplitude limiter in FM receivers. The first is to have a motor with poor control so that grid current cannot rise .Grid bias also grows, becoming more negative and tending to decrease grid current since grid current now tends to increase. Grid current is now balanced for any initial value such that even though it continues to climb. This increase is far less noticeable and may be perfectly fine. Grid current would normally tend to decrease at the peak of the positive modulation, but this fall is now mitigated by a concurrent drop in the negative bias, making the grid-current waveform resemble a much flattened version of . Grid voltage no longer remains constant, as seen in . As a result, the grid is now more positive at the peak plate current, which helps with modulation. It is now simpler to get such a high plate current value, which prevents distortion at the positive modulation peak. From a different angle, it can be observed that the waveform in .We get a more effective and less distorted grid and plate modulated amplifier.

Tetrode plate modulation the same satisfactory results may be obtained when a screen-grid tube is utilised as a plate-modulated class C amplifier, provided that the additional considerations are taken into account. It is definitely necessary to consider the fact that, if screen voltage exceeds plate voltage, screen current rises dramatically. If it weren't, this scenario (if the screen were just linked to voltage by a falling resistor) might happen here once per cycle of modulating voltage. , provides an illustration of this. By modulating the screen and plate concurrently, as illustrated on the circuit of the problem may be readily avoided. Otherwise, the system would become very inefficient and the tube would only last a short time.

By altering the plate voltage simply (while keeping the screen voltage constant), the same technique avoids the challenge of attempting to change the plate current of a screen-grid tube. Thus, when leak-type bias is applied, we obtain a high-level system that is concurrently plate-,

screen-, and even grid-modulated. This system also has excellent features, qualities, and a plate efficiency that, in reality, may surpass 90%.

MHz Modulated Transistor Amplifiers

Transistor RF and AF exciters are widespread because modern high-power AM transmitters often employ transistors at the lower power levels. Such transistors often use tubes as the drivers and output stages. For lower frequencies, all-transistor transmitters are employed. A few kilowatts of output are possible for power applications using a plate-modulated tetrode class C amplifier if transistors are used in parallel. Therefore, for maximum power output, modulated transistor amplifiers nearly always incorporate a push-pull final amplifier. Modulation techniques for transistor amplifiers are equivalent to those for tubes. Class C transistor amplifiers are widely used, and both collector and base modulation have the same benefits and characteristics as analogous tube circuits.

Better linearity, greater follower efficiency, and more power output per transistor are benefits of collector modulation over base modulation. As anticipated, greater modulating power is needed. Additionally, collector saturation makes it impossible to accomplish 100 percent modulation by modulating just the collector, necessitating the employment of a compound type of modulation in many instances depicts one of the options. In this case, the output amplifier and driver are both collector-modulated, but other than that, the circuit is similar to a tube circuit. The second option is to use the same amplifier's collector and base modulation. When grid leak bias is employed with tubes, this technique is often used. Although leak-type bias may once again be utilised for this purpose, there is a risk that the bias will become excessive and power output will increase if enough bias action is applied to allow base modulation shown below.

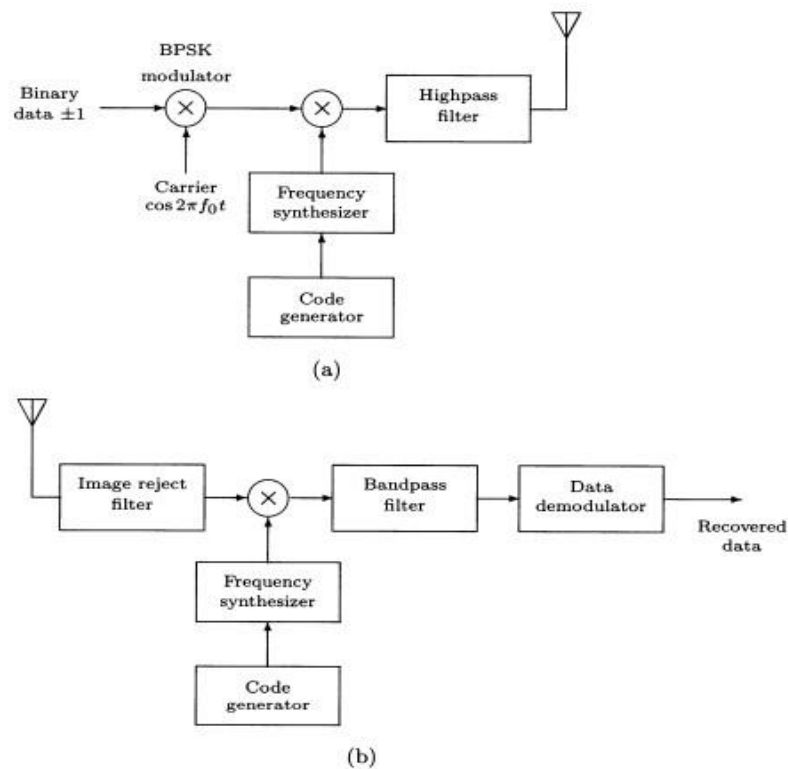


Figure 5.1 shows the base modulation.

AM transmitters are more complex than what has been previously explained. First off, there is the sheer size; a medium-power (let's say, 50 kW) broadcast transmitter takes up a respectable amount of space. With many outputs for the low- and high-power sections of the transmitter, a large and complex power supply, typically three-phase on the ac side and regulated on the dc side to prevent unwanted output variations, and carefully implemented isolation and de-coupling to prevent unwanted feedback and interference shown below.

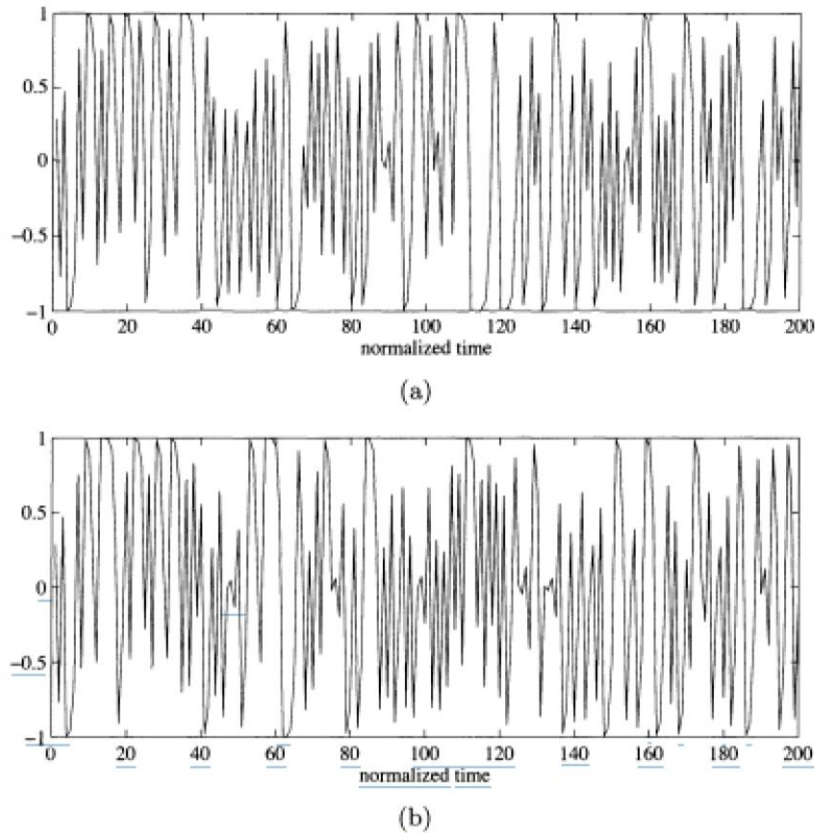


Figure 5.2 shows the feedback and interference.

In order to reduce the consequences of changes or breakdowns in the main supply, a backup diesel generator is often added. Some transmitters even incorporate a battery compartment, a dcac inverter, and complicated automated switchover circuitry to guarantee that there is no output interruption after a power supply loss before the backup generator kicks in. To take over during transmitter failures or maintenance, a standby transmitter with a power output of about one-fifth that of the main transmitter is often supplied. In order to maintain a lower, more consistent operating temperature while increasing operational life and power output, transmitters with power outputs in the kilowatt range also use forced cooling of the power stages.

A huge AM transmitter sounds as though it is functioning while air conditioning is active. It also seems to be in use because to the metering that is almost always given. Metering is offered for almost all operational elements and is utilized as an operational, maintenance, and diagnostic tool to help identify potential problems as early as possible. Most of the metering in older transmitters will take the form of dials for each step, with switches to show various values. Broadcast

transmitters are meant to have a working life of at least 20 years. Switchable digital displays are more likely to be found on more recent transmitters than most modern ones.

Amplification Modulator 53 include computer-controlled metering features that the operator may see on a screen as needed. The different voltages and currents, the transmit frequency, the audio and RF output, and the modulation % were the most crucial components. Over modulation must be avoided since else erroneous frequencies will be broadcast, disrupting legitimate communications.

The technique of amplitude modulation is one that has been practised for many years and is virtually solely employed in broadcasting. It is simple to produce and simpler to receive 111d demodulate. This last condition is crucial since it results in simple and reasonably priced receivers. It must not be overlooked that the receiver-to-transmitter ratio in broadcasting is quite high, with hundreds or even millions of receivers for every transmitter. This is particularly important since it suggests that not only are the typical tradeoffs between transmitter and receiver complexity reasonably constrained, but also that big improvements are hard to accomplish if they influence receivers.

As a result, despite the fact that AM is neither the greatest or most effective modulation system as will be seen in the chapters to follow its usage for broadcasting is so widespread that adjustments are not even being thought about. Since ship-to-shore and land-mobile communications, which were utilised for mobile communications until relatively recently, are no longer used, sound broadcasting is now the primary function for AM. AM is more prone than FM to be impacted by noise, as we shall discover in Chapter. In Chapter, the carrier and the two sidebands of an AM wave are analysed. The results demonstrate that considerable bandwidth and power savings may be achieved by suppressing the carrier and one of the sidebands prior to transmission. The consequences include increasing receiver complexity and expense. Therefore, point-to-point networks and other applications where the number of receivers is close to the number of transmitters are more likely to employ such systems shown below.

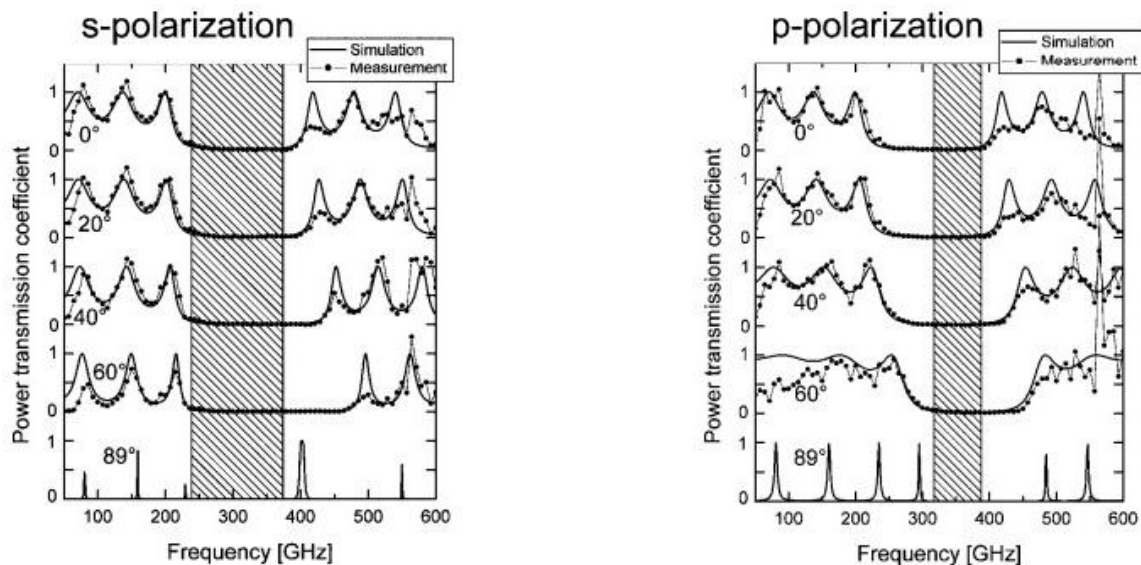


Figure 5.3 shows the point-to-point networks.

Different unpleasant side effects occur during transmitting and receiving. Since attenuation weakens the signal at the receiver, it is undesirable. However, turbulence, confusion, and interference take the form of modifications to the signal's waveshape or spectrum are more harmful. Although such contaminations might happen at any time, it is customary to bundle them all together on the channel and assume that the transmitter and receiver are in perfect condition.

A graph of a perfect 1101001 binary code as it exits the transmitter may be seen in the values of the signal are defined by their sharp edges. Square wave distortion is a result of the system's faulty reaction to the intended signal itself. Distortion does not go away when the information is switched off, in contrast to disturbance and noise. Equalizers are specialised filters that may be used to decrease distortion or, in certain cases, rectify it when a channel exhibits linear but distorted response shown below.

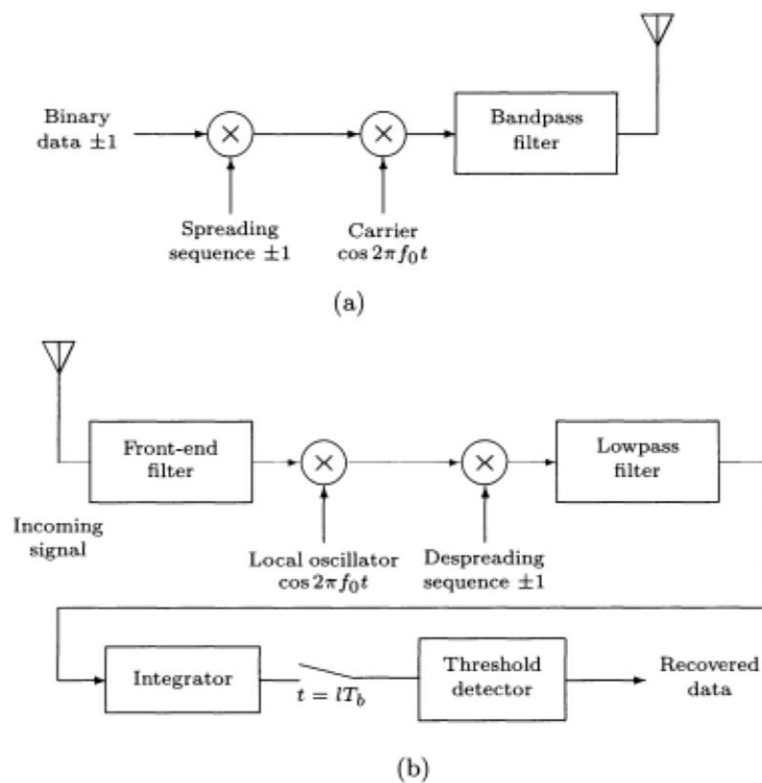


Figure 5.4 shows the distorted response.

Interference is the contaminating effect of superfluous signals involving human sources, such as other receivers, machinery, power lines, and switching circuits. The majority of intervention occurs in radio systems whereby receiving antennas often pick up several broadcasts at once. Cable systems may potentially experience radio-frequency interference (RFI) if the reception electronics or transmission lines pick up signals sent by neighboring sources. Despite the fact that systems using CDMA, effective filtering eliminates intervention to the degree that its unwanted signals comprise distinct frequency bands from the intended signal.

An ordered series of symbols chosen from a limited collection of discrete components constitutes a digital message. The letters on this page, a table of hourly temperature measurements, or the keys your press on a computer keyboard are all examples of digital communications. Since the

information is contained in discrete indicators, a digital connection must send these discrete symbols within a certain length of time and with a certain level of precision.

Few message sources, analogue or digital, are intrinsically electrical. For instance, a smartphone at the entrance and a public address system at the exhaust might serve as the piezoelectric in a speech data transmission. Moving forward, we'll assume that appropriate transducers are available, and we'll focus exclusively on the job of signal transmission. Since the signal and the message are both physical manifestations of information, the words signal and message shall be used synonymously in this connection.

CHAPTER 6

Modulation in Communication System

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The process of modulating involves encoding data out of a transmitter in a fashion that is appropriate for transmission. This is accomplished by changing a wave's properties. Video, speech, and other data may be communicated by superimposing a message over a high frequency signal classified as a carrier wave (or sinusoidal signal). The carrier wave's amplitude, frequency, or phase are changed in line with the message signal during the modulation process. This variant serves as a data transmission code. The transmitter then broadcasts this modified signal.

The receiver disconnects the modulated signal it has just received and receives the signal's original content. As was covered in the communication systems lecture, the goal of a telecommunications system is to transmit a message signal in a recognized form from an information source to a user destination, even while the source and the user are physically apart. The transmitter does this by modifying the original message into a format that is appropriate for channel broadcast. By modulating a carrier wave, which includes changing some of its properties in response to the message signal, it is possible to make this alteration. Additionally, after passage via the channel, the receiver reconstructs the genuine digital signals using a weakened version of the sent signal. Demodulation, a method, is used to produce this reconstruction. Whether or whether a steering method is present, an electromagnetic wave is constantly moving during signal transmission across a sizable distance.

The frequency of the signal being conveyed determines how effective a certain transmission technique is. A provider whose spectrum has been chosen for the intended transmission mode may have message information imprinted on it by taking use of the density capability of CW modulation. As an example, effective line-of-sight ratio propagation necessitates antennas with physical dimensions at least $1/10$ the wavelength of the signal. Thus, 300 km of antennae would be required for the arpeggiated transport of an audio signal with frequency components as low as 100 Hz. A realistic antenna size of roughly one metre is possible with modulated transmissions at 100 MHz, similar to FM broadcasting.

Alternate diffusion modalities with suitable antenna sizes are more effective at ranges below 100 MHz. In actuality, the modulation method utilized in the transmitter is reversed during the wavelet decomposition. In a more organized manner, we may characterize the instrumentation process as follows:

Modulation refers to the method through which a signal's component undergoes changes based on the current value of another frequency, the modulated signal, according to the definition of diversity. Modulating signals are described as having information or understanding in them. A baseband signal is another name for this data-carrying signal. The modulating frequency is lower than the carrier frequency. The modulated signal is the one produced by the modulation process.

Modulation Types

There are essentially two forms of modulation:

1. Continual Wave Modulation
2. Pulse Modulation

Continuous Wave Modulation:

1. The modulation technique is referred to as continuous wave (CW) modulation or analogue modulation when such carrier wave is continuous in nature.
2. Frequency division and angle instrumentation are two types of continuous-wave modulation.
3. Amplitude modulation is the process of changing the carrier's amplitude in response to the message signal (AM). Angle modulation is the term for the process of changing the carrier's angle in response to the input signal of the modulating signal.
4. The two further subtypes of angle modulation are frequency modulation (FM) and phase modulation (PM), in which the carrier's instantaneous frequency and phase are changed in response to the message signal, respectively.

Pulse Modulation: This sort of modulation is used whenever the frequency band has a pulse-like pattern. The carrier in pulse modulation is made up of a regular series of rectangular pulses. The kind of pulse manipulation might be either analogue or digital. When using analogue pulse modulation, the message signal's sample values are used to adjust the pulse's amplitude, length, or location. The following three forms of analogue pulse modulation are possible:

1. Pulse-amplitude modulation is the first (PAM)
2. Pulse-duration modulation is (PDM).
3. Pulse-position modulation (PPM).
4. On the other hand, pulse-code modulation refers to the digital version of pulse modulation (PCM).

Spread-Spectrum Systems Benefits

Spread-spectrum approaches undoubtedly provide a fundamental degree of security and effective anti-jamming capabilities.

Additionally, it can be shown that spread-spectrum communication systems provide a number of benefits that traditional systems cannot reasonably give. For instance, they may reduce the multipath effect in wireless channels and average the signal quality across all users in a multiple-access situation. Spread-spectrum systems save frequency planning effort and boost system capacity, especially for mobile cellular networks.

Multipath Effects Mitigation

Typically, there are several paths (multipath) between the transmitter and the receiver in a wireless communication environment. The interference between multipath signals will result in signal fades, which will lower the quality of the receiving signal. It can be shown that multipath components with differential delays of $1/W$ or longer are resolvable for a given bandwidth W of the transmitted signal. For example, the increased signal bandwidth in the DS-SS system enables a sharper resolution of the multipath components. After the components have been identified, we may use RAKE receivers to gather the signal energy from each component.

Signal quality averaging in environments

Each user wishing to send a message is given a specific time slot or frequency channel, which occupy a constrained bandwidth, under the traditional time-division multiple access (TDMA) or frequency-division multiple access (FDMA) schemes. Depending on the channel circumstances, various resources (time slots or frequency channels) may experience varying degrees of distortion. For instance, certain resources could have more interference and provide signal quality that is quite subpar. Various spreading or hopping sequences will be allocated to different users in DS-SS or FH-SS systems. All users will be getting signals with the same average signal quality since everyone is utilizing the same bandwidth (on average for FH users) for data transfer.

Less Work Required for Frequency Planning

Each geographic region is split into smaller regions known as cells in mobile cellular networks. Various cells are used to effectively use the bandwidth allotted. Concurrently use the same set of frequency bands. Frequency reuse is the term for this. Frequency planning is the process of allocating frequency bands (carriers) to cells in conventional TDMA or FDMA systems. Experienced engineers are typically in charge of frequency planning because they must make sure that each cell receives the maximum number of channels possible and that interference between cells using the same frequency band is kept to a minimum. Frequency planning is often a costly and time-consuming procedure that involves numerous rounds of frequency planning and field testing. Each user in a multi-user DS-SS system is given a unique spreading sequence. Direct-sequence code-division-multiple access is the name of this kind of multiple access (DS-CDMA). Here, all users are simultaneously transmitting their signals over the same spectrum. Only the spreading sequences they use allow for differentiation between them. Applications of Spread-Spectrum Communications.

Increase in System Capacity

Once all the resources in TDMA or FDMA systems are assigned, no further users may be supported even if part of the resources may be idle unused at a certain time. Unlike TDMA and FDMA systems, DS-SS and FH-SS schemes are flexible enough to include new spreading or hopping sequences, allowing for the system to support more users. Typically, there are a lot of spreading or hopping sequences. Naturally, as the number of users rises, so does the interference level for DS-SS systems and the likelihood of a carrier collision for FH-SS systems? The interference caused to other users may be lessened by lowering the transmission strength of users who have nothing to broadcast (for example, during the pauses in a chat). As a result, the total system capacity may be expanded without significantly lowering the consumers' signal quality. According to analysis DS-CDMA systems may attain three to seven times the capacity of digital TDMA systems in mobile cellular contexts.

Spread-spectrum Communications Applications

Spread-spectrum technologies are no longer just created for military use. The same methods are still used today in a variety of business and domestic communication systems. For instance, direct-sequence spread-spectrum (DS-SS) is used in several second- and third-generation mobile communication systems to spread the binary signals in both the uplink and the downlink. Some satellite communication systems employ DS-SS as their primary modulation technique in

addition to terrestrial communications .The Global Positioning System (GPS), commonly referred to as NAVSTAR, makes use of DS-SS).

In the NAVSTAR system, there are 24 satellites in equally spaced 12-hour orbits around the planet, and their exact locations are always known. Two DS-SS signals are sent by every satellite. A terrestrial user will be able to precisely determine his location when they concurrently decode the signals from at least four separate satellites. Originally designed for military usage, GPS is now extensively utilised for a variety of civil purposes, including fleet management, geodesic surveying, and navigation.

The wireless local area network and the short-range wireless communication protocol Bluetooth are the two systems that use the frequency-hopping spread-spectrum approach most often chaotic signals are non-periodic, random-like signals originating from nonlinear dynamical systems. A dynamical system typically contains a fixed number of independent state variables, and the movements or trajectories of these variables are controlled by a set of differential ,s that include all of the state variables shown below.

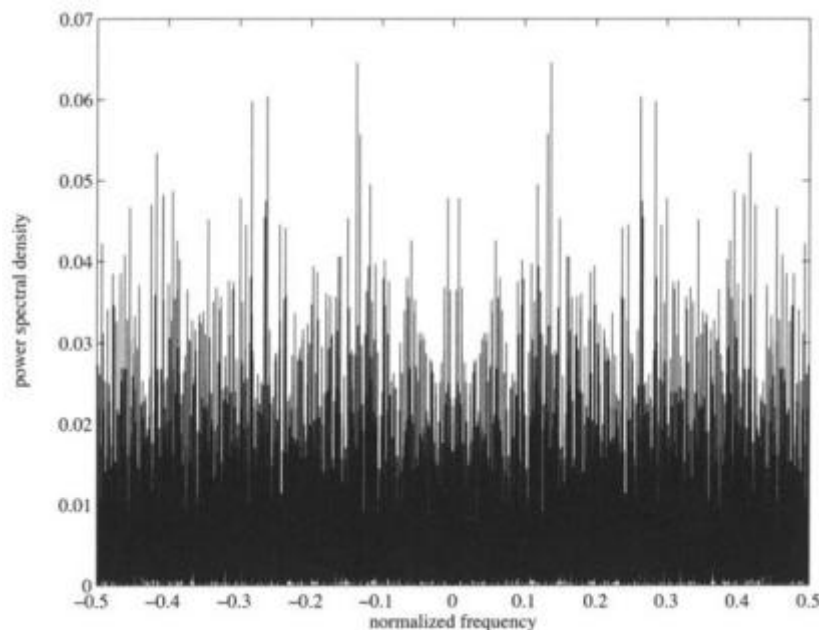


Figure 6.1 shows the state variable.

There are N state variables and N differential, s that can be formulated for a system of n th order. Consideration of discrete-time representations of dynamical systems is all that is necessary to comprehend how chaotic signals are produced are two kinds of frequently explored methods for transferring analogue information with chaotic signals. The analogue signal is added to a chaotic system's output in the simplest chaotic masking method. The analogue information is then recovered by deducting the replicated chaotic signal from the incoming signal at the receiving end, which is based on a procedure known as chaos synchronisation. In addition, more complex masking techniques have been developed, such as feedback-based masking.

Chaotic modulation's fundamental concept is to introduce analogue information into a chaotic system to change its behaviour. Usually, this is done by modulating a well selected parameter. As a consequence, the analogue information is included in the chaotic signal that the system

produces. In order to extract the analogue information, the receiver must monitor how the chaotic signal's dynamics evolve. Digitized modulation it has been suggested a number of times in the past to use chaotic signals to encode digital information. The fundamental idea behind the majority of suggested approaches is to map digital symbols to non-periodic chaotic base signals. For instance, chaotic switching or chaos shift keying (CSK), which is created from 1.5 Chaos-Based Communications 13 1.2r, maps various symbols to various chaotic basis signals.

Using various bifurcation parameter values or from a variety of dynamical systems, introduce a dynamical system. If the receiver has access to synchronised copies of the chaotic basis signals, detection may be accomplished by measuring the synchronisation error. Coherent detection is the name given to this kind of detection.

Differential keying is the foundation of yet another thoroughly researched modulation method for encoding digital information. Differential chaos shift keying (DCSK) is a method that, according to fabricates a specific information bit structure that enables detection to be carried out incoherently, that is, without the existence of synchronised copies of the chaotic signals at the receiver. Each transmitted symbol in the binary instance is represented by two chaotic signal sample sets. One is used as a reference sample set, while the other is a data sample set. The data sample set is either an identical or an inverted replica of the reference sample set, depending on the symbol being conveyed. Correlating the two chaotic sample sets makes demodulation simple to do. The output of the correlator may be compared to a threshold value to distinguish between the binary signals.

There have also been a few other digital modulation schemes that are derivations of CSK and DCSK, such as chaotic on-off-keying and quadrature CSK Spread-Spectrum Direct Sequence. Heidari-Bateni and McGillem originally reported on the direct application of chaos to a traditional direct-sequence spread-spectrum system in . The core idea is to use chaotic binary spreading sequences produced by a discrete-time nonlinear map in lieu of traditional binary spreading sequences like m-sequences or Gold sequences. It has been shown that the novel system's performance is on par with that of the established systems that use binary spreading sequences.

Mazzini and his coworkers suggested quantizing and regularly re2ing the data symbols as an alternative to using analogue chaotic sequences to distribute the data symbols. Throughout this book, we differentiate between coherent and noncoherent detection techniques based on the need that synchronised copies of the chaotic signals be present at the receiver. Therefore, it is necessary to assume that synchronised copies of the chaotic signals are present at the receiver as a result of a chaos synchronisation process while researching coherent detection. Chaos synchronisation, on the other hand, is a highly complex area of mathematics and physics that is not covered in this book.

Advantages and Drawbacks

Chaotic signals have large power spectra and a random-like nature, as was indicated in . Thus, it is feasible to significantly improve data security by encoding information in chaotic signals. When utilised for transmission, chaotic signals inherit the benefits of traditional spread-spectrum signals, such as low detection likelihood, anti-jamming, multipath mitigation, etc. In addition, chaotic signals are simple to create and potentially unlimited in number, offering a relatively inexpensive alternative to the development of spread-spectrum systems. Theoretically, it has

been shown that spreading sequences formed by quantizing and repeatedly repeating slices of chaotic time-series increase system performance in terms of capacity and bit error rates. This is especially true for direct-sequence code-division multiple-access systems.

From a practical engineering perspective, chaos-based communication systems are still in their infancy, and there are a number of significant technical problems that still need to be addressed. We try to list a few of the difficulties in creating useful chaos-based communication systems in the paragraphs that follow. The transmitted signal's bandwidth must always be understood in practice. To the best of our knowledge and as of this writing, there don't seem to be any formal methods for calculating the bandwidths of chaotic signals.

The only option is computer simulations.

As was before established, coherent detection depends on the receiver having access to synchronised copies of the chaotic signals. The chaotic systems at the transmitter and receiver then need to be strongly synchronised. The issue is complex, and as of this writing, no workable chaotic synchronisation algorithms exist that can be used in communication systems to achieve the necessary low signal-to-noise ratios. The study of non-coherent detection, which does not need chaotic synchronisation between the transmitter and receiver, is also motivated by this.

Because there are so many different possible detection strategies, non-coherent detection methods might be seen as being somewhat understudied. The non-coherent digital schemes have all been examined, but DCSK has received the most attention to far. However, DCSK does not employ the deterministic aspects of chaos at all. It is conceivable that non-coherent detection may provide new avenues for investigation into chaotic communications.

Designing communication systems must take into account non-ideal channel characteristics as distortion and noise. The impact of channel distortion may be more severe when chaotic signals are used for transmission since it may entirely prevent synchronisation at the receiver. Additionally, only a small number of particular systems have had the issue of multipath propagation taken into account clearly, more effort is required. Last but not least, each chaotic signal is unique. It is still unclear how to choose the "most desired" chaotic signals to be used in communication systems. To establish some key attributes for analysis, such as means, variances, probability density functions, etc., time-consuming simulations must now be undertaken.

For the most part, when a system is described in discrete time, its state variables are sampled at fixed time intervals, and its dynamics is described by an iterative function that expresses the state variables at one sampling instant in terms of those at the previous sampling instant. Dynamical systems that exhibit chaotic behavior have state variables that move in a bounded, irregular, and random-like manner. Sensitive dependency on beginning circumstances, which simply implies that any two neighboring starting conditions may quickly lead to two completely uncorrelated movements or trajectories of the state variables, is another unique characteristic that describes them. By using various beginning values, this attribute potentially enables us to produce an endless number of chaotic, uncorrelated signals from the same system.

The waveform of the state variable of a first-order discrete-time chaotic system is seen in we display the waveform once again with a slightly modified beginning value to demonstrate the sensitive dependency on initial circumstances. It is also important to note that chaotic signals exhibit white broad band power spectra and impulse-like auto-correlation functions as a result of their randomness. Additionally, chaotic signal cross-correlation has a very low value. A

dynamical system may be described in terms of an iterative function that uses the current state variables as input and produces new state variables at discrete times thanks to the discrete-time representation. The sample period determines the intervals at which the state variables are updated. The iterative function resembles a continuous-time representation that takes the form of differential when the sampling period approaches towards 0 in the limit shown below.

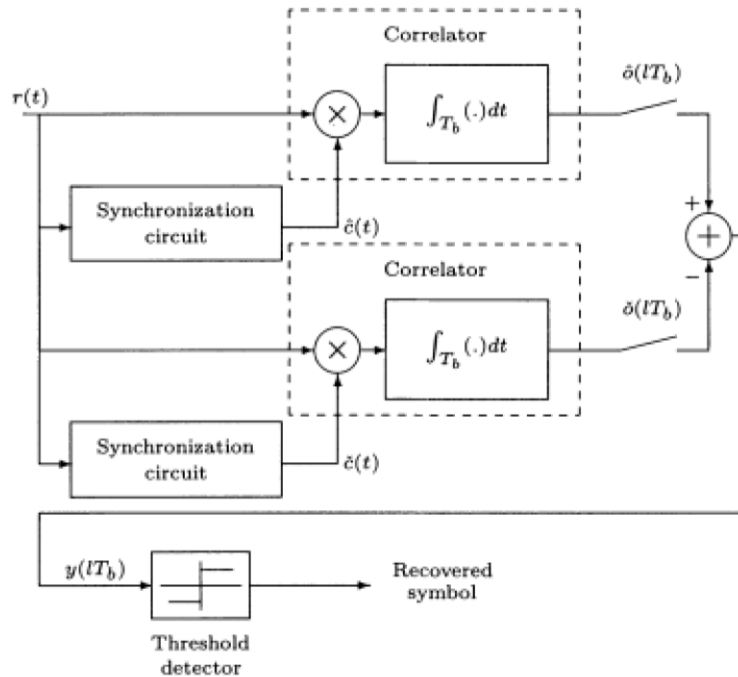


Figure 6.2 shows the sampling approach.

Chaos Applied to Communications

Chaos signals are ideal candidates for narrowband information dissemination due to their inherent broad band feature. Thus, spread-spectrum signals with greater bandwidths and lower power spectral densities are produced when chaotic signals are used to encode information. As was noted in the previous section, they benefit from all the advantages of spread-spectrum signals, including the difficulty of uninformed detection, mitigation of multipath fading's, antijamming, etc. The sensitive dependency on beginning circumstances and parameter adjustments also makes it simple to create a huge variety of spreading waveforms. As a result, chaos offers a flexible and affordable method for spread-spectrum communications. Numerous modulation and demodulation systems for communications have been presented in recent years. The three sorts of communication approaches that have received a lot of research are briefly reviewed in the sections that follow.

Digital Modulation and Demodulation Methods Based on Chaos

We present chaos-based digital communications in this chapter. We start out by talking about traditional digital communication technologies. First, we go through how digital modulation works in its most basic form, which is to represent digital symbols using periodic basis signals. In our primary subject, the same fundamental operation is extended to chaos-based digital communication systems, where the modulation process uses chaotic basis signals rather than

periodic basis signals. This chapter provides an overview of recent advancements in the subject and reviews some of the most extensively researched chaos-based digital modulation methods shown below.

Class	System		Correlator-type detection applicable
Coherent	Analog	Chaotic masking	No
	Digital	Generic: Chaos shift keying (CSK)	No
		CSK (correlation) Symmetric CSK	Yes Yes
		Direct-sequence spread-spectrum: Chaotic spreading sequence	Yes
		Chaotic digital CDMA Quantized chaotic spreading sequence	Yes Yes
Non-coherent	Analog	Chaotic modulation	No
		Signal-reconstruction-based system	No
	Digital	Differential CSK (DCSK) FM-DCSK	Yes Yes
		Chaotic on-off-keying CSK (bit-energy) CSK (optimal)	No No No
		CSK (regression) Correlation delay shift keying Quadrature CSK	No Yes Yes
	Ergodic CSK	No	

Figure 6.3 shows the digital modulation.

Moving from traditional to chaotic digital communications

The information (digital symbols) that must be conveyed in digital communication systems is first translated into some analogue base signals. The action is referred to as modulation. The generated modulated signals are then sent to the destinations via certain suitable channels. Attenuation, band pass filtering, nonlinear distortion, and noise contamination are just a few of the unwanted impacts that practical channels have on the signals being conveyed. All these deviations from the ideal will taint the signals and make it challenging to retrieve the original data. Therefore, using the damaged copies of the basic signals, the receiver must ascertain the identification of the digital symbols.

The analogue basis signals used to represent the digital symbols in traditional digital communication systems often vary in either amplitude (as in amplitude shift keying), frequency (as in frequency shift keying), or phase (as in phase shift keying). The receiver recognises the variations and decodes the signals it receives. With the exception of differential encoding techniques, the identical analogue basis signal is sent for every symbol that is transmitted. In general, there are two sorts of detection methods: coherent and non-coherent types. The phrase "basis functions" is often used in place of "basis signals" in a large portion of the literature. The two words are used interchangeably throughout this work shown below.

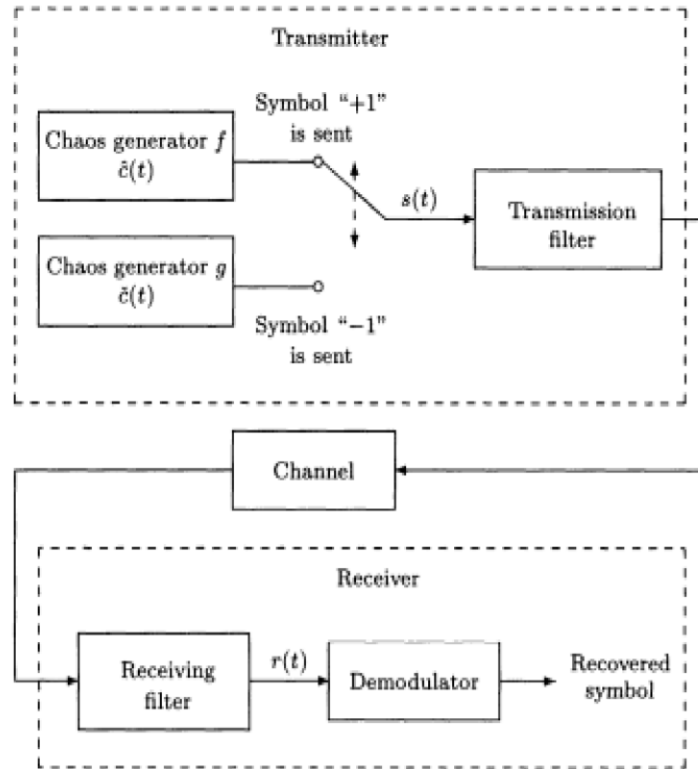


Figure 6.4 shows the interchangeable method.

Digital Modulation and Demodulation Based on Chaos Techniques signals unmodulated carriers are used for demodulation and must be duplicated at the receiver. The basis signals do not need to be recovered at the receiver for non-coherent detection. With differential phase shift keying (DPSK), the signal in one signaling interval is purposefully tied to the signal in the previous signaling interval in a specific manner. Determining the sort of connection between the signal in one signaling interval and that in the previous interval is therefore the challenge of demodulation.

Chaos-based digital communication systems are what we get when we employ chaotic basis signals instead of the traditional periodic basis signals for digital communications. The effect of adopting chaotic basis signals would result in major conceptual changes in the emerging systems, as is to be expected given the basic nature of chaos. First off, it is obvious that reproducing replica basis signals in the receiver would not be an easy process due to the sensitive reliance of chaotic signals on their beginning conditions. As a result, coherent detection may suffer greatly.

However, because coherent detection ought to theoretically perform better than non-coherent detection, research on coherent systems would provide standards for measuring performance. Because of this, we examine coherent systems in considerable detail in this book. Furthermore, even if replica basis signals are present in the receiver, the study of chaos-based communication systems is still challenging because chaotic signals may not be amenable to the same standard processing as periodic signals, such as the calculation of statistical means, variances, correlation functions, probability density functions, etc. Computer simulations are the sole option since traditional statistical analysis may not always result in analytical expressions for performance assessment. The study of non-coherent systems runs into the same issue as well. We discuss several analytical techniques for assessing the effectiveness of chaos-based digital

communication systems in the later chapters of this book. We restrict ourselves in this book to analytical techniques that communication engineers are acquainted with, while it should be emphasised that alternative approaches have also been offered for the analysis of chaos-based communication systems shown below.

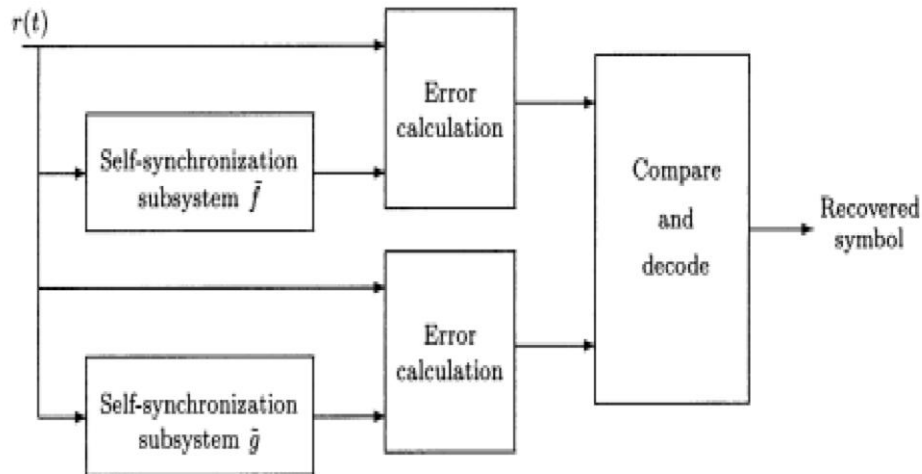


Figure 6.5 shows the communication system.

Following a brief overview of the many chaos-based communication systems, we aim to categorise these systems in order to make it easier to conduct a thorough examination into how they function. As in the typical situation, coherent and non-coherent systems may be used to categorise chaos-based communication systems shown below.

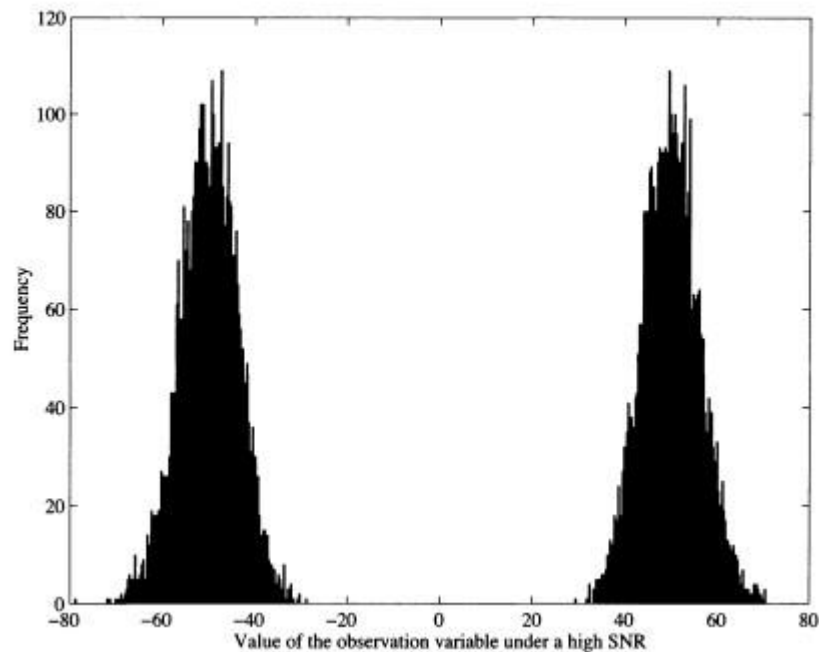


Figure 6.6 shows the chaos-based systems.

Shift Keying in Chaos

Initially introduced chaos shift keying (CSK) the concept is to use chaotic basis signals to encrypt digital symbols, as was previously described. The block diagram of a typical CSK digital communication system is shown. The following is a description of the operational principle. Two chaos generators, f and g , which produce the signals $c(t)$ and $c(t)$, respectively, make up the transmitter. During the period $[(l-1)n, ln]$, $c(t)$ is broadcast if a binary "+1" is to be sent, and $c(t)$ is communicated if a binary "-1" is to be sent. The CSK system operates on the basis of chaotic systems' ability to self-synchronize in its first suggested form. The receiver structure is shown in, where two self-synchronization subsystems f and g that are matched to f and g , respectively, are driven by the incoming signal. Assume that the channel is flawless and that there is no distortion in the filters at the transmitter and receiver. The subsystem f will be synchronised with the incoming signal when the sent signal is $c(t)$, but g will not be, and vice versa. Therefore, the transmitted symbol may be roughly calculated by measuring the discrepancy (error) between the incoming signal and the output of the self-synchronization subsystems. The systems perform effectively in a noiseless environment, according to results.

Correlation is a general method used in communications to assess the "likeness" of two signals. Clearly, with the CSK system indicated above, we may directly evaluate the performance instead of evaluating the synchronisation error. Utilize the correlation between the replica basis signals and the transmission signal to determine the transmitted symbol. A general coherent receiver for the CSK system is therefore formed by a correlator and a decision maker.

Coherent dithering according to correlation

Investigated coherent detection of CSK signals using correlator-based receivers in great detail. A coherent CSK demodulator based on correlators is shown in block diagram form in. From the received distorted signal r , the two synchronisation circuits make an effort to recover the two chaotic signals, $c(t)$ and $c(t)$ (t). For the synchronisation blocks to lock to the incoming signal, an acquisition time T_s is expected. The rest of the bit period is then utilised to correlate the replicated chaotic functions with the received signal. Following that, a sample of the correlators' outputs is compared.

A "+1" is deciphered for the l th symbol if y is positive. If not, a "-1" is translated. The histograms of y are useful to understand the demodulation process. We may visualise the histograms of $y(ln)$ for various signal-to-noise ratios by assuming that the filters are distortion-free and that the synchronisation time T_s is small in comparison to the bit period (SNRs),

Correlator-based coherent CSK demodulator, as illustrated in, is displayed in. Clearly, even for the same symbol, $y(ln)$ fluctuates as a result of the chaotic signal's non-periodic character. The two different zones in the histogram ensure that the transmitted symbols may be appropriately decoded when the SNR is high. The two zones, however, overlap when the SNR is low, making mistakes unavoidable.

Non-Coherent Demodulation Based on Calculation of Bit Energy

The chaotic basis signals are not accessible at the receiver in non-coherent CSK demodulation. A distinguishing feature of the basis signals must be used for detection. One such attribute is the bit energy, which during the modulation process may be purposefully altered to be different for various symbols.

Assume that the binary symbols are represented by chaotic basis signals that have various bit energies. A chaotic basis signal $c(t)$ with mean bit energy E_e is communicated if a binary "+1" is to be sent within the interval n, I_n , and if a binary "-1" is to be sent, a chaotic basis signal $c(t)$ with mean bit energy E_e is broadcast. We can use two chaos generators with different average bit energy to produce chaotic signals with various bit energies. As an alternative, the same chaos generator may create two shown below.

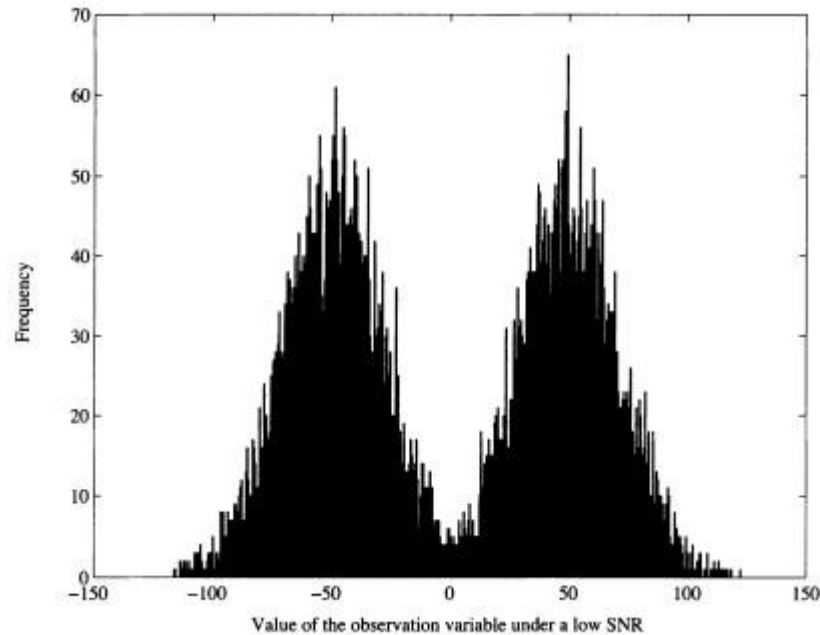


Figure 6.7 shows the chaos generator.

SSB'S Evolution and Definition

Understanding the transmission method will be aided by a quick, but not too simplistic, explanation of SSB. We must first go through some fundamental transmission procedures.

1. The antenna's physical length must match the wavelength of the transmitted signal, which is typically in the RF range.
2. A traditional antenna cannot directly transmit the audio signal due to its length.
3. To satisfy the system's transmission needs, the electronic circuitry must analyse the intelligence (audio). This action is referred to as mixing.
4. To guarantee that the signal satisfies the needs of the antenna system, the SSB system combines the mixing process with a signal-multiplying filtering improvement.

The frequency that results from combining audio (1 kHz) with a fundamental carrier (1 MHz) is 1.001 MHz; if the frequency is increased by 1000, the resulting frequency is 1001 MHz. The remaining frequency after filtering out the carrier (100 MHz) is 1 MHz, which may be used by the antenna system to broadcast audio. A reference carrier frequency is reinserted at the receiver, and a new filtering mechanism splits the frequency in order to retain audio quality despite intrinsic interference caused by external sources. Back down to the audible range. Only the freshly processed information's signal is allowed to be delivered at high power levels as a result of these mixing and filtering procedures, assuring efficiency and high fidelity (3-7) demonstrated that a

signal with three frequencies results when a carrier is amplitude-modulated by a single sine wave. Upper sideband frequency ($f_c + f_m$), lower sideband frequency, and original carrier frequency ($f_c - f_m$). This is an inherent result of AM mixing and will always occur unless precautions are made to stop it. Any combination of the AM wave's components may be removed or weakened either during or after the modulation process. This chapter's focus is on the elements that go into suppressing or eliminating the carrier and/or either of the sidebands, as well as the benefits and drawbacks of doing so. We'll also think about creating several kinds of single-sideband modulation.

In "standard" or double sideband, full carrier (DSBFC) AM (technically known as A3E modulation), the carrier transmits no data. This is so that no matter what the modulating voltage does, the carrier component's amplitude and frequency stay consistent. Just as how each sideband is impacted by variations in the modulating voltage amplitude through the exponent $mV_c/2$, causing the two sidebands to be mirror reflections of one another. One sideband may be used to transmit all the information. The opposite sideband is redundant, and the carrier is unnecessary. The very simple nature of the modulating and demodulating apparatus is the primary factor in A3E's widespread adoption.

Additionally, A3E is the approved format for broadcasting. Although "compatible" SSB is significant, costly modifications in home receivers if SSB were deployed widely has so far precluded any such adjustments. Domestic receivers wouldn't need to be modified for this kind of SSB. According to the AM power equation, $(1 + m^2/2):1$ is the ratio of total power to carrier power. Only the sideband power is left over if the carrier is suppressed.

Since this is simply $P_c (m^2/2)$, a two-thirds save is achieved at 100% modulation, and this saving increases as the modulation depth is decreased. The residual power, $P_c(m^2/4)$, is 50% less than carrier-suppressed AM if one of the sidebands is now also suppressed. The problem is best explained using the following example: Example 4-1 demonstrates how it is inefficient to transmit the carrier and both sidebands when only one sideband is necessary. A second examination reveals that, in comparison to A3E, using SSB instantly reduces the amount of bandwidth needed for transmission.

In real-world applications, such as mobile systems where weight and power consumption must naturally be kept to a minimum, SSB is utilised to conserve electricity. In situations where bandwidth is limited, single-sideband modulation is also employed. The biggest consumers of SSB in one way or another include point-to-point communications, land, air, and marine mobile communications, television, telemetry, military communications, radio navigation, and amateur radio. The modulating signal's frequency In order to properly demonstrate the impact, an upper sideband is displayed with its frequency increasing together with the modulation; however, this frequency rise has been exaggerated.

Restrictions on Carrier

For the creation of SSB, three primary methods are used: the filter technique, the phase cancellation method, and the "The third approach, Refer to Section 4-33. While they all use some kind of balanced modulator to suppress the carrier, they all vary in how they suppress the undesirable sideband. The crucial circuit in single-sideband creation is the balanced modulator.

The evidence of its effectiveness will be shown in the next section.

$I = bv$ represents the relationship between voltage and current in a linear resistance, where b is a proportionality constant. If a resistor is the object of, then b must be the conductance of the resistor. I will be the collector current and V will be the voltage delivered to the base of a transistor if, is made to apply to those values. There will also be a de component of collector current (a), which is independent of the signal voltage at the base, if the amplifier works in class A. We may write $i = a + bv$ where a denotes the collector current's de_ component and b denotes the transistor's transconductance shown below.

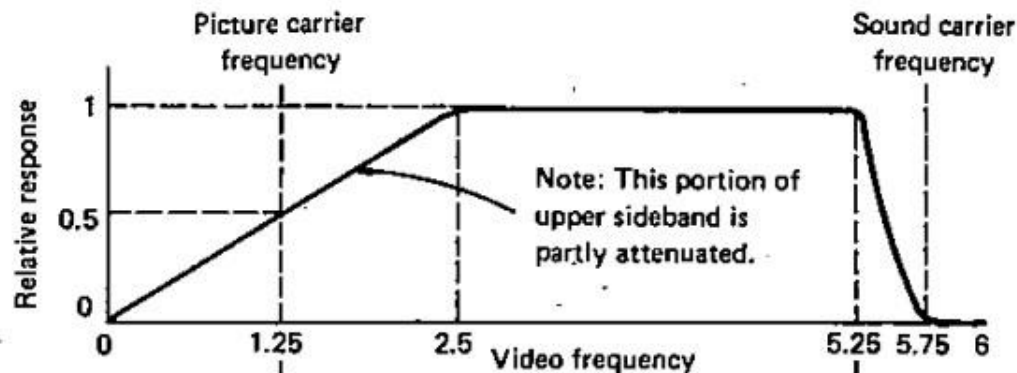
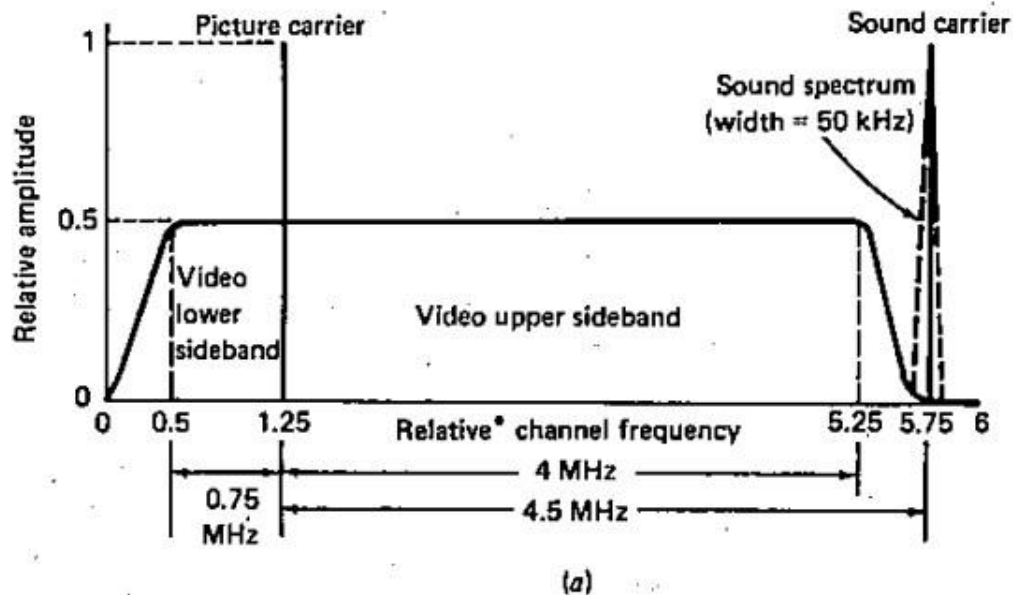


Figure 6.8 shows the transistor's transconductance.

Up to a certain point, the preceding linear relationship seems to be true, after which current increases more (or less) quickly with voltage. Depending on whether the device reaches saturation or whether an avalanche current multiplication occurs, the rise may be more or less fast. Now, current is inversely proportional to voltage, as well as to its square, cube, and higher powers. The most practical way to write this nonlinear relationship is as $I = a + bv + cv^2 + dv^3 + \dots$. The fact that the coefficient c is substantially less than b is the only explanation for why the graph's beginning section is linear. In a common numerical, such as $I = 5 + 15v + 0.2v^2$, curvature is unimportant until v is at least 3. Since d is in fact bigger than the constants before the higherpower

components, I in actual nonlinear resistances is significantly more than d . For the majority of applications, only the square term is significant enough to be taken into account, leaving us with.

The preceding derivation, which produced, may be the most significant one in terms of communications. It serves as evidence for (I) the possibility of harmonic and intermodulation distortion in RF and audio amplifiers, (II) the presence of sum and difference frequencies in a mixer's output, (III) the presence of audio frequencies in the output of a diode detector, (IV) the operation of the beat-frequency oscillator (BFO), and (V) a portion of the evidence for the balanced modulator's suppression of the carrier in AM.

If ω is assumed to be the carrier angular frequency and ω_m is assumed to be the modulating angular frequency, then term I is the dc component, term II is the carrier, term III is the modulating signal, term IV is made up of harmonics of the carrier and the modulation, term V represents the lower sideband voltage, and term VI is the upper sideband. Image symmetrical modulators nonlinear resistance is where the amplitude modulation process occurs in (a) diodes and (b) FETs. The voltages v_1 and v_2 would be generated across a circuit tuned to the carrier frequency and with a bandwidth just big enough to pass the carrier and two sideband frequencies but not others in a realistic modulation circuit.

Balancing Modulator

Figure 4-3b displays two circuits of the balanced modulator. Each makes use of the nonlinear concepts we just spoke about. A pair of identical diodes or class A (transistor or FET) amplifiers receive the modulation voltage (v_2) in push-pull mode and the carrier voltage (v_1) in parallel mode. As a result, the carrier voltage in the FET circuit is supplied in phase to the two gates, however the modulating voltage looks 180 degrees out of phase at the gates since they are located at the opposite ends of a center-tapped transformer.

The center-tapped primary of the push-pull output transformer combines the two FETs' modulated output currents. Because of this, they deduct, as shown by the arrows in, 4-3b. The carrier frequency will be entirely cancelled if this system is designed to be perfectly symmetrical.

Since no system can ever be totally symmetrical in reality, the carrier will always be severely suppressed rather than eliminated (a 45-dB suppression is normally regarded as acceptable). The two sidebands and a few other components are included in the output of the balanced modulator, which is handled by adjusting the secondary winding of the output transformer.

The only thing left behind are sidebands in the output.

It is now provided a mathematical explanation of the balanced modulator since it is not immediately clear how and why just the carrier is suppressed. As shown, the input voltage at the gate of T1 will be $v_1 + v_2$ while that at the gate of T2 will be $v_1 - v_2$. The proportionality constants for both FETs will be the same if perfect symmetry is assumed, and they may continue to be referred to as a , b , and c as previously.

It should be noted that the two devices used in the balanced modulator, whether diodes or transistors, must be matched demonstrates that the carrier has been cancelled out in perfect symmetrical circumstances, leaving just the two sidebands and the modulating frequencies. Systems for electronic communication shown below.

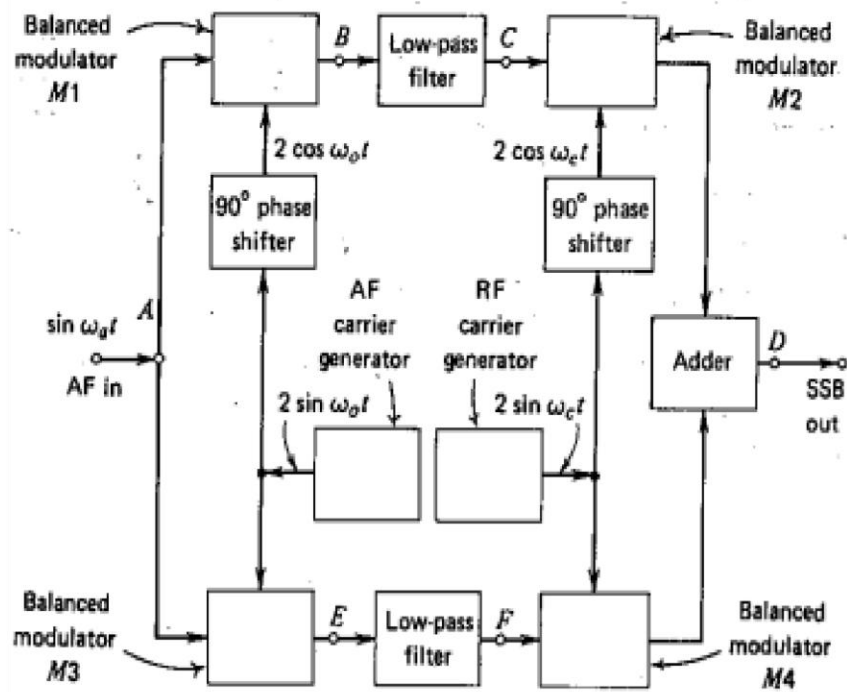


Figure 6.9 Shows the electronic communication.

The modulating frequencies may be eliminated from the output by calibrating the output transponder, but they can also be suppressed by the circuit's operation. To achieve this outcome, two more diodes must be added as the diode balanced modulator. At that point, the circuit is referred to as the ring modulator. As previously mentioned, the three practical techniques of SSB creation each use a unique strategy for eliminating the undesirable sideband, but they all utilise the balanced modulator to suppress the carrier. Depending on the particular circuit configuration, all three techniques will equally easily remove either the top or lower sideband. Now, in turn, each of the systems will be examined.

The filter system, the simplest of the three, removes (really significantly attenuates) the undesirable sideband after the balanced modulator. Depending on the carrier frequency and other criteria, the filter may be made of LC, crystal, ceramic, or mechanical materials. The balanced modulator and the sideband-suppression filter are the main circuits of this transmitter. We'll now look at the unique factors relating to sideband suppression.

Evaluation and Comparison of Systems

Regardless of the technique of production, the same SSB is produced. With either sideband deleted, a good single-sideband suppressed-carrier signal is produced. Subjective hearing tests have shown that the quality of all three systems is essentially the same. It is vital to look at the technical distinctions between the three generation techniques in order to put each system in the right context.

The filter system offers sideband suppression that is more than enough (up to 50 dB), and the sideband filter also aids in carrier attenuation, offering a safety element that is missing from the two phasing methods. With the possible exception of crystal filters at the lowest frequencies, where it tends to be constrained and produce a "tinny" character, the bandwidth is suitably flat

and broad. The main drawback of this system's bulk has been eliminated with the development of tiny, high-quality mechanical filters and compact crystal filters. The biggest drawback right now is that this technology can't produce SSB at high radio frequencies, necessitating repeated mixing in tandem with very steady crystal oscillators. There are further restrictions, such as the inability to utilise low audio frequencies and the need for two pricier filters with each transmitter in order for it to be able to selectively suppress either sideband. This is a great way to generate high-quality SSB transmissions. Except for multichannel equipment, where crystal or even LC filters are often employed, it is utilised in the great majority of commercial systems, especially with mechanical filters.

The phase-1 cancellation technique was first developed to get around the complexity of the LC filter technology. This first benefit no longer holds true since much tiny filters have taken their place, but there are still two others. The capacity to create SSB at any frequency and the flexibility to flip from one sideband to the other eliminate the need for mixing. Low audio frequencies may also be used for modulation. We have the crucial AF phase-shift network on the debit side.

The audio phase shifter is a significantly more complicated device since it must function over a wider frequency range than the RF phase shifter, which works at just one frequency and is thus a fairly simple RC circuit. Any audio frequency at which the phase shifter offers a phase change other than 90 degrees will not entirely be eliminated from the undesirable sideband. For commercial operation, where such attenuation of the undesired sideband should be at least 40 dB, the attenuation under the circumstances of Example 4-2 is insufficient. The example both clarifies the issue and implies that there must be less fluctuation in phase shift in actual practice than IO.

In addition, there are two identical-output balanced modulators in the system (this assumption was made in the proof), without which the cancellation will once again be insufficient. Last but not least, it has been discovered in practice that layout is quite important with this system. All of these factors together lead to the phase-shift system not being utilised commercially, although it is commonly used by amateurs due to the high cost of filters. The third approach doesn't need a wideband audio phase-shift network or a sideband-suppression filter. Without crucial parts or modifications, correct output may be easily maintained. Since the bulk of the circuitry is at the audio frequency (AF), low audio frequencies may be transmitted if desired, and layout and component tolerances are not crucial.

The switching of sidebands is likewise relatively simple, however it can call for an additional crystal. De coupling, on the other hand, could be required to prevent the loss of -signal components around the audio carrier frequency. If the balance of the low-frequency balanced modulators deteriorates, whistle will be present at that frequency. Of the three, this system is the most complicated. Because the filter approach meets current needs so well, it has a drawback. Despite being employed commercially, the third approach isn't expected to take the place of the filter method at this time. The different kinds of AM used for telephony and TV, notably the numerous variants of SSB, are defined, described, and listed in this section on amplitude modulation. All kinds of emission, regardless of modulation, are defined and described by the International Telecommunications Union (I. T. U.) Radio Regulations.

A3E (formerly A3) Full carrier, double sideband. As was previously said, this is "standard" AM, which is currently mostly utilised for broadcasting.

Reduced carrier, single-sideband R3E. An attenuated carrier is reinserted into the SSB signal in this pilot carrier scheme, which is covered, to make receiver tuning and demodulation easier. It is gradually being replaced by BE globally, with the exception of so-called maritime mobile distress frequencies (also known as SOLAS-Safety of Life at Sea), particularly 2182 kHz.

H3E: Single-sideband, complete carrier (formerly A3H). With A3E receivers, this might be utilised as an AM broadcasting system. The stated distortion for H3E signals received by an A3E receiver is no more than 5%. Single-sideband, suppressed-carrier J3E (formerly A3J). This is the so-called "SSB" system, in which the carrier is muted in the transmitter by at least 45 dB. Due to the high receiver stabilities needed, it took a while for it to take off at initially. But as soon as reliable synthesizer-driven receivers were available, it quickly replaced SSB as the preferred method of radio communication.

BSE, formerly known as A3B. Two separate sidebands, with a carrier that is often repressed or attenuated. When more than one channel is needed, this kind of modulation, also known as independent-sideband emission (ISB), is utilised for high-frequency point-to-point radiotelephony a system that transmits a remnant, or trace, of the undesirable sideband, generally together with a complete carrier. Section 4-4.4 addresses this system in detail. In order to save bandwidth, it is utilised for video broadcasts in all types of TV systems across the globe.

Lincompex LCE stands for "connected compressor and expander," an abbreviation. In essence, it is a system that filters out all audio frequencies over 2.7 kHz to make room for a control tone with a bandwidth of 120 Hz at 2.9 kHz. Lincompex may be applied to any AM variant, however it is most often employed with B8E, R3E, and BE. An amplitude limiter and a compressor are used on the signal before transmission to ensure that the transmitter output's amplitude is almost constant. This indicates that an amplitude limiter, similar to the amplitude limiter in an FM receiver the received signal will be considerably better than is typical for HF, and amplitude changes brought on by spurious effects will be virtually eliminated.

The transmitter compressor's output signal is used to frequency-modulate the control tone. This signal is provided to the receiver expander after reception and demodulation to guarantee that the signal exiting the receiver is expanded in the same manner as it was compressed in the transmitter. Once connected, the compressor and expander successfully recreated typical signal amplitude changes. For commercial HF radiotelephony, this method is fairly well-liked since it offers a less expensive option to satellite communications on thin routes like Australia, Antarctica. The communication quality may be virtually as excellent as that of satellite or underwater cable.

As is obvious, J3E demands exceptional frequency stability from both the transmitter and the receiver since any frequency change anywhere in the series of events that the information must go would result in an equivalent frequency shift in the signals that are received. Imagine a system that transmits three signals at 200, 800, and 1000 Hz with a 40-Hz frequency shift. They will all no longer be in harmony with one another in addition to having their frequencies altered to 160, 360, and 760 Hz, respectively. As a consequence, it is evident that sending high-quality music through J3E is challenging. If long-term stabilities on the order of 1 part in 10⁷ (or better) are not achieved, speech will likewise suffer albeit less than music.

For a long time, high-quality temperature-stabilized crystal oscillators have been able to provide this frequency stability. This is OK for fixed-frequency transmitters, but because receivers must be adjustable, the situation is quite different.

In reality, creating receiver variable-frequency oscillators stable enough for J3E was just not possible prior to the development of frequency synthesizers of less-than-monstrous bulk. The method that was used to address this issue and is still extensively utilised is the transmission of a pilot carrier along with the desired sideband. With the exception of the addition of an attenuated carrier signal to the broadcast after the undesired sideband has been eliminated, the block diagram of such a transmitter is quite similar to those previously presented. , 4-8 depicts the carrier reinsertion method for a filter system.

The carrier serves as a reference signal to aid with demodulation in the receiver and is often reinserted at a level that is 16 or 26 dB below the value that it would have had if it had not been suppressed in the first place. Automatic frequency control (AFC), which is identical to what is described in Section, may then be used by the receiver. Such systems are used often because R3E can provide frequency stability over lengthy periods of time that is on the order of 1 part in 10⁷. They are notably prevalent in maritime mobile communications and transmarine point-to-point radiotelephony, particularly at the distress frequencies. Different modulation methods are used for high-density traffic, whether it be short- or long-haul. The chapters 13 through 15 cover frequency- or time-division multiplex systems.

Three Independent Sideband Systems (ISB)

Multiplex methods are utilised for high-density point-to-point communications, as was indicated in the section above. ISB transmission is often used for traffic with low to medium density. From a single HF channel to a four-channel ISB system (with or without Lincompex) to satellite or undersea cable communications, modern communications have developed along many different paths.

To produce two sidebands around the decreased carrier, two SSB channels are added to R3E to create SB. The two sidebands are quite independent of one another. It can transmit two completely separate signals at once, such that the bottom sideband may carry telegraphy while the top sideband is utilised for telephony pushed (by 45 dB or more) in the balanced modulator and the subsequent filter, with the filter's primary purpose remaining the same as in all other SSB systems: the suppression of the undesirable sideband. One filter here suppresses the bottom sideband, while the other suppresses the top sideband. A low-frequency ISB signal with a pilot carrier is now present after the addition of both outputs into the adder with the -26 dB carrier. The frequency is then increased to the usual level of 3.1 MHz by mixing with the output of another crystal oscillator. Take note of the balanced mixer use, which makes it simpler for the output filter to filter out undesired frequencies.

Now that the driving unit has released the signal, the main transmitter has received it. By combining with the output of another crystal oscillator or frequency synthesiser, its frequency is increased once further. Due to the frequency range for such transmissions, this is done signal is then further boosted by linear amplifiers until it reaches the maximum strength, at which time it is sent to a rather directed antenna for transmission. At this time, the normal power output ranges from 10 to 60 kW peak.

Since the width of each sideband is 6 kHz, it can each carry two 3-kHz speech circuits, allowing for the simultaneous transmission of four conversations. Each 6-kHz slot will include one set of audio signals that are translated up by 3 kHz to fill the range of 3.3 to 5.8 kHz. Through the use of multiplexing, one or more of the 3-kHz bands may be filled with 15 or more telegraph channels.

Since "key clicks" may be heard in the voice circuit, mixing telephone and telegraph channels in one sideband is not entirely recommended. However, since demand usually always attempts to outpace available capacity, such hybrid solutions are sometimes necessary.

Although the power savings cannot be overlooked, it has been emphasised in this chapter that the main benefit of single sideband is the bandwidth savings that result from its usage. As we shall see in Chapter 6, the usage of BE systems, as opposed to AM systems in which a carrier is delivered, has certain demodulation issues. The more spectrum space that may be conserved by delivering one sideband rather than both, the more bandwidth a signal consumes. Demonstrated that the bandwidth needed to transfer information increases with the amount of information that must be delivered in a certain amount of time, or per second.

Now that we've established that visual signals must be sent in order for television to be properly received, we can go on to discussing how to do so. A minimum broadcast bandwidth of 9 MHz would be necessary if A3E video transmissions were employed, however this is not feasible given filter characteristics. The application of a kind of Here, SSB is explicitly mentioned to guarantee spectrum preservation. In reality, the carrier is transmitted undiminished to make video demodulation in the receiver simpler. A part of the undesirable (lower) sideband must also be sent since the phase response of filters on the borders of the flat bandpass would negatively affect the visual signals received in a TV receiver.

Vestigial sideband transmission, or C3F, is the end outcome, as depicted in, 4-9a. Please be aware that the frequencies shown there and those used in the text only pertain to the NTSC TV system used in the United States, Canada, and Japan. In the PAL TV system used in Europe, Australia, and other places, the concepts are the same, but the frequencies are somewhat different. The French SECAM system also uses different frequencies. The lowest frequencies in the desired upper sideband may be protected from phase distortion by the vestigial sideband filter by transmitting the first 1.25 MHz of the lower sideband (the first 0.75 MHz of it undiminished). Every TV station uses 3 MHz of spare spectrum since only the first 1.25 MHz of the lower sideband is broadcast. Since a television channel requires 74 Mbps of total bandwidth Systems for electronic communication

There has been a significant cost reduction, going from 9 MHz to 6 MHz, and more channels may now be supported as a result displays the frequency location of the position of the frequency-modulated sound broadcasts that accompany the video to complete the demonstration. It should be highlighted that these broadcasts would have existed independently of the video modulation method and have nothing to do with the fact that it is C3F. Simply because sound is necessary for the visuals, and it would not be very practical to have a fully separate receiver for the sound, operating at some frequency distant from the video broadcast frequencies, all of these signals occupy frequencies close to the video transmissions.

For the purpose of attenuation, the video frequencies starting at MHz are supplied. These frequencies carry more power since they are carried in both sidebands, unlike the other video

frequencies, which are exclusively conveyed in the upper sideband. If these frequencies weren't properly attenuated, they would be overly accentuated in the receiver's visual output shown below.

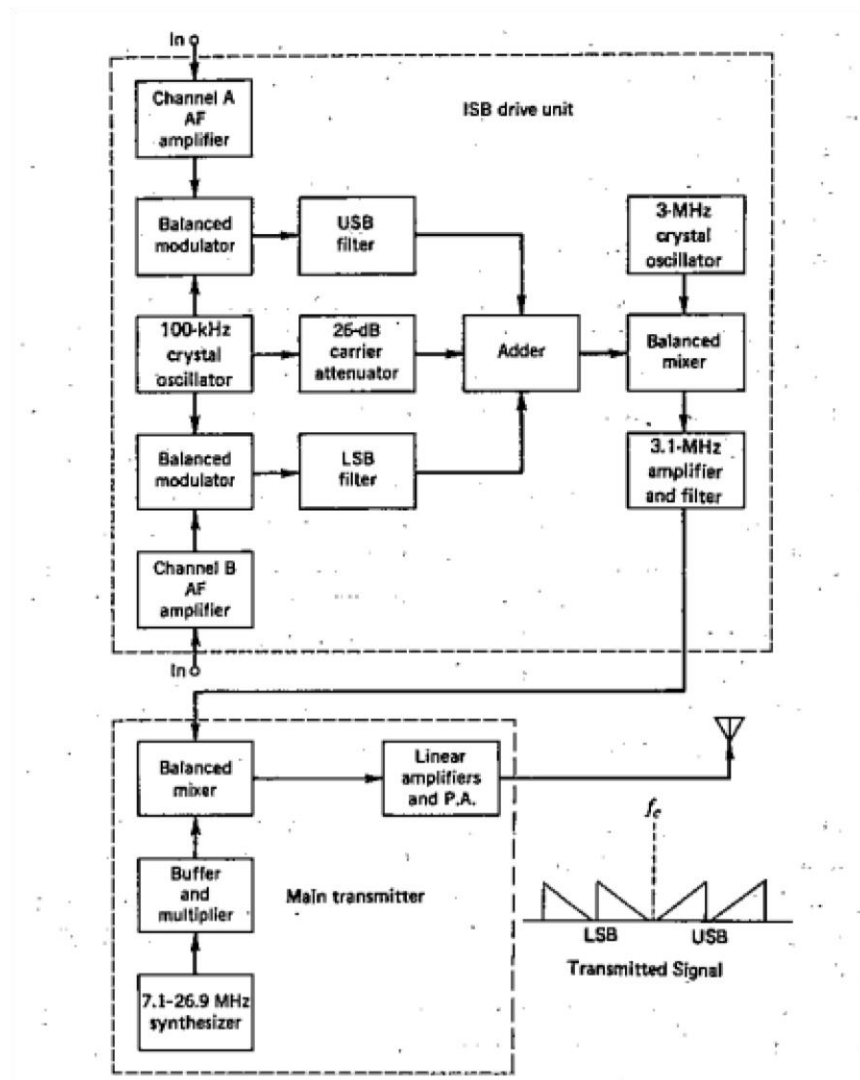


Figure 6.10 shows the receiver's visual output.

A flat bandpass and exceptionally high attenuation outside the bandpass are required for such a filter. This has no upper limit; the greater the attenuation, the better. The majority of the time, the frequency range utilised for speech in radio communications systems is 300 to around 2800 Hz. The lowest frequency that this filter must pass through unattenuated if the lower sideband must be suppressed and the transmitting frequency is, is $J + 300$ Hz, while the highest frequency that must be totally attenuated is over a range of just 600 Hz from zero attenuation to full attenuation. This is almost difficult if the transmitting frequency is significantly higher than 10 MHz. Lower modulating frequencies, such as the 50-Hz minimum in AM broadcasting, make the issue considerably worse. The tuned circuits' Q must be very high in order to produce a filter response curve with skirts as steep as those mentioned above. The Q must increase along with the

transmission frequency until it reaches a point where it is impossible to achieve the required Q using any practical means.

When we approach the problem from the opposite end, we see that every filter circuit must have a maximum frequency range. For instance, it has been discovered that multistage LC filters cannot be used to RF values much higher than about 1 kHz. The attenuation outside of the bandpass is inadequate above this frequency. Although LC filters may still be found in certain modern HF equipment, they have mostly been replaced by crystal, ceramic, or mechanical filters due to the large size of their components and the significant advancements made in mechanical filters. Up to 500 kHz, mechanical filters have been utilised, and up to 20 MHz or so, crystal or ceramic filters.

The mechanical filter seems to be the one of the three main SSB filter types with the greatest overall features; its main benefits are compact size, excellent bandpass, extremely good attenuation characteristics, and a sufficient upper frequency limit. Although crystal or ceramic filters may be less expensive, they are best used at frequencies greater than 1 MHz shown below.

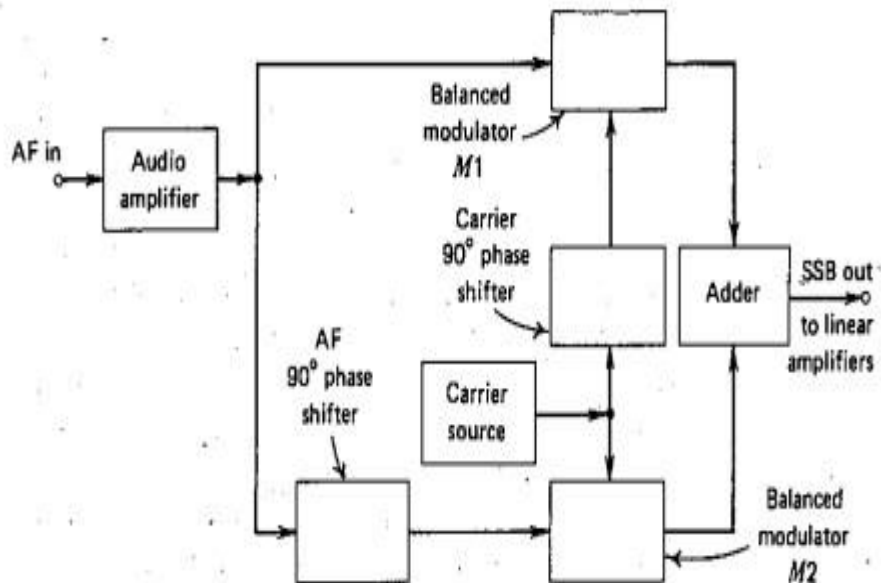


Figure 6.11 shows the frequencies greater.

The same drawback affects all of these filters, including the crystal: their maximum operating frequencies are lower than the typical transmission frequencies. This is one of the causes of the balanced mixer. (It is quite similar to a balanced modulator, but the total frequency may be chosen using a tuned circuit since it is considerably further away from the crystal oscillator frequency than the USB was from the carrier.) The SSB signal from the filter is mixed with the frequency of the crystal oscillator or synthesiser, raising the frequency to the necessary level for transmission.

The transmitter may also be tuned with such a setup. Two steps of mixing will be necessary if the transmitting frequency is much higher than the sideband filter's operational frequency. Filtering out the undesirable frequencies from the mixer's output becomes too challenging. It should be remembered that linear amplifiers come after the mixer. The SSB signal's fluctuating amplitude

cannot be put into a class C amplifier since doing so would cause distortion. Instead, a push-pull class B RF amplifier is utilised since it is more effective than a class an amplifier. The term "linear amplifier" is not only used to describe SSB systems. Any AM system that demands minimal or negligible signal distortion uses linear amplifiers.

CHAPTER 7

Pulse Wave Modulation in Communication System

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Modulation of the Pulse Amplitude

The amplitude of the pulse carrier changes in the Pulse Amplitude Modulation (PAM) method, and this variation is proportional to the actual amplitude of the message signal. As the signal follows the whole wave's journey, the pulse amplitude frequency response will match the original signal's amplitude. When using natural PAM, a signal sampling at Nyquist rate may be rebuilt by running it through a precise Low Pass Filter (LPF). The Pulse Amplitude Modulation is shown in the following images.

Natural Pam's Modulating Signal Carrier Pulse Train

Despite going via an LPF, the PAM signal cannot be recovered without distortion. Use flat-top sampling as a result to keep noise to a minimum. The following graphic displays the flat-top PAM signal. When a signal is sampled using flat-top sampling, its amplitude cannot be modified in relation to the analogue signal that will be used as the reference for the sampled signal. The amplitude's tops are still flat. The circuit design is made simpler by this method.

Modulation of the pulse width

The width, length, or time of the pulse carrier changes in the Pulse Width Modulation (PWM), Pulse Duration Modulation (PDM), or Pulse Time Modulation (PTM) approach, and is proportional to the actual brightness of something like the transfer function.

This technique adjusts the pulse width while maintaining a constant signal amplitude. To maintain a steady signal amplitude, amplitude limiters are used. These circuits restrict the noise by clipping off the amplitude at a preset level.

The many forms of control signal modulations are shown in the following,

Pulse width modulation types

There are three different PWM kinds.

The trailing edge of said pulse fluctuates depending on the message signal while the leading edge remains constant. In the illustration above, the pattern for this kind of PWM is designated as the leading edge of the pulsed fluctuates depending on the message signal while the following edge remains constant. In the above image, the frequency for this kind of PWM is designated as the promising strategy and the following edge of the pulse vary depending on the message signal while the pulse's core remains constant. This sort of PWM's waveform is designated as (c) in the image above.

Measurement of pulse position

PPM is an analogue modulation technique where the location of each pulse in relation to a reference pulse changes depending on the compared with the expected frequency of the carrier wave but the amplitude and breadth of the impulses are maintained constant. To keep the transmission and the recipient of the message in sync, the transmitter must emit synchronisation pulses, also known as sync pulses. These sync pulses aid in keeping the pulses in place. The Modulation Index Modulation is explained in the following.

Signal PPM Base Band

According to the pulse width modulated signal, pulse position modulation is applied. The PPM signal's pulses begin at each back edge of either the pulse width frequency response. As a result, the relationship between these pulses' positions and PWM pulse widths is linear. ***Advantage***

1. The power delivered is constant since the amplitude and breadth are likewise constant.
2. It's crucial for the transmitter and receiver to be in sync.
3. An evaluation of PAM, PWM, and PPM

The comparison of three modulation approaches Bandwidth is influenced by the pulse width the rising time of something like the pulse affects bandwidth. The rising time of either the pulse affects bandwidth. Variations in instantaneous transmitter power are caused by changes in pulse amplitude the pulse's amplitude and breadth affect the transmitter's instantaneous power. The pulse width has no effect on the instantaneous transmitter power. High system complexity Low system complexity Low system complexity Noise intrusion is prevalent. Low noise interference Low noise interference Amplitude modulation and this are comparable. In a way, it resembles frequency modulation. Comparable to phase modulation.

To fine-tune metabolic and physiological processes in response to external factors, cells have developed signal transduction pathways. Similar to human-engineered communication networks, many biological processes spread information through temporal encoding of signals. Living things are made up of linked signalling networks that control processes including metabolism, cell cycle, inflammation, and stress response. Architectural motifs that have dynamic modulatory qualities, such as signal filtering, oscillations, and hysteresis, make up these networks.

Given the significance of signal dynamics on biological function, precise control of gene expression is essential for living cells as well as for many applications in genetic engineering, where the development and analysis of complex systems necessitates the robust and predictive specification of protein levels. The processes of how signal transduction pathway topologies adapt to and modify dynamically changing signals are also made possible by techniques for simply programming signal perturbations. An ideal control method from the perspective of bioengineering would provide reasonable, quick tuning of expression throughout a range of levels and would permit experimental determination of the kinetics of induction and repression of expression. Optogenetic systems, which employ light-responsive receptors to regulate gene expression in response to certain light wavelengths, are effective methods for encoding spatial control of biological systems. They have been used to control pattern generation, cell motility, and neuron function shown below.

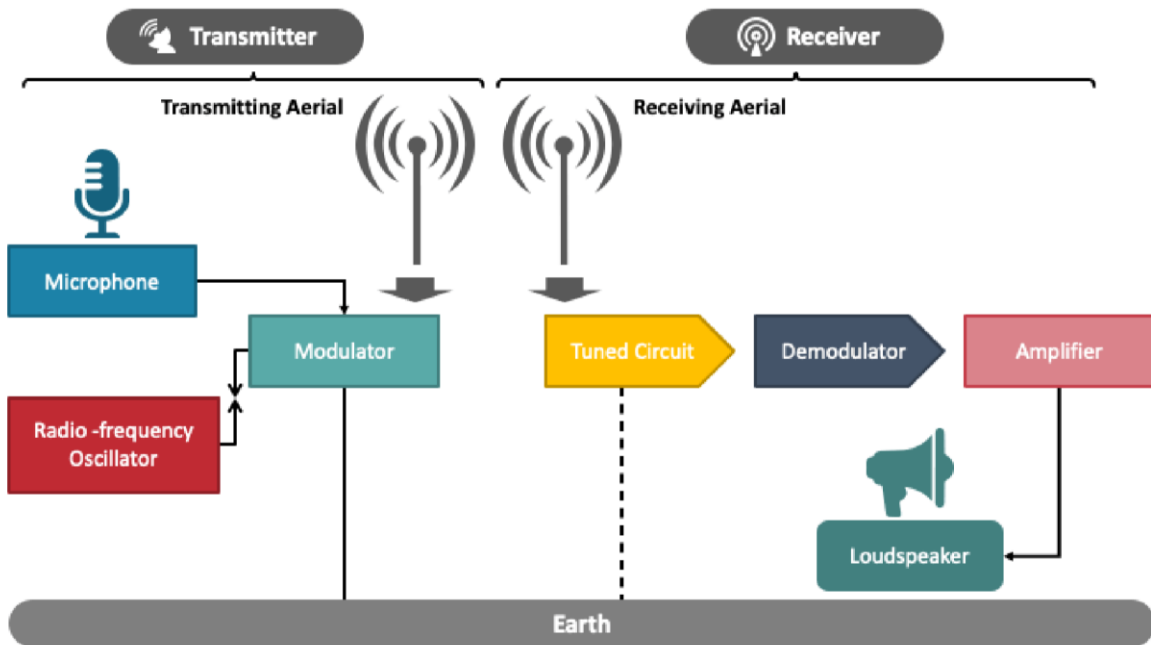


Figure 7.1 shows the neuron function.

Here, we aimed to increase the utility and adaptability of an *Escherichia coli* system that can induce the green light, which is based on a two-component cyanobacterial system. The response regulator *ccaR* is phosphorylated by the histidine kinase *ccaS* in the presence of green light, boosting transcription. Graded regulation of gene expression is possible using PWM of optical signals. A genetic and designed hardware system for altering gene expression. A 96-well, clearbottom microplate is illuminated by an 8 12 dual (red and green) LED array controlled by a computer. The LEDs' red and green light is employed to regulate the two-component *ccaS/ccaR* signal transduction pathway. Red light inhibits *ccaS*, which results in less GFP gene transcription, whereas green light activates *ccaS*, boosting GFP gene transcription shown below.

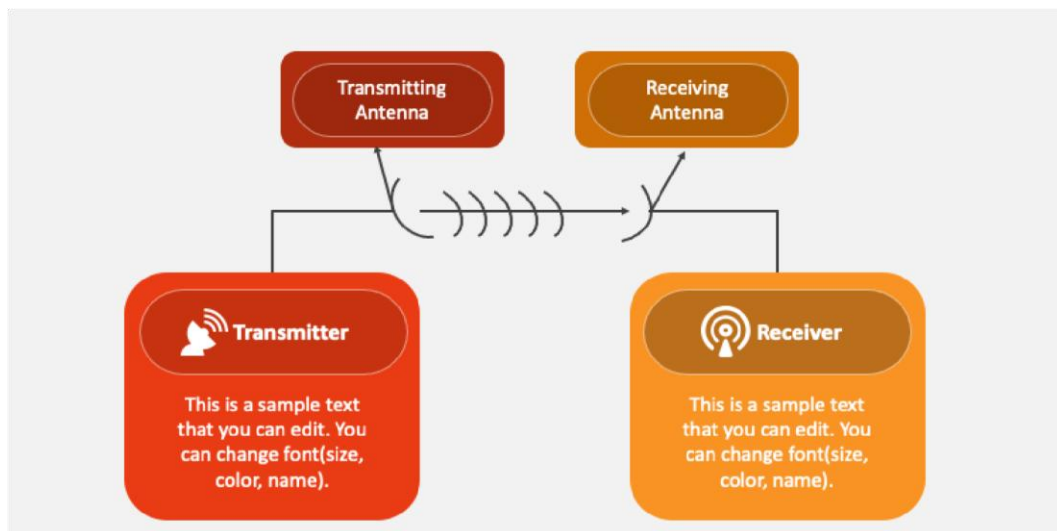


Figure 7.2 shows the gene transcription.

In response to input signal strength, the optogenetic system exhibits a quick shift between the repressed and induced states. For visualisation, red light intensity is expressed as a percentage of the maximum LED intensity, which is around 30 W/m². As red light intensity increases, progressively negative numbers are used to indicate it. At low frequencies, the GFP output of the device follows the input optical signal, but not at high frequencies. Each graph has a green and red representation of the applied light pattern. Cells were stimulated using oscillating green and red signals with duty cycles of 0.25 and frequencies of 0.0083, 0.017, 0.033, and 0.1 min⁻¹ from left to right.

Low-pass filtering is evident from the connection between input frequency and output amplitude. The difference between the maximal and smallest fluorescence levels shown in (c), where 1.0 is the maximum difference between completely induced (green light) and totally repressed (red light) states, is used to compute the oscillation's amplitude. The maximum amplitude is represented by the frequency value for the 0.0014 min⁻¹ data point (shown in red), which was computed using a duty cycle of 0.25 and the 180 min necessary to get from entirely repressed to fully induced. (e) System output exhibits a dependency on oscillating input signal duty cycle, enabling tweaking over the whole expression range. Cells were subjected to a square wave that was pulsating at a frequency of 0.1 min⁻¹. Connecting lines serve as visual cues for all graphs. Gene expression points represent the average of at least three independent measurements of GFP fluorescence, scaled from repressed to induced (0.0 to 1.0) to depict the movement from "off" to "on" states.

Computer control over the optical microtiter plate enables automatic modification of optical signals throughout time. To allow a high-throughput operation, each well may be separately programmed. We started by adjusting the intensity of the red and green light in each well to characterise the optogenetic system's signal response. Repression is shown in the system under red light, while induction is displayed under green light, with an incredibly abrupt transition between the two states. Since it is difficult to reach intermediate levels of gene expression by adjusting signal strength, this is not the best control technique.

Conceptually, converting from a sharp reaction to a graded response is similar to converting from digital to analogue information in electronics. Pulse width modulation (PWM) is a standard technique for carrying out digital-to-analog conversion when controlling electrical devices. PWM regulates power to a device by quickly turning the provided voltage on and off. The system's average power is determined by the duty cycle, or the percentage of time the voltage is on. PWM offers exact, linear control of the time-averaged power since duty cycle may be adjusted digitally to an analogue output.

Despite its widespread usage in electronics, PWM has not been applied to the regulation of biological systems. In this case, duty cycle is the percentage of a wave period during which the LED emits green light at its brightest, with red light at its brightest for the remaining time. In order for the system to "average" the pulse signal input and produce an output, the implementation of a PWM control technique necessitates switching between on and off signals occurring faster than the system is capable of responding. We characterised the response to periodic input signals at various frequencies to determine if the optogenetic system was appropriate for PWM control (Fig. 1c). The system delayed tracking the input at low frequencies (less than 0.03 min⁻¹), which caused the output expression to oscillate. The system is unable to follow the input signal at high frequencies. Fig. 1d shows a plot of the oscillation amplitude's

size vs signal frequency. When the frequency is high, the signal transduction system attenuates input signals; when the frequency is low, the input is "passed."

The system can't react quickly enough to follow input signals for induction and repression at high input signal frequencies, which makes PWM control possible. Next, we looked at how the system responded to a high-frequency duty cycle change (frequency = 0.1 min⁻¹). It is possible to obtain expression levels between the lowest and maximum states thanks to the reporter gene expression's graded response to duty cycle change. According to assessments of reporter gene expression performed using a flow cytometer, this is a graded response at the single cell level.

It is well known that the patterns of gene expression in response to cellular and environmental stimuli play a significant role in biological regulation and adaptation. In the NF- κ B signalling pathway of mammals, temporal dynamics of gene expression programming. Three alternative final expression levels—low expression (a), medium expression (b), and high expression (c) were targeted by the gradual (triangle), moderate (diamond), or quick with overshoot (square) induction strategies that were used to programme gene expression. The induction/repression pattern for each gene expression curve is shown in the graph legends below. The target gene expression level is indicated visually by red broken lines on all graphs. Gene expression points represent the average of at least three independent measurements of GFP fluorescence, scaled from repressed (0.0) to induced (1.0) to represent the progression from "off" to "on" states. Error bars represent standard deviations.

Different inflammatory stimuli, such as microbes and Pulse Width Modulation, produce unique patterns of NF- κ B activation. The characteristics of these patterns include the pace of expression growth and decline, the "overshoot" kinetics, and the latency of induction or repression after the application of a stimulus. With typical inducible promoters, it is challenging to experimentally tune these features, which has hampered our knowledge of how signals are sent and "interpreted" by cellular networks. Characterizing the biological impacts of initiating gene expression at various beginning rates that attain the same steady-state value, for instance, might be helpful. This would enable experimental evaluations of the relative impact of temporal dynamics factors on cellular signalling, metabolism, and physiology. Genetic network structure, characteristics, and resilience may be learned about via dynamic input-output investigations of biological systems.

The next step was to use a succession of specially crafted pulsed signals to control the kinetics of gene expression and independently programme temporal features. We investigated the possibility of modifying the time needed to obtain a desired steady-state value. We created straightforward protocols that programme gene expression to advance towards a predetermined steady-state value by three different induction profiles: slow, moderate, and rapid with overshoot. These protocols were based on experimentally derived parameters for the duty cycle transfer function, the temporal induction and repression curves, and the duty cycle transfer function.

The slow approach programme moves straight out of repression (duty cycle = 0.0) and into the final duty cycle. Until 20 minutes before the time at which the target final gene expression level is obtained under maximum induction, the programme for a moderate approach uses maximal induction (duty cycle = 1.0). In order to maintain the correct level of gene expression, the induction is then switched to the final state duty cycle. Maximal induction (duty cycle = 1.0) is used to design a quick approach with overshoot until 20 min after the required gene expression level was attained. The final state duty cycle is now applied, causing the gene expression level to

approach the final level from above after transcription has been suppressed (duty cycle = 0.0) for 20 min. A variety of expression values and temporal dynamics may be obtained using this control method, as shown by the effective application of these procedures to three distinct final gene expression levels.

Additionally, PWM may be utilised to regulate the expression of many different signal frequencies. A potent tool for disrupting cellular metabolism and physiology is the capacity to accurately control gene expression levels and dynamics. We created a genetic system to put an *E. coli* metabolic pathway under the control of the optogenetic system in order to further investigate PWM as a control mechanism. Light can be applied to a culture reversibly without harming the cells, making it the perfect instrument for modifying bacterial physiology. The *metE* gene was cloned into the optogenetic system. A crucial gene for growth in medium deficient in methionine is *metE*, a methyltransferase involved in methionine production shows how PWM of a metabolic protein regulates the pace of bacterial growth. The optogenetic system was used to regulate the *E. coli* methyltransferase *metE*, resulting in the creation of a *metE* chromosomal deletion strain that cannot grow in the absence of methionine. Growth curves of the optically controlled *metE* strain under various duty cycles of light perturbation in medium deficient in methionine. The green line represents complete induction of the system, whereas the red line represents full suppression. Grey lines show cultures that were treated to duty cycles ranging from 0.1 to 0.8. The lines reflect the average absorbance values for three distinct cultures.

Dependent on the duty cycle used, growth rate exhibits a graded rise with increased duty cycle. The techniques are outlined in the methods section for calculating growth rate. Error bars are standard deviations, while growth rate statistics are averages derived from three separate growth rate computations. Microorganisms and pulse rate by adjusting the duty cycle of green and red light pulses, a strain with a genomic *met* deletion was modified. Engineered strains demonstrated that the PWM technique may be utilised to regulate bacterial metabolism by showing growth rates related to duty cycle applied. In the absence of methionine, a control strain that expresses GFP rather than *met* did not develop, and the wild-type strain did not respond to light by growing. A broad variety of growth rates may be obtained, as shown by the fact that modified cultures' growth rates at high duty cycles are comparable to those of the wild-type strain. We also observe that the GFP-duty cycle curve closely resembles the transfer function of the dependency of growth rate on duty cycle demonstrating a trustworthy dose-response curve for both the fluorescent reporter and a metabolic output.

A promising field with the potential to provide innovative applications and methods for exploring living cells is the interaction between electrical and biological systems. We have shown that genetic and hardware engineering, along with a control technique from electronics, is a practical approach for controlling gene expression levels, temporal dynamics, and cell physiology. We predict that PWM may be used to similar biological systems, including bacterial and eukaryotic ones, where the signal input can be quickly altered in relation to the response and output of the system. This presumably includes a broad class of electronic-biological interfaces. Since the *Saccharomyces cerevisiae* high-osmolarity sensing route is known to serve as a lowpass filter, analogue control via PWM should be possible. A major shift in synthetic biology may be possible thanks to efforts to control biology using similar principles given the revolutionary effects of digital information processing in electronics and communications.

CHAPTER 8

Electromagnetic Wave Propagation

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Edison developed the first wireless link between Europe and America more than a century ago. Today, the term "wireless communication" is used more specifically to refer to things like wireless sensors, wireless computer networks, and other personal communication devices. Similar to light particles, radio signals can only propagate in a horizontal line by nature, and hence LOS propagation necessitates a method of wave deflection. Given the spherical shape of the globe, the realistic range for LOS transmission is around 48 km, or 30 miles, guess it depends on the topography and the antenna height. Therefore, broadcast network antennas and mobile phone base antennas are often situated on hills, high buildings, and/or mountains in order to optimize coverage shown below.

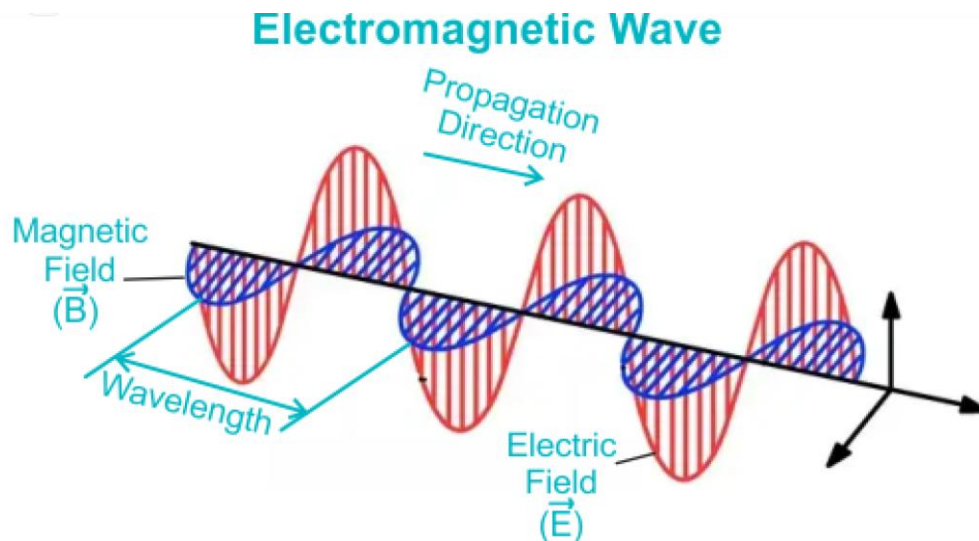


Figure 8.1 Shows the optimize coverage.

However, a number of phenomena allow electromagnetic (EM) and light waves to go over barriers or above the horizon of the earth. These include reflection, scattering, diffraction, and refraction. For the radio engineer, these methods may be both helpful and problematic. For instance, prior to the development of satellite technology, military and international broadcasts made use of the fact that the F-layer of the ionosphere reflects short-wave radio signals. Here, signals travel 3900 miles to reach New York City from Los Angeles (LA) (NY). However, the frequency, kind of equipment, sunspots, and other ionosphere-related factors all determine whether a certain location may be reached by ionosphere reflection. Additionally, we see that while our signal of interest will go from LA to NY, Salt Lake City and Chicago are likely to be

missed. As a result, radio frequency transmission over the ionosphere space is not very dependable. The ionosphere really causes radio waves to refract further discussion shown below.

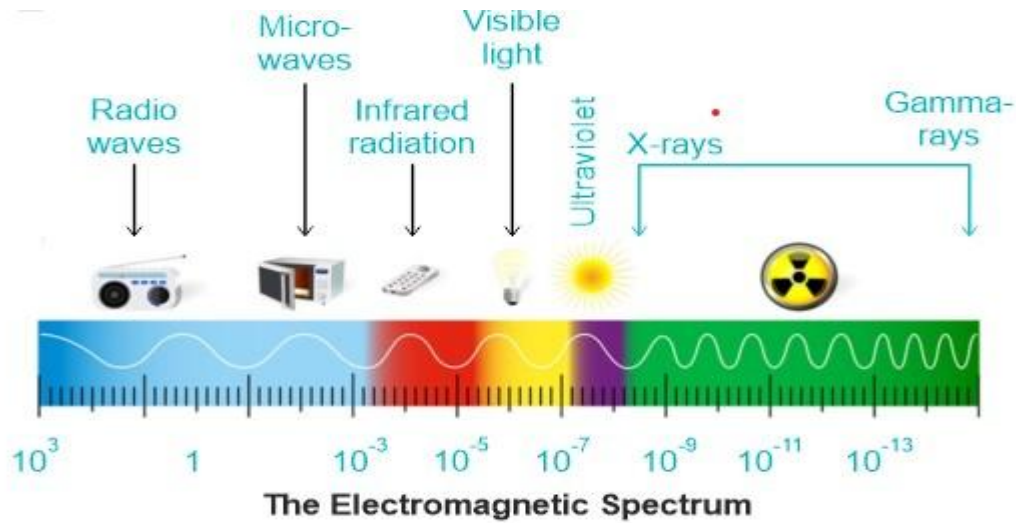


Figure 8.2 Shows the radio waves.

RF communication However, reliability may be increased by using frequency diversity, which involves sending the identical signal across a number of various frequencies to enhance the likelihood that each of them will reach the desired location. On the other side, reflective thinking of electromagnetic radiation may result in multipath interference, where the original signal and any delayed versions interfere with one another at the target location. Signal fading results from this damaging signal addition a direct component plus two multipath components, or $y(t) = a_1 x(t) + a_2 x(t - \tau) + a_3 x(t - \tau)$. The amplitude of $y(t)$ may be significantly lowered or increased depending on the values of a and b , which can result in either constructive or destructive interference shown below.

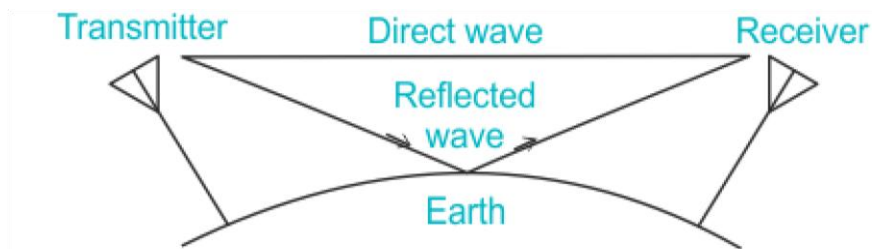


Figure 8.3 Shows the destructive interference.

Losses in the medium may also result in signal attenuation or fading. Let's think about the several ways that RF signals might be redirected and provide a quick overview of basic radio propagation. We reference E. Jordan and K. Balmain (1971) as well as the sections on radio propagation in the ARRL Handbook. Electromagnetic waves are used in wireless communications to deliver messages across great distances. Wireless connections are similar to regular network connections from the user's point of view in that your web browser, email, and other program all function as you would expect them to. However, compared to Ethernet wire, radio waves have several surprising characteristics. An Ethernet cable, for instance, is quite simple to spot; just find the connector protruding from your computer, follow the cable to the other end, and there it

is! It's crucial to comprehend how radio waves function in the actual world in order to construct reliable highspeed wireless communications.

Wavelength, amplitude, and frequency are shown in, RP 1. The frequency of this wave is 2 cycles per second, or 2 Hz, and its speed is 1 m/s. All acquainted with oscillations or vibrations in a variety of shapes and sizes. Examples of oscillations include a pendulum, a tree swaying in the wind, and the string of a guitar. What unites them is the periodic swinging of some material or object, with a predetermined number of cycles per unit of time. Since it is determined by the motion of an item or the medium through which it is propagating, this kind of wave is sometimes referred to as a mechanical wave. We refer to waves propagating in space when such oscillations move (i.e., when the swinging does not remain confined to a single location). For instance, when a vocalist sings, the vocal cords oscillate on a regular basis. The air is compressed and decompressed on a regular basis by these oscillations, and this regular change in air pressure then exits the singer's lips and travels at the speed of sound.

When a stone falls into a lake, it creates a disturbance that later spreads over the lake as a wave. The speed, frequency, and wavelength of a wave are fixed. These are related by a straightforward relation: Speed equals Frequency times Wavelength. The wavelength, also known as λ , is the distance between one point on a wave and its corresponding portion on the next wave (or, to put it another way, to the next point that is in the same phase), for example, from the peak's top to the peak's peak. The frequency is the quantity of complete waves passing a particular place over time. The units of measurement for speed, frequency, and wavelength are metres, cycles per second (or Hertz, denoted by the sign Hz), and metres, respectively. A wave on water, for instance, will have five oscillations per second at a speed of one metre per second, resulting in waves that are each 20 centimetres long:

A further characteristic of waves is amplitude. The "height" of a water wave may be conceived of as the distance from the wave's centre to one of its extreme peaks. , RP 1 displays frequency, wavelength, and amplitude. You may easily see the waves as they travel over the water over time by dropping a stone into the lake. What is oscillating in the case of electromagnetic waves is maybe the most difficult concept to comprehend. You must understand electromagnetic forces in order to comprehend that.

Electrifying Forces

The forces between electrical charges and currents are known as electromagnetic forces. When our palm meets a door handle after stepping on synthetic carpet or brushes up against an electrical fence, we have the most direct access to them. Lightning is a stronger manifestation of electromagnetic energies that occurs during thunderstorms. The force between electrical charges is known as the electrical force. The force separating electrical currents called the magnetic force. Particles with a negative electrical charge are known as electrons. Even though there are other charged particles, the majority of what we need to know about how radio works is caused by electrons. Let's examine what happens when we periodically drive electrons from one end of a straight vertical wire to the other and back. The top of the wire becomes negatively charged at one point because all of the negative electrons are concentrated there. From the positively charged end of the wire to the negatively charged one, an electric field is created as a result. The electric field is now pointing in the other direction, and all of the electrons have now been forced to the opposite side. The electric field vectors shown by arrows from plus to negative are radiating out into the region around the wire as this keeps happening repeatedly.

Due to the two differentially charged poles, plus and minus, generated in the straight vertical line, what we just described is known as a dipole, or more popularly, a dipole antenna. The simplest omnidirectional antenna is one like this. Because there is a corresponding magnetic field, the moving electric field is often referred to as an electromagnetic wave. Electrically charged items produce an electric field.

Moving electrically charged objects, like the dipole antenna we just discussed, create a moving electric field. Anywhere that electrical charges are flowing, a magnetic field is created. This is expressed mathematically in Maxwell's. We refer to an electromagnetic field because of the connection between the electrical and magnetic components. Although the magnetic component is always there, we tend to concentrate on the electrical component in practical wireless networking.

Let's revisit the connection: Speed equals Frequency times Wavelength. The speed of electromagnetic waves is equal to the speed of light, or c . In contrast to mechanical waves, electromagnetic waves don't need a medium to travel. Even in an ideal vacuum, electromagnetic waves may travel. A notable illustration is the way that light from the stars travels to earth via the void of space. Phase Two waves' phase differences RF Café. We shall discuss ideas like interference, multipath, and Fresnel zones later on in this chapter. We must grasp the phase of a wave or rather, the changes in phases between waves in order to comprehend them. Consider the sine wave and then picture two of them moving at once.

These might be in the same precise position: The other has a peak exactly where the first one does. Then, we would state that they are in phase or that there is no longer any phase difference. However, one wave may also be offset from the other, for instance, by having its peak where the other wave has zero. We have a phase difference in this instance. One whole cycle of the wave is 360 degrees, hence the phase difference may be stated as fractions of the wavelength, such as $1/4$, or as degrees, such as 90 degrees. A phase difference of 360 degrees equals a phase difference of 0 degrees, or zero.

Polarization

Polarization is a crucial aspect of electromagnetic waves. The term "polarisation" refers to the electrical field vector's direction electromagnetic wave with a vertical polarisation RF Café. Electromagnetic wave with vertical polarisation, Electrons can only go up and down, never laterally, in a vertically aligned dipole antenna (the straight length of wire), and as a result, electrical fields can only ever point vertically up or down. The field has strict linear and in this example, vertical polarisation as it exits the wire and travels as a wave. We would discover horizontal linear polarisation if we laid the antenna flat on the ground.

In general, we will always have some component of the field pointing in other directions as well; linear polarisation is merely one exception to this rule. A circularly polarised wave, in which the electric field vector rotates perpendicular to the wave's course, may be produced by combining two equal dipoles supplied with the same signal.

Ellipsoidal polarisation, in which the maximum value of the electric field vector differs in the vertical and horizontal directions, is the most prevalent scenario. Polarization becomes crucial for aligning antennas, as one would expect. Even with the greatest antennas, you could only get a very weak signal if you disregard polarisation. This is referred to as polarisation mismatch.

Similar to this, polarisation can be used intelligently to maintain the independence and lack of interference between two wireless links, even though they may use the same end points and, consequently, the same trajectory: if one link is polarised vertically and the other horizontally, they will not be able to "see" each other. This is an easy approach to use a single frequency to double the data throughput over a single connection.

An antenna designed for vertical polarisation must neither receive or transmit any horizontally polarised signal, and vice versa. This kind of application necessitates precisely constructed antennas that reject the "unwanted" polarisation. They need to resist "cross polarisation" strongly, according to us.

1. Spectrum of electromagnetic waves
2. Radio frequency spectrum RF Café
3. The electromagnetic spectrum

The frequency of electromagnetic waves are quite varied (and, accordingly, wavelengths). The electromagnetic spectrum is the name given to this collection of frequencies or wavelengths. Light, or the electromagnetic spectrum's visible region, is undoubtedly the part of the spectrum that people are most used to.

The wavelength range of light is generally between 7.5×10^{14} Hz and 3.8×10^{14} Hz, or between 400 nm (violet/blue) and 800 nm (red). Alternating Current (AC) or grid electricity at 50/60 Hz, AM and FM radio, Ultraviolet (at frequencies higher than those of visible light), Infrared (at frequencies lower than those of visible light), X-Ray radiation, and many other types of electromagnetic radiation are also regular sources of exposure for us.

The word "radio" refers to the region of the electromagnetic spectrum where waves may be broadcast using an antenna and alternating current. In the more restricted meaning of the phrase, the highest frequency limit would be about 1 GHz, beyond which we speak of microwaves and millimetre waves.

This is valid for the range of 30 kHz to 300 GHz. Many people consider FM radio when discussing radio, which operates at a frequency of roughly 100 MHz. The area of microwaves, which has frequencies between 1 GHz and 300 GHz and wavelengths between 30 cm and 1 mm, is between the radio and infrared spectrums.

The microwave oven, which operates in the exact same frequency range as the wireless standards we are working with, may be the most common use for microwaves. These areas are located in the bands that are still available for unrestricted public access. The Industrial, Scientific, and Medical (ISM) band is the name of this area.

The majority of the other regions of the electromagnetic spectrum are subject to strict licencing regulations, with licence prices playing a significant economic role. In several nations, telecommunication corporations have paid millions of dollars for the right to utilise certain spectrum bands. The ISM bands are generally not subject to licencing requirements since they have been set aside for unlicensed usage.

The frequencies that interest us the most are 2.400–2.495 GHz, used by 802.11b and 802.11g standards (corresponding to wavelengths of around 12.5 cm), and 5.150–5.850 GHz, used by 802.11a standards (corresponding to wavelengths of approximately 5–6 cm). Both of these bands

are compatible with the 802.11n standard. For a summary of standards and frequencies, see to the WiFi Family Chapter. Additionally, the chapter titled Radio Spectrum has additional information about the radio frequency range of the electromagnetic spectrum.

Power

We may feel the energy carried by any electromagnetic wave when we enjoy or endure the sun's warmth. Power is defined as the quantity of energy divided by the measurement period. For a wireless connection to function, the power P , which is measured in W (watts), is essential since a receiver needs a specific minimum power to understand the signal. In the chapter titled Antennas/Transmission Lines, we will return to specifics of transmission power, losses, gains, and radio sensitivity.

Here, we'll quickly go through the definition and measurement of the power P . The electric field's power is proportional to the square of the electric field, which is measured in V/m (potential difference per metre).

Practically, we use a receiver of some kind, such as an antenna and voltmeter, power metre, oscilloscope, spectrum analyzer, or even a radio card and laptop, to measure the power in watts.

To get the signal's power directly, divide the square of the voltage level by the electrical resistance. Using dB for calculation

Decibel calculations are by far the most crucial method for determining power (dB). This is only a practical strategy that simplifies computations significantly; there is no new science concealed here. The decibel describes the connection between two measures of power since it is a dimensionless unit. Its definition is where the two numbers you wish to compare, P_1 and P_0 , are any two values. In our situation, this will often be a certain quantity of electricity. Why is it so useful to utilise decibels? Numerous natural processes exhibit what is known as an exponential behaviour. For instance, if a sound has ten times the actual signal strength of another, the human ear perceives it as being twice as loud.

Absorption is another illustration that is highly relevant to our area of study. Let's say a wall blocks 50% of the available signal for each metre it is in the way of our wireless connection. This would lead to this behaviour is exponential.

The method of applying the logarithm (\log) makes things much simpler after we've used it, however; now we merely multiply by n instead of raising a number to the n -th power. We add values instead of multiplying them. It's crucial to keep in mind the following values that are often used: Triple power (+3 dB) Half the power equals -3 dB. Order of magnitude: +10 dB (10 times power) -10 dB equals a tenth power.

There are other definitions that are based on a certain basis value P_0 in addition to dimensionless dB. The ones who matter most to us are: dBm vs P_0 equals 1 mW. dBi in comparison to a perfect isotropic antenna. A hypothetical antenna that disperses electricity equally in all directions is called an isotropic antenna. A dipole may get close to it, but an actual perfect isotropic antenna cannot be constructed. The relative power gain of an antenna in the actual world may be accurately described using the isotropic model.

Milliwatts are a different popular, but less practical, standard for representing power. The following are equal power levels in milliwatts and decibels shown below:

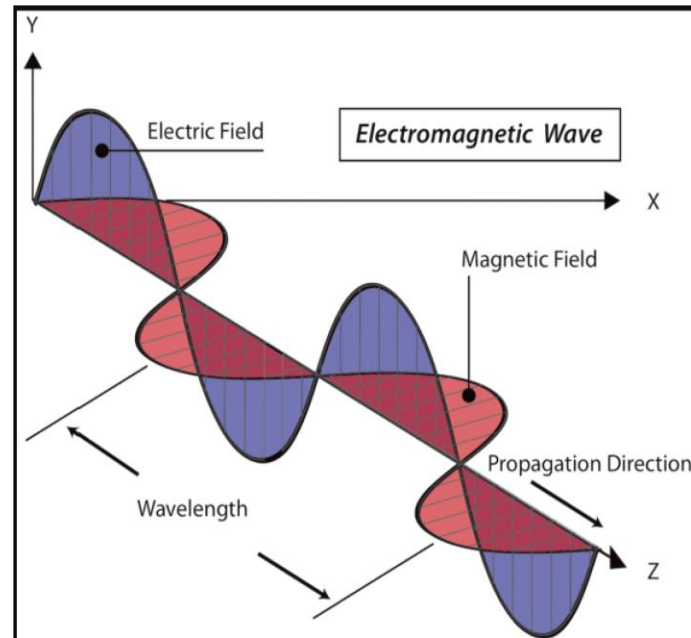


Figure 8.4 Shows the power levels in milliwatts.

RF Deflection of waves

In addition to reflecting off of buildings, hills, cars, and even aircraft, waves may also do so. For instance, reflection from an aircraft at 12 km altitude allows two stations that are 900 kilometres distant to interact. This would obviously only work for experimental systems. When waves travel through two different media with different indices of refraction, their velocity varies, causing the waves to bend through refraction. This explains why a floating item may not be where it first seems to be shown below.

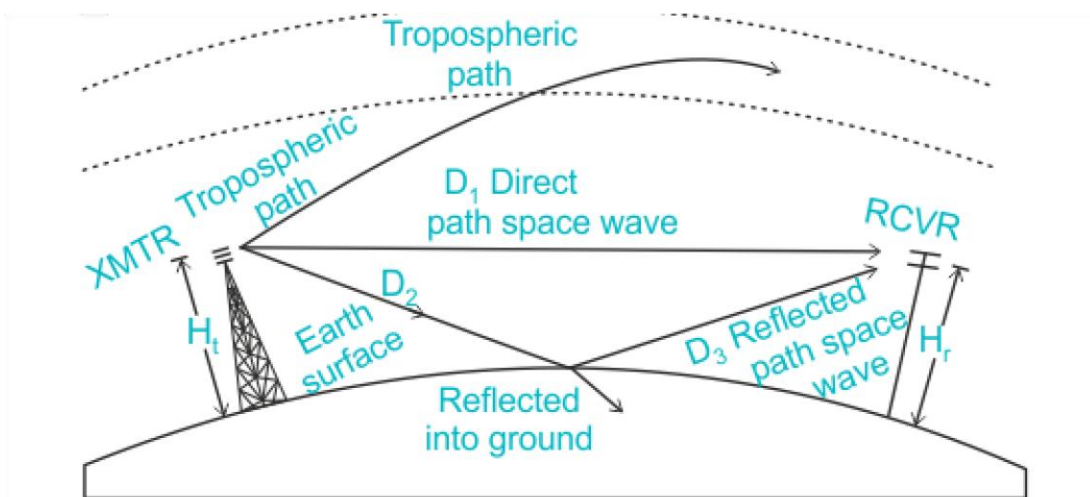


Figure 8.5 Shows the floating item.

As seen in, diffraction happens when a wave front encounters a sharp edge, is delayed, and is subsequently reflected off to the other side. As shown in and c, the edge need not always be sharp in order for signals to be diffracted by a building or mountain. Note another example of

multipath brought on by diffraction and reflection. Ground-wave propagation is made possible by the earth's ability to function as a diffract or at wavelengths over 300 metres shown below.

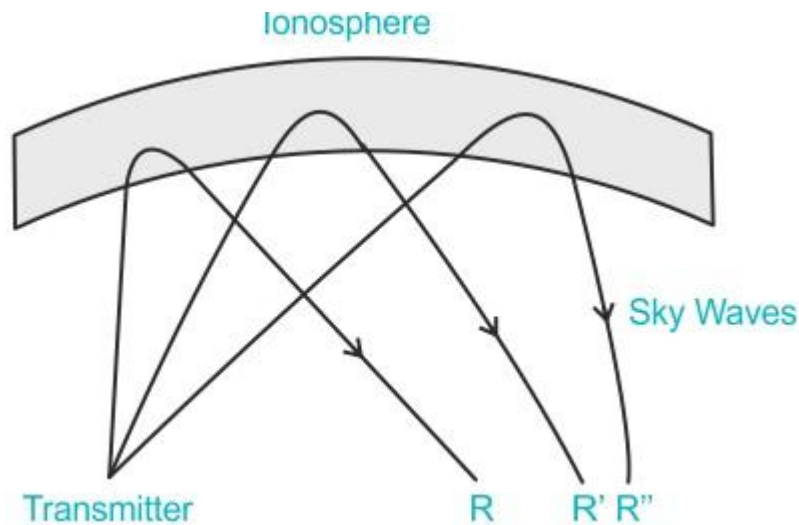


Figure 8.6 shows the wavelengths.

Light or radio waves might be deflected if the medium includes reflecting particles. One frequent instance is the scattering of headlight beams caused by fog. Similar to how meteor showers scatter electromagnetic waves and enable non-LOS propagation for communications in the 28432 MHz frequency band, meteor showers also leave ionized trails in the earth's atmosphere. This may be a very fleeting phenomena, much as other transmission processes.

Left-handed media, a novel class of electromagnetic materials, has recently attracted a lot of attention. Veselago predicted more than 30 years ago that electromagnetic wave propagation in a material with concurrently negative permittivity ϵ and permeability μ should result in a number of unique properties. According to Maxwell's, the direction of the Poynting vector which is the cross product of the electric field E and the magnetic field H gives the direction of energy flow of a plane wave. The Poynting vector and the wave itself, which is the phase velocity, or wave vector, are both given by the cross product of the electric field E and the magnetic field H for plane waves propagating in isotropic regular media with simultaneously positive ϵ and μ . E , H , and wave vector k form a right-handed triplet of vectors. Although $E \times H$ for a plane wave still indicates the direction of energy flow, Veselago predicted that the phase velocity wave vector! shall be in the opposite direction of energy flow, and E , H , and wave vector k shall form a left-handed triplet of vectors in a medium having simultaneously negative ϵ and μ .

Given this left-handed trait, Veselago designated this sort of material as a left-handed medium (LHM), and all other normal materials as right-handed mediums (RHM). Due to the simultaneous change in the signs of ϵ and μ , left-handed materials also exhibit a number of other dramatically different electrodynamic properties than regular materials. These electrodynamic properties include anomalous refraction, reversal of the Doppler shift and Cerenkov radiation, and reversal of radiation tension from radiation pressure. Veselago's prediction did not receive much attention until very recently, when a system consisting of an array of resonators and metallic wires was successfully prepared following the suggestion was demonstrated to be left-handed for electromagnetic waves propagating in som. Although these counterintuitive

properties follow directly from Maxwell's, due to the absence of naturally occurring materials having simultaneously negative ϵ and μ , Veselago's prediction did not attract much attention until very.

This finding sparked a lot of curiosity in the peculiar electrodynamic characteristics of lefthanded materials. The properties of electromagnetic wave propagation in uniaxially lefthanded anisotropic media are covered in this article. The majority of recent theoretical works and the original paper by Veselago focused primarily on the properties of electromagnetic wave propagation in isotropic left-handed media, but up to this point, the LHM that have been successfully prepared in experiments have actually been anisotropic, and it may be very challenging to prepare an isotropic left-handed medium. It is widely known in traditional electrodynamics that the electrodynamic characteristics of anisotropic materials vary greatly from those of isotropic materials. Uniaxial anisotropy is the most basic and typical kind of anisotropy, and the left-handed medium predicted in References should likewise be uniaxially anisotropic based on a study of its symmetry.

We give a thorough analysis of the features of electromagnetic wave propagation in uniaxially left-handed medium in this study. We will demonstrate how uniaxially anisotropic LHM dramatically differs from isotropic LHM in terms of the features of electromagnetic wave propagation. The following is how the paper is set up: The left-handed feature of electromagnetic wave propagation in uniaxially anisotropic LHM is briefly reviewed explore the circumstances under which anomalous reflection or refraction must occur at the interface when a propagating wave transitions from one uniaxially anisotropic right-handed medium into another one that is isotropic regular. When an evanescent wave is transmitted via a slab of uniaxially anisotropic lefthanded material, we analyse the circumstances under which anomalous transmission must occur.

We provide a succinct overview of the lefthanded property of electromagnetic wave propagation in uniaxially anisotropic left-handed media in this section. One or both of the permittivity and permeability tensors are second-rank tensors for anisotropic materials. Here, we assume that the permeability and permittivity are both uniaxially aniso shown below.

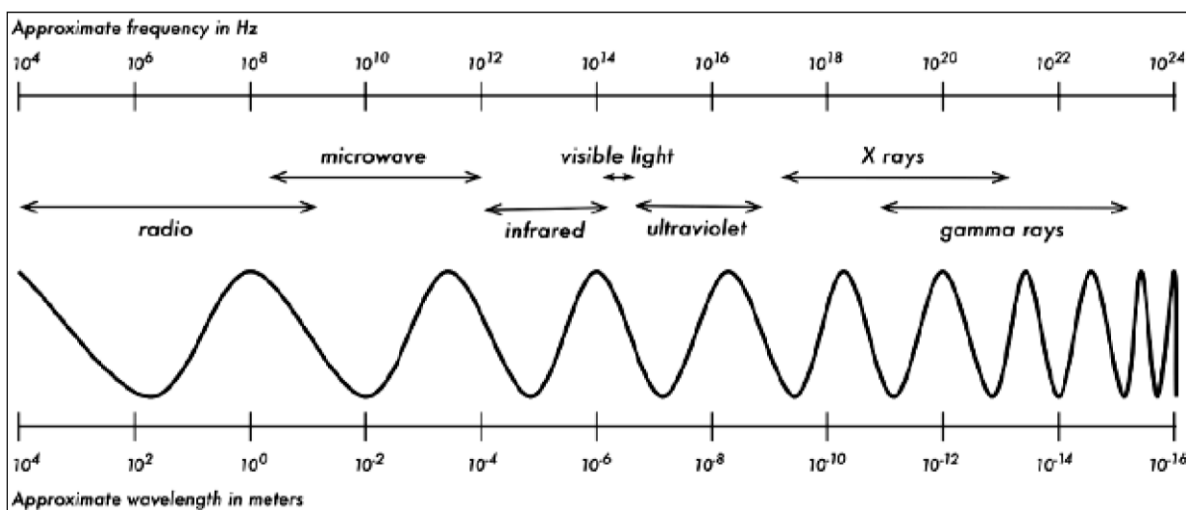


Figure 8.7 Shows the permeability and permittivity.

CHAPTER 9

Advantages of Communication System

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There are numerous different digital communication technologies, including SMS, instant messaging, email, desk phones, mobile phones, and many more. Email is a popular form of communication in many companies. Coworkers used to talk to one another in person or through mobile phones before email was invented.

The benefits and drawbacks of digital communication

We'll talk about the advantages and drawbacks of digital communication in this essay. Students who are writing essays or preparing presentations on the advantages and disadvantages of digital communication may find this material useful. So let's get started on the subject right now. Let's first examine a quick explanation of digital communication before moving on to perks and restrictions.

Digital communication:

Digital communication is the exchange of information across devices in a digital format. It offers the option of video conferencing, which helps to save time, money, and a lot of work. Because it can be carried out across long distances using the internet and other resources, it is simpler, less expensive, and quicker. The hardware implementation in digital circuits is more versatile than it is in analogue circuits. Compared to analogue communication, digital communication provides a number of benefits, but it also has certain drawbacks. Let's now examine the advantages and drawbacks of digital communication. The following are some advantages of digital communication versus analogue: The influence of noise interference and distortion is less noticeable in digital communications.

Humans and robots are only two examples of the many diverse data carriers, and exchanges may come in different forms. Analogue and digital messages may be distinguished from one another, however. The criteria for successful communication are thus set by this distinction. An analogue message is a physical quantity that changes with time, often in a smooth and consistent way. Case examples of analogue communications include the pressure you produce when you speak, the movement of a helicopter's gyro, or even merely the level of light intensity in a particular environment of a television screen. The information is encoded as a time-varying waveform, hence an analogue communication system must accurately transmit this waveform.

It makes video conferencing possible, which helps to save time, dollars, and effort. Without having to travel, we may have video conferences with one individual or a group of individuals. We can observe facial expressions during video conferences, which is useful for interpreting people's reactions. It is less costly and simple to apply. It is used in professional settings. Since channel coding is used in digital communication, error repair and detection are simple. Digital signals are simpler to store and retrieve than analogue signals.

Compared to analogue communications, configuring digital signals is simple. Similar devices may be utilised for many operations since most digital circuits employ a common encoding approach. Cross-talk is very unlikely in digital communication. In digital communication, hardware implementation is more versatile. IN digital communication, the spread spectrum approach is used to prevent signal jamming. We can also communicate with a person or a group of individuals in another area without having to travel thanks to audio conferencing. As a result, it saves money, time, and effort.

Digital circuits use signal processing techniques like compaction and encryption to keep information private. Because of improvements in integrated circuit (IC) technology, digital communication is less expensive and easier to use than analogue transmissions. Let's now examine the restrictions placed on digital communication. Digital Communication Drawbacks the following is a list of digital communication's drawbacks: In digital communication, a lot of electricity is used. In the case of synchronous modulation, synchronisation is necessary.

Digital communication is frequently constrained by the need for more transmission bandwidth. It results from the analogue to digital conversion's higher data rate. A high rate of analogue to digital conversion is necessary for digital communication. If a user doesn't comprehend anything, there may be a chance of misunderstanding. The advantages and drawbacks of digital communication have been shown here. While embracing the newest communication technologies, avoid becoming a slave to technology. This implies that we need to control our digital communication tools rather than letting them control us. I really hope this essay has given you enough knowledge and insight to help you understand the advantages and drawbacks of digital communication.

Electromagnetic waves exhibit anomalous reflection and refraction at the interfaces of isotropic regular media and uniaxially anisotropic left-handed media. Snell's law states that when a beam of light travels from one regular medium into another, it will reflect and refract at the interface between the two media, bending toward the interface normal but never emerging on the same side of the normal as the incident ray. However, Veselago anticipated that the refracted ray should sit on the same side of the interface's normal as the incident ray if the second medium is an isotropic left-handed medium (LHM). One of the most intriguing unusual characteristics of isotropic left-handed medium is the phenomena of anomalous refraction, which has just lately been empirically confirmed. The features of electromagnetic wave reflection and refraction at the interface between an isotropic regular media and a uniaxially anisotropic left-handed medium are covered in this section. We will demonstrate that, in addition to the anomalous refraction phenomena, the interface between one isotropic regular medium and the second uniaxially anisotropic left-handed medium may also sometimes experience the anomalous total reflection phenomenon.

The typical total internal reflection phenomena, which is widely known in classical electrodynamics, is substantially unlike from this anomalous total reflection occurrence. The incidence angles must be less than a critical angle for this abnormal total reflection event to occur. The typical total internal reflection phenomena, in contrast, can only happen if the incidence angles are greater than a critical angle but not smaller. The next two paragraphs will examine two instances. In the first instance, the interface of two media has a left-handed medium's optical axis, abbreviated LHM, as typical. The second scenario is when two media interfaces are parallel to the optical axis of the LHM.

After providing some background information, example metrics for underground coal mines will be discussed. Performance metrics are measurements of performance based on system behaviour during a certain time period for the purposes of this lesson. Both qualitative and quantitative metrics may be used. Qualitative measurements, such as simplicity of installation and complexity of troubleshooting, involve some amount of human judgment. Bit error rates (BERs), received signal strength indicators (RSSI), and system update intervals are a few examples of quantitative measurements that are either directly monitored or include values that may be explicitly given. In this context, a performance target is the lowest or highest value that may be achieved for a certain performance indicator. In general, reaching consensus on qualitative performance targets is not too difficult. The majority of individuals agree that CT systems must be able to provide two-way conversations.

Able to pinpoint the position of a miner. Simple to use simple to instal and keep up. Both before and after an accident, it is safe to use dependable in both every day and emergency circumstances. Being able to function after an injury qualifies as being survivable. But perspectives quickly divide when performance measurements and objectives are quantified. For a CT system, for instance, the following inquiries come up: How much damage and how much force from mechanical and explosive sources must the system withstand? How often should the system be tested, and how is its functionality confirmed? How long must a system continue to function after an accident? How much availability or dependability must a system have? What is the longest amount of time that normal maintenance and repairs may be put off?

What is the longest time a miner's communication may be delayed from being sent to the surface (during routine operations or after an accident)? What entails adequately safe battery-powered gadget functioning in a potentially explosive environment (methane and/or coal dust)? How precise must the position of a miner be determined? Once survival objectives have been determined, how is a system tested? It is highly challenging to provide answers to these issues and to develop quantitative performance measurements that will enjoy widespread acceptance for a number of different reasons. These motives consist of: Underground CT systems function differently. In "free space" or aboveground situations, electromagnetic radiation propagates differently than it does beneath. As a result, the usual techniques for verifying these metrics do not work. For instance: A linear parameter, underground coverage may be expressed in feet or miles.

An area in square miles or square feet is used to describe aboveground coverage. In contrast to aboveground measurements, which are generally based on permanent infrastructure, working spaces in underground coal mines are continually advancing and receding. As a result, approaches for estimating survivability and dependability that are used aboveground are not suitable for use in subterranean systems. The underlying system prerequisites vary. Underground coal mine CT systems are primarily installed to enable post-accident communications that adhere to the MINER Act of 2006. Aboveground, the majority of systems are automated and designed to increase productivity; as a result, performance measures like survivability and dependability are often secondary. Installation-specific considerations are needed for the risks and alternatives related to survivability and dependability. In underground mines, a conventional one-size-fits-all approach is inapplicable. For CT systems, system installation and layout are just as important to system survival as the technology itself.

Therefore, it is challenging to establish consistently acknowledged performance criteria across the mining industry. There are several compromises in defining performance objectives. There are times when strategies to attain one performance objective make it harder to achieve another in the design of CT systems. For instance, making a system more user-friendly by automating certain tasks might result in a more complicated design, more costs, and perhaps worse dependability. As another example, extending the amount of time a system is operating during an emergency may result in bigger and/or extra backup power-supply locations, increasing the risk of battery safety issues. Third, coverage objectives could mandate the installation of active components in return airways, which would raise security issues potential ignition sources. For underground mines, CT systems constitute a brand-new technological frontier.

The majority of communications networks are run aboveground by telecommunications corporations, who are also in charge of their dependable operation. Additionally, aboveground businesses may easily access service firms that can design and instal systems should they decide to build their own infrastructure. The CT systems that are suggested for usage underground do not fall under this category. As a consequence, three problems develop: There are few appropriate instruments to gauge and forecast performance in an underground mine. There is a lack of personnel skill, experience, and historical data to develop performance indicators in an underground mining setting.

There is currently very little information available that can be used to establish system criteria that is pertinent to CT systems in any underground mine catastrophe scenarios. As mine operators and regulators begin to acquire experience with these systems, new measures, methodologies, and potentially even nomenclature will emerge in response to the aforementioned problems. However, the mining sector should make every effort to maintain as much practicable consistency in these performance measurements and language with other industries. Several projects being worked on by NIOSH will provide a foundation for determining what system measurements and objectives are acceptable for the subterranean environment.

The LHM's optical axis is parallel to the interface

The optical axis of the LHM, or z axis, is normal to the interface of the two media, and in this part, we explore the features of reflection and refraction of electromagnetic waves travelling from one isotropic regular medium into a second uniaxially anisotropic left-handed medium provides a schematic representation of the system. The normal medium's permeability and permittivity will be denoted as $\epsilon_r(0)$ and μ_r in the text that follows (.0).

Since the tangential components of the refracted waves' wave vectors are equal to those of the incident waves in the case where the second medium is uniaxially anisotropic, it is simple to deduce from the boundary conditions that the refracted waves should maintain the same polarisation as the incident waves. Since the refracted waves are likewise E-polarized for where anisotropic right-handed medium into a second one that is isotropic and regular. Incident beam, reflected ray, refracted ray if normal refraction occurs, and fourth refracted ray if abnormal refraction occurs.

The energy current density S of the refracted waves, which establishes their directions, may be computed once the transmission coefficients have been established. The formula for S , which provide a clear picture of the fundamental characteristics of reflection and refraction. Let's first examine the circumstances that will cause refraction at the contact. The z component of the wave

vectors of the refracted waves must, in theory, be real for refraction to occur; otherwise, the incident waves will be completely reflected. This is because, as can be seen from Eqs. 23 to 24, if the wave vectors of the refracted waves' z component are imaginary, the normal component of their energy current density, or $S \cdot e_z$, will be zero.

As a result, no power will be transmitted into the second medium, and the incident waves will be completely reflected. The refraction will only happen if the incidence angles meet the following inequality E-polarized incident waves, and for H-polarized incident waves. This is evident from Eqs. 18 and 20. The refracted waves' directions may be found by using the following rules. The x component of the energy current density of the refracted waves will be determined by mz for E-polarized incident waves and $e z$ for H-polarized incident waves, according to Eqs. 23 to 24. First, the boundary conditions demand that the x component of the wave vectors of the refracted waves should equal the x component of the wave vectors of the incident waves. Second, for causality to exist, the energy stream of the refracted waves in the second medium must always be transported away from the two media's interface and never toward it. The z component of the energy current density of the refracted waves must, therefore, always have the same signs as the z component of the energy current density of the incident waves in order for this to be true.

Anomaly complete reflection for E-polarized incident waves will happen if m'/mz and $e'm'$ are both concurrently negative. Eq. 18 shows that the incidence angle must be greater than a critical angle $u c \arcsin A(e'mz)/$ for refraction to occur if m'/mz and $e'm'$ are both concurrently negative ($e' r m r$). The incident waves must be completely reflected if the incidence angle is less than the critical angle ($u c$), at which point kz will be fictitious. The critical angle $u c$ will be equal to $\pi/2$ if $e'mz.e' r m r$. The E-polarized incident waves in this scenario must be completely reflected at all incidence angles. If the second medium is an isotropic lefthanded medium, this anomalous complete reflection cannot happen.

Anomaly complete reflection for H-polarized incident waves will happen if $e'/e z$ and $e'm'$ are both concurrently negative. According to Eq. 20! The incidence angle must be greater than the critical angle $u c \arcsin A(m'e z)/$ for refraction to occur if $e'/e z$ and $e'm'$ are both concurrently negative ($e' r m r$). The incident waves must be completely reflected if the incidence angle is less than the critical angle ($u c$), at which point kz will be fictitious. The crucial angle $u c$ will equal $\pi/2$ if $m'e z.e' r m r$. The H-polarized incident waves in this scenario must be completely reflected at all incidence angles. The second medium must be an isotropic left-handed medium in order for this aberrant total reflection phenomena to occur.

Anomaly refraction will occur for E-polarized incident waves if $mz,0$ and the incident angles satisfy the inequality 25!, and other elements of the permittivity and permeability tensors do not need to be negative. Anomaly refraction will occur for H-polarized incident waves if $e z,0$ and the incident angles satisfy the inequality 26!. The same result was attained in Reference 13. The existence of anisotropy means that the refracted waves do not necessarily need to be left-handed or backward waves, even if the refraction is anomalous. Alternatively, even if the refracted waves are left-handed or backward waves, the refraction may be conventional but not anomalous. For E-polarized incident waves, for instance, if $mz, 0$ and $e'.0$, the refraction must be anomalous but the refracted waves must not be left-handed or backward waves because in this scenario, the refracted waves' energy flow must be in the wave vectors' forward but not backward direction. This demonstrates once again the necessity to expand on the initial ideas concerning left-handed medium in the presence of anisotropy.

The LHM's optical axis is perpendicular to the interface.

We demonstrate that anomalous reflection or refraction may still happen under certain circumstances if the optical axis of the uniaxial anisotropic left-handed medium is parallel to the interface of the two media. We shall choose the x axis to be parallel to the interface and the z axis to be along the optical axis in the following for convenience's sake, and assume that the wave vectors of the incident waves, the incident, reflected, and refracted wave fields can still be expressed using similar forms to those given, and the refracted wave energy current density can be expressed using the same forms. The existence of refraction will necessitate the reality of k_x (8) and k_x (9). As a result, the incidence angle θ for waves that are E-polarized should meet the inequality shown below.

By using the following rules, one may identify the directions of the refracted waves. The x component of the energy current density of the refracted waves must have the same signs as the x component of the energy current density of the incident waves in the second medium for causality to exist. From the boundary conditions, second we can see that m_z for E-polarized incident waves and e_z for H-polarized incident waves will define the z component of the energy current density of the refracted waves. These justifications allow us to draw the subsequent conclusions.

Anomalous complete reflection for E-polarized incident waves will happen if m_z/m' and $e_z m_z$ are both negatively polarized at the same time. From we can deduce that refraction must occur if the incidence angle is greater than a critical angle $\theta_c = \arcsin(A(e'm')/c)$ if m_z/m' and $e_z m_z$ are both negative ($e' m_r$). The incident waves must be completely reflected if the incidence angle is less than the critical angle ($\theta < \theta_c$), at which point k_x (8) will be imaginary. If $e'm' > e' m_r$, all incident E-polarized waves will be completely reflected, regardless of incidence angle.

Anomalous complete reflection for H-polarized incident waves will happen when both e_z/e' and $e_z m_z$ are concurrently negative. The incidence angle must be greater than the critical angle $\theta_c = \arcsin(A(e'm')/c)$ for refraction to occur if e_z/e' and $e_z m_z$ are both negative ($e' m_r$). The incident waves must be completely reflected if the incidence angle is less than the critical angle ($\theta < \theta_c$), at which point k_x (9) will be fictitious. The H-polarized incident waves must be completely reflected at all incidence angles if the incidence angles meet the inequality for E-polarized incident waves, anomalous refraction will happen, but other components of the permittivity and permeability tensors do not have to be negative, and the refracted waves must be roughly left-handed waves. Although other components of the permittivity and permeability tensors do not have to be negative, anomalous refraction of H-polarized incident waves will happen if $e' > 0$ and the incidence angles fulfil the inequality. The refracted waves will also be roughly left-handed waves.

The amplitude of the transmitted wave will exponentially decrease with increasing slab thickness when an evanescent wave is transmitted through a slab of regular medium with concurrently positive permittivity and permeability. The classical electrodynamics community is aware of this. However, it has recently been demonstrated that when an evanescent wave incident from a nearby isotropic regular medium is transmitted through a slab of isotropic left-handed media, the LHM slab will exponentially increase the transmitted wave's amplitude if its permittivity and permeability constants are equal to the negative values of the surrounding regular medium's permittivity and permeability constants.

Even though evanescent waves don't carry any energy, their anomalous transmission is an odd characteristic of isotropic left-handed medium that is quite intriguing and may result in some unusual optics. For instance, lenses created from a slab of isotropic left-handed material will have the ability to focus all Fourier components of a two-dimensional image, including evanescent waves that cannot be accessed by conventional imaging optics and propagating waves. All of the source's information could then be brought into focus. In this section, we discuss the circumstances under which anomalous transmission will occur when an evanescent wave incident from a nearby isotropic regular medium is transmitted through a slab of uniaxially anisotropic left-handed media with simultaneously positive permittivity ϵ_r and permeability μ_r . The LHM slab's thickness will be indicated as d in the sentences that follow. The LHM slab's optical axis, or "z axis," is perpendicular to its contacts with the surrounding medium, which are situated in the planes of $z=0$ and $z=d$. Where r is the slab's total reflection coefficient. Since some of the incident wave is transmitted into the LHM slab and vice versa, a wave incident on the LHM slab's interfaces with the surrounding medium also experiences transmission and reflection, the electric field of the wave inside the slab be found by matching the electric and magnetic fields at the two interfaces between the LHM slab and the surrounding medium, and we can obtain that the overall transmission through both surfaces of the LHM slab is given by t_5 in most situations, an evanescent wave would experience exponential amplitude decay as the slab's thickness grows, i.e., when $d \rightarrow \infty$. However, the transmission process across the LHM slab will exponentially increase the amplitude of the transmitted evanescent wave if the following criteria are met if requirements 38 and 39 are met, the transmitted evanescent wave's amplitude will grow exponentially as the thickness of the LHM slab rises, as shown by (10). So, for E-polarized evanescent waves, a slab of uniaxially anisotropic left-handed medium does enhance the transmitted waves if criteria 38 and 39 are met. Similar methods can be used to determine the overall transmission through both surfaces of a slab of uniaxially anisotropic medium for H-polarized evanescent waves, and we can determine that the overall transmission coefficient is

The amplitude of the transmitted H-polarized evanescent wave will be increased exponentially by the transmission process across the LHM slab, and the total transmission coefficient t_8 will be equal to $\exp(\text{Im}(k_z) d)$. Therefore, for H-polarized evanescent waves, a slab of uniaxially anisotropic left-handed medium will exponentially increase the transmitted waves provided criteria 42 and 43 are met for E- and H-polarized evanescent waves, the requirements for the development of this sort of anomalous transmission are different in the presence of uniaxial anisotropy. According to the findings in References 8 and 9, if the LHM slab is isotropic.

We have provided a thorough analysis of the features of electromagnetic wave propagation in uniaxially left-handed medium. We have thoroughly covered the circumstances under which anomalous reflection and anomalous refraction must take place at the interface between two uniaxially anisotropic media and the circumstances under which anomalous transmission must take place when an evanescent wave passes through a slab of uniaxially anisotropic left-handed media. We have shown that the properties of electromagnetic wave propagation in uniaxially left-handed anisotropic media vary dramatically from those in left-handed isotropic media.

CHAPTER 10

Emerging Development in Communication System

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The Internet employs packet switching, in which all the data stream is divided into particles but instead routed to the destinations through a set of accessible channels to be reassembled at the destination. The Internet was initially developed for efficient and quick text and data transfer. Although it would generally not be acceptable for voice telephone, data transmission is more productive than bus topology if the communications are bursty or interrupted, as is the case with text. Internet telecommunications, or Voice-over-Internet Protocol (VoIP), is developing as a competitive alternative to traditional telephone circuit switching thanks to the continuous development of high-speed data routers and the already-existing cable television infrastructure. In actuality, packet switching will be predominantly used by third-generation (3G) cellular phones.

Better multiple access techniques have been developed continuously, in addition to packet switching, to make it possible to use an existing channel more effectively. This allows for cheaper service and more users per cell in the example of wireless or mobile phones without a reduction in service quality (QoS). The other's speech in the background. Thus, there is the proverbial trade-off between interference and economic with FDMA and TDMA. This is especially true for mobile phones, where we must impose strict restrictions. Although one current user is about to hang up and release the frequency or time slot, this hard restriction prohibits other users from making calls. Contrarily, with CDMA, an unauthorised listener will only hear noise; as a result, when someone wishes to make a call in a crowded cell area, the extra CDMA user will momentarily increase the amount of background noise since it is probable that someone else will soon be hanging up. By choosing a set of carrier frequencies that are orthogonal to one another, we may decrease interference between users in a frequency division multiplexing variant known as orthogonal frequency division multiplexing (OFDM).

In other words, the power output of a UWB is below such inadvertent radiators as computer boards and other digital logic devices. Ultra-wideband (UWB) systems may function at average power levels below the ambient levels of current RF interference. Recent Federal Communications Commission (FCC) regulations permit unlicensed UWB operation at power levels no higher than -41 dBm between about 3.1 and 10.6 GHz. This will enable increased utilisation of the RF spectrum and thus allow for even more users and services on the RF spectrum, along with continuous development of UWB technology.

Due to the FCC opening up sections of the 915 MHz, 2.45 GHz, and 5.8-GHz ISM as well as additional UHF and microwave bands for communication, computer networks Wi-Fi (or IEEE 802.11) and WiMax (or IEEE 802.16) have become quite popular. The phrase "hot spots" is often used because local area networks (LANs), such those used by laptop computers in coffee shops and other public places, employ Wi-Fi technology. It has a range of around 100 metres.

WiMax is a mobile wireless technology that often leverages the current network of cell phone towers and has a range similar to that of a cell phone. WiMax has been promoted as a wireless phone alternative for data service and as a cable replacement for enabling Internet access in buildings. WiMax may thus act as the last mile of broadband access. Keep in mind that WiMax, Wi-Fi, and mobile phones all use different frequencies and are thus independent networks.

Software radio, also known as software-defined radio (SDR), is a relatively new advancement in communication technology that offers more flexibility than is feasible with conventional analogue circuit techniques. A radio frequency (RF) amplifier and an analog-to-digital converter both work to amplify and digitise the signal at the antenna (ADC). The digital-to-analog converter (DAC), which converts the output of the ADC back into a format that the user can hear, receives the signal from the digital signal processor (DSP), which performs the necessary demodulation, among other operations. It would be the opposite for a software radio transmitter. Through software control, the station frequency, filter properties, modulation types, gain, and other parameters may be changed. Notably, the equipment is often a combination of analogue and software radio due to technical hardware limits, especially in the GHz frequency range. Radio frequency identification technology has emerged from obscurity and into the mainstream in recent years, enabling applications that hasten the processing of materials and produced items. In contrast to older bar-code technology, RFID (Radio Frequency Identification) permits identification from a distance and does so without need a line of sight. Compared to bar codes, RFID tags offer a wider range of unique IDs and may also include extra information about the product's maker, kind, and even environmental variables like temperature.

Furthermore, without human aid, RFID devices can recognise several tags that are scattered around the same geographical region. Consider a supermarket checkout counter as an example, where each bar-coded item must face the reader before being scanned. Why then did it take this technology more than 50 years to become widely used? The main justification is cost. Electronic identification technologies must either be similarly inexpensive as printed symbols or provide enough extra value for an organisation to recoup the expense somewhere else in order to compete with their cheap prices. Although more expensive than conventional labelling methods, RFID adds value and has reached a price range where widespread use for managing consumer retail products is possible. Here, we evaluate the manuscript that was received on July 30, 2010, explore the fundamentals of RFID, and go through its main technologies and applications.

RFID versus BAR CODES

1. In a similar vein, a tool to help process automation and enhance operations management.
2. Puts a plethora of data at your fingertips;
3. Reduces work;
4. Eliminates human mistakes.
5. Distinct in that:
6. Line-of-sight is not required to embed or hide tags. Except for metal, they can read through wood, plastic, and cardboard. Tags may be instantly reprogrammed.
7. Useful in challenging conditions, such as the outdoors, where chemicals, wetness, and high temperatures are present.

There are many different kinds of RFID, but at the most fundamental level, active and passive RFID devices may be distinguished.

Active tags need a power source to function; they either are wired into an electrical infrastructure or draw power from an inbuilt battery. In the latter scenario, the amount of energy that is stored and the number of read operations that the tag must endure determine the tag's lifespan. The transponder affixed to an aeroplane that identifies its country of origin is one example of an active tag shown below.

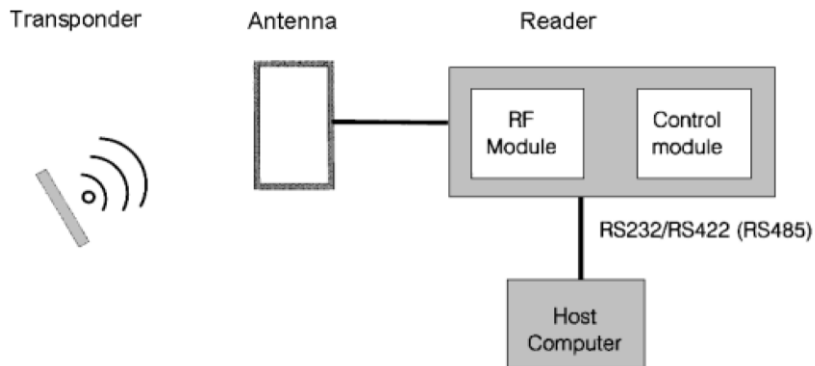


Figure 10.1 shows the transponder affixed.

Because passive RFID tags don't need batteries or upkeep, they are appealing. The tags are tiny enough to fit inside a useful adhesive label and have an infinite operating life. An antenna, a semi-conductor chip connected to the antenna, and some kind of encapsulation make up a passive tag. A tag can only be powered and communicated with via a tag reader. The tag chip manages this operation while the tag antenna absorbs energy and transmits the tag's ID. The encapsulation preserves the integrity of the tag and shields the antenna and chip from the elements or chemicals.

There are two fundamentally distinct RFID design strategies magnetic induction and electromagnetic (EM) wave capture for moving power from the reader to the tag. These two designs make use of the near field and far field electromagnetic (EM) characteristics of an RF antenna shown below.

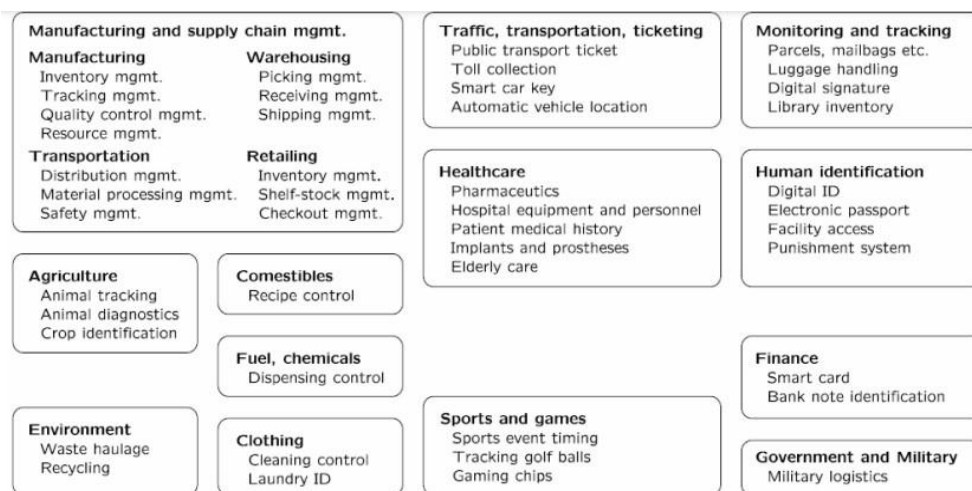


Figure 10.2 Characteristics of an RF antenna.

Both are capable of sending a remote tag enough power to keep it operating, generally between 10 W and 1 mW depending on the kind of tag. (By way of reference, an Intel XScale processor's nominal power consumption is around RFID Technology Principles, Advantages, and Limitations & Its Applications. Near- and far-field based signals may both send and receive data using different modulation methods.

Close-range RFID

Near-field coupling between a reader and a tag is based on Faraday's idea of magnetic induction. A reader creates an alternating magnetic field nearby by passing a sizable alternating current via a reading coil. An alternating voltage will be seen across a tag with a smaller coil if it is placed in this field. This voltage may be rectified, linked to a capacitor, and used to build up a reservoir of charge that can be used to power the tag chip.

Near-field coupling tags employ load modulation to relay information back to the reader. The reader coil may detect this as a little increase in current passing through it because any current pulled from the tag coil will create its own tiny magnetic field, which will oppose the reader's field. This current varies according on the stress placed on the coil of the tag (thus load modulation). Although a transformer's main and secondary coil are often twisted tightly together to promote efficient power transmission, this is the same idea employed in power transformers found in the majority of houses today. A secondary coil, like a reader and a tag, may still pick up part of the energy at a distance as the magnetic field spreads beyond the first coil. By keeping an eye on any changes in the current flowing through the reader coil, the reader can then retrieve this signal shown below.

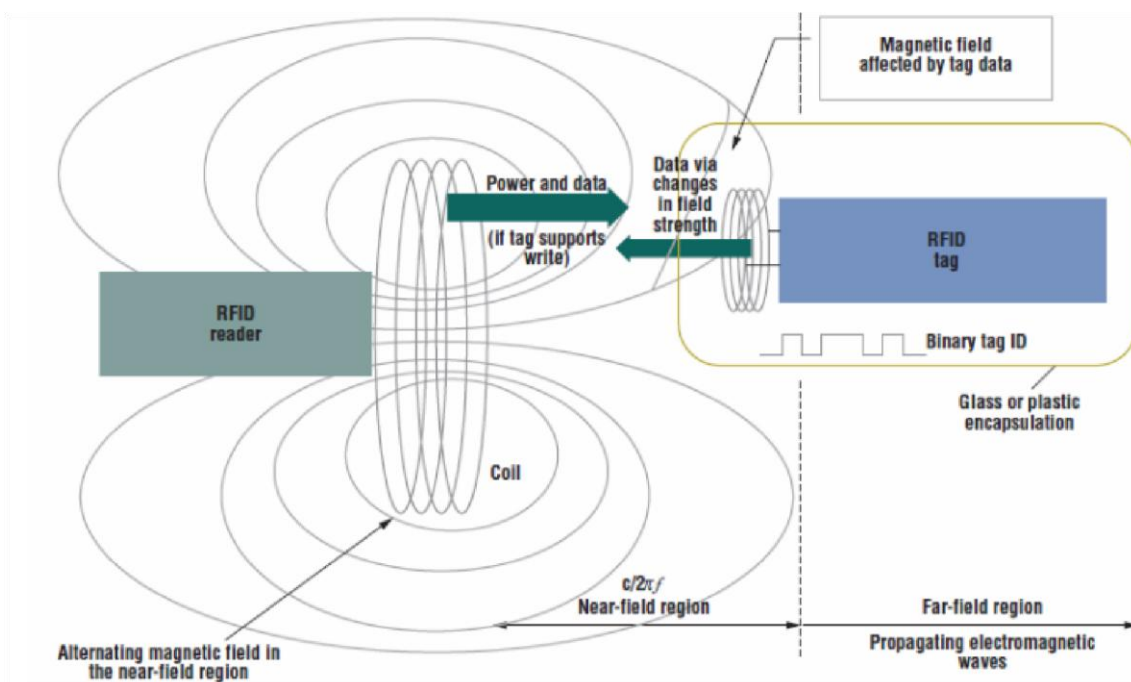


Figure 10.3 Shows the signal.

Depending on the amount of ID bits necessary, the data transmission rate, and extra redundancy bits included into the code to eliminate mistakes brought on by noise in the communication channel, a variety of modulation encodings are conceivable. Near-field communication does have

certain physical restrictions, however. The frequency f and the constant c (the speed of light) define the range for which we may employ magnetic induction. As a result, the maximum operating distance for near-field coupling diminishes as the frequency of operation rises.

The energy available for induction as a function of the reader coil's distance is another restriction. Along a central line perpendicular to the plane of the coil, the magnetic field begins to weaken at a value of $1/r^3$, where r is the distance between the tag and reader.

Therefore, each tag needs a greater data rate and therefore a higher operational frequency since applications need to distinguish between numerous tags in the same location for a given read time while also requiring additional ID bits. New passive RFID designs based on far-field communication have emerged as a result of these design challenges shown below.

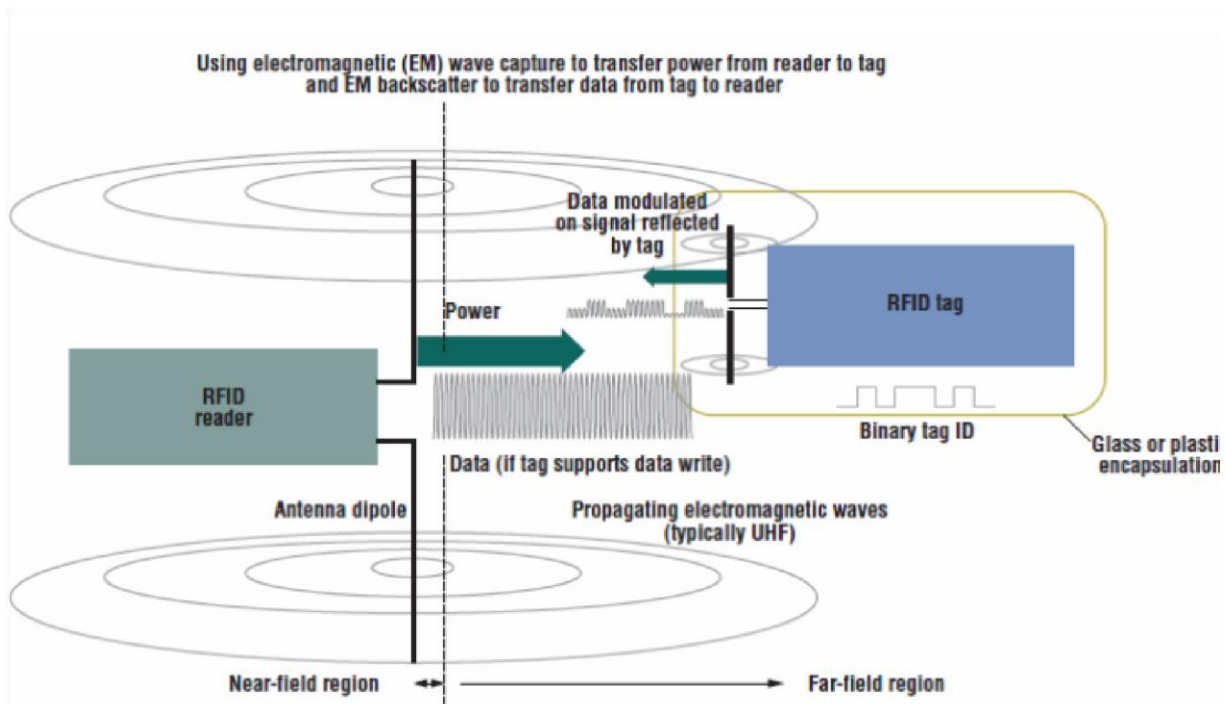


Figure 10.4 RFID designs based on far-field.

RFID tags based on far-field emissions that catch electromagnetic (EM) waves that are travelling from a dipole antenna linked to the reader. This energy is received by a smaller dipole antenna in the tag as an alternating potential difference that spreads across the dipole's arms. This potential may be rectified by a diode and connected to a capacitor, causing a buildup of energy that will power the capacitor's electronics.

Back scattering is the design method used for commercial farfield RFID tags. They can tune an antenna to a certain frequency and have it absorb the majority of the energy that comes its way if they create it with exact measurements. The antenna will, however, reflect back part of the energy (as minute waves) toward the reader if an impedance mismatch occurs at this frequency. The reader may then detect the energy using a sensitive radio receiver.

The tag may reflect back more or less of the incoming signal in a pattern that encodes the tag's ID by gradually adjusting the impedance of the antenna. In fact, you may do this by putting a transistor across the dipole of a tag's antenna and then turning it on and off intermittently. As a

general design reference, tags based on far-field principles work at frequencies larger than 100 MHz, often in the ultra-high-frequency (UHF) band (such as 2.45 GHz); RFID tags based on near-field principles function at frequencies lower than these.

CHAPTER 11

Development of Communication System

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The rapid technical development of communication networks demonstrates yet another time that "engineers are the catalysts of social change and are responsible for fundamental shifts in government interest, whether they be related to intellectual property, commerce, or privacy. All of these paradigm shifts are a result of the hard work of the engineers and financiers who build the newest communications technologies. Telephone service used to be a monopoly controlled by the government, only accessible via landlines. Long distance was more expensive and charged by the minute. These days, customers also have the option of using a mobile phone or Internet-based voice over IP (VOIP) service for their phone needs. The difference among both long-distance and local calls has been eliminated by these new technologies, and often both are accessible for a low, set charge regardless of how much time is spent utilising the service. This has reduced the need of national utility commissions. Similar to traditional phone lines, digital subscriber lines (DSLs) allow phone providers to offer both traditional phone and video services. The need for wired network access is declining as a result of WiMax but instead, to a lesser degree, Wi-Fi technologies. WiMax is anticipated to provide video, data, and phone services to homes and businesses in the same way that cable can today. What's even more intriguing is that WiMax businesses are often tiny independent startups, in contrast to many mobile phone carriers that are a subsidiary of a local telecommunications company.

The efficiency of a particular transmission method depends on the frequency at which the message being sent. Utilizing the density potential of CW modulation, transmission information may be imprinted on a provider whose spectrum has been selected for the desired transmission mode. Effective line-of-sight ratio propagation, as an example, requires antennas with physical properties at least $1/10$ the signal's wavelength. For the arpeggiated conveyance of an audio signal with frequency range as low as 100 Hz, 300 kilometres of antennas would be needed. With modulated broadcasts at 100 MHz, comparable to FM broadcasting, an antenna size of around one metre is realistically achievable.

At frequencies below 100 MHz, other diffusion modalities with acceptable antenna sizes perform better. Actually, during the wavelet decomposition, the modulation technique used in the transmission is reversed. We may describe the instrumentation procedure in a more structured way as follows: According to the concept of diversity, modulation is the process by which a signal's component is altered dependent on the present value of a different frequency, the modulated signal. Signals that modulate are said to contain knowledge or information. This signal that transmits data is also known as a baseband signal. Relatively low than with the carrier frequency is the modulating frequency. The result of the modulation process is the signal that has been modulated.

Offering a substitute for the unregulated local telecommunications or cable provider is one of the driving forces behind WiMax startup companies. Finally, satellite TV is now accessible utilising

dishes with a diameter of less than a metre, making it feasible to get satellite TV without breaking municipal zoning regulations. Any college campus will reveal that the majority of students have access to a wireless phone network that rivals telephone lines in terms of both quality and price and can reach any place in the United States. Voice, music, text, and video may all be sent and received on phones. State governments have been compelled to reconsider their sales tax laws as a result of e-commerce, but VOIP and mobile phone services have given the government another revenue stream to tax.

No regardless where we are, we are all always accessible "24/7" thanks to the Internet and the pervasive mobile phone. In order to "get away from it all," an employee may now have to respectfully inform the supervisor that he or she wishes not to be reachable by mobile phone and that, because there won't be any "hot spots," he or she won't be checking email while on vacation. The movie industry has had to reevaluate its business model and come up with new strategies to safeguard its copyrights as a result of digital and electronic recording methods that make it simpler to obtain music and video material.

Three parts make up RFID systems, which may be integrated in two ways. Typically, an RFID reader is made up of an antenna and a transceiver (transmitter/receiver). An RFID tag is made up of an antenna and a transponder transmitter/responder. When the reader sends out a radio signal that activates the transponder and causes it to communicate information back to the transceiver, the RFID tag has been read.

A standard RFID system comprises of the following three parts:

1. A coil or antenna
2. A transponder (RF tag) that has been electronically programmed with specific information.
3. An internal power source powers an active transponder or tag, which it utilises to produce a signal in response to a reader.

There are two kinds of transponders, which correspond to the two main categories of RFID tags: passive and active. Passive transponders and RFID tags lack an internal energy source and depend on the energy emitted by the reader for response. The RFID tags that are less expensive and passive are more likely to be utilised for consumer items. The cost of active transponders is higher than that of passive ones. Like regular radio communications, they can communicate across long distances. They are often used in the navigation systems of both private and commercial aero planes.

Although they are often unseen to consumers, there are several applications for this technology in our modern world. You could discover that you already own and use one or more RFID tags. RFID, at its most basic, is a wireless connection used to identify things or persons in a particular way. In certain cases, specialised short-range communication is used (DSRC). RFID systems include reader electronics that talk to the tags and electronic devices known as transponders or tags.

The radio signals used by these devices to communicate might be either unidirectional or bidirectional data transmissions when a transponder reaches a red zone, the reader detects its data and transmits it to a host computer, printer, or programmable logic controller for storage or processing.

1. Radio waves are sent by the antenna to turn on the tag and read and write data to it.
2. Depending on its power output and the radio frequency utilised, the reader may generate radio waves that can travel up to 100 feet or more. The activation signal from the reader is detected by an RFID tag as it moves through the electromagnetic field. The integrated circuit (silicon chip) in the tag's reader decodes the data, which is then sent to the host computer for processing.

An RFID system's goal is to make it possible for data to be communicated by a small device known as a tag, which is read by an RFID reader and processed in accordance with the demands of a specific application. The information provided by the tag might be used to identify or locate the goods, or it could include details about the tagged item, including its cost, colour, date of purchase, etc. Since at least a decade ago, hundreds of businesses have been using RFID technology. RFID's capacity to follow moving objects rapidly attracted notice. More ubiquitous - and intrusive - applications for RFID tags are being developed as the technology is improved. A radio antenna set on a substrate and a microchip are the basic components of an RFID tag. The chip has a maximum data storage capacity of 2 kilobytes. You need a reader in order to access the data on an RFID tag. A standard reader is a piece of equipment with one or more antennas that broadcast radio waves and take signals from tags. The reader then transmits the data to a computer system in digital form. Automation of a variety of operations is guaranteed once a connection is created with a unique ID on an object.

RFID BENEFITS

Although barcodes will likely continue to be widely utilised in the near future, the following benefits point to the possibility of using RFID in addition for identifying purposes:

1. Because tag detection doesn't need human interaction, labour costs are lower and human error in data collecting is eliminated.
2. Because line-of-sight is not necessary, tag placement is not as restricted.
3. Compared to barcodes, for example, RFID tags have a greater read range.
4. Barcodes lack the read/write memory capabilities that tags possess,
5. In addition to a unique identity, an RFID tag may contain a significant quantity of data.
6. RFID makes it simpler to apply unique item identification than barcodes, because it can identify goods specifically rather than generally.
7. Adverse circumstances (dust, chemicals, physical damage, etc.) have less of an impact on tags.
8. RFID tags may be used in conjunction with sensors, and several tags can be scanned concurrently.
9. Automatic reading decreases time delays and inconsistencies in an inventory at several locations,
10. Tags may locally store extra data, including

Distributed data storage may improve the system's failure tolerance, reduce expenses associated with inventory management and provisioning, and streamline the processing of warranty claims.

International Journal of Computer and Electrical Engineering, Although numerous RFID application examples have been documented, technical, process, and security challenges still need to be resolved in advance if the technology is to be widely adopted and fully used. The technology's current limits are anticipated to be addressed, and experts are actively working on a number of these problems.

The features of the application and the context of usage decide the right tag, but the lack of standards still gives a lot of latitude in terms of the communication protocols used as well as the format and quantity of data included in the tag. Companies that want to share their application with others after moving beyond closed-loop solutions may run into problems because the standards that cooperating partners must follow for communication protocols, signal modulation types, data transmission rates, data encoding and frames, and collision handling algorithms must all be agreed upon.

The price of tags varies according on the kind. RFID Systems in the Manufacturing Supply Chain, a 2003 paper by ARC This anticipated decline is still deemed insufficient because the economic use of tags would require a maximum of 25 cents per tag for high-end products and 5 cents for common item-level tagging, even after accounting for the associated 5–35% decrease in labour costs and zero tag information generation costs. Even more prohibitive are the costs of active or semi-passive tags (at least \$1 per tag), which limit their economic use to scanning expensive products at a distance.

Signal collision and eventual data loss might arise from attempting to read many tags at once. Anti-collision algorithms, the majority of which are patented or patent-pending, may be used to stop this at an additional expense. These techniques are continuously being developed, with the goal of shortening read times overall and increasing the number of tags read at once

Frequency

The best frequency selection is influenced by a number of variables, including Transmission mode. Basically, RFID tags employ one of two data transmission methods, depending on how electromagnetic fields behave at the applied frequency. Wave backscattering is the primary method of transmission in frequency bands above UHF, with typical frequency ranges of 433MHz, 865-956MHz, and 2.45GHz, whereas inductive coupling is employed at lower frequencies (such as 125-134 kHz in the LF band or 13.56MHz in the HF band). As it is simpler to construct direction-selective devices with a greater read range in higher frequencies, this also influences the safe reading range. If either reading range or spatial selectivity are significant issues, this may limit design flexibility.

Some materials' characteristics might make it difficult to use RFID at a certain frequency because they could skew data transmission via signal absorption or environment reflection. Problems are often caused by conductive materials like metal surfaces or items that contain water. Failure at one frequency does not preclude use at other frequencies, albeit absorption and reflection are frequency-dependent. External sources for electromagnetic disturbance are another possibility, which makes it a frequent yet frequency-dependent issue in an industrial setting.

Four major areas of performance measures have been presented by an internal NIOSH working group: Functionality. The miner's and other end users' perspectives on the system requirements. Installation and upkeep capabilities. Metrics related to the setup, upkeep, troubleshooting, and growth of the CT system. Coverage and range for communications and tracking. Metrics that

outline the CT system's service area. Safety after an accident and survivability. Metrics that demonstrate a system's capacity to function securely after an accident. Other metrics and objectives, such as system capacity, cost per foot or mile, mean time to repair, etc., may be connected to system productivity. These are not mentioned in the examples from the working group. Performance improvements should come with the advancement of CT technology.

These long-term objectives provide a vision of the ideal CT world in the mining environment; it's possible that some of them won't be attainable in the near future. NIOSH is still in favour of setting performance benchmarks and objectives in conjunction with regulatory, business, and labour organizations. In order to understand the minimal performance standards anticipated by those agencies, readers should consult the most recent MSHA and state laws and policies. Example CT system performance metrics and targets are shown. Generally Accepted Performance Metrics for Systems Continually Aiming Range and coverage Comm. wireless protection Miners go everywhere. Scope of coverage tracking reporting region of the tracking system Miners go everywhere.

Functionality Comm. capacity to communicate wirelessly Voice and data, plus messaging in any format Functionality Comm. Mutually exclusive communication Every mobile radio should be able to communicate with other mobile radios without the need of any infrastructure. Communication paging functionality to be developed Functionality Tracking Rescue team victim location Page all Tracking data storage needs radio or proximity-activated audible alarm Functionality both Remote power management and shutdown System may be remotely switched on and off for power saving and security. Functionality both of the surface requirements for a mine operations centre graphical representation of miners, batteries, and faults/alarms in real time Functionality Interoperability in both communications across voice and data to all devices and places Functionality Both battery upkeep and observation reliable battery condition monitoring with alerts Maintenance and installation Verification of Coverage Verification on a monthly basis using "drive" tests Tracking functionality Tracking system update frequency To be created Tracking system resolution functionality to be implemented

Tracking Miner location update frequency Suitability for installation and upkeep both upkeep and observation End-to-end automated testing and real-time monitoring of all components with alerts Survivability Communication. Wireless coverage endurance refers to access link Infrastructure that is susceptible Maximum outage area with a single element failure for survivability communications (worst case) Infrastructure that is susceptible Survivability Communications path survivability (affects voice/data and backhaul for tracking systems) Infrastructure that is susceptible Battery life for mobile communications, resilience Program

Policy Letters from MSHA (PPL) Battery life - communications fixed infrastructure: resilience 96 hours with power control, indefinitely Survivability Tracking tracking system endurance Infrastructure that is susceptible Survivability Tracking Battery life for mobile tracking Survival to be created Battery life monitoring and fixed infrastructure monitoring hours with power control, indefinitely Survivability Infinite battery life for both after-accident security Safety of both battery systems Infrastructure that is susceptible after-accident security Permittivity and post-disaster safe air certification Infrastructure that is susceptible.

The phrase "to be developed" means that it is anticipated that long-term objectives will be defined taking current research efforts into account. These efforts involve a thorough examination of the development, nature, and frequency of coal mine catastrophes. Considerations

for Wireless Systems. The antenna in wireless systems plays a crucial part in coupling energy to and from the transmission medium. An effective antenna must cover a significant percentage of the wavelength in order to be effective. As a result, the antenna has the issue of being fairly big for lower frequencies.

Low-frequency systems also have the drawback of having relatively limited throughput to sustain routine operations when several users and substantial data flow are common. Point-to-Point Communications, in this lesson, the terms "direct communications link" (one link) and "communications route requiring a network (many links) to complete the connection" are used interchangeably. In point-to-point (P2P) communications, two devices are directly connected. One example is an intercom system, in which a sender talks to a receiver who receives the message on a different electronic device by pressing a button on one of the devices. The two units are connected via a wired connection. Yet another illustration is a set of walkie-talkies (i.e., hand-held radios). They function in a manner similar to an intercom system, except the transmitter and receiver are connected wirelessly. Another kind of P2P communication is through-the-earth (TTE) communication. Only the earth's strata serve as a transmission channel between an antenna on the surface and an antenna within a mine.

TTE communications offers a backup communications path out of the mine at a specified place, however it is unable to provide underground radio coverage in areas that are not close to the region immediately under the surface antenna. P2P only allows for limited communication between two devices; to increase the communications range, extra route components must be used (i.e., some type of network or a large distributed antenna system such as a leaky feeder). Wired Communications. The majority of mines use some kind of wired communications system, where "wired" communications refers to the need that the miner utilise a device that is located in a permanent or stationary position.

Numerous of these wired systems transmit data instead of speech. Pager phones, ethernet networks, and conveyor monitoring and control are a few examples of wired data communications. The Twisted Pair Two insulated copper wires are wrapped around one another to form a twisted pair. Multiple wire pairs may sometimes be bundled into a single cable for installation. For instance, twisted pair is used to link house telephones. The cheapest kind of hardwire connection is a twisted pair. Twisted pair is the preferred technology for connecting miners beneath and the surface when using conventional pager phones in coal mines. A "party line" is created by connecting several phones in parallel to allow for more communication within the mine.

The amplifiers in each phone are turned on when a handset switch is pressed, making the message broadcast to everyone around. Ethernet cable, when used for local area networks (LANs) and at the output of cable and digital subscriber line (DSL) modems for Internet access, Ethernet cable is typically an eight-wire cable terminating on an RJ-45 connection. Computers are routinely linked using this form of Ethernet connection, which is also known as CAT5E (for LANs) and CAT6 (for the Internet). Ethernet cable may be used to send mine sensor data and/or control data, although the supported range is limited. Since coaxial cable or fiber-optic cable cannot accommodate Ethernet and other signals, numerous mediation devices can. Coaxial cable is less sensitive to electromagnetic interference than or twisted pair connections because it has lower signal losses and typically stronger shielding (EMI).

But the cost of coaxial cable is also higher than that of twisted pair. Optical Fiber Cable In comparison to metallic connections, fiber-optic cables have substantially greater data transmission speeds. Continuous optical fibres are bundled together into flexible cables to form fiber-optic cable. Copper communications cables may be replaced with this kind of cable. Rather of utilising electrical pulses to transport information over copper lines, fiber-optic cable utilises light pulses to do so. Because it employs light pulses rather than electrical pulses, the cable is far less vulnerable to EMI. The cable can transport data over extremely long distances because there is less attenuation than with copper.

An interpreter is needed for the fiber-optic cable. Copper wire carrying encoded electronic pulse data is accepted by the translator. The information is subsequently processed and converted into light pulses with equal coding. At the other end of the line, where the translator turns light pulses back into electrical pulses, the process is reversed. In general, fiber-optic cables cost more than copper cables. In order to reconnect a broken fiber-optic cable, more than just a simple splice is needed. Fortunately, producers are always enhancing fiber-optic cable designs to make them more durable and affordable. Secondary and Primary Communications During their shifts, miners employ primary communications systems, which provide regular daily subterranean and surface contacts. These systems operate in the standard radio spectrum. The miners may employ wearable technology with lengthy battery lives (lasting more than one shift) and enough throughput for basic mining operations thanks to the usage of tiny antennas. Examples of basic communications systems include node-based and leaky feeder systems.

Secondary communications systems use non-traditional frequency ranges to function (100 Hz to 1 MHz). They need big antennas at such low frequencies, which are either put at permanent places or are not easily movable. Additionally, they don't have enough throughput to communicate during routine mining activities because to the low frequencies. Secondary systems seem to have a good chance of surviving a catastrophe since they contain a small number of active components. Examples of secondary systems that might provide viable alternatives to main systems are medium frequency (MF) and through-the-earth (TTE) systems. It should be emphasised that in the event of a mining emergency or catastrophe (such as a methane and/or coal dust explosion, roof or rib collapse, water inundation, etc.), major communications systems may be exposed. Depending on the magnitude and location of the occurrence, the core systems' resilience to these catastrophes might be in doubt. One strategy is to provide a different, very dependable, and diversified communications channel.

There would be no shared elements between the main and alternative pathways that would fail due to a single occurrence. Although a moving borehole is not particularly feasible, a straight borehole to the miner would be the best alternative communications channel. Particularly close to the face, secondary systems, with their minimal infrastructure requirements, provide a wonderful opportunity for an alternative communications channel. Consider a hybrid system, which would be designed such that a low bandwidth secondary communications system could be utilised as a backup for the main communications system. This alternative option would presume compatibility between the primary and secondary systems.

A major objective would be to make sure that miners could continue to interact using the same wearable device that they use for routine tasks. Leaky Feeder Systems in Primary Communications An underground radio transceiver (base station), which is typically situated in the mine operations centre (MOC), and additional hand-held radios carried by the miners

underground are used in a leaky feeder communications system. The base station's effective range is substantially increased by specially constructed leaky feeder cable.

The handheld radio and cable are connected wirelessly. , 2-8 depicts one sort of feeder cable with a leak. Along its whole length, the cable functions as a dispersed antenna, able to pick up and send radio signals. EM waves may enter or exit the coaxial cable via the perforations in the outer conductor.

Additionally, the cable serves as a low-loss transmission medium, allowing RF signals to travel across distances that are several times greater than they would be able to do without it.

Global guidelines for frequency distribution.

Due to historical factors, the world is divided into three major regions for the purpose of allocating frequencies: regions 1 and 2, which include north and South America and the portion of the Pacific Ocean east of the date line, respectively, and regions 3 and 4, which include Asia, Australia, and the Pacific Ocean west of the date line.

There are still significant discrepancies between the three zones, despite the industry's efforts to uniformize the frequencies permitted for RFID, requiring businesses wishing to use tags across several regions to limit their use to bands that are available in all three regions.

The capacity of tags to operate across a larger frequency range than nominally stated, enabling their use even in areas where RFID bands are "near enough," may be a tradeoff for tags that just modulate the reader signal without actively creating a carrier wave on their own.

Poor tag manufacturing

Currently, there are still some manufacturing flaws; roughly 20–30% of the tags used in early RFID tests had problems.

Faulty or ineffective tag detection

While being used, tags could become damaged. The abundance of appropriate tags may address a broad variety of application difficulties, but none of them are fully impervious to harm, and the reasons for damage can differ from type to type. The outcome is a read failure, which is often hard to identify as is the harm itself for a concealed tag.

Poor placement and unfavourable environmental factors may impair reading. As previously indicated, read mistakes may be caused by absorption, ambient signal reflection, and other signal sources such as security systems, cordless phones, and barcode scanners.

Similar to this, as most antennas used in tags are direction-sensitive, poor orientation of tags may reduce reading efficiency.

Accidental data registration from tags that come into contact with an RFID reader. An error in the reader. Since this possibility cannot be foreseen or entirely prevented, other backup mechanisms such as barcodes are required in the event that a reader malfunctions.

Rapid technological extinction

The quick obsolescence of the technology, particularly in light of the investment cost, is one of the main worries that businesses have when deploying RFID nowadays. New protocol standards, quicker, and fault-tolerant readers rapidly surpass their predecessors as a result of the ongoing advancement of technology.

Privacy and Security Concerns

It could be important to restrict who can access or write data stored on or transferred from tags depending on the application and in certain situations, as required by law. To do this, encryption must be made sure at all interfaces (on the medium itself, as well as in tag-reader and reader-host interactions) where data may be intercepted or conveyed.

Potential viral assaults

Although it hasn't been widely published up to this point, research from the Vrije Universities in Amsterdam has shown a possible weakness in the backend database compatibility of existing RFID software. Similar to previously recognised SQL system attacks (like the Slammer virus), maliciously affected buffer overflow, false end-of-row characters, and hidden comments can cause unverified data to be interpreted as SQL commands that can perform malicious operations on the database contents or cause the system to copy the infected data to additional tags.

RFID Applications

Uses for RFID include the following:

Class or instance identification

When RFID tags are just used to identify a certain item type or instance, a data base is often kept in the background to send or receive the extra information required. With the use of this assistance, it will be possible to detect the item's destination or method of handling, a logistical solution that has already been shown by a number of companies (including UPS, FedEx, USPS, and Finland Post [15]).

Identifying the location

A given individually identified object may be tracked to its present position if a reader is assigned to a known location. Several shipping and postal services, including UPS, FedEx, USPS, and Finland Post; automatic vehicle location systems in public transport control in Vejle, Denmark; and location of rolling stock at the Swiss Federal Railways—have already incorporated such RFID-based features into their tracking services. Similarly, the physical location of work pieces is being tracked in several manufacturing facilities.

Link for Physical Communications

The creation of a physical communications connection between the devices is essential for communication between two radios. The components of the most basic communications connection between a transmitter (Tx) and a receiver are shown. (Rx). Along this connection, radio frequency (RF) power travels from the sender (transmitter) to the receiver. For instance, the power delivered to the Tx antenna passes via the cable from the transmitter to the Tx antenna, the Tx antenna, the medium through which the electromagnetic (EM) signal travels, the Rx antenna, and any cables that may be needed to link the Rx antenna to the receiver. The power is referred to as the receiver power at this point in the communications channel.

The quantitative assessment of the elements that affect RF power gain or loss while creating a communications connection between a transmitter and receiver is known as a link budget analysis. A link budget analysis's goal is to determine the permissible route loss (L_p). The greatest amount of energy that may be lost in the transmission channel before the communications connection becomes unusable is known as the allowed path loss. The maximum

permitted route loss may be used to calculate the maximum separation distance between the transmitter and receiver, often known as the transmission or coverage range, since the path loss rises with distance. It is also possible to compare the effectiveness of various systems and system configurations using the link budget analysis. Calculating the route loss is done as follows:

Route loss in (1) demonstrates that the permitted path loss L_p equals the minimum received power P_{mr} plus the transmitter antenna gain, minus the transmit power P_t plus the receiver antenna gain plus the subscript t G_r - any further losses L_{misc} . The units used throughout are decibels (dB). (1) demonstrates that the Tx power (P_t), Rx signal level threshold, or minimum received power (P_{mr}), Tx antenna gain (G_t), and Rx antenna gain all affect the permissible route loss (L_p) (G_r). Miscellaneous losses are any extra losses, such as cable losses (L_{misc}). The antenna gains are expressed in decibels (dBi), and the Tx and Rx powers are expressed in decibels (dBm) or decibels (dBW), respectively (see Appendix B.1.1). The received power must be greater than the receiver signal level threshold in order to establish the communications connection; if it is not, the signal may be too faint for the receiver to comprehend and the link will not be established.

The equipment being utilised fixes the majority of the variables in (1) that help create and sustain the communications relationship. With the exception of the P_{mr} component, which encompasses both natural and artificial noise and is a site-specific (mine-specific) concern, the values of those terms may be acquired from the manufacturers. The formula produces the permitted path loss or propagation loss (L_p). The standard name for electromagnetic waves (or energy) moving across a medium is propagation. As will be covered in Section, the propagation loss mostly depends on the properties of the transmission medium and the electromagnetic energy's wavelength.

EM waves may go through the ground directly at extremely low frequencies (less than about 10,000 Hz). The electromagnetic waves (EM waves) couple to and are carried by metallic conductors at somewhat higher frequencies (100–1,000 kHz). At much higher frequencies, the waves may travel considerable distances fully through the air (around roughly 100 MHz). The attenuation due to propagation loss varies greatly for each of these material and frequency ranges. Additionally, the performance and size of the antennas drastically alter as the frequency varies. These adjustments are taken into consideration using the link budget analysis (1).

The effective receiver sensitivity (P_{mr}) and the effective transmit power are influenced by a number of variables (P_t). P_t is essentially how loud the signal is as it leaves the transmitter antenna, and P_{mr} is the receiver's capacity to "hear" the signal. The main pieces of information sent across a physical communications connection are either speech or text messages, or data messages from sensors. Unlike spoken communications, which are sound waves (pressure waves in the air) that must be converted to an electrical format through the use of a microphone, text messages can be entered into a computer-like device to generate an electrical version of the message because the data are already in an electrical format. Pressure waves are converted into electrical impulses by vibrations of the speaker diaphragm or piezoelectric crystal within a microphone.

Transferring more data

In the third application group, additional data are read or written in addition to the identification that is taken from the tag. Data read from the tag often comprises measurements or information that would be challenging, prohibitive, or impossible to collect from a distant or pre-recorded

database. Some products may offer instructions for proper handling in this way for example, food packaging tags could tell an oven the ideal cooking time or clothing tags could choose the appropriate washing machine programme; however, in many already existing uses, tags offer medical measurement data, such as information about eye-ball pressure sensor and transmitter integrated into artificial lens implant.

For reusable containers, pallets, etc., as in a pilot project at the Finnish Post, rewriting data to a tag sometimes results in a new identity being assigned to the tag. Writing data to a tag typically adds information about the processing of the given item or delivery progress in transportation. The use of read-write tags in clothing to keep track of how many times a given item has been washed and choose the appropriate washing cycle is envisioned as an intriguing application for washing machines.

Asset Monitoring

It comes as no surprise that one of the most popular applications for RFID is asset tracking. Assets that are often lost or stolen, underused, or just difficult to find when required may all be RFID-tagged by businesses. For asset management, almost every form of RFID technology is employed. At its Long Beach, California, distribution hub, Secaucus, New Jersey-based NYK Logistics wanted to monitor cargoes. It selected a real-time finding technology that can locate containers within 10 feet of them using active RFID beacons.

Manufacturing

For more than ten years, RFID has been employed in industrial facilities. It is used to manage the manufacturing of many iterations of the same product, eliminate faults, boost throughput, and monitor components and work in progress. In closed-loop supply chains or to automate portions of the supply chain under a company's control, RFID technology has been employed for years. Companies are increasingly using RFID Retailers leading the way in RFID adoption include Best Buy, Metro, Target, Tesco, and Wal-Mart. These merchants are now concentrating on enhancing the effectiveness of the supply chain and ensuring that the product is available when consumers wish to purchase it [135]–[143].

Although RFID is used in the supply chain industry, it is also becoming popular as a simple payment method. The ability to pay for tolls without stopping is one of the most widely used applications of RFID today. Quick service restaurants are experimenting with utilising the same active RFID tags to pay for meals through drive-through windows now that these active systems have gained popularity in several nations.

Security and access management

RFID has long been used as an electronic key to manage entry to office buildings and the spaces inside of them. RFID tags with a low frequency were utilised in the initial access control systems. Vendors have unveiled 13.56 MHz systems that provide a greater scan range.

With RFID, there is no need to search for a key or swipe a magnetic stripe card to open a door. Additionally, because there is no physical touch between the card and scanner, there is less wear and tear and therefore less maintenance.

It's expected that businesses and RFID providers will create a variety of new applications as RFID technology develops and becomes more durable, less costly, and capable of solving a wide range of business challenges.

A port's use of RFID technology

The fact that RFID is an "automatic" data collecting technology is its main benefit in a port or terminal application. In other words, no operator involvement or action is necessary. Employees are required to record data using manual or bar code techniques in traditional kinds of data collecting, but RFID frees them from this labor-intensive and error-prone task. Accurate and thorough data gathering and better use of workers' time are the two primary advantages of this.

- In a port cargo terminal, RFID may be utilised successfully in five key areas: access control, container security, container identification and location, activity tracking, and regulatory compliance. Some of these apps provide the terminal/port operator advantages, either directly or via providing extra services to shippers. The other advantages should be seen more as a way to make it easier to comply with the growing security and record-keeping mandates of the government.

Application of RFID Technology in Manufacturing and Distribution

System for picking and sorting Located in a warehouse

There is a requirement for a sophisticated enterprise-wide information management infrastructure in order to maximise the benefits of RFID. The programme might be built around a central database, use a decentralised route, update data directly on the tag, or do some mix of the two. In any case, the IMS must be ready to swiftly process real-time data and transfer it to other systems in the chain that may make use of the data.

Analog signals are continuous current or voltage signals that fluctuate smoothly with time. They are the electrical representation of speech sounds from a microphone. A text or data communication, however, is more likely to be a digital signal. As shown in, a digital signal is one in which the signal intensity maintains a constant amplitude for a certain amount of time before suddenly changing to another constant level. Both analogue and digital operating formats are now available for CT systems. While digital signals have the benefit of being able to be read, stored, and modified by computers, analogue systems often have fewer components and are less costly than digital systems. As long as the digital information is not lost or distorted, digital signals may also be replicated an infinite number of times and transported across great distances without the pattern altering or deteriorating.

The format of the message transmission might be either digital for example, a text message or analogue for example, speech. A streamlined analogue transmission model, 3a the message transmits as an analogue signal. The original transmitted message might be in analogue or digital format and can be speech or data. The carrier frequency, also known as the assigned or advertised operating frequency, is combined with the analogue or digital signal by a device known as a modulator, which also modulates the analogue or digital signal. The analogue message is sent through the medium by the transmitter using the modulated signal. When an analogue signal comes, the process repeats in reverse order, or demodulates, to retrieve the analogue information. A digital transmission system the encoder/decoder (codec), also known as a codec when used with analogue signals, digitises the analogue signal by sampling it at predetermined intervals. There are a few ways to digitise analogue signals; one is briefly covered here. An analogue signal's digitalization is shown in by the vertical dashed lines, which are spaced consistently.

The closest to one of the 2^n possible values, where n is the number of bits represented in the voltage amplitude at each time interval, is selected as the discrete value. The voltage resolution is the voltage interval divided by the number of levels, or $(1 - (-1))/256 = 7.8$ millivolts, for example, if the voltage amplitude is limited to the range of -1 to $+1$ volts and an 8-bit digitizer ($n = 8$) is used. Each voltage level would be represented by an 8-bit number, like 01101001, that included solely 0s and 1s. The analogue signal is now represented as a series of binary values. Figure 2-4c illustrates a possible reconstructed signal using this illustration. Models of simplified analogue and digital communications are shown in Figure 2-4d.

The capacity of a channel is determined by the data rate, or number of bits per second (bits/s), that it can convey. According to Shannon's Channel Capacity Theorem [Stallings 2007], there is a maximum data rate. The quantity $\log_2(1 + \frac{S}{N})$ multiplied by the channel bandwidth B in hertz gives the channel capacity C , which is equal to the channel bandwidth B in hertz times the log base 2 of the quantity. Where S = signal intensity (watts), C = channel capacity (bits/s), B = channel bandwidth (Hz), and N = noise power (watts). According to the theorem, the channel capacity (C) likewise increases when the signal-to-noise ratio (SNR) (S/N) rises. S/N and channel capacity both decrease if the noise power (N) rises while the signal level stays constant (C). If the other factors in the equation stay the same, a bigger channel bandwidth (B) may support a higher data rate (C). All communication systems combine the sent signal with different transmission-related distortions as well as undesired signals (noise) injected at some point between the transmission and reception processes. Thermal noise is one kind of noise. All electrical devices produce thermal noise, which results from the thermal agitation of electrons.

The following equation may be used to compute the thermal noise, which is equally distributed over the channel bandwidth. The Boltzmann's constant k_B (1.38×10^{-23} joules/degree Kelvin) times the system temperature T in degrees Kelvin times the channel bandwidth B in Hz equals the thermal noise N in watts. Where T = system temperature (Kelvin scale), often considered to be 290°K , B = channel bandwidth Hz, and N = noise power (watts). Think of the theoretical noise floor for a perfect receiver as being the thermal noise. Due to extra noise sources within the device, the noise floor of a genuine receiver will always be greater. The amount of noise that the receiver itself adds is quantified by the noise figure (NF). An average receiver may have an NF between 7 and 15 dB.

A receiver, for instance, may have a voice channel with a bandwidth $B = 80$ kHz. Figure 2-4d displays the receiver noise floor as follows under the assumption that the device's $\text{NF} = 7$ dB. This system of equations provides a practical demonstration of how to determine the thermal noise floor of a receiver. It is equal to the temperature T times the channel bandwidth B times the Boltzmann constant 1.38×10^{-23} times 290 degrees Kelvin (the temperature). Then, N is equivalent to 3.2×10^{-13} milliwatts. The next step is to translate this N value from milliwatts to decibels (dB). The receiver's thermal noise floor is equivalent to -125 dBm, and when you add a noise factor of 7 dB, you get -118 dBm. The manufacturer will typically provide the receiver signal-level threshold (P_r), although it is possible to approximate it if the modulation method and acceptable error rates are known. As was already noted, modulation is a technique for transforming analogue or digital data into signals that are sent at the required RF frequency. There are several modulation strategies available, and the system bandwidth, power efficiency, sensitivity, and complexity are all impacted by the method used. Commercial radio often use modulation techniques including amplitude modulation (AM) and frequency modulation (FM).

Frequency shift keying (FSK), phase shift keying (PSK), and orthogonal frequency shift keying (OFSK) are other examples of modulation methods. For the purposes of this tutorial and link budget analysis, it is vital to understand that the modulation method determines the signal level above the noise or the signal-to-noise ratio (SNR) which is sufficient for a receiver to achieve a set degree of dependability in reading bits. The likelihood of misreading a bit is measured by the bit error rate, or BER. Data may be represented in binary digital communications systems by a series of binary digits (bits). Each bit is connected with a different waveform and may take on one of two potential values (0 or 1). As a result of their waveform representation, bits have the following characteristics: The bit duration T_b (sec) is the duration of the waveform associated with each bit. The quantity of bits delivered each second is known as the bit rate (or data rate), R (bits/s or Hz).

The energy included in the bit waveform is known as the bit energy E_b (energy needed per bit of information, in Joules). The bit duration and bit rate are related by: $R = 1$ divided by the bit duration T_b in seconds. The signal power S (watts) and the bit energy are related by: $E_b = S \times T_b$. The bit duration T_b times the signal strength S in watts equals the bit energy. If the thermal noise power is constant over the bandwidth, then $N_0 = N / B$, where N_0 = thermal noise with a bandwidth of 1 Hz and N and B are as previously specified. The SNR is: $SNR = E_b / N_0$. If the value of E_b / N_0 is known, $SNR = R / B$. The amount open bracket bit energy E_b divided by the thermal noise N_0 close bracket times the quantity open bracket data rate R divided by the bandwidth B in hertz close bracket gives the signal-to-noise ratio SNR. $R =$ data rate, $B =$ channel bandwidth, and N_0 (Hz). The 8 implies that the SNR must likewise grow as the data rate (R) increases. The needed SNR drops as the signal's bandwidth increases. BER charts for the PSK and OFSK modulation methods The normal range of acceptable BER values. Applying the aforementioned ,s, for instance, if the acceptable BER is specified as , the necessary data rate is assumed to be $R = 40$ kilobits per second (kbps), and the modulation technique is PSK, then , gives the corresponding E_b / N_0 value of about 10.4 dB or a numeric value of 11, and the following , 9 is derived from .

An example of the signal-to-noise ratio (SNR) $SNR = 11$ dB times open bracket (40 kilobits/s) divided by 80 kilohertz close bracket, which is 7.4 dB. Probability of bit error rate (BER) for two modulation techniques, shown. Probability of bit error rate (BER) for two modulation techniques, shown in. To obtain the necessary BER in this case, the receiver signal must be 7.4 dB above the receiver noise floor, thus The receiver signal level threshold $P_{sub r}$ is consequently equal to -118 dBm + 7.4 dB, or -110.6 dBm. When evaluating this example, take note of the fact that the receiver signal strength began at a level, -125 dBm that was constrained by thermal noise. The receiver's parts made a 7 dB increase in the noise floor to -118 dBm. The receiver threshold level needed to achieve the desired BER was -110.6 dBm, meaning that the signal level had to be dB higher than the noise level. Due to the receiver's high sensitivity, the receiver power is expressed as a huge negative number (-110.6 dBm), which is equal to 8.7×10^{15} mW. However, the words that convert the receiver level to a smaller negative value (in dBm) indicate that a higher minimum receiver power is needed. The route loss in, 1 is affected by this rising power shown below.

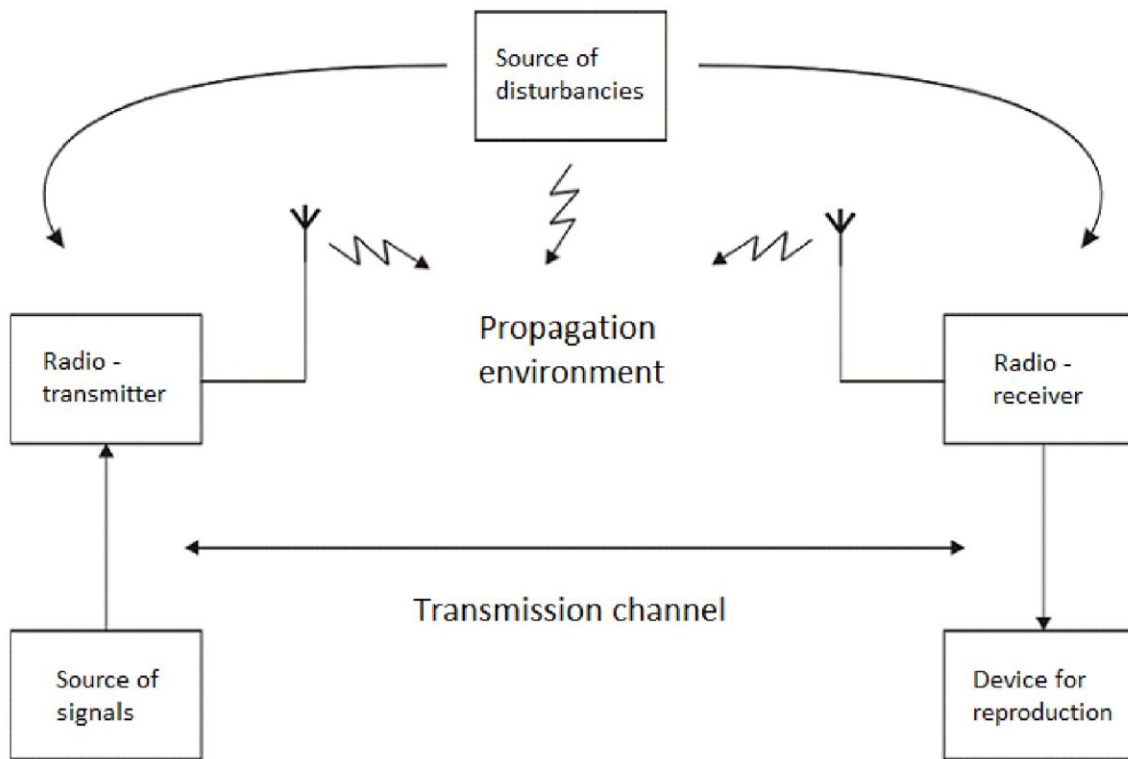


Figure 11.1 Transmission channel.

In addition to the major multinational brewers, Germany is home to several smaller yet successful breweries that have found ways to stay competitive. One of them is Uerige Brewery, which has automated its supply chain and asset management using auto ID. The lowest P_r 's magnitude determines the maximum route loss; as the minimum P_r 's magnitude rises (as in the example above), the maximum path loss also reduces, as does the distance that may be allowed between the Tx and Rx.

Hence, an increasing noise level, or a bigger necessary SNR, will limit the maximum separation distance between a Tx and Rx. Although the discussion in this section has mostly concentrated on the variables that govern a physical connection between two communication devices, a source and a destination are often connected by numerous links. , 2-6 depicts a more intricate, though more typical, communications circuit between the sender (transmitter) and receiver. To establish communications, the Tx and Rx access a network (located within the dashed line in this diagram). Before the message reaches the recipient, it is relayed by many nodes in a sequential communications network. This sets up the section's discussion of networks. Network communications.

A network is made up of many communications components connected together in order to increase the number of users who may access the services being offered as well as the coverage area. Any wireless communications or electronic tracking systems installed in a mine will need a network of some kind, with the possible exception of very small mines, which are less than 600 m (2,000 ft) in length, due to the limited range of a single wireless communications link and the vast geographic extent of modern underground coal mines. The configuration of the network's components is known as topology. The performance of the network and its propensity to

withstand accidents are significantly influenced by the topology decision (i.e., its survivability). , displays a number of fundamental network topologies. The lines between the green circles, which stand in for nodes, are node connections. The connections might be made through wireless networks, fiber-optic cables, or hardwired metallic conductors. Examples of common network topologies are shown in. Examples of common network topologies are shown.

There are benefits and drawbacks to each topology shown. Easier line topology makes it simple to isolate faults. The nodes to the right (within the functioning face) of the failure have their communications cut off, however, if the leftmost node is on the surface and one of the connections or other nodes fails. The network is thus susceptible to a single point of failure. Although each branch has the same potential for a single-point failure mode as the linear structure, the tree topology is superior to the line topology merely because a failure on one branch does not influence the other branches. Each node in the full-mesh topology is linked to every other node. As a result, a miner may connect to one of the nodes through radio, but the signal may travel over many different routes before it reaches the intended recipient. There are several routes that may be taken around a failing node as well.

The full-mesh topology, however, is unlikely to ever be used in a coal mine with room-and-pillar construction. Connecting every node to every other node would be impractical or impossible given the hundreds of feet of mine entrances that need to be covered. A partial mesh is significantly more useful in the mining setting and delivers many of the benefits of a complete mesh. Electromagnetic spectrum management The MINER Act of 2006 mandates that mine operators add wireless, or partly wireless, communications and tracking equipment into a mine environment that previously had a very small number of purposeful RF emitters. There is thus a chance for electromagnetic interference (EMI).

When unwanted electromagnetic (EM) radiation from another RF system obstructs the receipt or processing of a desirable signal, EMI takes place in the system. In contrast, electromagnetic compatibility (EMC) is a desirable state in which electronic systems are capable of carrying out their intended duties without unacceptably impairing the performance of other systems or themselves by being exposed to RF radiation. Any possible EMI between systems is removed or lowered to a tolerable level before EMC is developed. EMC has two aspects: (a) a system shouldn't emit electromagnetic disturbances that might damage or destroy another system; and (b) a system should be able to operate in its electromagnetic environment without malfunctioning (usually referred to as the immunity or susceptibility aspect).The devices that are generating RF energy must be located, together with the frequencies at which they operate, in order to eliminate EMI. The phrase "spectrum management" refers to the control of radio frequency use. Potential radio frequency emitters in a coal mine are listed in Potential RF emitters in a coal mine, Application of Frequency Comments 300-10,000 Hz

Personal safety equipment Trans-plane communications 70-500 kHz equipment for detecting distance both audible and visible alert 300-800 kHz radios with a medium frequency Talk and text 150-175 MHz leaky feeding systems for VHF Low bandwidth data and voice 400-410 MHz asset tracking program or miners Identification via radio frequency (RFID) 450-470 MHz UHF feeding systems with leaks Low bandwidth data and voice 490 MHz Continuous miner that is remote-operated Continuous miner remote control 900 MHz Active radio frequency identification (RFID) tags RFID to monitor miner's whereabouts 900 MHz radios with line-of-sight Text and voice 900 MHz Robotic rescue robot command 2.4 GHz Robotic Rescue Line-

of sight 2.4 GHz video radios Talk and text Noise, which consists of erroneous electrical voltages, is another cause of interference. As was previously mentioned, EM noise may come from the outside or inside a radio receiver. Both natural and man-made noises are considered external noise. Electrical equipment (such as motors), electronic equipment (remote-control devices), transformers, power lines, and electrical/mechanical switching devices may all produce man-made EM noise in a coal mine.

Additionally, electrically driven mining equipment makes loud, low-frequency noise when it first starts up or when the power demand changes from high to low (or vice versa). An example of a naturally occurring noise is lightning. Because of the low transmission loss and low frequency, every location in the planet might potentially contribute noise to this EM noise. Lightning and other EM noise created outside the mine may travel via wires that go into it.

Analysis and Modeling the link budget analysis, which was previously described, is an effective method for determining the largest coverage area that a CT system can provide. In order to provide dependable and high-quality communications, it may also be used to estimate the distance between any pair of antennas. Hand-held radios used above ground may connect people who are many kilometres apart.

In contrast, in a deep mine, the same radios may only go a few hundred feet. The effect of the underground environment on the propagation of EM waves is what caused this abrupt shift in performance. The Tx antenna emits electromagnetic waves, which move through the medium around them and lose energy as they do so. There is a propagation loss as a consequence of this process, which is known as EM wave propagation (path loss). Take the EM propagation of ultrahigh frequency (UHF) waves in a mine entrance as an example. By simulating the tunnel as a waveguide, the route loss may be explained.

Only specific defined modes of propagation are permitted when EM waves are propagating, and even then only if the wavelength is less than twice the tunnel dimensions. The wave's permitted angles of reflection throughout its tunnel travel are determined by the modes. After adding an insertion loss (Linsertion) to account for the weak coupling of the Tx and Rx antennas to the fundamental waveguide mode, the fundamental (lowest order) mode seems to accurately reflect the route loss some distance (usually a few hundred feet) from the transmitter.

After the first few hundred feet from the Tx antenna, the RF fundamental mode signal attenuation varies linearly with the distance z down the entrance. As a result, the path loss rises with increasing distance from the transmitter. Other factors that affect the route loss are also mentioned in the model One result of this is that some RF energy may be diffusely dispersed by the contact of the EM wave with the walls, which is made possible by the roughness of the walls. Since it is expected that wall scattering occurs continuously as the EM wave travels down the tunnel, its variation with z is similarly linear.

The potential for the wall spacing (or floor and ceiling spacing) to gradually change in size, as indicated by an angle, has another influence (tilt angle). Another linear function of z is the attenuation caused by tilt (Ctilt).

For UHF signals travelling down turns like crosscuts, additional losses may be considered, but they won't be covered in further detail here provides the LOS route loss for UHF propagation down an entry for the previously mentioned effects shown below.

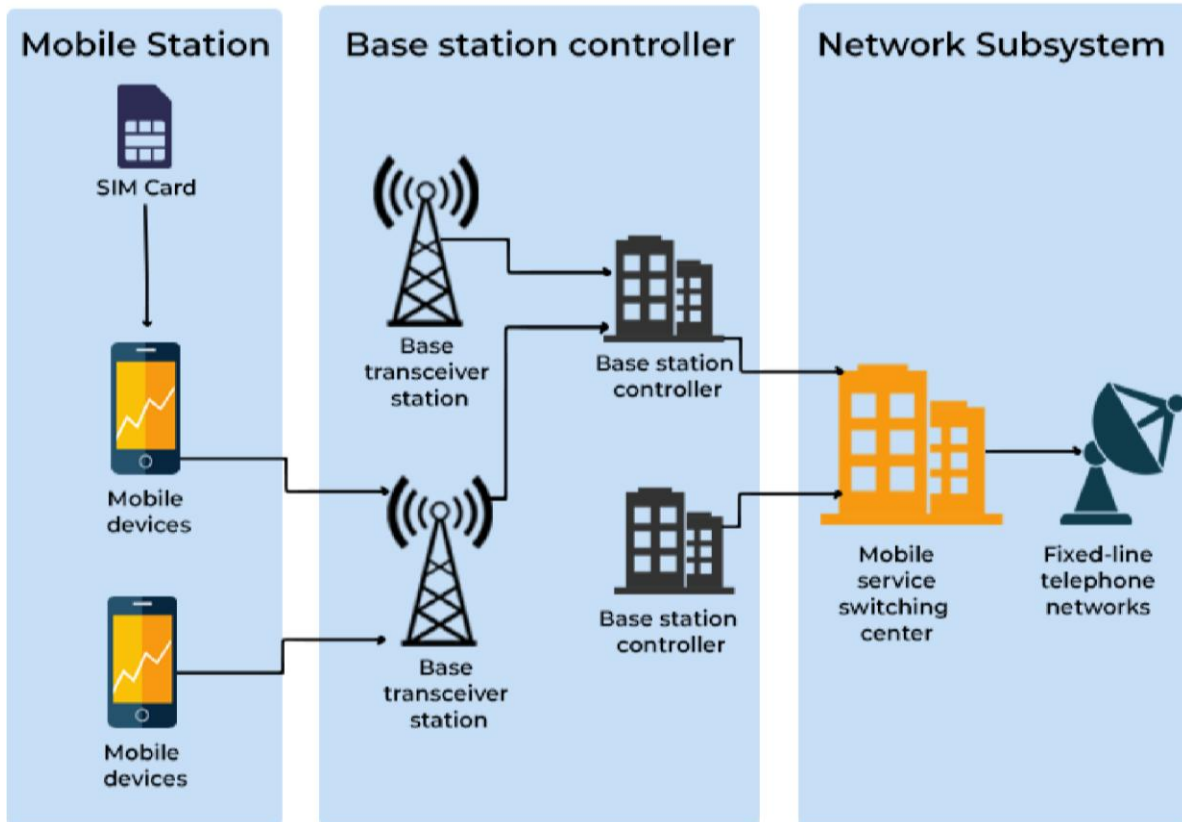


Figure 11.2 shows the LOS route.

The loss due to the line-of-sight route 11 Representative values of the terms on the right side of the , are assuming a 14-ft-wide by 7-ft-high entry, frequency of 900 MHz, wall roughness of 4 in, and tilt angle of 1 degree) $L_{sub p}$ in dB equals 2 times $L_{sub insertion}$ loss plus the quantity open bracket $C_{sub mode}$ plus $C_{sub wall}$ plus $C_{sub tilt}$ close bracket times open bracket distance z divided by 100 close bracket. $L_{insertion}$ is equal to 22 dB, C_{mode} is 1.4 dB/100 ft, shows that, as one would anticipate, the route loss grows as z increases. The challenge in applying general CT performance statements to all mines is made clear by L_p 's dependency on mine-specific characteristics.

As was mentioned above, the surrounding medium (wall, roof, or floor roughness), any obstructions in the passage (such as mining equipment), frequency of the propagating wave, and size of the mine entrance may all affect the propagation loss. It could be necessary to create a model of the behaviour that incorporates a thorough computer analysis in order to determine the route loss.

The most probable possibility is the creation of "rules of thumb" for operation in a certain mine based on device testing in several mine locations. The CT system would then be designed using these "rules of thumb" as a guide, along with extension planning and system testing following installation.

An EMI analysis, in addition to link budget analysis, may be used to estimate the amount of unwanted power that a receiving system possibly a victim of EMI receives as a result of radiation from a transmitting system a possible source of EMI. An EMI analysis may also be needed to

establish the appropriate distance between antennas or to change the frequency that the source and victim utilise in order to prevent interference (receiver). Testing and Maintenance for optimal functioning, communications and tracking systems for coal mines need to be periodically maintained.

Despite the ruggedness of these devices, the mining environment is quite hostile. Periodic maintenance inspections should be specified by RF system makers. For instance, the majority of systems will include battery backups in case the power goes out during an emergency. To make sure these batteries are functional, frequent inspections are required. Even rechargeable batteries used in handheld gadgets have a limited lifespan and must be replaced from time to time. The routine in the mine must include frequent testing of CT systems to ensure that the coverage is completely operational. Quantitative or qualitative testing is possible.

To quantify radio signal intensity as a function of location across a region, specialist equipment is needed. Spot inspections of communications lines employing a series of "Can you hear me now?" exchanges between subterranean and surface users will probably be used in qualitative testing. Performance Metrics and Objectives it is debatable what the performance measures and objectives should be for CT systems in underground coal mines. Different people have different ideas on what certain measurements should be in regard to the reachable performance objectives. The range of viewpoints and challenges involved in defining these measures and objectives are discussed in this section.

The most costly asset in a brewery's operation are barrels. The barrels in this application each have an integrated Read/Write tag that uniquely identifies them, and whose memory is partitioned so that each page may be encoded with fresh data as it travels from the manufacturer to the consumer and back to the factory shown below.

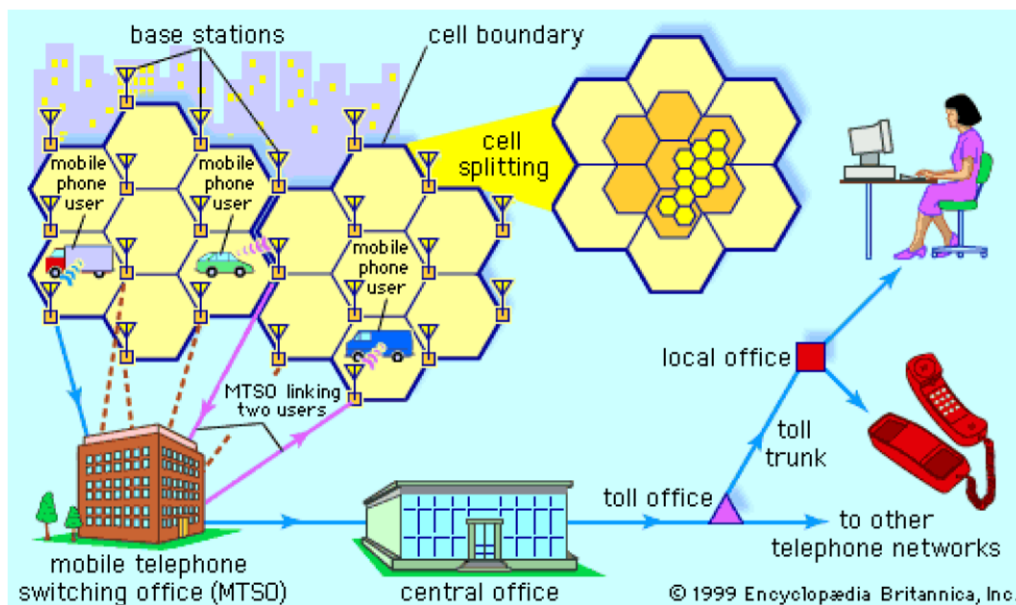


Figure 11.3 shows the manufacturer to the consumer.

Several organisations handle barrels, including factories, wholesalers, and bars. The advantages include managing barrel loss, identifying barrel damage, compiling thorough, automated records of client service, and creating invoices. The article provided a summary of the present and future

directions of RFID technology. Although a number of restrictions and unsolved problems continue to prevent RFID from being widely used. Despite these obstacles, RFID is making progress in inventory management systems, and it won't be long until component prices are low enough to make RFID a compelling business model. Additionally, significant engineering work is being done to develop precise and dependable tag reading systems and to get beyond existing technological constraints.

Additionally, the bigger distributors may start to put economic pressure on manufacturers to alter product packaging and related materials to better incorporate RFID. And last, at this critical juncture, when significant firms are testing the technology, public opinion and vocal privacy organizations may have an impact on the guidelines we adopt.

Tradition has claimed that the "natural" environment chooses according to evolution theory. According to this viewpoint, the environment is an external given for the developing system, which by itself is only capable of displaying variety. The environment must now be thought of as a different communication system that displays variety rather than being thought of as a given if selection, on the other hand, feeds information back into the evolutionary system. Therefore, the relationship between systems and their environments is one between communication systems. Through communication, the communication systems exchange information.

Generally speaking, information can only be shared across communication networks. Conversation or "mutual information" is how communication systems communicate. Systems may start to co-evolve, or mutually shape one another, if a pattern of co-variation among them is sustained over time. As a result, co-evolution rather than evolution is the fundamental idea for comprehending dynamic processes. We can comprehend how new information might enter a system from its surroundings, among other things, using the notion of co-evolution.

According to conventional evolution theory, "natural" selection should promote the survival of certain forms. The stabilisation of certain co-evolutions in the context of co-evolution theory adds a third mechanism to the first two, variation and selection. At least two cybernetics may be defined among these three mechanisms variation, selection, and stability. While selection might take place at specific points in time, stabilisation assumes that variation and selection have been evaluated throughout the time dimension. Therefore, stabilisation is a higher-dimensional issue. I'll demonstrate how the potential for stability and self-organization may be seen as a result of the selected operation's recursively.

Selection and Variation

Focusing on the connection between "variation" and "selection" initially by running, the systems change how they interact with other systems in their contexts and so share information. If it is physically possible, each system may process this data internally for a self-referential update (see below). The information enters a transmitting system externally, i.e., by crossing the system/environment border, but this system sends the information as a message. The information that was initially delivered is bundled into this message, which has a nature peculiar to the sending system. Messages are sent by a transmitting system as its information, however this information is distinct from the information that was first transmitted. One such example is how the telephone converts spoken words on the phone line into an electrical message shown below.

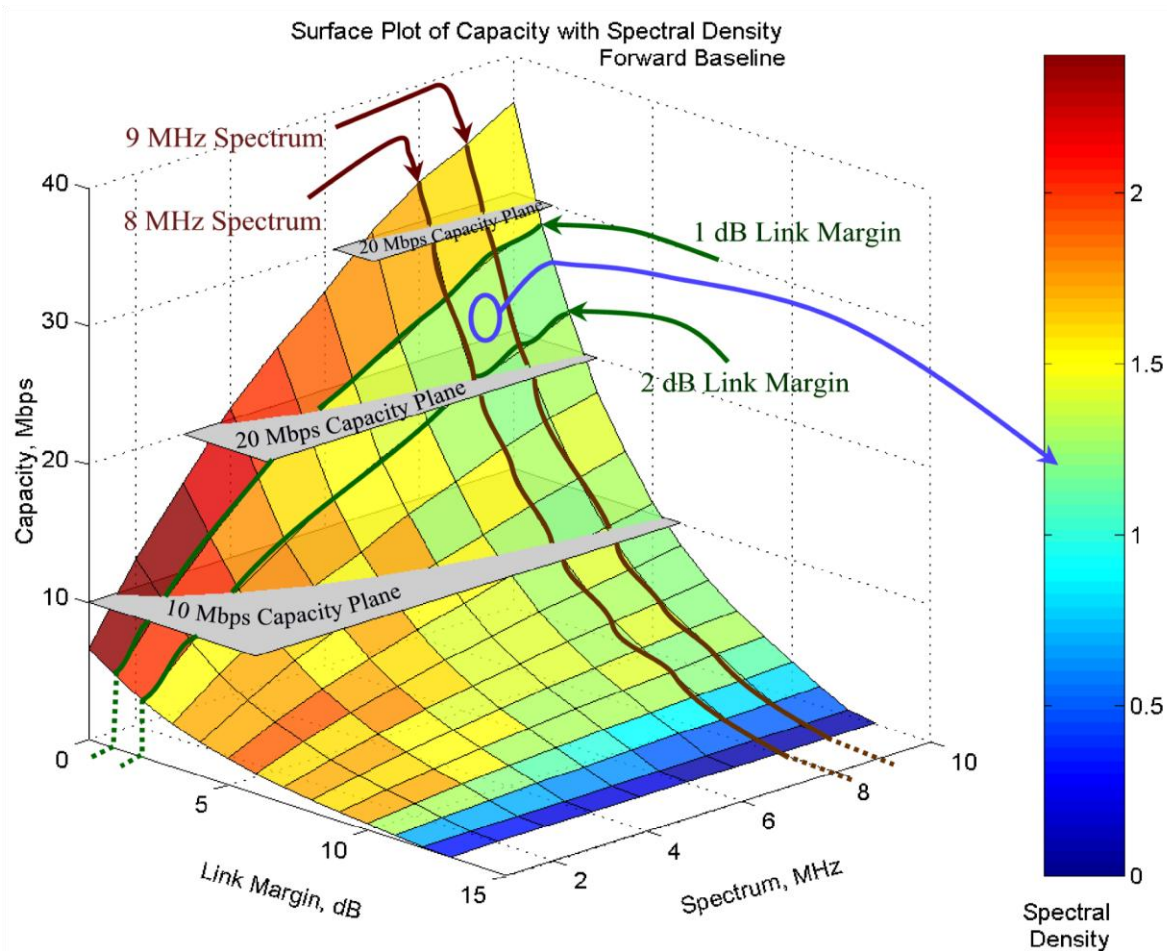


Figure 11.4 Electrical message.

As a result, the communication systems may be distinguished by what they convey and are fundamentally distinct from one another. The interactions between the different components only occur via co-variations, which operate as communication windows. Two distinct variations in apparently orthogonal dimensions make up the co-variation. Since the communication systems are fundamentally distinct from one another, the dimensions stand analytically in orthogonal connections to one another. This does not rule out the possibility of them both being a member of a super system, but as I will demonstrate later, this requires a third dimension.

In other words, because communication implies co-variation, each communication causes a communication in the communication system(s) to which the transmitting system is related. Each communication system has the option to co-variate with a number of other communication systems, and each co-variation increases the degree of communication flexibility within each system. Nevertheless, a co-variation is a component of the overall variation of the co-varying systems. The systems exchange mutually beneficial information via co-variation. Therefore, metrics of communication might be the mutual information or the co-variance. The complement of a residual variance to a total variance is always a covariance. The remaining variance is composed of a number of co-variances, each of which represents a co-variation at a different time. In other words, the anticipation of communication in a variety of dimensions is all that the information content of communication networks really is shown below.

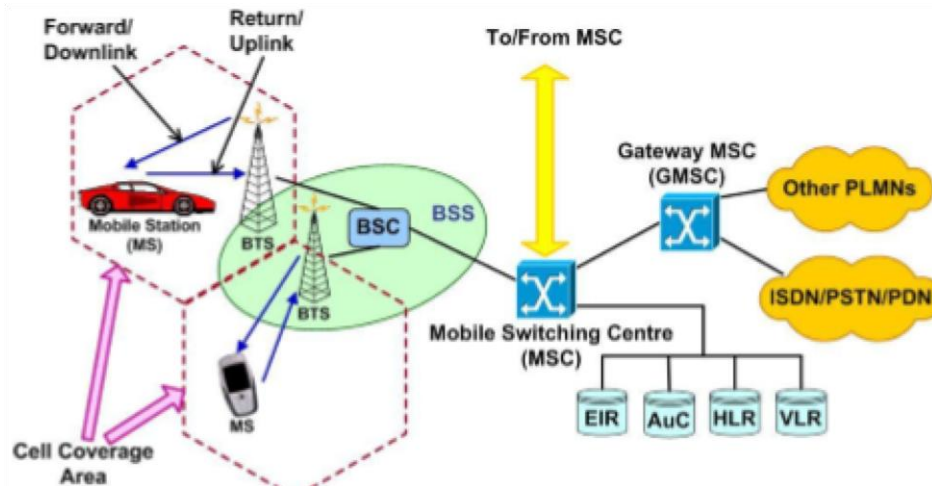


Figure 11.5 shows the communication networks.

The residual variance is stable in regard to the co-variance in a particular instance as compared to a prior stage. As previously said, stability must be evaluated across time as a different dimension. You may think of the remaining variance in the time dimension as the auto-covariance at each a posteriori point. Auto-covariance implies the existence of a system since it is self-referential. Communication systems are anticipated to work in several dimensions with distinct frequencies since it is yet unknown empirically if communications in different dimensions co-occur. As a result, they might display shift in terms of stability.

Since they are only capable of functioning via co-variations, communication systems replicate themselves in terms of sums of co-variations. Variation must be operationalized as co-variance and structure as the residual variance at each point in time or auto-covariance. The predicted information content of the system is conceptually similar to the covariance plus the system's residual variance. The difference between this information content and its maximum information content, which is equal to redundancy by definition, is the information content. Because it includes the residual variance as a second dimension of the probabilistic entropy, structure should not be confused with redundancy. With regard to the incoming signal, structure may be added to the redundancy, but because the signal includes information, structure can also interact with it i.e., communicate with it. The relative weight of a communication system lowers when more structure is added given the redundancy shown below.

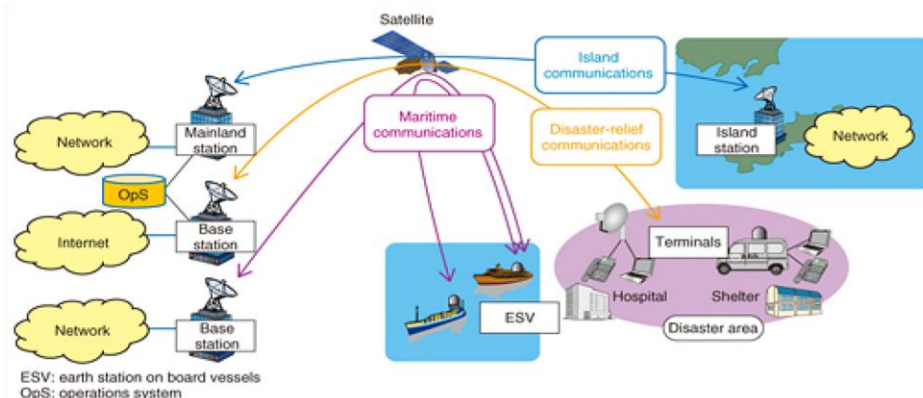


Figure 11.6 shows the relative weight of a communication system.

Selection lowers uncertainty by adjusting the observed data in relation to the observing system. The negative sign introduced by the a posteriori, or observing, system's selective function is an important consideration. If the predicted information content of the transmitted signal was initially equal to a , this value is lowered to $f(x) = a - bx$ upon selection by a structure x . (Parameter b stands for a relative weight. In a two-dimensional extension, the predicted information values for the incoming signals are lined up. Alternatively said, selection denotes the positioning of relational information employing structure as a second dimension of the information. Although the incoming data may be created stochastically, the system's structure determines where it will be placed.

In conclusion, communication systems serve as filtration mechanisms for the systems they interact with. Structure acts as a selection, packaging the incoming data in light of its own substantial uncertainty. By situating it, it gives the choosing system a (but irreflexive) value for the incoming information. Keep in mind that the first decision is made by the transmitting system, not the receiving system. When a system receives, it can only choose from the signals that the transmitting system ($a-bx$) sends to it, not from those that the sender system sent. Each exchange of information across communication systems implies a different choice, which results in the addition of a higher-order feedback term to the initial signal. Selection involves normalization by the selective device, which is why it is asymmetrical. Selection is thus, in theory, irreversible.

Self- organization and Stabilization

Second-order feedback, which must be built upon the cybernetics between (co-)variation and first-order selection, is required for the study of the dynamics between selection and stabilization. Second-order selection is identical to stabilization. Actor relationships may be seen as vectors, and the network can be visualised as the total of these vectors, or as a two-dimensional matrix. A communication system is created in each cycle by the players' possibly co-varying relationships with one another. The time dimension adds a third axis to the two-dimensional representation: matrices at various periods in time add up to a cube. Analyzing the eigen-structure in the matrices at each instant in time is equivalent to analysing structure in the time dimension by rotating this cube ninety degrees. Let's call this reconstruction the system's eigen-time. Eigen-time is an analytical expectation with regard to the clock of the system, just as eigen-structure is an analytical expectation with respect to structure. It is well known that the eigen-vectors of the system under investigation may be used to deconstruct eigen-structure. In a similar manner, eigen-time may be broken down into eigenfrequencies. Each clock's many frequencies may be seen as a spectrum. Keep in mind that several clocks are required to run the systems shown below.

In other words, if a communication system has information in the time dimension and organises co-occurrences of co-variations in terms of its history, it has two selection structures. The information in the relations is positioned on a second dimension by the first structure, and the outcome of this operation may be seen on a third dimension. Although the two selection structures are orthogonally opposed, their formal equality suggests that they are fundamentally unlike.

Because the higher-order cybernetics depend on the lower-order cybernetics as their foundation, there cannot be a reflection in a third dimension of the probabilistic entropy if there is no signal in the substance. Formally, reflection is a third-dimensional recursion of selection. A significant

theoretical consequence of this formal result is that reflexive systems cannot be entirely transparent to themselves because they cannot concentrate on first-order and second-order cybernetics at the same time and at the same location in memory. Thus, separation between what is reflected and the reflecting instance must occur internally in reflexivity.

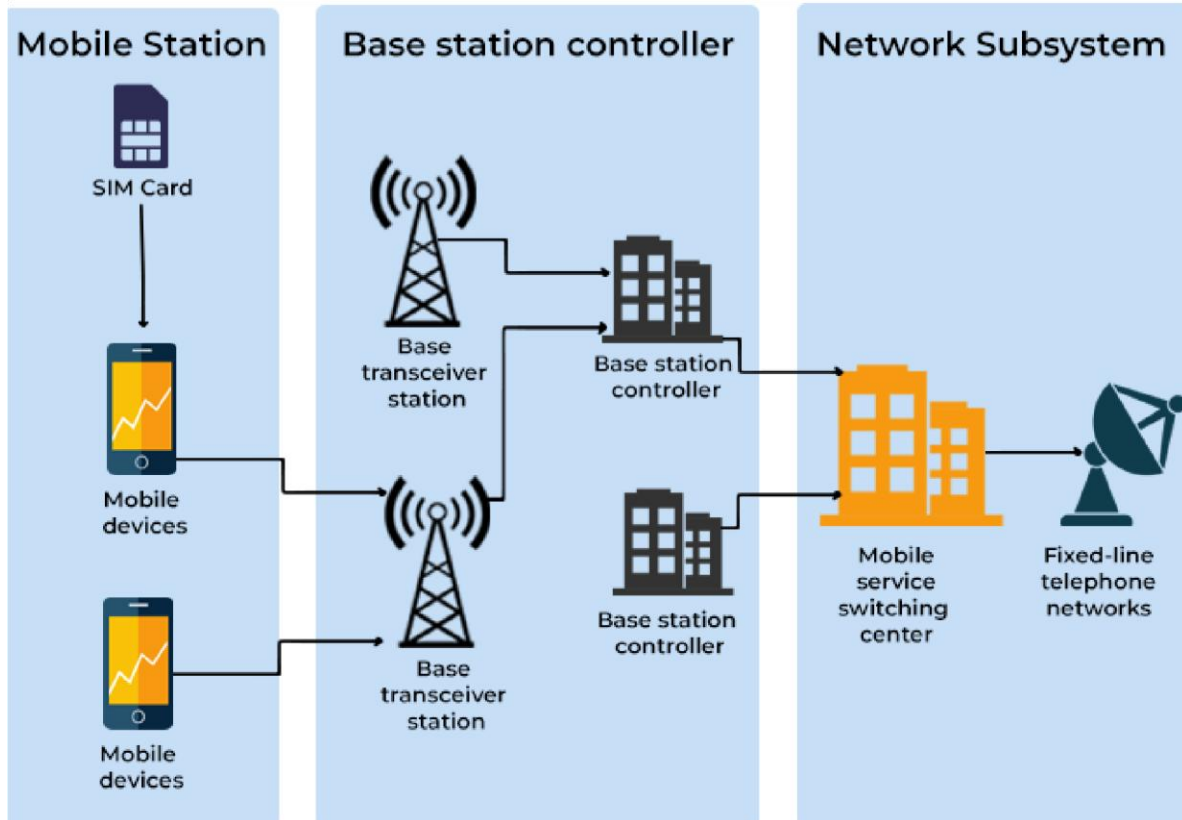


Figure 11.7 shows the Base station controller.

The Eigen-vectors of the matrices may also be integrated with the eigen-frequencies of the communication system in a third-order cybernetics, but this needs an extra degree of freedom. The system will have alternatives to arrange itself progressively in terms of operation, i.e., to retain (changing) structure over time, if it can employ this level of flexibility for the selection of certain relations between eigen-vectors and eigen-frequencies. After then, the system is anticipated to rearrange what it would see as pertinent messages and coincidental events in order to identify its identity in the present (i.e., as a receiver). Self-organization hence needs a component beyond contemplation.

One may conceive of a self-organizing system in terms of different cylinders in the cube, which the system has accessible as internal representations of its identity, using the spatial metaphor of a cube mentioned above. Different expectations about the makeup of the following round are generated by each cylinder. In relation to its three-dimensional representations, the selforganizing system's behaviour is unknown in a fourth dimension. Both the communications and the co-occurrences must be chosen by the system and reinterpreted self-referentially as knowledge about the system in order for the self-organizing system to sustain identity. This "and" denotes a fourth dimension and third operation. The system must regularly restructure its uncertainty because the system's future activity may alter the relative weight of the different

representations. The hyper-cycle that a four-dimensional system by definition experiences can only be seen in terms of a three-dimensional representation. A self-organizing system will disintegrate into three-dimensional representations if it is unable to function in four dimensions. It subsequently either returns to its original state or disappears.

Given the significant potential advantages of RFID, there will undoubtedly be a wide range of innovative uses for it in the future, some of which we can't even begin to fathom. Simple radio communications make up the RFID readers and tags, but their lower size and widespread use increase the technology's potency and raise questions about how the implementation of RFID may affect privacy. These worries are often based on improbable predictions about the future of technology and how it will be used.

CHAPTER 12

Future of Communication System

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It's important to consider how conducting this project should respond to the resulting increasing competition in the context of the constantly expanding use of cloud based systems engineering, IoT-enabled devices, and information exchange machinery when examining the evolving of customary mobile communication configurations towards to the growing demands of the next generation technologies.

Over the last several years, wireless communication technologies have made significant revolutionary advances. The recent 5G and beyond developments, which include paradigmdefining methods like network soft variation and software as a service, massive MIMO, ultradensification, and the introduction of new frequency bands, have greatly benefited a variety of stakeholders, including commercial solution providers, academic research groups, standards bodies, and end-users. Numerous mushrooming industries and applications, including as ecommerce, contactless payments, machine-to-machine communications, improved mobile broadband, and virtual and augmented reality (VAR), among others, have shown the enormous promise of 5G and beyond. These will enable pervasive wireless connection for everyone and meet the needs of a fully connected world. However, the primary difficulties faced by designers of wireless apps and devices include preserving high-speed connection, range, product design, efficiency, and dependability from cell phones to Wi-Fi and the Internet of Things.

When the American Telephone & Telegraph Company introduced mobile telephone service (MTS) in the United States in 1946, mobile transmitters and receivers were first connected to the public switched telephone network (PSTN) (AT&T). A user who wanted to make a call from a mobile phone had to actively look for an open channel in the U.S. MTS system before doing so. After speaking with a mobile operator, who made the PSTN connection, the user was connected. The radio connection was simplex, which meant that only one side could speak at once. The mobile handset's push-to-talk switch managed the call's direction.

AT&T debuted the enhanced mobile telephone service in 1964. (IMTS). This enabled automated dialling, full duplex operation, and channel finding. There were 11 channels accessible at first, but in 1969, 12 more channels were added. The IMTS system faced a high demand for a relatively scarce channel resource since there were only 11 (or 12) channels accessible for all system users within a certain geographic region (such as the metropolitan area of a big city). Each base-station antenna furthermore needed to be mounted on a tall building and broadcast with great power in order to reach the full service region. All subscriber units in the IMTS system were motor vehicle-based devices with large storage batteries due to the system's high power needs.

The Motorola DynaTAC 8000X was the first commercially available portable handheld mobile phone, debuting in 1983. The advanced mobile phone system, sometimes known as AMPS, was

created about this period, principally by AT&T and Motorola, Inc. 666 paired speech channels, spaced every 30 kilohertz in the 800-megahertz range, were the foundation of AMPS. The system used a frequency modulation, or FM, analogue modulation technique and was created from the ground up to accommodate subscriber units for usage by both drivers and pedestrians of vehicles. It was a hit right away after its 1983 public debut in Chicago. At the conclusion of the first year of operation, there were a total of 200,000 AMPS customers across the United States; five years later there were more than 2,000,000.

The American cellular industry has out a number of ideas for expanding capacity without the need for new spectrum licences in response to anticipated service problems. NAMPS, or narrowband AMPS, was a 1991 Motorola proposal for an analogue FM method. Each 30kilohertz speech channel that was previously in use was divided into three 10-kilohertz channels in NAMPS systems.

Thus, the NAMPS system featured 2,496 channels as opposed to the 832 channels included in AMPS systems. A second technique was created by a committee of the Telecommunications Industry Association (TIA) in 1988 and used time-division multiple access (TDMA) together with digital voice compression and modulation to replace one AMPS channel with three additional voice channels. A third strategy, first created by Qualcomm, Inc. but later approved as a standard by the TIA, arose in 1994.

This third strategy made use of code-division multiple access (CDMA), a kind of spread spectrum multiple access that, like the first TIA strategy, combines digital voice compression and digital modulation. (See telecommunications for further details on signal modulation, multiple access, and information compression methods.) The CDMA system provided 10 to 20 times the capacity of AMPS cellular technologies that were already in use. Eventually, all of these higher-capacity cellular systems were implemented in the United States, but because to their compatibility issues, they supplemented rather than completely replaced the earlier AMPS standard.

With an emphasis on unique and cutting-edge technologies as well as experimental and theoretical findings in applied sciences, this Special Issue intends to publish research showcasing cutting-edge advancements in the area of wireless communications. Contributions to cuttingedge techniques and innovations, including those using wireless communication systems, are highly welcomed. The emphasis of this Special Issue is on current developments in wireless communication systems. Original research as well as review papers are also invited.

Every aspect of our lives, companies, and industries are being impacted by communication technology. In the context of a firm, technology increases efficiency, productivity, and profitability. The deployment of the 5G wireless communication and the possibilities provided by the Internet of Things (IoT) will serve to further amplify this.

The speed of human-to-human and machine-to-machine communication will increase because to 5G's improved connection. This is partly because 5G will enable virtually real-time telepresence across various places because to its quick speeds, increased bandwidth, and reduced latency. Globally, the growth of smart cities is beginning to show how 5G and IoT offer up a world of possibility. More IoT devices, such as smartphones, laptops, self-driving vehicles, robots, machines, etc., can connect to the network thanks to this improved connection, spurring innovation in this field.

GSM is a widely used standard for digital cellular communication. The GSM standard was developed by the European Telecommunications Standards Institute to specify the processes for second-generation digital mobile networks, which are used by devices such as mobile phones. It is a wide-area communications technology initiative that develops audio, information, and multimedia communication systems using digital radio channelling.

GSM is a mobile network, not a network for computers.

This means that devices interact with it by seeking for neighbouring cells since it opens a new window. The development of mobile wireless communications services has been impacted by GSM as well as other technical developments. Between mobile stations, base stations, and switching systems, a GSM system controls communication.

Each GSM radio channel has a width of 200 kHz and is further split into frames of 8 time slots. The abbreviation "GSM" refers to Groupe Special Mobile, the original name of the worldwide system for mobile communication. The GSM network consists of base stations, mobile stations, and interconnected switching networks.

Every radio channel may be shared by 8 to 16 audio users thanks to the GSM software, and each radio transmission site may have several radio channels. GSM is now the most often utilised network technology in the Internet of Things due to its simplicity, accessibility, and low cost (IoT) opens new windows for program.

However, in the next years, this is probably going to alter. Various program have been created during the evolution of mobile communications services without the benefit of standardised standards. This had a big impact on many consistency-related concerns as digital radio technology developed. These problems are intended to be addressed by the international mobile communication system. Seventy percent or more of digital cellular services worldwide are GSM-based. Prior to transmission across a channel with three independent streams of user information within each time slot, GSM automates and encodes the data. It is also the most widely used 2G digital mobile phone standard throughout the globe. It controls how mobile phones communicate with the network of terrestrial towers.

While GSM works in the 900MHz and 1.8GHz bands in Europe, the 1.9GHz PCS frequency is where it does so in the US. Given that it is based on a circuit-switched architecture that divides each 200 kHz channel into eight 25 kHz time frames, GSM refers to the whole mobile network, not just the Time division multiple access air interface. By the early 2000s, there were more than 250 million GSM subscribers, making it a transmission method that is fast increasing. By the middle of 2004, the one billionth GSM user was connected.

Learn more about distributed computing here. Types of Architecture, Important Elements, and Examples a new window is opened. It was originally intended for the Global System of the mobile communication line to use the 900 MHz bandwidth, however this is no longer required. Since then, GSM systems have developed and can now function in a number of frequency bands. The two pathways of the GSM frequency bandwidths are typically 900/1800 MHz and 850/1900 MHz. The 900 MHz / 1800 MHz spectrum is used throughout the majority of Europe, Asia, Africa, the Middle East, and Australia. The 850 MHz / 1900 MHz spectrum is used by North and South America, as well as the United States, Canada, Mexico, and other nations. While the 1800 MHz band extends 1710 to 1880 MHz in the Global system for mobile communication, the 900 MHz bandwidth ranges from 880 to 960 MHz.

Contrarily, the 850 MHz frequency band ranges from 824 to 894 MHz, whereas the 1900 MHz band is from 1850 to 1990 MHz. Cellular customers are identified and provided with the necessary support by GSM-based cellular networks using a set of numbers or distinctive codes. Every SIM card has a different serial number, known as the IMSI (International Mobile Subscriber Identity). The phone network may generate a temporary code called Temporary Mobile Subscriber Identity for each IMSI in order to hide the permanent identity. The whole phone number, including all prefixes, for a specific SIM is known as the Mobile Station International Subscriber Directory Number. The last word is MSRN, which stands for Mobile Subscriber Roaming Number. If a cellular station is not connected to the local network, it is issued this short-term phone number (roaming). As a result, it may be connected to any calls or communication networks.

With the use of roaming agreements with foreign businesses, several GSM network providers enable their customers to use their phones when on the go abroad. To reduce roaming fees while keeping service, SIM cards with residential network access designs may be switched to ones with a metered local connection. The size of the hexagonal cells formed by the global mobile communication system depends on the number of end users and the strength of the transmitter. A base station with a transceiver (which combines the transmitter and receiver) and an antenna is located in the centre of the cell. The two fundamental methods used by GSM are frequency division multiple access (FDMA) and time division multiple access (TDMA):

With FDMA, frequency bands are split up into several bands, each of which is allotted to a different user. FDMA divides the 25MHz bandwidth of GSM into 124 carrier frequencies by a distance of 200 kHz. One or more carrier frequencies are allocated to each base station. By dividing the bandwidths into different time slots, Time Division Multiple Access (TDMA) assigns the same frequency to multiple users at once. Each subscriber receives a timeslot, which enables many stations to divide the same broadcast region. Each subdivision carrier frequency is split into several GSM time slots using TDMA. There are 8 time slots in each Time-division Multiple Access frame, and it takes 4.164 milliseconds (ms). Accordingly, each time slot or physical channel in this arrangement should last 577 microseconds, during which time data is conveyed in bursts. There are several cell sizes in a GSM network, including macro, micro, pico, and umbrella cells. Depending on the execution domain, each cell is unique.

The five cell sizes in a GSM network are macro, micro, pico, and umbrella. The connection of each cell varies depending on the choice offered. Every client is given a different time slot on a comparable frequency in the time division multiple access (TDMA) approach. This can accommodate bandwidths ranging from 64kbps to 120Mbps and is readily adaptable to transmitting and receiving voice and data transmission.

The GSM Architecture

Three main systems make up the GSM architecture. The main elements of the GSM architecture are as follows:

1. The system for network switching (NSS)
2. The portable facility (MS)
3. The system of base stations (BSS)
4. The system for operations and support (OSS)
5. The system for network switching (NSS)

The NSS is a GSM component that manages call processing and flow for mobile devices when they switch between base stations. The functional components of the switching system are given below.

Mobile Services Switching Center (MSC): The core network space of the GSM network architecture is comprised of the Mobile Switching Center. Call switching between mobile devices and other fixed or mobile network users is supported by the MSC. Additionally, it keeps an eye on cellular services including signups, location updates, and call forwarding to a roaming user shown below.

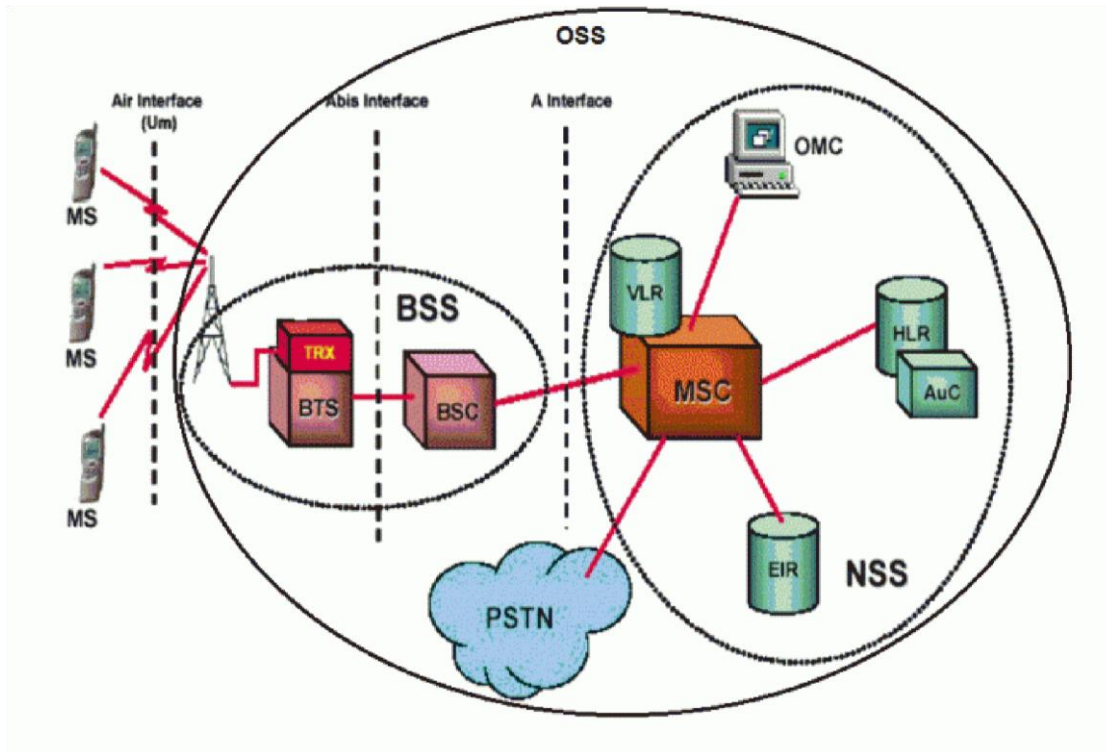


Figure 12.1 shows the call forwarding to a roaming user.

HLR: Home Location Register It is a collection of informational pieces used to store and control subscriptions. Each consumer's information is provided, along with their most recent location. Given that it keeps long-lasting records on users, the HLR is regarded as the most important database. One of the operators will enroll them in their HLR when they buy a membership from them.

Visitor Location Register (VLR): is a database that contains subscriber data required by the MSC for passenger service. A condensed version of the majority of the information kept in the HLR is included in this. The visitor location register is often built as a part of the MSC, however it may be performed independently as well.

Equipment Identity Register (EIR): This system component establishes whether a certain piece of mobile equipment may be used. Every working mobile device on the system is listed here, and each one is identified by its unique International Mobile Equipment Identity (IMEI) number. **Authentication Center (AuC):** The AUC is a unit that provides authentication and encryption elements to guarantee the user's identity and the confidentiality of each call. The

user's private key is stored in the SIM card's verification centre, a protected file. The AUC protects network operators against the different fraud kinds that are pervasive in today's cellular environment shown below.

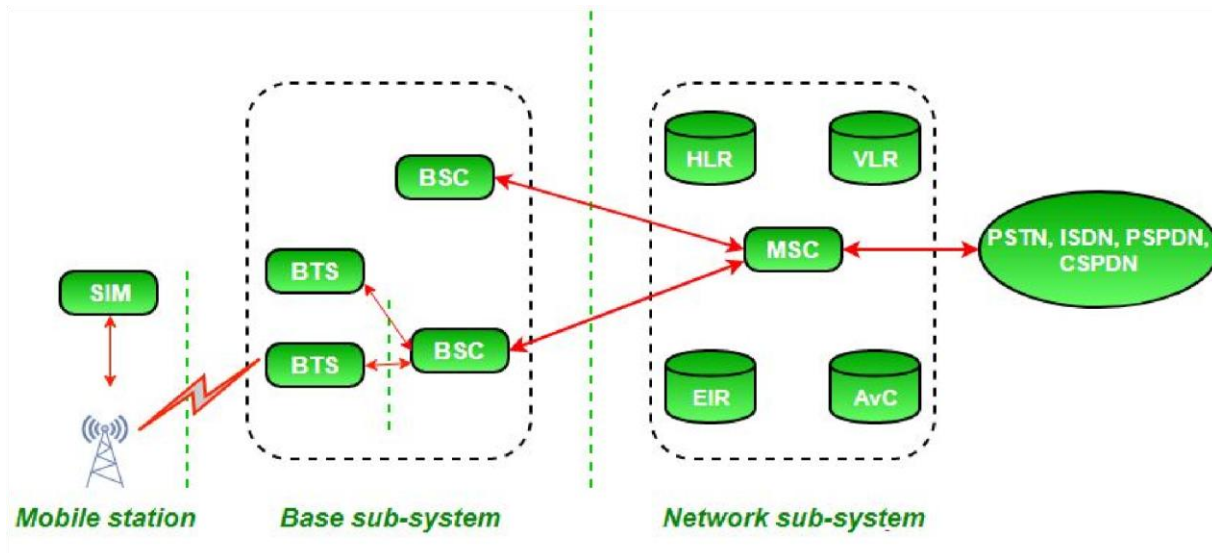


Figure 12.2 Cellular environment.

The mobile station is a mobile phone that includes a radio transceiver, digital signal processor, and display that is controlled by a SIM card that works on a system. The two components of the MS that are most crucial are the hardware and SIM card. Cell phones, which are part of a GSM mobile communications network that the operator manages, are the devices that are most often used to refer to the MS (Mobile Stations). Their size has significantly decreased but their talents have greatly increased in the present. The interval between charges has also been greatly increased.

Base station infrastructure (BSS)

It acts as a link between the mobile station and the network subsystem. It is divided into two parts. The Base Transceiver Station (BTS) houses the radio transceivers for the cell and is in charge of radio connection procedures with the MS. Businesses may deploy a large number of BTSs in a major metro region. The BTS is made up of transceivers and antennas and is present in each network cell. Every BTS has one to sixteen transceivers, depending on the cell's consumer density.

Managing the base station (BSC): One or more BTS's radio resources must be managed by the BSC (s). This controls the handovers and radio channel setup. The MSC and mobile are connected through the BSC. It assigns and emits MS time slots and frequency ranges. Additionally, the BSC transmits the BSS and MS power within its authority and is in charge of intercell handover.

The system for operations and support (OSS)

The entire GSM network architecture includes the operation support system (OSS). The NSS and BSC components are connected to this. The GSM network and BSS traffic load are mostly managed by the OSS. A few maintenance tasks are transferred to the base transceiver stations

when the number of BS rises as a result of customer population growing, reducing the system's financial liability. Having a network overview and assisting different services and maintenance groups with their regular maintenance plans are the key goals of OSS.

Sending and receiving text messages, for starters

The Short Message Service refers to the capability of sending and receiving text messages to and from mobile phones (SMS). SMS offers two-way paging-related services, but with additional functionality built into the mobile phone or port. A mobile phone user may get a fast, brief message on their phone using text messaging. The user may also write a short message to send to other users.

SMS utilises the control system air interface of the GSM platform to send brief text messages of up to 140 octets. Mobile users' brief messages are stored and sent to their intended recipients via the Short Message Service Center (SMSC). It may be used to send and receive short messages, saving time since communications are sent quickly. Additionally, because the mobile device has a signal and can send and receive text messages, there is no need to access the internet.

Data security and GSM

For use operators, data security is the most important consideration. To increase security, certain features are now introduced in GSM. Currently, this framework has an indication for ME and MS. Two subsystems are suggested by the system. While the security alert subsystem offers completely automated security monitoring, the appliance control subsystem enables customers to remotely operate home appliances.

The same technology may provide consumers with SMS instructions from a specific phone number on how to modify the home appliance's state depending on their requirements and preferences. The system is able to monitor Mobile subscribers on the database since the client is setup through SIM. Signal encryption characteristics are also part of GSM.

The system would be designed to enable the automated production of SMS upon detection of an intrusion, alerting the user to a possible danger. This would complete the second component of GSM security, security alert. Communication with anybody, everywhere, at any time will be possible thanks to GSM technology. The concept behind GSM proposes the development of GSM as the first step towards a real personal communication network with enough uniformity to ensure compatibility. GSM's functional design uses complex networking techniques.

GSM for switching over mobile systems

In every mobile system, the handover process is crucial. Due to the need of the procedure, poor handover might result in call loss. Subscribers may find undelivered calls to be particularly infuriating, and as the proportion of such calls rises, so does user annoyance, making them more inclined to transfer to another network.

As a consequence, while developing the standard, GSM handover received significant attention. The radio signal transfers from the old to the new cell whenever a mobile phone user changes cells. Contrary to previous systems, the GSM network is more complex, but customers benefit more from its flexibility since it offers superior performance. There are four standard forms of handoffs in a GSM network shown below:

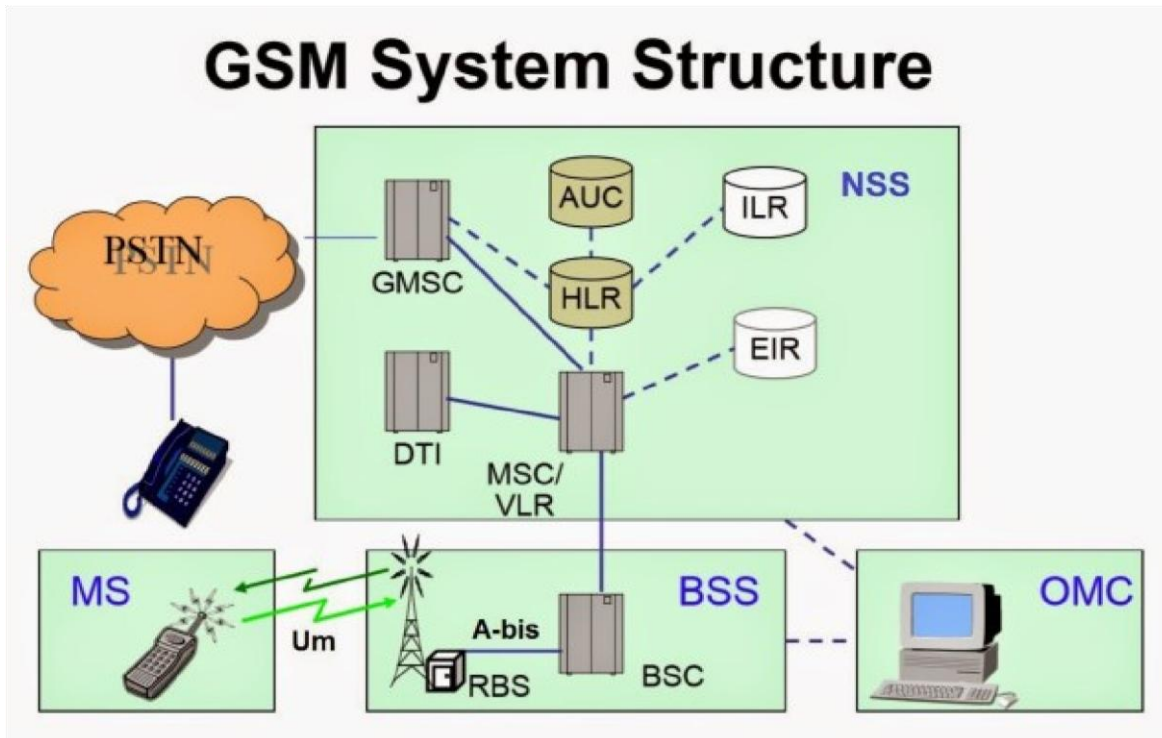


Figure 12.3 shows the GSM network.

Intra-cell handover: By altering the carrier signal, this sort of handover is used to increase data traffic inside the cell or to boost connection performance. **Cell to cell handoff:** It is sometimes referred to as intra-BSC handover. The mobile in this case switches cells while staying in the BSC. The transfer process in this case is under the supervision of the BSC. It's also referred to as an intra-MSC handover when it happens between BSCs. We may need to relocate a phone from one BSC to another since each BSC can only accommodate a certain number of cells. The MSC oversees the transfer in this case. **Inter-MSC handoff:** When a mobile device switches from one MSC region to another, this happens. MSC covers a wide geographic region.

The use of GSM in healthcare

If the patient just had access to a phone and is very ill or wounded, it would be easy to contact the nearest hospital. When travelling to the medical institution, the patient might obtain first treatment if they are linked to the doctor. When a condition is present, clinicians may study the patient's medical history and be ready for more testing while still giving the necessary treatment.

When a power loss leaves a patient, attendant, or hospital employee stranded on hospital property, GSM-fixed cellular terminals enable the person to quickly communicate with the nearest emergency services. In such case, a person may use the GSM SIM in the installed Fixed Cellular Terminal to seek assistance (FCT). The whole scenario is the fault of telemedicine services. Any of the three methods below might be used to use the telemedicine system.

Using satellites to make phone calls

Several satellite-based systems have been put into operation to supplement the mobile telephone networks that are based on the ground and in the air. These systems are designed to provide immediate connectivity to the PSTN from anywhere on the surface of the Earth, particularly in

locations where cellular phone coverage is currently unavailable. Airborne cellular systems that use Inmarsat satellites have long provided a means of mobile satellite communication. The Inmarsat satellites, on the other hand, are geostationary, orbiting the Earth at a height of around 35,000 kilometres (22,000 miles). Earth-based communication transceivers need strong transmitting power, sizable communication antennas, or both in order to connect with the satellite due to its high-altitude orbit. Additionally, a two-way audio discussion will have a perceptible delay of about a quarter second due to the lengthy communication channel. A more extensive network of satellites in low Earth orbit would be one practical substitute for geostationary satellites (LEO). LEO satellites are not geostationary since they orbit less than 1,600 km (1,000 miles) above Earth. As a result, they cannot continuously cover a particular region of the planet. However, a constellation of satellites may ensure that no call is missed just because a single satellite has moved out of range by enabling radio communications with a mobile instrument to be passed over between satellites.

The Iridium system, created by Motorola, Inc. and controlled by the global coalition of businesses and governments known as Iridium LLC, was the first LEO system intended for commercial use. A constellation of 66 satellites circling the Earth in six different planes was used for the Iridium idea. They were introduced between May 1997 and May 1998, and their first paid service started in November 1998. Each satellite could send 48 spot beams to Earth while orbiting at a height of 778 kilometres (483 miles). All of the satellites were conversing with one another using 23-gigahertz radio "crosslinks" at the same time, enabling seamless satellite handoff whether speaking with a stationary or moving user on Earth. Between the satellite servicing a user at any given time and the satellite linking the complete constellation with the gateway ground station to the PSTN, the crosslinks offered an unbroken communication connection. The 66 satellites enabled continuous telephone contact for subscriber units all across the world in this fashion. However, since not enough people used the service, Iridium LLC closed its doors in March 2000. Iridium Satellite LLC bought its assets, continuing to provide the US Department of Defense as well as commercial and private consumers international communication services.

By using video conferencing, patients who are sitting in one place may speak with doctors immediately, advancing the healing process using health monitoring devices to provide hospitals and clinicians with ongoing information about a patient's health and to direct therapy transferring the collected health information and the data for analysis and consultation. The quantity of data and information transferred through networks, our ability to communicate quickly, and the manner in which we communicate will all be significantly impacted by this. Future communications technology may be divided into three main categories: machine-to-machine (M2M), machine-to-machine, and human-to-human. Below, we go into further depth on each of them.

Communications from machines to machines (M2M)

Machine-to-machine communication, or M2M as it is often known, employs artificial intelligence (AI) and machine learning (ML) to transmit data between networked devices and carry out tasks automatically and in real-time without the need of people. These data are processed and used by M2M apps to start pre-set automatic reactions and processes. Although it may seem like science fiction, this technology is often used in situations when remote monitoring is required. Robotics, remote-control software, logistics, fleet management, warehouse

management, and other fields may all benefit from M2M technology. M2M may be used in the telecommunications industry for managing connection, remote work, data use, managing mobile assets, and more. This gives organizations the chance to increase operational effectiveness, improve decision-making with real-time data, save expenses, and increase revenue.

The use of this digital communication is widespread. In the healthcare sector, it is used to continuously monitor patient vital signs, data, etc. and subsequently deliver medicine as necessary. Additionally, it may be used to monitor other hospital resources including equipment and available beds. Future communication technology is prominently featured in smart houses, which are being built using this technology and allow for remote control of consumer electronics and other technologies.

Questions for Revision

How Communication System Works?

What Is The Systems For Electronic Communication?

What Is Transmitter In The System?

How The Communication System Work Effectively?

How the Analog And Digital Communication Is Different From Each Other?

What Are The Elements Of The Communication System?

How The Tendency Of Communication Differ From Each Other?

What is Ambient Noise?

What is industrial noise?

How noise plays an important role in the communication system?

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